

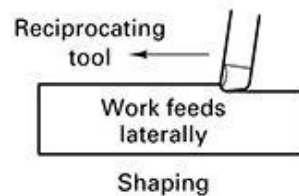
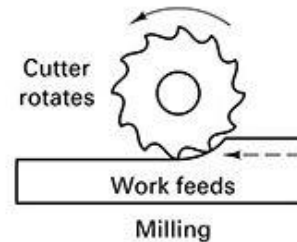
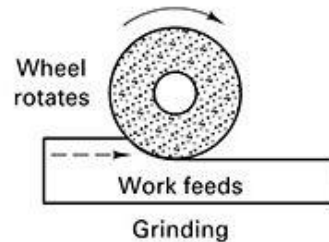
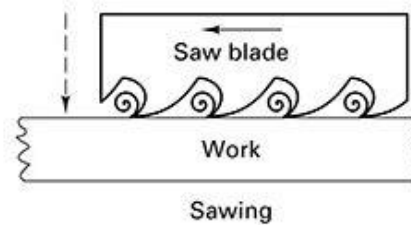
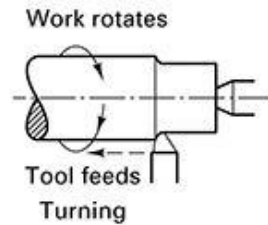
Fundamentals of Chip-Type Machining Processes

Machining

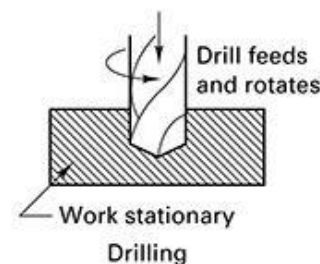
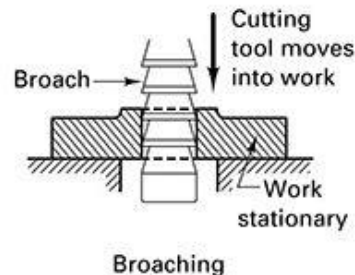
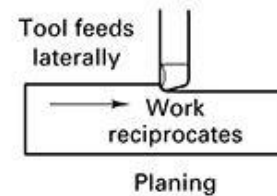
Removing unwanted material in the form of chips:

- Turning
- Sawing
- Grinding
- Milling
- Shaping or planing
- Broaching
- Drilling

Seven Basic Machining Processes



or

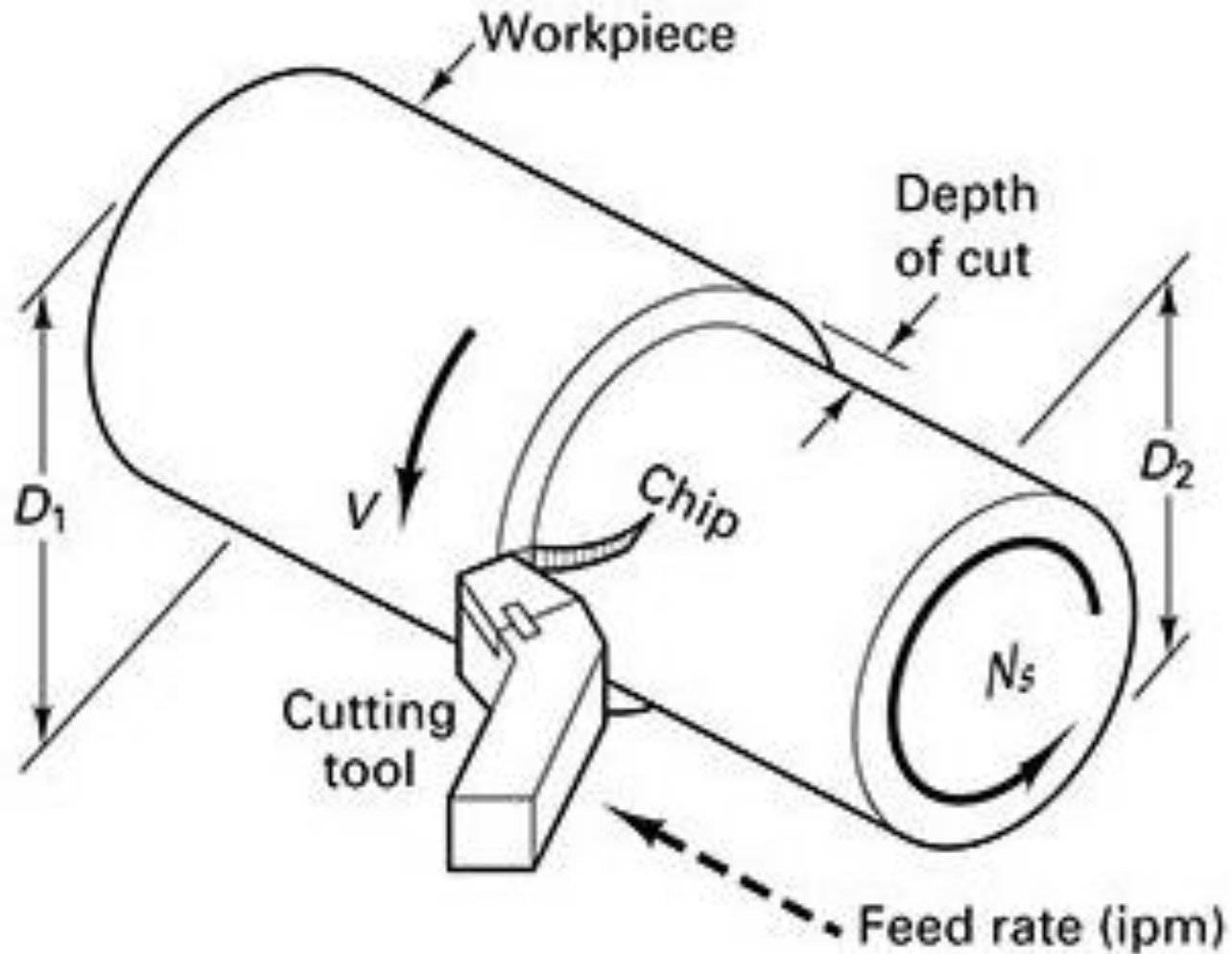


Machining Process

Affected by:

- Machine tool (the machine itself)
- Cutting tool (geometry and material)
- Workpiece (properties and material)
- Cutting tool parameters
 - ❖ Speed
 - ❖ Feed
 - ❖ Depth of cut
- Workpiece holding devices

Cutting Parameters



Four Cutting Tool Parameters

- 1. Speed
- 2. Depth of Cut (DOC)
- 3. Feed Rate (f_r)
- 4. Material Removal Rate (MRR)

Speed

Speed – velocity of workpiece relative to cutting tool; the **primary cutting motion**

- $V = \pi D_1 N_s / 12$, in *ft/min*
- D_1 = original diameter, inches
- N_s = angular velocity of workpiece, *RPM*
- $N_s \cong 3.8V / D_1$

Depth of Cut

Depth of Cut (DOC) – distance tool plunged into workpiece

- $d = (D_1 - D_2)/2$, inches

Feed Rate

Feed Rate (f_r) – amount of material removed per revolution (inches/rev)

