



Legacy remote API functions (Matlab)

simxAddStatusbarMessage

Description	Adds a message to the status bar.
Matlab synopsis	[number returnType]=simxAddStatusbarMessage(number clientID,string message,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . message : the message to display operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxAppendStringSignal

Description	Deprecated. Refer to simxWriteStringStream instead.
	Appends a string to a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxSetStringSignal .
Matlab synopsis	[Number returnType]=simxAppendStringSignal(number clientID,string signalName,string signalValueToAppend,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . signalName : name of the signal signalValueToAppend : value to append to the signal. That value may contain any value, including embedded zeros. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxAuxiliaryConsoleClose

Description	Closes an auxiliary console window. See also simxAuxiliaryConsoleOpen .
Matlab synopsis	[number returnType]=simxAuxiliaryConsoleClose(number clientID,number consoleHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . consoleHandle : the handle of the console window, previously returned by the simxAuxiliaryConsoleOpen command operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxAuxiliaryConsoleOpen

Description	Opens an auxiliary console window for text display. This console window is different from the application main console window. Console window handles are shared across all simulator scenes. See also simxAuxiliaryConsolePrint , simxAuxiliaryConsoleShow and simxAuxiliaryConsoleClose .
Matlab synopsis	[number returnType,number consoleHandle]=simxAuxiliaryConsoleOpen(number clientID,string title,number maxLines,number mode,array position,array size,array textColor,array backgroundColor,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . title : the title of the console window maxLines : the number of text lines that can be displayed and buffered mode : bit-coded value. Bit0 set indicates that the console window will automatically close at simulation end, bit1 set indicates that lines will be wrapped, bit2 set indicates that the user can close the console

	window, bit3 set indicates that the console will automatically be hidden during simulation pause, bit4 set indicates that the console will not automatically hide when the user switches to another scene. position : the initial position of the console window (x and y value). Can be [] for default values size : the initial size of the console window (x and y value). Can be [] for default values textColor : the color of the text (rgb values, 0-1). Can be [] for default values backgroundColor : the background color of the console window (rgb values, 0-1). Can be [] for default values operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code consoleHandle : the handle of the created console
Other languages	C/C++, Python, Java, Octave

simxAuxiliaryConsolePrint

Description	Prints to an auxiliary console window. See also simxAuxiliaryConsoleOpen .
Matlab synopsis	[number returnType]=simxAuxiliaryConsolePrint(number clientID,number consoleHandle,string txt,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . consoleHandle : the handle of the console window, previously returned by the simxAuxiliaryConsoleOpen command txt : the text to append, or [] to clear the console window operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxAuxiliaryConsoleShow

Description	Shows or hides an auxiliary console window. See also simxAuxiliaryConsoleOpen and simxAuxiliaryConsoleClose .
Matlab synopsis	[number returnType]=simxAuxiliaryConsoleShow(number clientID,number consoleHandle,bool showState,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . consoleHandle : the handle of the console window, previously returned by the simxAuxiliaryConsoleOpen command showState : indicates whether the console should be hidden (false) or shown (true) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxCallScriptFunction

Description	Remotely calls a CoppeliaSim script function. When calling simulation scripts , then simulation must be running. Refer to this section for additional details.
Matlab synopsis	[number returnType,array outInts,array outFloats,string outStrings,array outBuffer]=simxCallScriptFunction(number clientID,string scriptName,number scriptHandleOrType,string functionName,array inInts,array inFloats,string inStrings,array inBuffer,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . scriptName : an empty string, or: if scriptHandleOrType is sim_scripttype_childscript (1) or sim_scripttype_customizationscript (6), then this should be the path to the scene object this script is attached to (e.g. "/path/to/object") if scriptHandleOrType is sim_scripttype_addonscript (2), then this should be the name of the add-on (e.g. "Isometric scaling;") scriptHandleOrType : the handle of the script, otherwise the type of the script functionName : the name of the script function to call in the specified script. inInts : the input integer values that are handed over to the script function. Can be []. inFloats : the input floating-point values that are handed over to the script function. Can be []. inStrings : the input strings that are handed over to the script function. Each string should be terminated with a zero char, e.g. ['Hello' 0 'world!' 0]. Can be an empty string. inBuffer : the input buffer that is handed over to the script function. Can be []. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking

Matlab return values	returnCode: a remote API function return code outInts: the returned integer values. outFloats: the returned floating-point values. outStrings: the returned strings. Each string is terminated with a zero char. outBuffer: the returned buffer.
Other languages	C/C++ , Python , Java , Octave

simxCheckCollision

Description	Checks whether two entities collide.
Matlab synopsis	[number returnType,bool collisionState]=simxCheckCollision(number clientID,number entity1,number entity2,number operationMode)
Matlab parameters	clientID: the client ID. refer to simxStart . entity1: the handle of the first entity. entity2: the handle of the second entity. operationMode: a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode: a remote API function return code collisionState: the collision state (false: not colliding)
Other languages	C/C++ , Python , Java , Octave

simxCheckDistance

Description	Measures the distance between two entities.
Matlab synopsis	[number returnType,number minimumDistance]=simxCheckDistance(number clientID,number distanceObjectHandle,number operationMode)
Matlab parameters	clientID: the client ID. refer to simxStart . entity1: the handle of the first entity. entity2: the handle of the second entity. operationMode: a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode: a remote API function return code minimumDistance: the minimum distance.
Other languages	C/C++ , Python , Java , Octave

simxClearFloatSignal

Description	Clears a float signal (removes it). See also simxSetFloatSignal , simxClearInt32Signal and simxClearStringSignal .
Matlab synopsis	[number returnType]=simxClearFloatSignal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID: the client ID. refer to simxStart . signalName: name of the signal operationMode: a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxClearInt32Signal

Description	Clears an integer signal (removes it). See also simxSetInt32Signal , simxClearFloatSignal and simxClearStringSignal .
Matlab synopsis	[number returnType]=simxClearInt32Signal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID: the client ID. refer to simxStart . signalName: name of the signal operationMode: a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxClearStringSignal

Description	Clears a string signal (removes it). See also simxSetStringSignal , simxClearInt32Signal and simxClearFloatSignal .
Matlab synopsis	[number returnType]=simxClearStringSignal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . signalName : name of the signal operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxCloseScene

Description	Closes current scene, and switches to another open scene. If there is no other open scene, a new scene is then created. Should only be called when simulation is not running and is only executed by continuous remote API server services . See also simxLoadScene .
Matlab synopsis	[number returnType]=simxCloseScene(number clientID,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxCopyPasteObjects

Description	Copies and pastes objects, together with all their associated child scripts. To copy and paste whole models, you can simply copy and paste the model base object.
Matlab synopsis	[number returnType,array newObjectHandles]=simxCopyPasteObjects(number clientID,array objectHandles,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandles : an array containing the handles of the objects to copy operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code newObjectHandles : an array of handles of newly created objects. Individual objects of a new model are not returned, but only the model base.
Other languages	C/C++ , Python , Java , Octave

simxCreateBuffer

Description	Creates a buffer. The buffer needs to be released with simxReleaseBuffer except otherwise explicitly specified. This is a remote API helper function.
Matlab synopsis	[libpointer buffer]=simxCreateBuffer(number bufferSize)
Matlab parameters	bufferSize : size of the buffer in bytes
Matlab return values	buffer : a pointer to the created buffer
Other languages	C/C++ , Python

simxCreateDummy

Description	Creates a dummy in the scene.
Matlab synopsis	[number returnType,number dummyHandle]=simxCreateDummy(number clientID,number size,array colors,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . size : the size of the dummy. colors : 4*3 bytes (0-255) for ambient_diffuse RGB, 3 reserved values (set to zero), specular RGB and emissive RGB. Can be [] for default colors. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return value	returnCode : a remote API function return code dummyHandle : handle of the created dummy.
Other languages	C/C++ , Python , Java , Octave

