
Algorithm 1 Exhaustive RFID-data cleaning algorithm.

Require: a d -sequence $D = R_1, \dots, R_T$, a map M , the object maximum speed v_{\max} .

Ensure: a p-trajectory p_1, \dots, p_T .

Forward phase:

1: $C(1) = \text{Cells}(R_1)$

2: **for all** $c \in C(1)$ **do**

3: $p_1^{\text{fw}}(c) = \frac{1}{|C(1)|}$

4: **for** $t = 2$ **to** T **do**

5: $C(t) = \{c \mid c \in \text{Cells}(R_t) \wedge \exists c' \in C(t-1) \text{ s.t. } \frac{d_{\min}(c', c)}{\Delta} \leq v_{\max}\}$

6: **for all** $c \in C(t)$ **do**

7: $p_t^{\text{fw}}(c) = \sum_{c' \in C(t-1)} p_{t-1}^{\text{fw}}(c') \cdot p^{\text{mov}}(v \geq \frac{d_{\min}(c', c)}{\Delta})$

Backward phase:

8: **for** $t = T$ **downTo** 1 **do**

9: **for all** $c \in C(t)$ **do**

10: **if** $t = T$ **then**

11: $p_T^{\text{bw}}(c) = \frac{1}{|C(T)|}$

12: **else**

13: $p_t^{\text{bw}}(c) = \sum_{c' \in C(t+1)} p_{t+1}^{\text{bw}}(c') \cdot p^{\text{mov}}(v \geq \frac{d_{\min}(c, c')}{\Delta})$

14: **if** $p_t^{\text{bw}}(c) = 0$ **then**

15: $C(t) = C(t) \setminus \{c\}$

16: **else**

17: $p_t(c) = p_t^{\text{fw}}(c) \cdot p_t^{\text{bw}}(c) \cdot h(R_t|c)$

18: Project p_1, \dots, p_T on \mathcal{L} and normalize

19: **return** p_1, \dots, p_T