Material Removal Rate

Material Removal Rate

$MRR = (\text{volume removed})/(\text{cutting time}), \text{ in}^3/\text{min}$

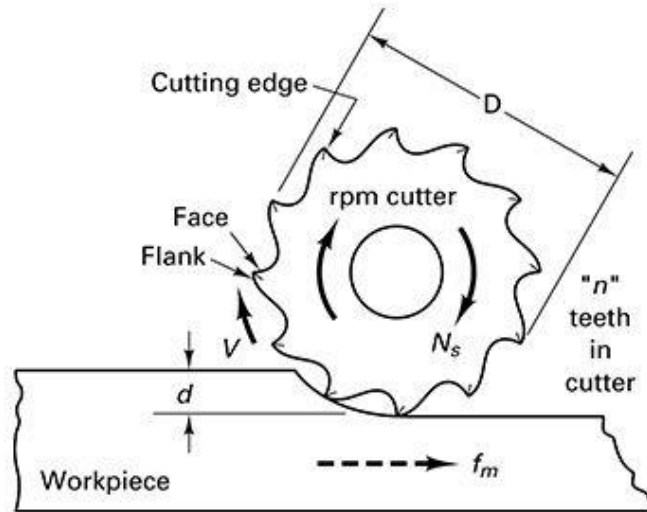
- $MRR \cong 12V f_r d, \text{ in}^3/\text{min}$
- $MRR \cong \pi D_1 N_s f_r d, \text{ in}^3/\text{min}$
- $d = \text{depth of cut}$

Milling Material Removal Rate

Multiple-tooth cutter is used

- Table feed: $f_m = f_t n N_s$
- f_t = feed per tooth pass, inches/rev
- n = number of teeth
- N_s = angular velocity, RPM
- $MRR = W d f_m$, in³/min

Slab/Face Milling Basics



Slab milling - multiple tooth

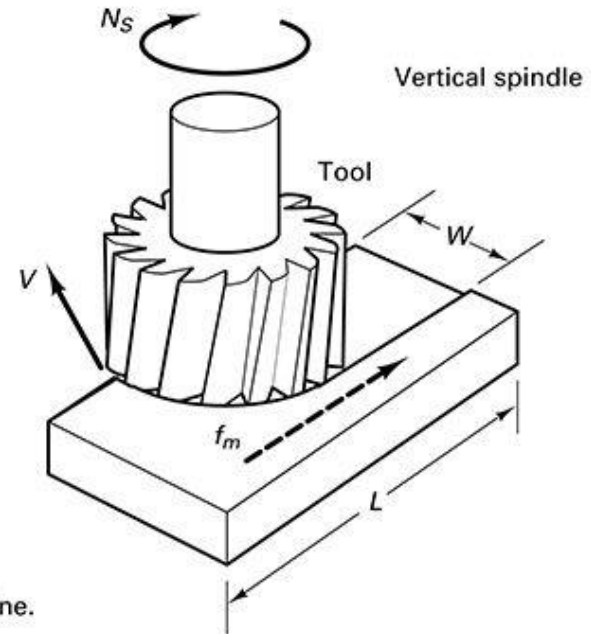
Slab milling is usually performed on a horizontal milling machine. Equations for T_m and MRR derived in Chapter 25.

The tool rotates at rpm N_s . The workpiece translates past the cutter at feed rate f_m , the table feed. The length of cut, L , is the length of workpiece plus allowance, L_A .

$$L_A = \sqrt{\frac{D^2}{4} - \left(\frac{D}{2} - d\right)^2} = \sqrt{d(D-d)} \text{ inches}$$

$$T_m = (L + L_A)/f_m$$

The MRR = Wdf_m where W = width of the cut and d = depth of cut.



Face milling
Multiple-tooth cutting

Given a selected cutting speed V and a feed per tooth f_t , the rpm of the cutter is $N_s = 12V/\pi D$ for a cutting of diameter D . The table feed rate is $f_m = f_t n N_s$ for a cutter with n teeth.

The cutting time, $T_m = (L + L_A + L_o)/f_m$ where $L_o = L_A = \sqrt{W(D-W)}$ for $W < D/2$ or $L_o = L_A = D/2$ for $W \geq D/2$.

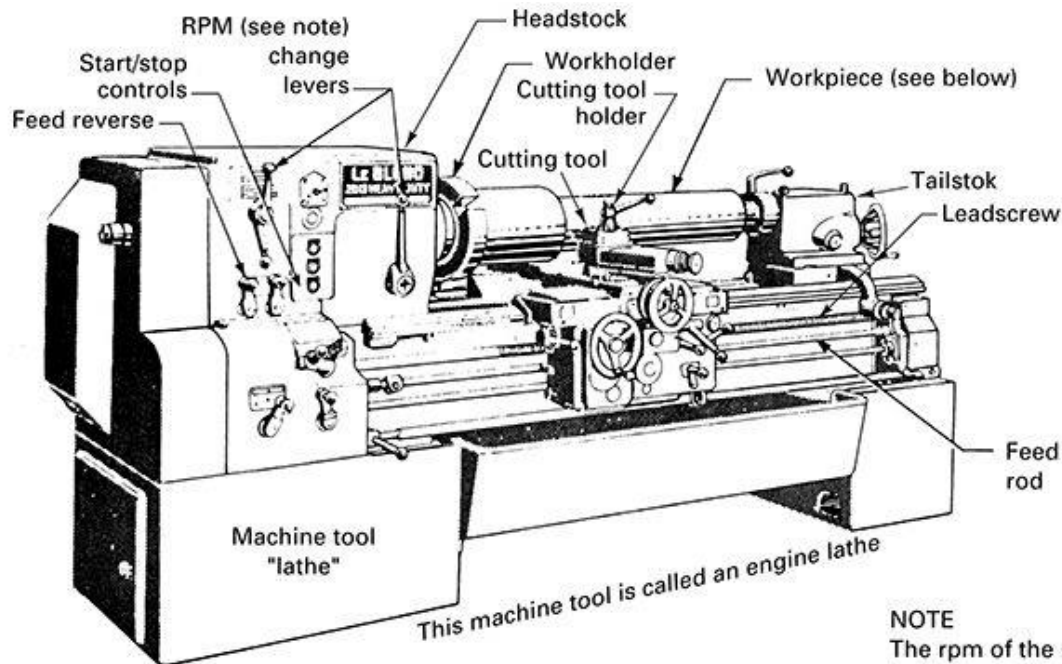
The MRR = Wdf_m where d = depth of cut.

