

Algorithm 3 **findAllPaths**(Probabilistic distance-aware graph model G_{pdm} , Source reader R_s , Destination reader R_d)

```
1: stack  $S \leftarrow \emptyset$  ;  $neighbors \leftarrow \emptyset$  ;  $paths \leftarrow \emptyset$  ;  
2:  $S.push(R_s)$   
3: if ( $curr = R_d$ ) then  
4:    $paths[] \leftarrow S$   
5:  $neighbors \leftarrow getNeighbors(R_s, G_{pdm})$   
6: for each  $n$  in  $neighbors$  do  
7:   if ( $n$  not in stack  $S$ ) then  
8:      $findAllPaths(G_{pdm}, n, R_d)$   
9:  $S.pop()$ 
```
