

§2.4 基变换与坐标变换

一、线性组合的形式记法

二、基变换

三、坐标变换

一、线性组合的形式记法

1、设 V 为数域 P 上的 n 维线性空间, $\alpha_1, \alpha_2, \cdots, \alpha_n$ 为 V 中的一组向量, $\beta \in V$, 若

$$\beta = x_1\alpha_1 + x_2\alpha_2 + \cdots + x_n\alpha_n$$

则可记作

$$\beta = (\alpha_1, \alpha_2, \cdots, \alpha_n) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$\beta_1, \beta_2, \dots, \beta_n$ 为V中的两组向量, 若

[illegible]

则可记作

$$(\beta_1, \beta_2, \dots, \beta_n) = (\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}$$

注：在形式书写法下有下列运算规律

$$1) \alpha_1, \alpha_2, \dots, \alpha_n \in V, a_1, a_2, \dots, a_n, b_1, b_2, \dots, b_n \in P$$

$$(\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} + (\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} = (\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} a_1 + b_1 \\ a_2 + b_2 \\ \vdots \\ a_n + b_n \end{pmatrix}$$

若 $\alpha_1, \alpha_2, \dots, \alpha_n$ 线性无关，则

$$(\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} = (\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \Leftrightarrow \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

2) $\alpha_1, \alpha_2, \dots, \alpha_n; \beta_1, \beta_2, \dots, \beta_n$ 为 V 中的两组向量,

矩阵 $A, B \in P^{n \times n}$, 则

$$((\alpha_1, \alpha_2, \dots, \alpha_n)A)B = (\alpha_1, \alpha_2, \dots, \alpha_n)(AB);$$

$$\begin{aligned} (\alpha_1, \alpha_2, \dots, \alpha_n)A + (\alpha_1, \alpha_2, \dots, \alpha_n)B \\ = (\alpha_1, \alpha_2, \dots, \alpha_n)(A + B); \end{aligned}$$

$$\begin{aligned} (\alpha_1, \alpha_2, \dots, \alpha_n)A + (\beta_1, \beta_2, \dots, \beta_n)A \\ = (\alpha_1 + \beta_1, \alpha_2 + \beta_2, \dots, \alpha_n + \beta_n)A; \end{aligned}$$

若 $\alpha_1, \alpha_2, \dots, \alpha_n$ 线性无关, 则

$$(\alpha_1, \alpha_2, \dots, \alpha_n)A = (\alpha_1, \alpha_2, \dots, \alpha_n)B \Leftrightarrow A = B$$

1、定义

$\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n$ 为V中的两组基, 若

[illegible]

即，

$$(\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n) = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n) \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \quad (2)$$

则称矩阵

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}$$

为由基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 到基 $\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n$ 的**过渡矩阵**;

称 ① 或 ② 为由基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 到基 $\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n$

的**基变换公式**.

2、性质

1) 过渡矩阵都是可逆矩阵；反过来，任一可逆矩阵都可看成是两组基之间的过渡矩阵.

证明： 若 $\alpha_1, \alpha_2, \dots, \alpha_n; \beta_1, \beta_2, \dots, \beta_n$ 为 V 的两组基，
且由基 $\alpha_1, \alpha_2, \dots, \alpha_n$ 到 $\beta_1, \beta_2, \dots, \beta_n$ 的过渡矩阵为 A ，
即 $(\beta_1, \beta_2, \dots, \beta_n) = (\alpha_1, \alpha_2, \dots, \alpha_n)A$ ③

又由基 $\beta_1, \beta_2, \dots, \beta_n$ 到 $\alpha_1, \alpha_2, \dots, \alpha_n$ 也有一个过渡矩阵，
设为 B ，即 $(\alpha_1, \alpha_2, \dots, \alpha_n) = (\beta_1, \beta_2, \dots, \beta_n)B$ ④

比较③、④两个等式，有

$$(\alpha_1, \alpha_2, \dots, \alpha_n) = (\alpha_1, \alpha_2, \dots, \alpha_n)AB$$

$\because \alpha_1, \alpha_2, \dots, \alpha_n$ 是V的一组基,

$\therefore AB = E$. 即, A是可逆矩阵, 且 $A^{-1} = B$.