Shop Formulas for Various Processes

Shop Formulas for Turning, Milling, Drilling, and Broaching (English Units)

Parameter	Turning	Milling	Drilling	Broaching
Cutting speed, fpm	$V = 0.262 \times D_t \times \text{rpm}$	$V = 0.262 \times D_m \times \text{rpm}$	$V = 0.262 \times D_d \times \text{rpm}$	V
Revolutions per minute, N_s	$\text{rpm} = 3.82 \times V_c/D_t$	$\text{rpm} = 3.82 \times V_c/D_m$	$\text{rpm} = 3.82 \times V_c/D_d$	—
Feed rate, in./min Feed per rev tooth pass, in./rev	$f_m = f_r \times \text{rpm}$ f_r	$f_m = f_r \times \text{rpm}$ f_t	$f_m = f_r \times \text{rpm}$ f_r	— —
Cutting time, min, T_m	$T_m = L/f_m$	$T_m = L/f_m$	$T_m = L/f_m$	$T_m = L/12V$
Rate of metal removal, in. ³ /min	$\text{MRR} = 12 \times d \times f_r \times V_c$	$\text{MRR} = w \times d \times f_m$	$\text{MRR} = \pi D^2 d/4 \times f_m$	$\text{MRR} = 12 \times w \times d \times V$
Horsepower required at spindle	$\text{hp} = \text{MRR} \times \text{HP}_s$	$\text{hp} = \text{MRR} \times \text{HP}_s$	$\text{hp} = \text{MRR} \times \text{HP}_s$	—
Horsepower required at motor	$\text{hp}_m = \text{MRR} \times \text{HP}_s/E$	$\text{hp}_m = \text{MRR} \times \text{HP}_s/E$	$\text{hp}_m = \text{MRR} \times \text{HP}_s/E$	$\text{hp}_m = \text{MRR} \times \text{HP}_s/E$
Torque at spindle	$t_s = 63,030 \text{ hp/rpm}$	$t_s = 63,030 \text{ hp/rpm}$	$t_s = 63,030 \text{ hp/rpm}$	—
Symbols	D_t = Diameter of workpiece in turning, inches D_m = Diameter of milling cutter, inches D_d = Diameter of drill, inches d = Depth of cut, inches E = Efficiency of spindle drive f_m = Feed rate, inches per minute f_r = Feed, inches per revolution f_t = Feed, inches per tooth hp_m = Horsepower at motor MRR = Metal removal rate, in. ³ /min			hp = horsepower at spindle L = Length of cut, inches n = Number of teeth in cutter HP_s = Unit power, horsepower per cubic inch per minute, specific horsepower N_s = Revolution per minute of work or cutter t_s = Torque at spindle, inch-pound T_m = Cutting time, minutes V = Cutting speed, feet per minute w = Width of cut, inches

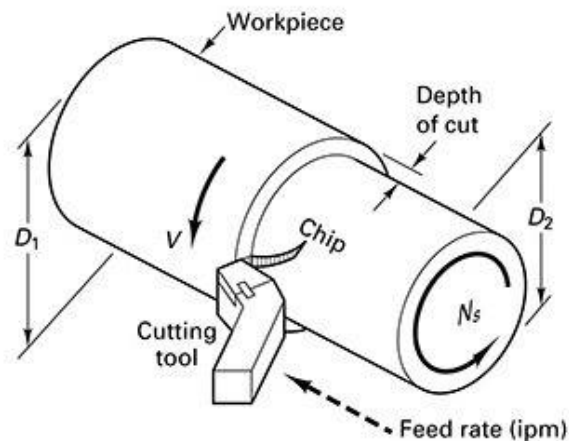
Lathe Turning

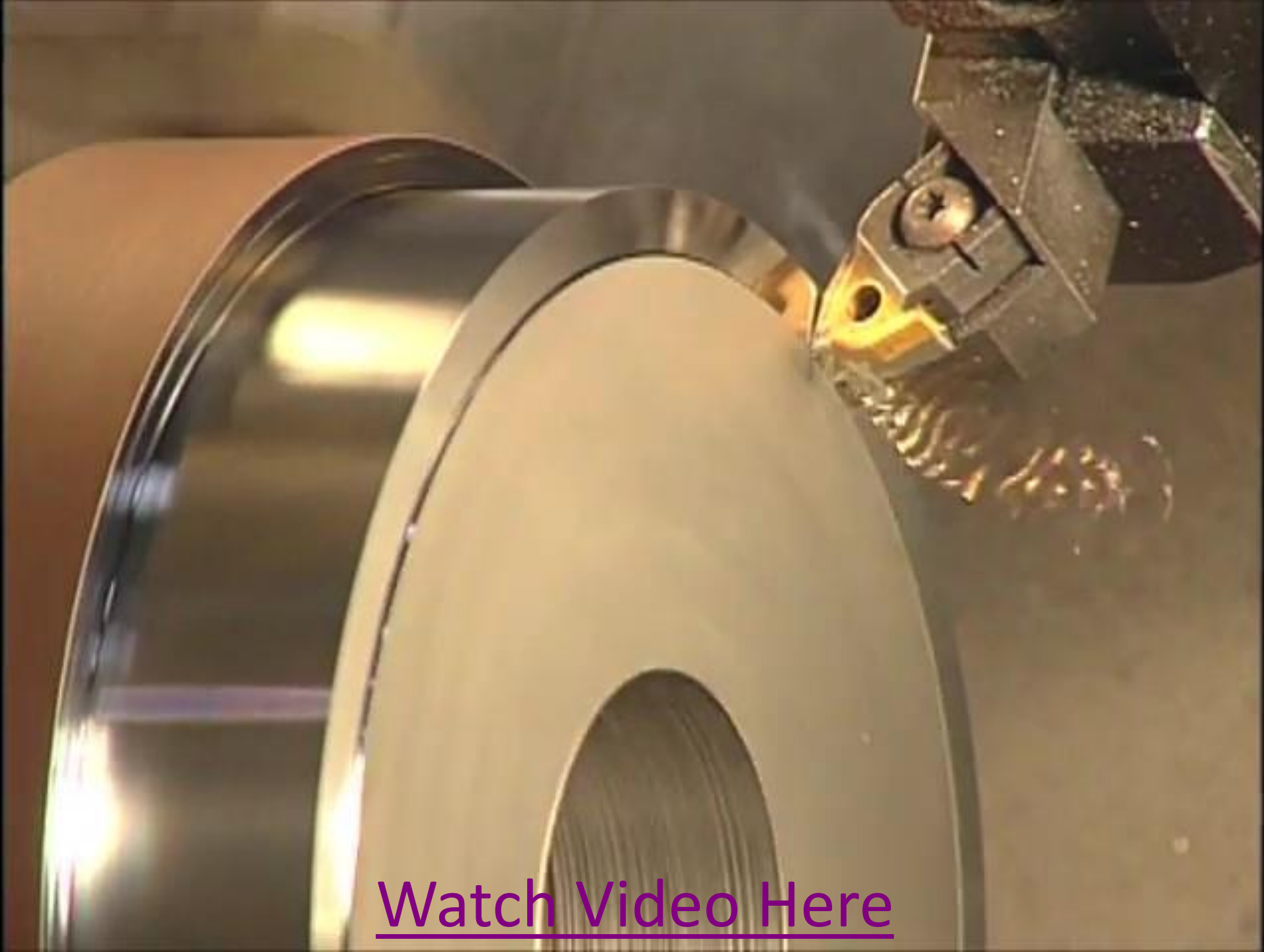


NOTE

The rpm of the rotating workpiece is N_s . It establishes the cutting speed V , at the tool, according to $N_s = 12V/\pi D$.