simxDisplayDialog

Description	Displays a generic dialog box during simulation (and only during simulation!). Use in conjunction with simxGetDialogResult , simxGetDialogInput and simxEndDialog . Use custom user interfaces instead if a higher customization level is required.
Matlab synopsis	[number returnType,number dialogHandle,number uiHandle]=simxDisplayDialog(number clientID,string titleText,string mainText,number dialogType,string initialText,array titleColors,array dialogColors,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . titleText : Title bar text mainText : Information text dialogType : a generic dialog style initialText : Initial text in the edit box if the dialog is of type sim_dlgstyle_input. titleColors : Title bar color (6 number values for RGB for background and foreground), can be [] for default colors dialogColors : Dialog color (6 number values for RGB for background and foreground), can be [] for default colors operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code dialogHandle : handle of the generic dialog (different from an OpenGL-based custom UI handle!! (see hereafter)). This handle should be used with the following functions: simxGetDialogResult , simxGetDialogInput and simxEndDialog . uiHandle : the handle of the corresponding OpenGL-based custom UI.
Other languages	C/C++ , Python , Java , Octave

simxEraseFile

Description	Closes and releases resource from a previous call to simxDisplayDialog . Even if the dialog is not visible anymore, you should release resources by using this function (however at the end of a simulation, all dialog resources are automatically released).
Matlab synopsis	[number returnType]=simxEraseFile(number clientID,number dialogHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . dialogHandle : handle of generic dialog (return value of simxDisplayDialog) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxFinish

Description	Ends the communication thread. This should be the very last remote API function called on the client side. simxFinish should only be called after a successfull call to simxStart . This is a remote API helper function.
Matlab synopsis	simxFinish(number clientID)
Matlab parameters	clientID : the client ID. refer to simxStart . Can be -1 to end all running communication threads.
Matlab return values	
Other languages	C/C++ , Python , Java , Octave

simxGetAndClearStringSignal

Description	Deprecated. Refer to simxReadStringStream instead.
	Gets the value of a string signal, then clears it. Useful to retrieve continuous data from the server. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxGetStringSignal .
Matlab synopsis	[number returnType, string signalValue]=simxGetAndClearStringSignal(number clientID, string signalName, number operationMode)
Matlab parameters	<p>clientID: the client ID, refer to simxStart.</p> <p>signalName: name of the signal</p> <p>operationMode: a remote API function operation mode. Since this function will clear a read signal, and we cannot afford to wait for a reply (well, we could, but that would mean a blocking operation), the function operates in a special mode and should be used as in following example:</p> <pre>% Initialization phase: [err,signal]=sim.simxGetAndClearStringSignal(clientID, 'sig', sim.simx_opmode_streaming); % while we are connected: while (sim.simxGetConnectionId(clientID)~=-1) [err,signal]=sim.simxGetAndClearStringSignal(clientID, 'sig', sim.simx_opmode_buffer); if (err==sim.simx_return_ok) % A signal was retrieved. % Enable streaming again (was automatically disabled with the positive event): [err,signal]=sim.simxGetAndClearStringSignal(clientID, 'sig', sim.simx_opmode_streaming); end .. end</pre>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>signalValue: the signal data (that may contain any value, including embedded zeros).</p>
Other languages	C/C++ , Python , Java , Octave

simxGetArrayParam

Description	Retrieves 3 values from an array. See the array parameter identifiers . See also simxSetArrayParam , simxGetBoolParam , simxGetInt32Param , simxGetFloatParam and simxGetStringParam .
Matlab synopsis	[number returnType, array paramValues]=simxGetArrayParam(number clientID, number paramIdentifier, number operationMode)
Matlab parameters	<p>clientID: the client ID, refer to simxStart.</p> <p>paramIdentifier: an array parameter identifier</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is <code>simx_opmode_blocking</code> (if not called on a regular basis)</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>paramValues: 3 values representing the array parameter</p>
Other languages	C/C++ , Python , Java , Octave

simxGetBoolParam

Description	Retrieves a bool value. See the bool parameter identifiers . See also simxSetBoolParam , simxGetInt32Param , simxGetFloatParam , simxGetArrayParam and simxGetStringParam .
Matlab synopsis	[number returnType, bool paramValue]=simxGetBoolParam(number clientID, number paramIdentifier, number operationMode)
Matlab parameters	<p>clientID: the client ID, refer to simxStart.</p> <p>paramIdentifier: a bool parameter identifier</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is <code>simx_opmode_blocking</code> (if not called on a regular basis)</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>paramValue: the parameter value</p>
Other languages	C/C++ , Python , Java , Octave

