

Input Images
3@200x200

Input Norm
3@200x200

Feature map
24@98x98

Feature map
36@47x47

Feature map
48@22x22

Feature map
64@20x20

Feature map
64@18x18

5x5 Conv

5x5 Conv

5x5 Conv

3x3 Conv

3x3 Conv

Input

Convolutional Layer

Flatten
Features
20736

FC1
100

FC2
50

FC3
10

FC4
1

Fully Connected Layer

Steering Angle
Prediction

Ground Truth

Loss Value

Output