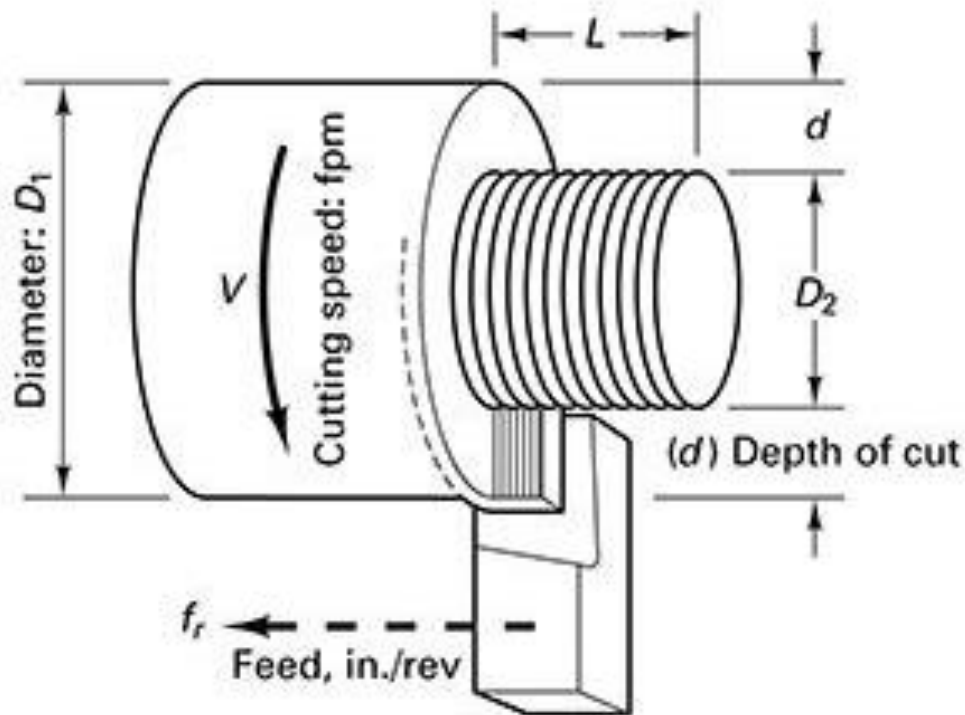
The depth of cut, d , is equal to $(D_1 - D_2)/2$.
The length of cut is the distance the tool travels parallel to the axis, L .





[Watch Video Here](#)

Lathe Turning



Turning

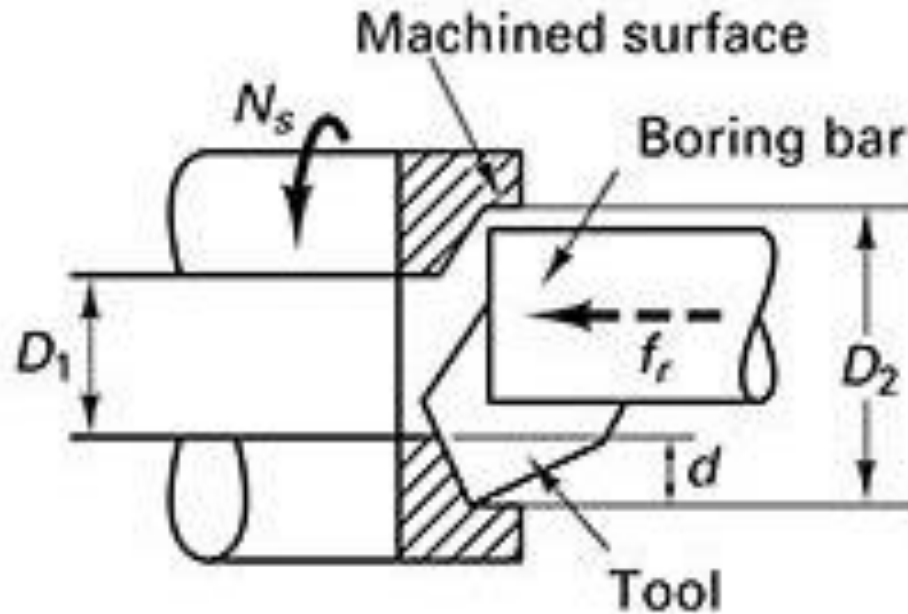
Speed, stated in surface feet per minute (sfpm), is the peripheral speed at the cutting edge. Feed per revolution in turning is a linear motion of the tool parallel to the rotating axis of the workpiece. The depth of cut reflects the third dimension.

L = length of cut

$$T_m = \frac{L + A}{f_r N_s}$$

T_m = cutting time, minutes

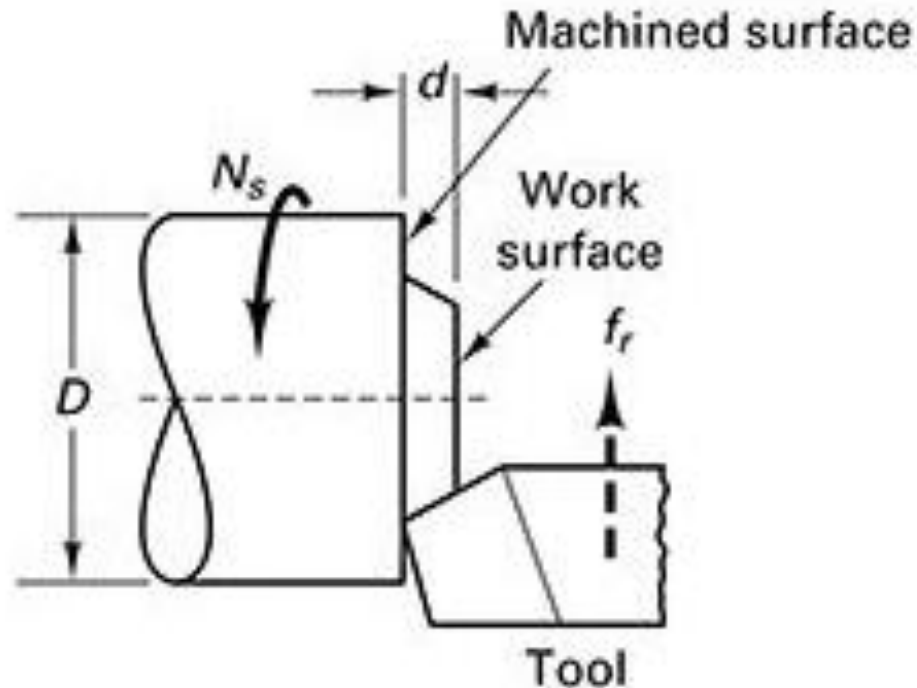
Boring Basics



Boring

Enlarging hole of diameter D_1 to diameter D_2 . Boring can be done with multiple cutting tools. Feed in inches per revolution, f_r

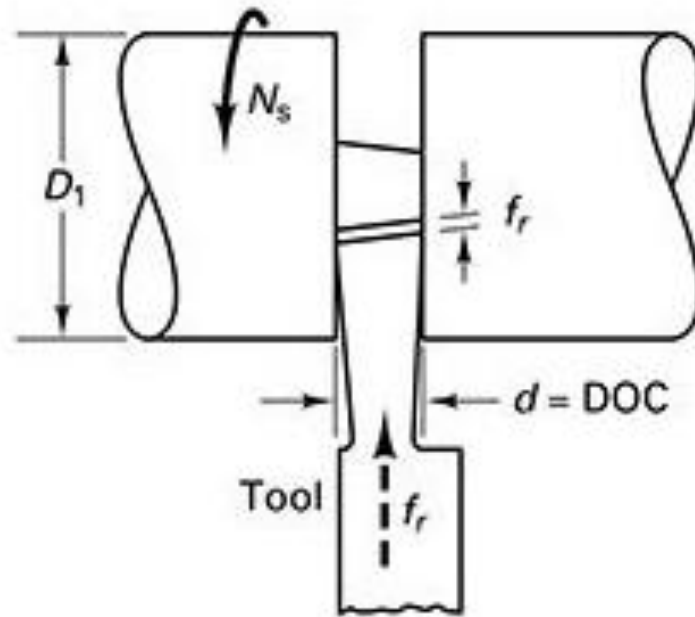
Facing Basics



Facing

Tool feeds to center of workpiece so $L = D/2$. The cutting speed is decreasing as the tool approaches the center of the workpiece.

