Manage the Data from Indoor Spaces: Models, Indexes & Query Processing

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Overview

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- 3. Indoor Data Cleansing
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Aims

- To give a brief review introduction to *indoor data* management techniques.
- To review a series of works in this field, including their proposed models, indexes and algorithms.
- To discuss how to bring those advanced theoretical contents into practice.

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About This Work...

Probabilistic Threshold k Nearest Neighbor Queries over Moving Objects in Symbolic Indoor Space. [4]
B. Yang, H. Lu, and C. S. Jensen.

- Published in year 2010 at the *EDBT* conference.
- Minimal Indoor Walking Distance(MIWD) along with algorithms and data structures are proposed for distance computing and storage.
- Effective object indexing structures, also capture the uncertainty of object locations.
- On this foundation, Probabilistic threshold kNN (PTkNN) query is studied.

Motivation

- Indoor positioning makes it possible to support interesting queries over large populations of moving objects.
 - shopping mall, airports, office buildings
 - kNN queries over indoor moving objects enables the detection of approaching potential threats at sensitive locations in a subway system
- Existing kNN techniques in spatial and spatialtemporal databases are inapplicable in indoor spaces.
 - complex entities and topologies
 - indoor positioning techniques differ fundamentally from outdoor GPS, low sampling frequency and accuracy

 $2.3 \; \text{Probabilistic Threshold} \; k \; \text{Nearest Neighbor Queries over Moving Objects in Symbolic Indoor Space}$

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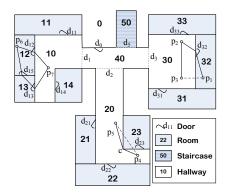
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The mapping Doors maps a room to the doors that connect the room to an adjacent room:

$$Doors: \Sigma_{rooms} \to 2^{\Sigma_{doors}}$$
 (2)

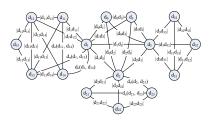
Minimal Indoor Walking Distance



- intra-room obstructed distance, termed as d_o . E.g., $d_o(p_2, p_3) = |p_2p_3|$ and $d_o(p_4, p_5) = |p_4c| + |cp_5|$.
- if in different rooms, it should take into account the doors connecting the rooms. E.g., $d_{MIN}(p_1,p_2) = |p_1d_{32}| + |d_{17}p_9|.$
- if there exist several paths, the correct path should be the shortest one. E.g., $d_{MIN}(p_6,p_7) = |p_6d_{12}| + |d_{12}p_7| \\ \neq |p_6d_{15}| + |d_{15}d_{13}| + |d_{13}p_7|.$

Minimal Indoor Walking Distance

Doors Graph is capable of retrieving the connecting doors between two rooms, which is convenient for computing MIWD.



Doors Graph

- $G_d = \{D, E, l_{weight}\}$
- $D = \Sigma_{doors}$ is the set of the vertices
- E: An edge $\{d_i, d_j\}$ exists if a room rm exists in Σ_{rooms} such that $\{d_i, d_j\} \subseteq Doors(rm)$
- l_{weight}: E → R assigns to an edge the obstructed distance between the two doors as d_o(d_i, d_j)

Minimal Indoor Walking Distance

All door-to-door shortest path distances can be computed and recorded in a hash table $\rm D2D$ according to the Doors Graph.

 $2.3 \ \mathsf{Probabilistic} \ \mathsf{Threshold} \ \mathsf{k} \ \mathsf{Nearest} \ \mathsf{Neighbor} \ \mathsf{Queries} \ \mathsf{over} \ \mathsf{Moving} \ \mathsf{Objects} \ \mathsf{in} \ \mathsf{Symbolic} \ \mathsf{Indoor} \ \mathsf{Space}$

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$$d_{MIN}(d_p, d_q) = d_o(p, d_p) + D2D(d_p, d_q) + d_o(d_q, q)$$
(4)

where $d_p(d_q)$ ranges over all doors of room p(q).

```
Algorithm 1 d_{MW} (Position p, Position q)

1: if Rooms(p) = Rooms(q) then

2: minDist \leftarrow d_0(p, q);

3: else

4: minDist \leftarrow +\infty

5: for each door d_p in Doors(Rooms(p)) do

6: for each door d_p in Doors(Rooms(q)) do

7: l \leftarrow d_n(p, d_p) + d_n(d_q, q) + D2D(d_p, d_q)

8: if l < minDist \leftarrow l;

9: minDist \leftarrow l;

10: return minDist.
```

it is possible to adapt this notion of distance to accommodate other semantics. For example, a person might prefer a longer indoor path that passes as few doos as possible.

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The End. Thanks:)