simxGetCollectionHandle

Description	This is a convenience function. Since CoppeliaSim V4.2.0, collections should be dynamically created and do not have a name anymore. This function will first try to retrieve a static collection with the specified name (for backward compatibility's sake). If such a collection does not exist, it will try to return the integer signal with the specified name. On CoppeliaSim's side, one could do: <code>local collectionHandle=sim.createCollection(0)</code>
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	<code>sim.addItemToCollection(collectionHandle...) ..</code> <code>sim.setInt32Signal('collectionName',collectionHandle)</code>
Matlab synopsis	[number returnType,number handle]=simxGetCollectionHandle(number clientID,string collectionName,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . collectionName : name of the collection. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code handle : the handle
Other languages	C/C++ , Python , Java , Octave

simxGetCollisionHandle

Description	Deprecated. see simxCheckCollision instead.
Matlab synopsis	[number returnType,number handle]=simxGetCollisionHandle(number clientID,string collisionObjectName,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . collisionObjectName : name of the collision object. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code handle : the handle
Other languages	C/C++ , Python , Java , Octave

simxGetConnectionId

Description	Returns the ID of the current connection. Use this function to track the connection state to the server. See also simxStart . This is a remote API helper function.
Matlab synopsis	[number connectionId]=simxGetConnectionId(number clientID)
Matlab parameters	clientID : the client ID. refer to simxStart .
Matlab return values	connectionId : a connection ID, or -1 if the client is not connected to the server. Different connection IDs indicate temporary disconnections in-between.
Other languages	C/C++ , Python , Java , Octave

simxGetDialogInput

Description	Queries the text the user entered into a generic dialog box of style sim_dlgstyle_input. To be used after simxDisplayDialog was called and after simxGetDialogResult returned sim_dlgret_ok.
Matlab synopsis	[number returnType,string inputText]=simxGetDialogInput(number clientID,number dialogHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . dialogHandle : handle of generic dialog (return value of simxDisplayDialog) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code inputText : the string the user entered.
Other languages	C/C++ , Python , Java , Octave

simxGetDialogResult

Description	Queries the result of a dialog box. To be used after simxDisplayDialog was called.
Matlab synopsis	[number returnType,number result]=simxGetDialogResult(number clientID,number dialogHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . dialogHandle : handle of generic dialog (return value of simxDisplayDialog) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code result : the result value.

	Note. If the return value is sim_dlgret_still_open, the dialog was not closed and no button was pressed. Otherwise, you should free resources with simxEndDialog (the dialog might not be visible anymore, but is still present)
Other languages	C/C++ , Python , Java , Octave

simxGetDistanceHandle

Description	Deprecated. see simxCheckDistance instead.
Matlab synopsis	[number returnType,number handle]=simxGetDistanceHandle(number clientID,string distanceObjectName,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . distanceObjectName : name of the distance object. operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code handle : the handle
Other languages	C/C++ , Python , Java , Octave

simxGetFloatParam

Description	Retrieves a floating point value. See the floating-point parameter identifiers . See also simxSetFloatParam , simxGetBoolParam , simxGetInt32Param , simxGetArrayParam and simxGetStringParam .
Matlab synopsis	[number returnType,number paramValue]=simxGetFloatParam(number clientID,number paramIdentifier,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . paramIdentifier : a floating parameter identifier operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking (if not called on a regular basis)
Matlab return values	returnCode : a remote API function return code paramValue : the parameter value
Other languages	C/C++ , Python , Java , Octave

simxGetFloatSignal

Description	Gets the value of a float signal. Signals are cleared at simulation start. See also simxSetFloatSignal , simxClearFloatSignal , simxGetInt32Signal and simxGetStringSignal .
Matlab synopsis	[number returnType,number signalValue]=simxGetFloatSignal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . signalName : name of the signal operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code signalValue : the value of the signal
Other languages	C/C++ , Python , Java , Octave

simxGetInMessageInfo

Description	Retrieves information about the last received message from the server. This is a remote API helper function. See also simxGetOutMessageInfo .
	If the client didn't receive any command reply from the server for a while, the data retrieved with this function won't be up-to-date. In order to avoid this, you should start at least one streaming command, which will guarantee regular message income.
Matlab synopsis	[number result,number info]=simxGetInMessageInfo(number clientID,number infoType)
Matlab parameters	clientID : the client ID. refer to simxStart . infoType : an inbox message info type
Matlab return values	result : -1 in case of an error info : the requested information
Other languages	C/C++ , Python , Java , Octave