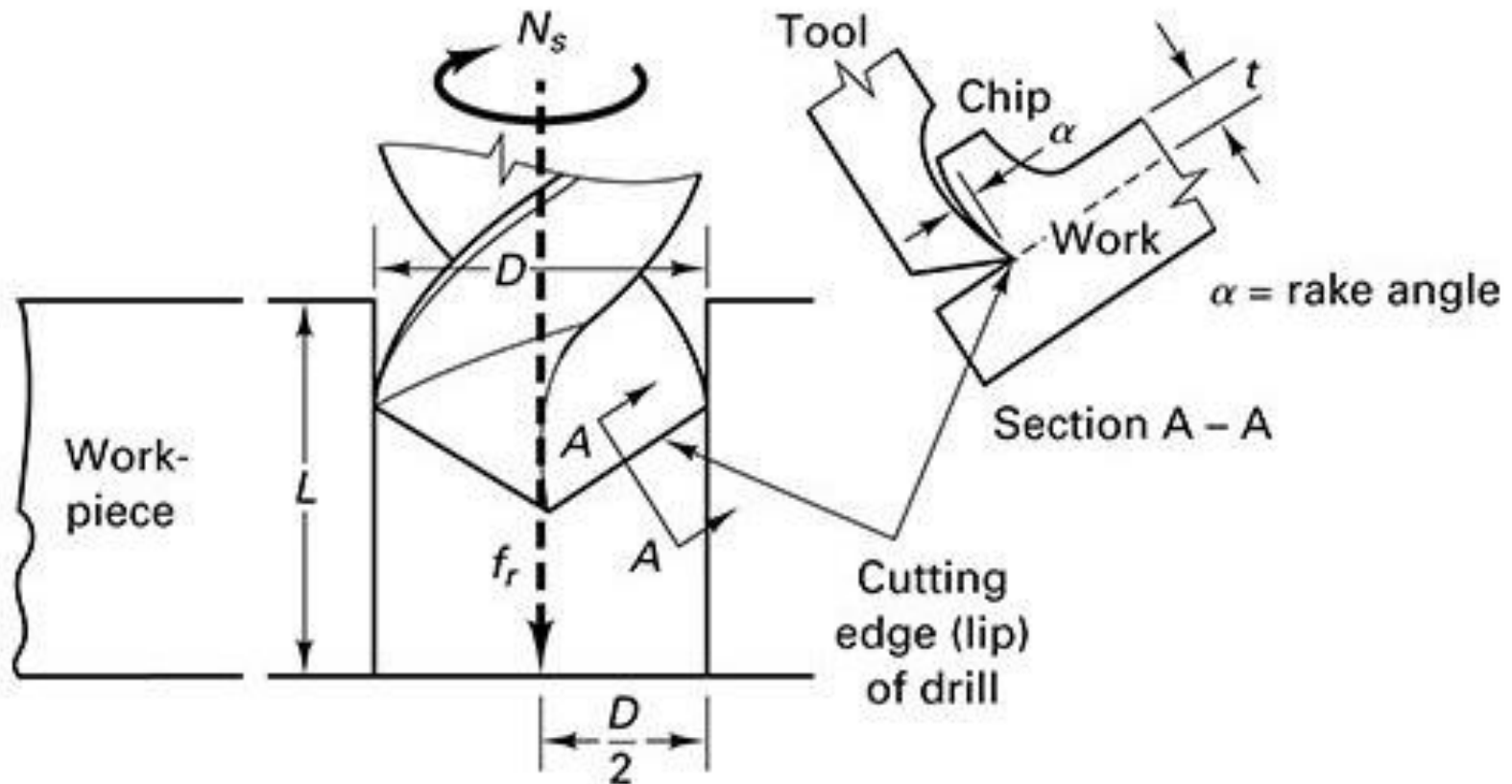
Grooving, Parting, or Cut-off



Grooving, parting, or cutoff

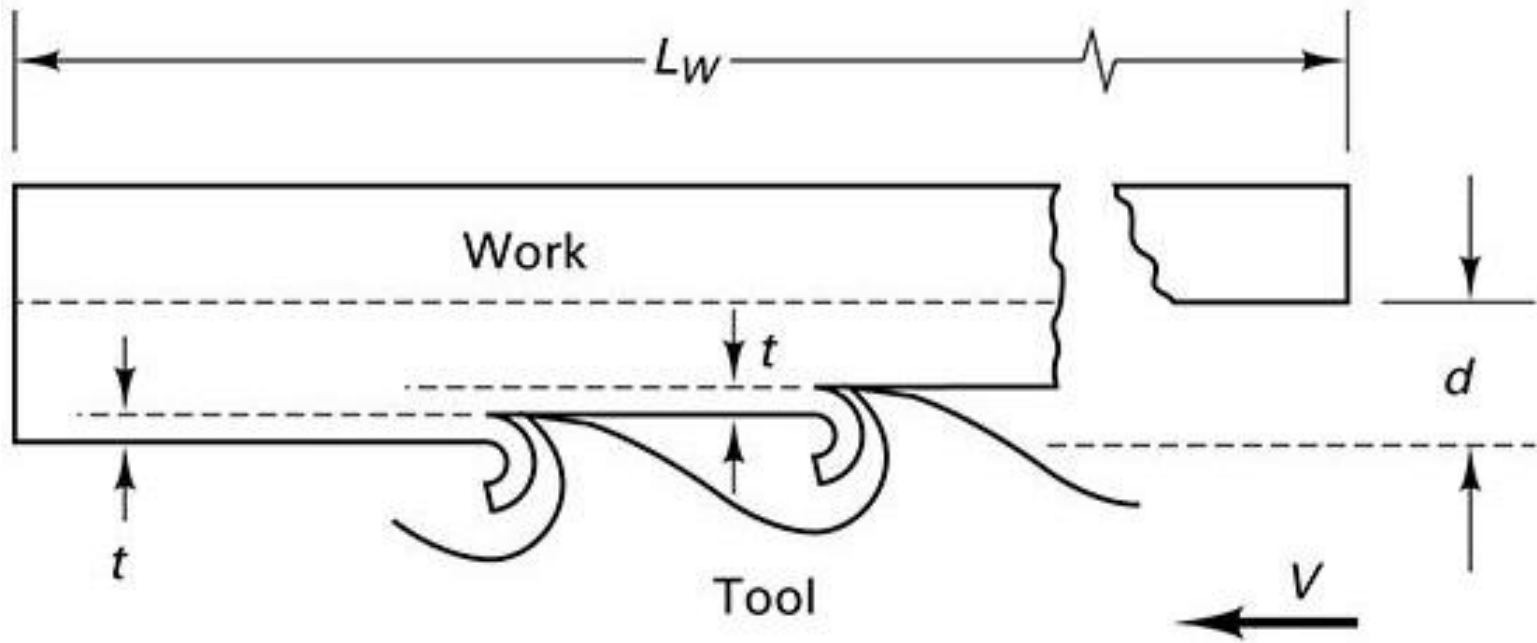
Tool feed perpendicular to the axis of rotation. The width of the tool produces the depth of cut (DOC).

