

西安交通大学

计算机视觉与
模式识别

计算机 53 班

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一、 补全 SIFT1Scale 的 Line268-Line271

补全的代码如下：

```
odiff = repmat(ori(:),[1 num_bins]) -  
repmat(hist_orient(:)',[length(ori(:)),1]);  
odiff = mod(odiff, 2*pi) - pi;  
  
owght = 1 - abs(odiff) / hist_step;  
owght(owght < 0) = 0;
```

二、 调通 demo_sift_keypoint 程序

想要调通 demo_sift_keypoint 需要补充 gaussian_filter 和

display_keypoints 函数，如下：

gaussian_filter

```
sample = 7.0/2.0;  
n = 2*round(sample * sigma)+1;  
x = 1:n;  
x = x - ceil(n/2);  
  
g = exp(-(x.^2)/(2*sigma^2))/(sigma*sqrt(2*pi));
```

display_keypoints

```
hold on;  
  
alpha = 0.33;  
beta = 0.33;  
autoscale = 1.5;  
plotarrows = 1;  
sym = '';  
  
filled = 0;  
ls = '-';  
ms = '';  
col = '';  
  
varin = nargin - 3;  
  
while (varin > 0) & isstr(varargin{varin}),
```

```

vv = varargin{varin};
if ~isempty(vv) & strcmp(lower(vv(1)), 'f')
    filled = 1;
    nin = nin-1;
else
    [l,c,m,msg] = colstyle(vv);
    if ~isempty(msg),
        error(sprintf('Unknown option "%s".', vv));
    end
    if ~isempty(l), ls = l; end
    if ~isempty(c), col = c; end
    if ~isempty(m), ms = m; plotarrows = 0; end
    if isequal(m, '.'), ms = ''; end % Don't plot '.'
    varin = varin-1;
end
end

if varin > 0
    autoscale = varargin{varin};
end

x = pos(:,1);
y = pos(:,2);
u = scale.*cos(orient);
v = scale.*sin(orient);

if prod(size(u))==1, u = u(ones(size(x))); end
if prod(size(v))==1, v = v(ones(size(u))); end

if autoscale,
    u = u*autoscale; v = v*autoscale;
end

ax = newplot;
next = lower(get(ax, 'NextPlot'));
hold_state = ishold;

x = x(:).'; y = y(:).';
u = u(:).'; v = v(:).';
uu = [x;x+u;repmat(NaN, size(u))];
vv = [y;y+v;repmat(NaN, size(u))];

h1 = plot(uu(:), vv(:), [col ls]);

```

```

if plotarrows,
    hu = [x+u-alpha*(u+beta*(v+eps));x+u; ...
          x+u-alpha*(u-beta*(v+eps)); repmat(NaN,size(u))];
    hv = [y+v-alpha*(v-beta*(u+eps));y+v; ...
          y+v-alpha*(v+beta*(u+eps)); repmat(NaN,size(v))];
    hold on
    h2 = plot(hu(:),hv(:),[col ls]);
else
    h2 = [];
end

if ~isempty(ms),
    hu = x; hv = y;
    hold on
    h3 = plot(hu(:),hv(:),[col ms]);
    if filled, set(h3,'markerfacecolor',get(h1,'color')); end
else
    h3 = [];
end

if ~hold_state, hold off, view(2); set(ax,'NextPlot',next); end

if nargout>0, hh = [h1;h2;h3]; end

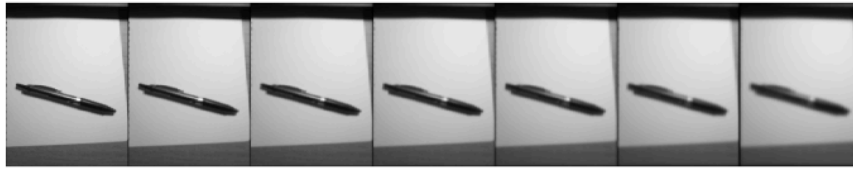
```

三、 自己找两幅照片，进行调试，生成中间结果，包括特征点的生成，方向的搜索以及描述子的生成

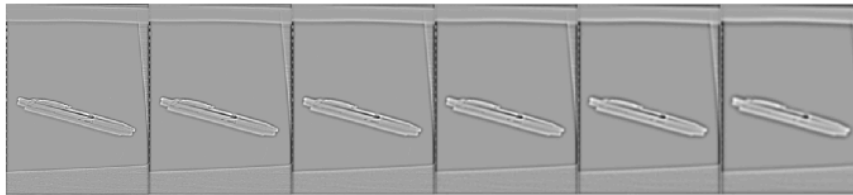
原图



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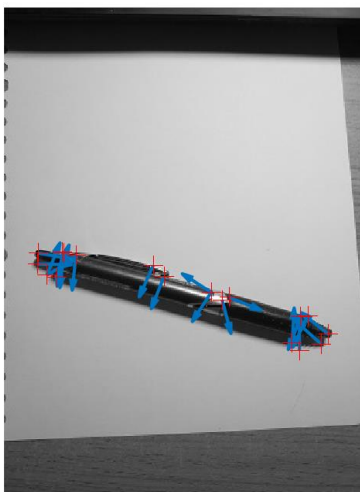
DOG



SIFT 特征点



描述子



原图



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DOG



SIFT 特征点



描述子