simxGetInt32Param

Description	Retrieves an integer value. See the integer parameter identifiers . See also simxSetInt32Param , simxGetBoolParam , simxGetFloatParam , simxGetArrayParam and simxGetStringParam .
Matlab synopsis	[number returnCode,number paramValue]=simxGetInt32Param(number clientID,number paramIdentifier,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . paramIdentifier : an integer parameter identifier operationMode : a remote API function operation mode . Recommended operation mode for this function is <code>simx_opmode_blocking</code> (if not called on a regular basis)
Matlab return values	returnCode : a remote API function return code paramValue : the parameter value
Other languages	C/C++ , Python , Java , Octave

simxGetInt32Signal

Description	Gets the value of an integer signal. Signals are cleared at simulation start. See also simxSetInt32Signal , simxClearInt32Signal , simxGetFloatSignal and simxGetStringSignal .
Matlab synopsis	[number returnCode,number signalValue]=simxGetInt32Signal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code signalValue : the value of the signal
Other languages	C/C++ , Python , Java , Octave

simxGetJointForce

Description	Retrieves the force or torque applied to a joint along/about its active axis. This function retrieves meaningful information only if the joint is prismatic or revolute, and is dynamically enabled. With the Bullet engine, this function returns the force or torque applied to the joint motor (torques from joint limits are not taken into account). With the ODE or Vortex engine, this function returns the total force or torque applied to a joint along/about its z-axis. See also simxSetJointMaxForce , simxReadForceSensor and simxGetObjectGroupData .
Matlab synopsis	[number returnCode,number force]=simxGetJointForce(number clientID,number jointHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code force : the force or the torque applied to the joint along/about its z-axis
Other languages	C/C++ , Python , Java , Octave

simxGetJointMaxForce

Description	Retrieves the maximum force the joint is able to exert. See also simxSetJointMaxForce and simxGetJointForce .
Matlab synopsis	[number returnCode,number force]=simxGetJointMaxForce(number clientID,number jointHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code force : the maximum force the joint can exert
Other languages	C/C++ , Python , Java , Octave

simxGetJointMatrix

Description	Retrieves the intrinsic transformation matrix of a joint (the transformation caused by the joint movement). See also simxSetSphericalJointMatrix .
Matlab synopsis	[number returnType,array matrix]=simxGetJointMatrix(number clientID,number jointHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . jointHandle : handle of the joint operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code matrix : 12 number values. See the regular API equivalent function for details
Other languages	C/C++ , Python , Java , Octave

simxGetJointPosition

Description	Retrieves the intrinsic position of a joint. This function cannot be used with spherical joints (use simxGetJointMatrix instead). See also simxSetJointPosition and simxGetObjectGroupData .
Matlab synopsis	[number returnType,number position]=simxGetJointPosition(number clientID,number jointHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . jointHandle : handle of the joint operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code position : intrinsic position of the joint. This is a one-dimensional value: if the joint is revolute, the rotation angle is returned, if the joint is prismatic, the translation amount is returned, etc.
Other languages	C/C++ , Python , Java , Octave

simxGetLastCmdTime

Description	Retrieves the simulation time of the last fetched command (i.e. when the last fetched command was processed on the server side). The function can be used to verify how <i>fresh</i> a command reply is, or whether a command reply was recently updated. For example:
	<pre>[err,res,img]=sim.simxGetVisionSensorImage(clientID,handle,0,sim.simx_opmode_buffer); if_(err==sim.simx_return_ok) imageAcquisitionTime=sim.simxGetLastCmdTime(clientID); end</pre> If some streaming commands are running, simxGetLastCmdTime will always retrieve the current simulation time, otherwise, only the simulation time of the last command that retrieved data from CoppeliaSim. This is a remote API helper function.
Matlab synopsis	[number cmdTime]=simxGetLastCmdTime(number clientID)
Matlab parameters	clientID : the client ID. refer to simxStart .
Matlab return values	cmdTime : the simulation time in milliseconds when the command reply was generated, or 0 if simulation was not running.
Other languages	C/C++ , Python , Java , Octave