Drilling Basics

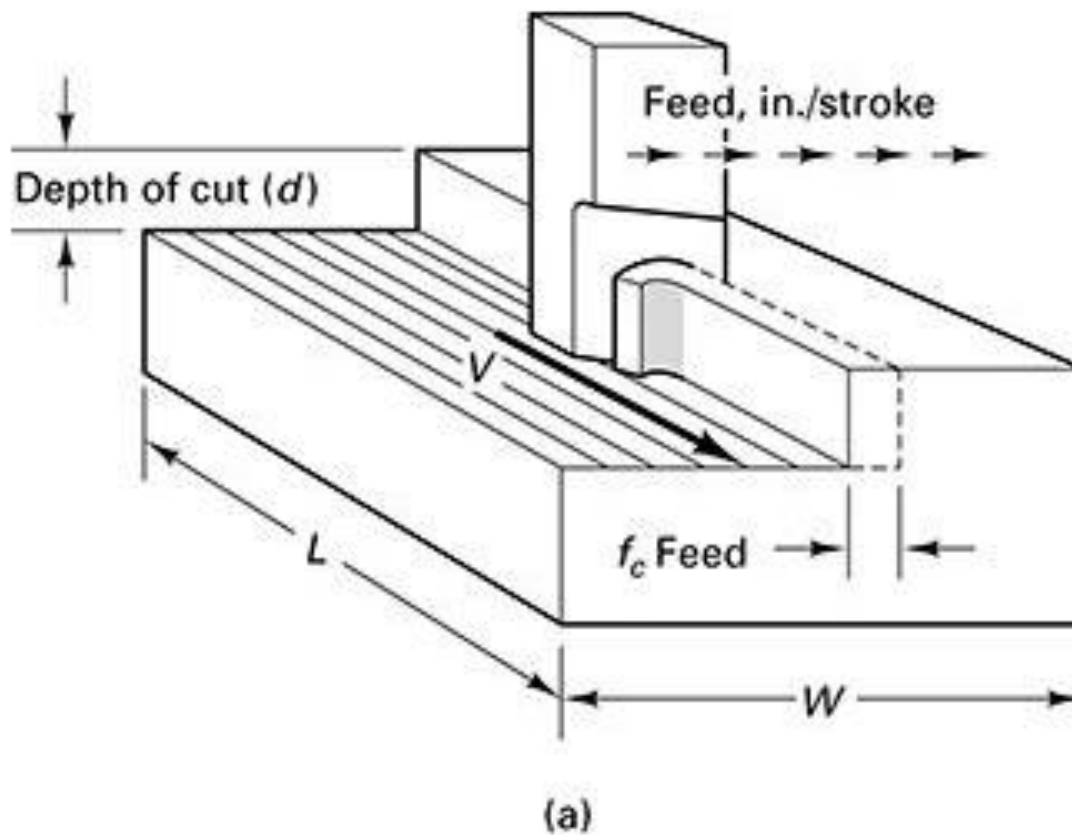


Drilling multiple-edge tool

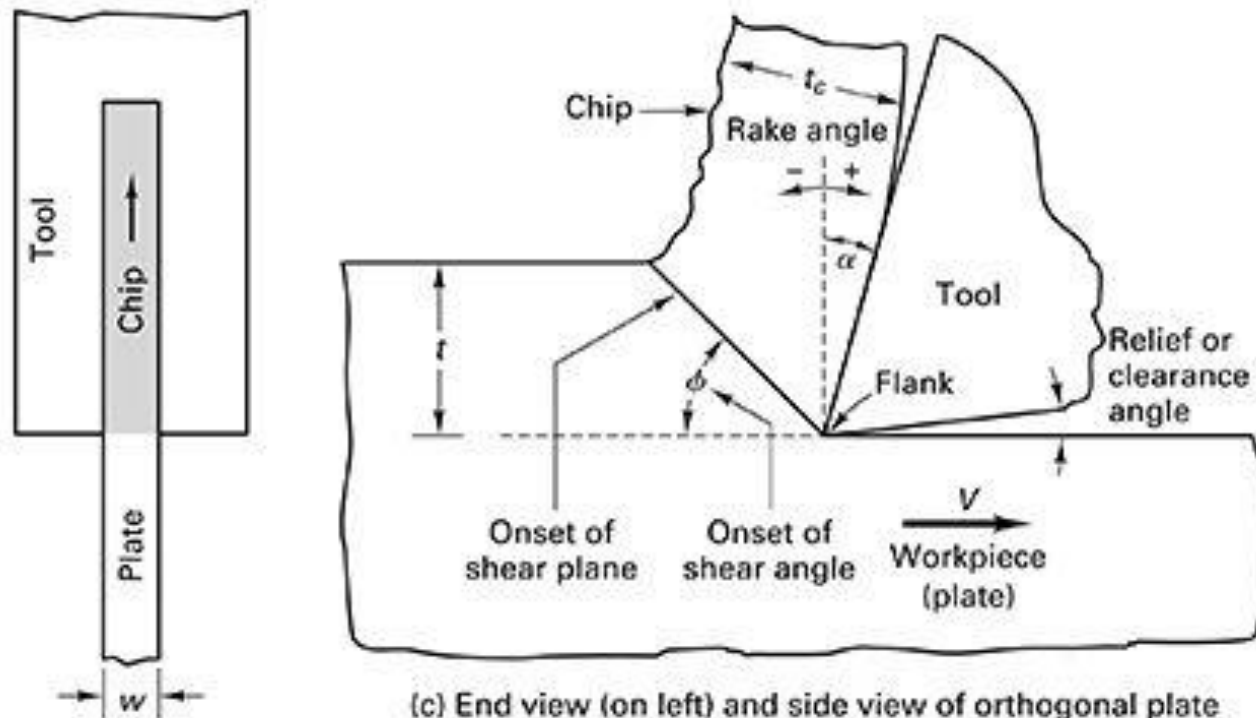
Broaching Basics



Shaping/Planing Basics

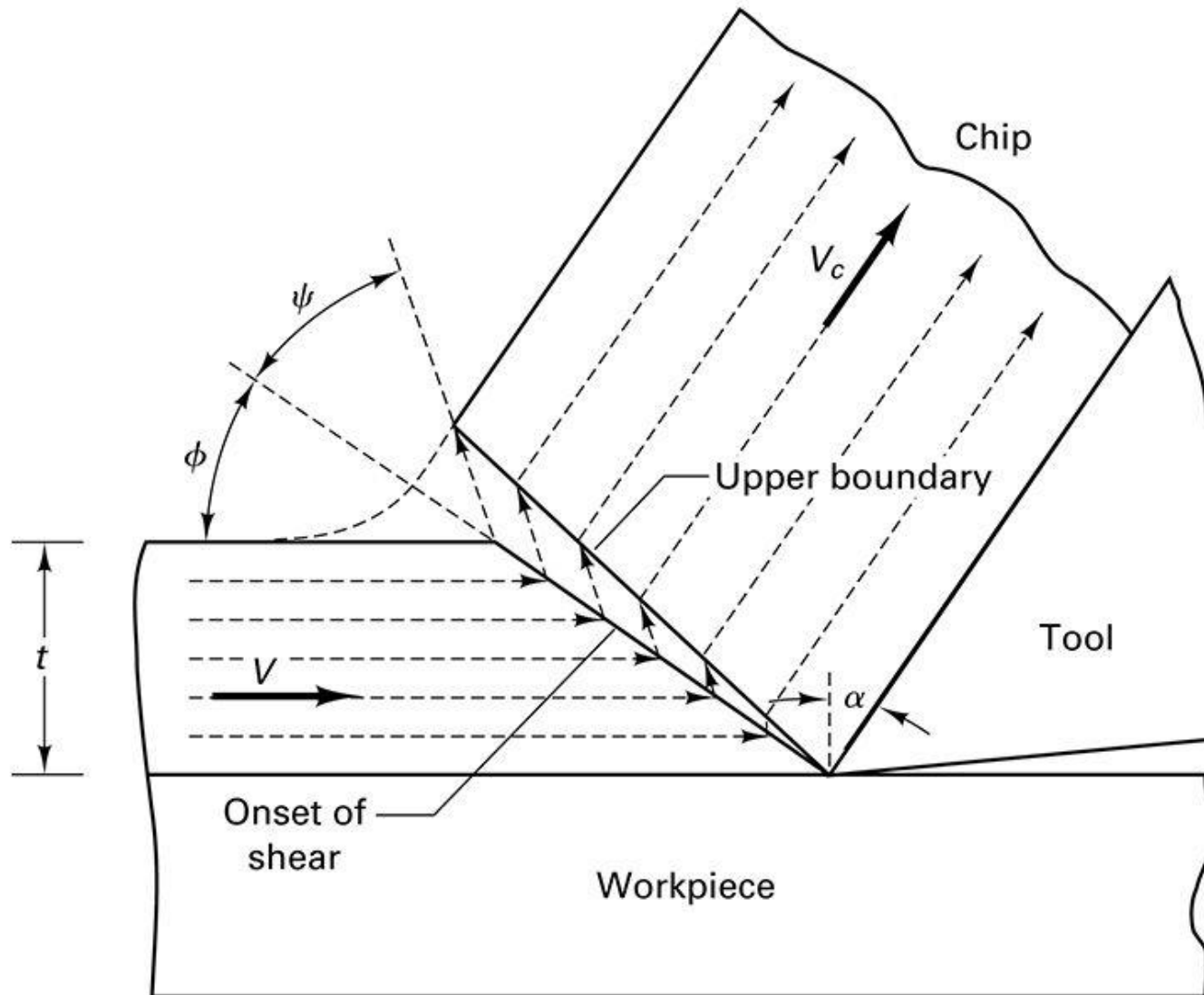