反过来, 设 $A = (a_{ij})_{n \times n}$ 为P上任一可逆矩阵,

任取V的一组基 $\alpha_1, \alpha_2, \dots, \alpha_n$,

$$\text{令 } \beta_j = \sum_{i=1}^n a_{ij} \alpha_i = (\alpha_1, \alpha_2, \dots, \alpha_n) \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{nj} \end{pmatrix}, j = 1, 2, \dots, n$$

于是有, $(\beta_1, \beta_2, \dots, \beta_n) = (\alpha_1, \alpha_2, \dots, \alpha_n)A$

由 \mathbf{A} 可逆, 有 $(\alpha_1, \alpha_2, \dots, \alpha_n) = (\beta_1, \beta_2, \dots, \beta_n) \mathbf{A}^{-1}$

即, $\alpha_1, \alpha_2, \dots, \alpha_n$ 也可由 $\beta_1, \beta_2, \dots, \beta_n$ 线性表出.

$\therefore \alpha_1, \alpha_2, \dots, \alpha_n$ 与 $\beta_1, \beta_2, \dots, \beta_n$ 等价.

故 $\beta_1, \beta_2, \dots, \beta_n$ 线性无关, 从而也为 V 的一组基.

并且 \mathbf{A} 就是 $\alpha_1, \alpha_2, \dots, \alpha_n$ 到 $\beta_1, \beta_2, \dots, \beta_n$ 的过渡矩阵.

2) 若由基 $\alpha_1, \alpha_2, \dots, \alpha_n$ 到基 $\beta_1, \beta_2, \dots, \beta_n$ 的过渡矩阵为 \mathbf{A} ,

则由基 $\beta_1, \beta_2, \dots, \beta_n$ 到基 $\alpha_1, \alpha_2, \dots, \alpha_n$ 的过渡矩阵为 \mathbf{A}^{-1} .

3) 若由基 $\alpha_1, \alpha_2, \dots, \alpha_n$ 到基 $\beta_1, \beta_2, \dots, \beta_n$ 的过渡矩阵为 A ,
由基 $\beta_1, \beta_2, \dots, \beta_n$ 到基 $\gamma_1, \gamma_2, \dots, \gamma_n$ 的过渡矩阵为 B , 则
由基 $\alpha_1, \alpha_2, \dots, \alpha_n$ 到基 $\gamma_1, \gamma_2, \dots, \gamma_n$ 的过渡矩阵为 AB .

事实上, 若 $(\beta_1, \beta_2, \dots, \beta_n) = (\alpha_1, \alpha_2, \dots, \alpha_n)A$

$$(\gamma_1, \gamma_2, \dots, \gamma_n) = (\beta_1, \beta_2, \dots, \beta_n)B$$

$$\begin{aligned} \text{则有, } (\gamma_1, \gamma_2, \dots, \gamma_n) &= ((\alpha_1, \alpha_2, \dots, \alpha_n)A)B \\ &= (\alpha_1, \alpha_2, \dots, \alpha_n)AB \end{aligned}$$

三、坐标变换

1、定义： V 为数域 P 上 n 维线性空间 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$;
 $\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n$ 为 V 中的两组基, 且

$$(\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n) = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n) \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \quad (5)$$

设 $\xi \in V$ 且 ξ 在基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 与基 $\varepsilon'_1, \varepsilon'_2, \dots, \varepsilon'_n$ 下的坐标分别为 (x_1, x_2, \dots, x_n) 与 $(x'_1, x'_2, \dots, x'_n)$,

$$\text{即, } \xi = (\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \text{ 与 } \xi = (\varepsilon'_1, \varepsilon'_2, \cdots, \varepsilon'_n) \begin{pmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{pmatrix}$$

$$\text{因为, } (\varepsilon'_1, \varepsilon'_2, \cdots, \varepsilon'_n) = (\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n) \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix},$$

从而,

$$(\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = (\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n) \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{pmatrix}$$

$$\text{则} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{pmatrix} \quad \textcircled{6}$$

$$\text{或} \begin{pmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}^{-1} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad \textcircled{7}$$

称⑥或⑦为向量 ξ 在基变换⑤下的坐标变换公式.

例1 在 \mathbf{P}^n 中, 求由基 $\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n$ 到基 $\eta_1, \eta_2, \cdots, \eta_n$ 的过渡矩阵及由基 $\eta_1, \eta_2, \cdots, \eta_n$ 到基 $\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n$ 的过渡矩阵. 其中

$$\varepsilon_1 = (1, 0, \dots, 0), \varepsilon_2 = (0, 1, \dots, 0), \dots, \varepsilon_n = (0, \dots, 0, 1)$$

$$\eta_1 = (1, 1, \dots, 1), \eta_2 = (0, 1, \dots, 1), \dots, \eta_n = (0, \dots, 0, 1)$$

并求向量 $\alpha = (a_1, a_2, \cdots, a_n)$ 在基 $\eta_1, \eta_2, \cdots, \eta_n$ 下的坐标.