simxGetLastErrors

Description	Retrieves the last 50 errors that occurred on the server side, and clears the error buffer there. Only errors that occurred because of this client will be reported.
Matlab synopsis	[number returnType,cell errorStrings]=simxGetLastErrors(number clientID,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls) when not debugging. For debugging purposes, use simx_opmode_blocking.
Matlab return values	returnCode : a remote API function return code errorStrings : all error strings
Other languages	C/C++ , Python , Java , Octave

simxGetProperty

Description	Retrieves the properties of a model. See also simxSetModelProperty .
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Matlab synopsis	<code>[number returnType,number prop]=simxGetModelProperty(number clientID,number objectHandle,number operationMode)</code>
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_blocking</code> (depending on the intended usage)
Matlab return values	returnCode : a remote API function return code prop : the model property value
Other languages	C/C++ , Python , Java , Octave

simxGetObjectChild

Description	Retrieves the handle of an object's child object. See also simxGetObjectParent .
Matlab synopsis	<code>[number returnType,number childObjectHandle]=simxGetObjectChild(number clientID,number parentObjectHandle,number childIndex,number operationMode)</code>
Matlab parameters	clientID : the client ID. refer to simxStart . parentObjectHandle : handle of the object childIndex : zero-based index of the child's position. To retrieve all children of an object, call the function by increasing the index until the child handle is -1 operationMode : a remote API function operation mode . Recommended operation mode for this function is <code>simx_opmode_blocking</code>
Matlab return values	returnCode : a remote API function return code childObjectHandle : the handle of the child object. If the value is -1, there is no child at the given index
Other languages	C/C++ , Python , Java , Octave

simxGetObjectFloatParameter

Description	Retrieves a floating-point parameter of a object. See also simxSetObjectFloatParameter and simxGetObjectIntParameter .
Matlab synopsis	<code>[number returnType,number parameterValue]=simxGetObjectFloatParameter(number clientID,number objectHandle,number parameterID,number operationMode)</code>
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object parameterID : identifier of the parameter to retrieve. See the list of all possible object parameter identifiers operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls), or <code>simx_opmode_blocking</code> (depending on the intended usage)
Matlab return values	returnCode : a remote API function return code parameterValue : the value of the parameter
Other languages	C/C++ , Python , Java , Octave

simxGetObjectGroupData

Description	Simultaneously retrieves data of various objects in a CoppeliaSim scene.
Matlab synopsis	<code>[number returnType,array handles,array intData,array floatData,array stringData]=simxGetObjectGroupData(number clientID,number objectType,number dataType,number operationMode)</code>
Matlab parameters	clientID : the client ID. refer to simxStart . objectType : a scene object type , <code>sim_appobj_object_type</code> for all scene objects , or a collection handle. dataType : the type of data that is desired: 0: retrieves the object names (deprecated. See further down) 1: retrieves the object types (in <code>intData</code>) 2: retrieves the parent object handles (in <code>intData</code>) 3: retrieves the absolute object positions (in <code>floatData</code>). There are 3 values for each object (x,y,z) 4: retrieves the local object positions (in <code>floatData</code>). There are 3 values for each object (x,y,z) 5: retrieves the absolute object orientations as Euler angles (in <code>floatData</code>). There are 3 values for each object (α,β,γ) 6: retrieves the local object orientations as Euler angles (in <code>floatData</code>). There are 3 values for each object (α,β,γ)