Understanding Chip Formation

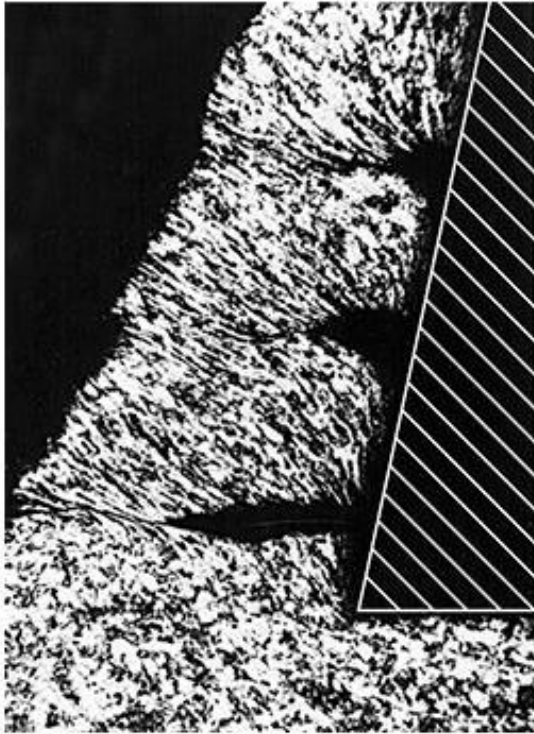


(c) End view (on left) and side view of orthogonal plate machining with fixed tool and moving plate.

