Algorithm 2 pt2ptDistance(Source indoor position p_s , destination indoor position p_t) 1: $v_s \leftarrow \text{getHostPartition}(p_s)$ 2: $v_t \leftarrow \text{getHostPartition}(p_t)$ 3. $dist \leftarrow \infty$ 4: **for** each door $d_s \in P2D_{\sqsubset}(v_s)$ **do** $dist_1 \leftarrow dist_V(p_s, d_s)$ 5: for each door $d_t \in P2D_{\neg}(v_t)$ do $dist_2 \leftarrow dist_V(p_t, d_t)$

6: 7: 8:

if $dist > dist_1 + d2dDistance(d_s, d_t) + dist_2$ then

 $dist \leftarrow dist_1 + d2dDistance(d_s, d_t) + dist_2$ 9: return dist