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**Algorithm 1** CD2XMappingInit(XRegionSet  $X$ )

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1: Initialize  $CovD2X$ ,  $IntD2X$ ,  $CovC2X$ ,  $IntC2X$ ;
2: RTree  $rt \leftarrow \emptyset$ ;
3: for each device  $dev$  in  $D$  do
4:   Add  $Cir(Loc(dev), Rad(dev))$  into  $rt$ ;
5: for each cell  $c$  in  $C$  do
6:   Add the spatial extent of  $c$  into  $rt$ ;
7: for each X-region  $x$  in  $X$  do
8:   ResultSet  $covR \leftarrow Search(rt, x, COVER)$ ;
9:   for each item  $a$  in  $covR$  do
10:    if  $a$  indicates device  $dev$ 's detection range then
11:       $CovD2X[dev] \leftarrow x$ ;
12:    else if  $a$  indicates cell  $c$ 's detection range then
13:       $CovC2X[c] \leftarrow x$ ;
14:   ResultSet  $intR \leftarrow Search(rt, x, INTERSECT)$ ;
15:   for each item  $a$  in  $(intR \setminus covR)$  do
16:    if  $a$  indicates device  $dev$ 's detection range then
17:       $IntD2X[dev] \leftarrow IntD2X[dev] \cup \{x\}$ ;
18:    else if  $a$  indicates cell  $c$ 's detection range then
19:       $IntC2X[c] \leftarrow IntC2X[c] \cup \{x\}$ ;
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