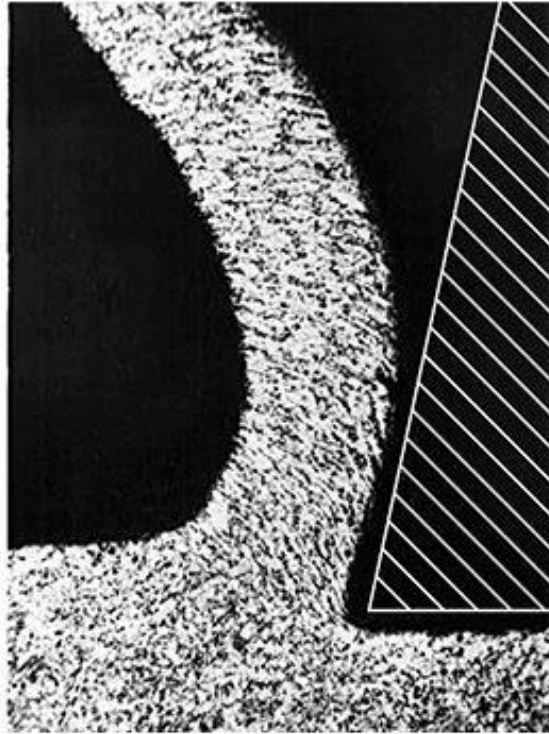
Removing a Chip



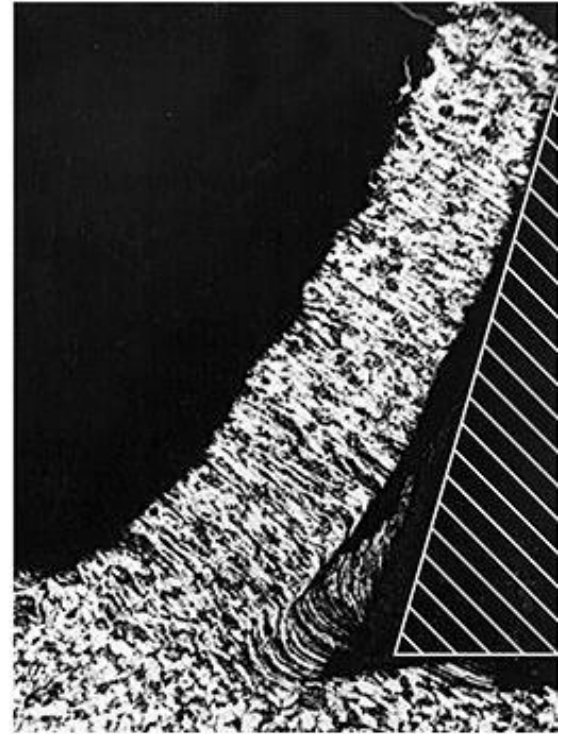
Effect of Workpiece Material Properties



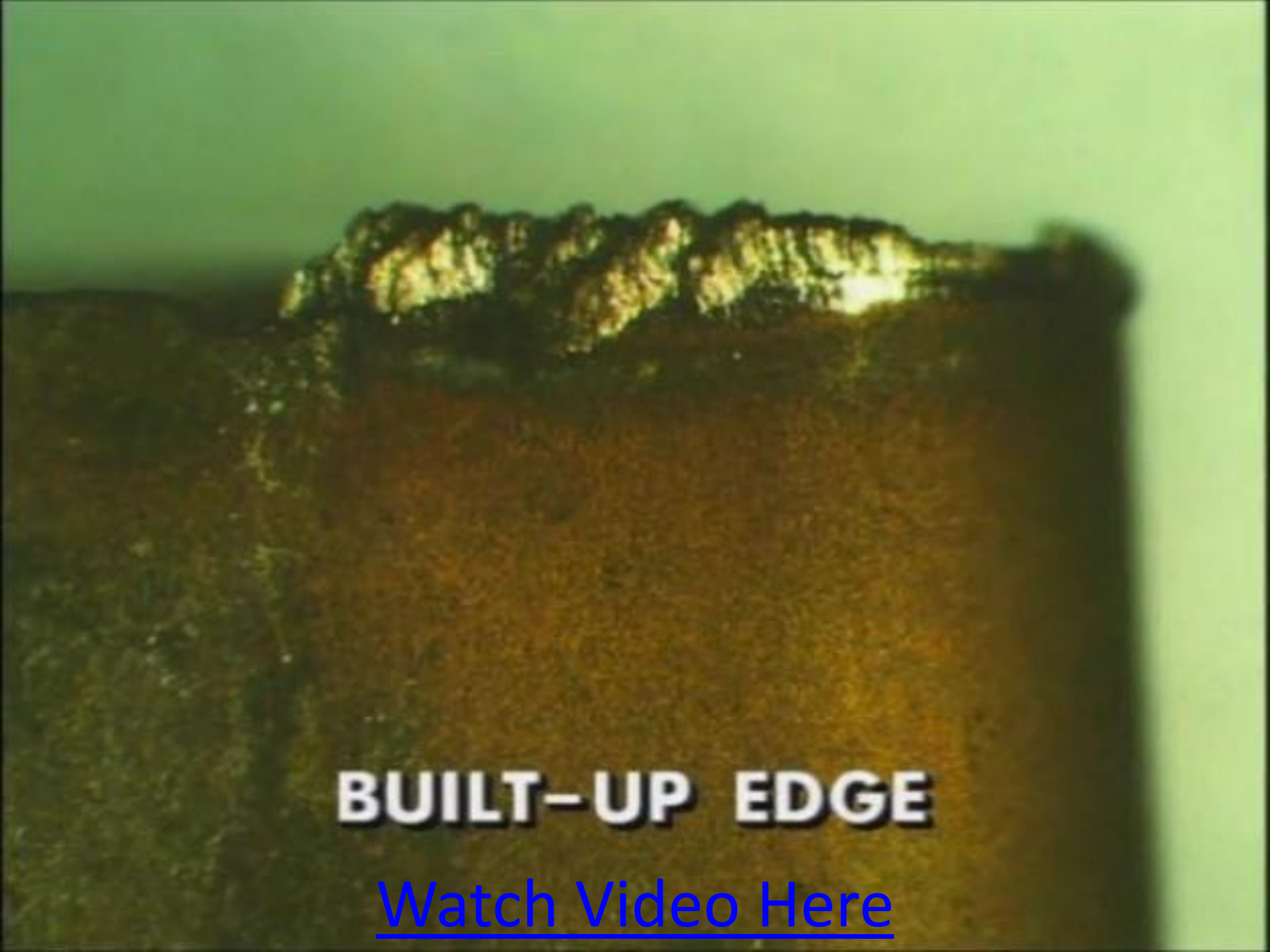
Discontinuous



Continuous



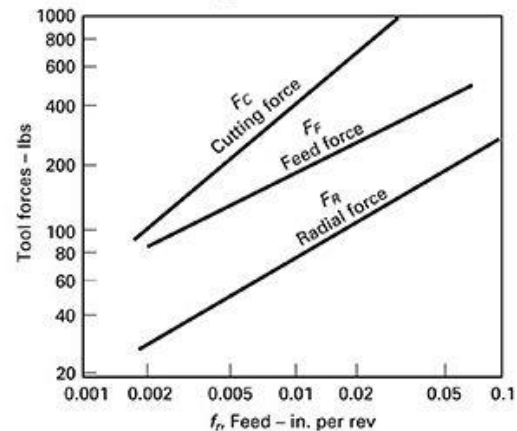
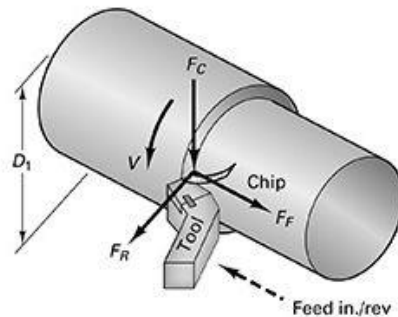
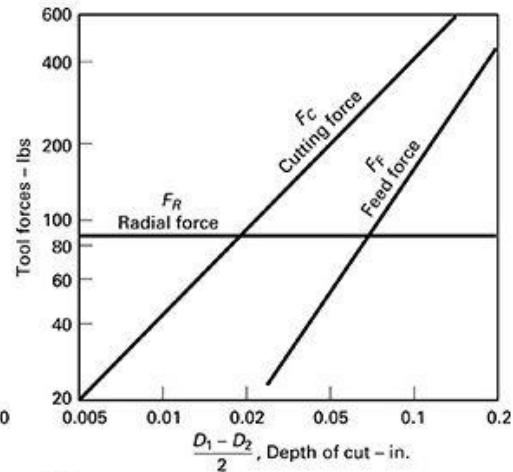
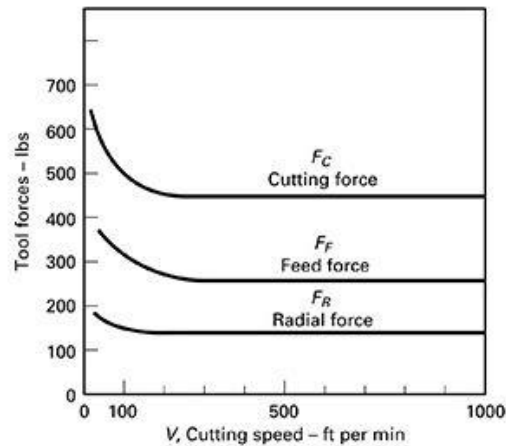
Continuous
with built-up edge



BUILT-UP EDGE

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Energy and Power in Machining



3 Force

F_C = Cutting force (vertical)

F_R = Radial force (thrust)

F_F = Feed force

Power

- $Power = F_c V$, ft-lbs/min
 V , ft/min
 F_c , lbs
- $HP = F_c V / 33000$, horsepower
- Specific horsepower $HP_s = HP / MRR$, ft-lbs/in³

TOOL FAILURE MODES

[Watch Video Here](#)