[illegible]

$$\therefore (\eta_1, \eta_2, \dots, \eta_n) = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n) \begin{pmatrix} 1 & 0 & \dots & 0 \\ 1 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 1 & 1 & \dots & 1 \end{pmatrix}$$

$$\text{从而, } (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n) = (\eta_1, \eta_2, \dots, \eta_n) \begin{pmatrix} 1 & 0 & \dots & 0 \\ 1 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 1 & 1 & \dots & 1 \end{pmatrix}^{-1}$$

$$= (\eta_1, \eta_2, \dots, \eta_n) \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}$$

故，由基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 到基 $\eta_1, \eta_2, \dots, \eta_n$ 的过渡矩阵为

$$\begin{pmatrix} 1 & 0 & \cdots & 0 \\ 1 & 1 & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots \\ 1 & 1 & \cdots & 1 \end{pmatrix}$$

由基 $\eta_1, \eta_2, \dots, \eta_n$ 到基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 的过渡矩阵为

$$\begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ -1 & 1 & 0 & \cdots & 0 \\ 0 & -1 & 1 & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix}$$

$\alpha = (a_1, a_2, \dots, a_n)$ 在基 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 下的坐标就是

$$(a_1, a_2, \dots, a_n)$$

设 α 在基 $\eta_1, \eta_2, \dots, \eta_n$ 下的坐标为 (x_1, x_2, \dots, x_n) , 则

$$\begin{aligned}\alpha &= \sum_{i=1}^n a_i \varepsilon_i = (\varepsilon_1 \ \varepsilon_2 \ \cdots \ \varepsilon_n) \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \\ &= (\eta_1 \ \eta_2 \ \cdots \ \eta_n) \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ -1 & 1 & 0 & \cdots & 0 \\ 0 & -1 & 1 & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}\end{aligned}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ -1 & 1 & 0 & \cdots & 0 \\ 0 & -1 & 1 & \cdots & 0 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 & -a_1 \\ \vdots \\ a_n & -a_{n-1} \end{pmatrix},$$

所以 α 在基 $\eta_1, \eta_2, \cdots, \eta_n$ 下的坐标为

$$(a_1, a_2 - a_1, \cdots, a_n - a_{n-1}).$$

例2 在 $P[x]_3$ 中, 设

$$\eta_1 = x^2 - x + 1, \eta_2 = x - 1, \eta_3 = 1,$$

$$\alpha_1 = x^2 + x + 3, \alpha_2 = x - 5, \alpha_3 = x^2 + 2x - 1,$$

- (1) 求由基 η_1, η_2, η_3 到基 $\alpha_1, \alpha_2, \alpha_3$ 的过渡矩阵;
- (2) 设向量 β 在基 $\alpha_1, \alpha_2, \alpha_3$ 下的坐标为 $(1, -1, 2)$,
求向量 β 在基 η_1, η_2, η_3 下的坐标.

解：(1) 设 $\varepsilon_1 = x^2, \varepsilon_2 = x, \varepsilon_3 = 1$,

则有

$$(\eta_1, \eta_2, \eta_3) = (\varepsilon_1, \varepsilon_2, \varepsilon_3) \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix},$$
$$(\alpha_1, \alpha_2, \alpha_3) = (\varepsilon_1, \varepsilon_2, \varepsilon_3) \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 3 & -5 & -1 \end{pmatrix},$$

设 $(\alpha_1, \alpha_2, \alpha_3) = (\eta_1, \eta_2, \eta_3)A$, 则有

$$(\varepsilon_1, \varepsilon_2, \varepsilon_3) \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 3 & -5 & -1 \end{pmatrix} = (\varepsilon_1, \varepsilon_2, \varepsilon_3) \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} A,$$

从而,

$$\begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 3 & -5 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} A,$$

解得,

$$A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 3 & -5 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 3 \\ 4 & -4 & 1 \end{pmatrix}$$

(2) $\beta = \alpha_1 - \alpha_2 + 2\alpha_3$

$$= (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = (\eta_1, \eta_2, \eta_3) A \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = (\eta_1, \eta_2, \eta_3) \begin{pmatrix} 3 \\ 7 \\ 10 \end{pmatrix}$$

求向量 β 在基 η_1, η_2, η_3 下的坐标为 $(3, 7, 10)$.