	<p>7: retrieves the absolute object orientations as quaternions (in floatData. There are 4 values for each object (qx,qy,qz,qw))</p> <p>8: retrieves the local object orientations as quaternions (in floatData. There are 4 values for each object (qx,qy,qz,qw))</p> <p>9: retrieves the absolute object positions and orientations (as Euler angles) (in floatData. There are 6 values for each object (x,y,z,alpha,beta,gamma))</p> <p>10: retrieves the local object positions and orientations (as Euler angles) (in floatData. There are 6 values for each object (x,y,z,alpha,beta,gamma))</p> <p>11: retrieves the absolute object positions and orientations (as quaternions) (in floatData. There are 7 values for each object (x,y,z,qx,qy,qz,qw))</p> <p>12: retrieves the local object positions and orientations (as quaternions) (in floatData. There are 7 values for each object (x,y,z,qx,qy,qz,qw))</p> <p>13: retrieves proximity sensor data (in intData (2 values): detection state, detected object handle. In floatData (6 values): detected point (x,y,z) and detected surface normal (nx,ny,nz))</p> <p>14: retrieves force sensor data (in intData (1 values): force sensor state. In floatData (6 values): force (fx,fy,fz) and torque (tx,ty,tz))</p> <p>15: retrieves joint state data (in floatData (2 values): position, force/torque)</p> <p>16: retrieves joint properties data (in intData (2 values): joint type, joint mode (bit16=hybrid operation). In floatData (2 values): joint limit low, joint range (-1.0 if joint is cyclic))</p> <p>17: retrieves the object linear velocity (in floatData. There are 3 values for each object (vx,vy,vz))</p> <p>18: retrieves the object angular velocity as Euler angles per seconds (in floatData. There are 3 values for each object (dAlpha,dBeta,dGamma))</p> <p>19: retrieves the object linear and angular velocity (in floatData. There are 6 values for each object (vx,vy,vz,dAlpha,dBeta,dGamma))</p> <p>20: retrieves the object aliases (in stringData.)</p> <p>21: retrieves the object paths (in stringData.)</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is simx_opmode_blocking or simx_opmode_streaming.</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>handles: the object handles.</p> <p>intData: the integer values.</p> <p>floatData: the float values.</p> <p>stringData: the string values.</p>
Other languages	C/C++, Python, Java, Octave

simxGetObjectHandle

Description	Retrieves an object handle based on its path and alias.
Matlab synopsis	[number returnType,number handle]=simxGetObjectHandle(number clientID,string objectPath,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>objectPath: the path of the object. See the section on accessing scene objects for details.</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is simx_opmode_blocking</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>handle: the handle</p>
Other languages	C/C++, Python, Java, Octave

simxGetObjectIntParameter

Description	Retrieves an integer parameter of a object. See also simxSetObjectIntParameter and simxGetObjectFloatParameter .
Matlab synopsis	[number returnType,number parameterValue]=simxGetObjectIntParameter(number clientID,number objectHandle,number parameterID,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>objectHandle: handle of the object</p> <p>parameterID: identifier of the parameter to retrieve. See the list of all possible object parameter identifiers</p> <p>operationMode: a remote API function operation mode. Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls), or simx_opmode_blocking (depending on the intended usage)</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>parameterValue: the value of the parameter</p>
Other languages	C/C++, Python, Java, Octave

simxGetObjectOrientation

Description	Retrieves the orientation (Euler angles) of an object. See also simxSetObjectOrientation , simxGetObjectQuaternion , simxGetObjectPosition and simxGetObjectGroupData .
Matlab synopsis	[number returnType,array eulerAngles]=simxGetObjectOrientation(number clientID,number objectHandle,number relativeToObjectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame we want the orientation. Specify -1 to retrieve the absolute orientation, sim_handle_parent to retrieve the orientation relative to the object's parent, or an object handle relative to whose reference frame you want the orientation operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code eulerAngles : 3 values representing the Euler angles (alpha, beta and gamma)
Other languages	C/C++ , Python , Java , Octave

simxGetObjectParent

Description	Retrieves the handle of an object's parent object. See also simxGetObjectChild and simxGetObjectGroupData .
Matlab synopsis	[number returnType,number parentObjectHandle]=simxGetObjectParent(number clientID,number objectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code parentObjectHandle : the handle of the parent object. If the value is -1, the object has no parent
Other languages	C/C++ , Python , Java , Octave

simxGetObjectPosition

Description	Retrieves the position of an object. See also simxSetObjectPosition , simxGetObjectOrientation , simxGetObjectQuaternion and simxGetObjectGroupData .
Matlab synopsis	[number returnType,array position]=simxGetObjectPosition(number clientID,number objectHandle,number relativeToObjectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame we want the position. Specify -1 to retrieve the absolute position, sim_handle_parent to retrieve the position relative to the object's parent, or an object handle relative to whose reference frame you want the position operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code position : 3 values representing the position
Other languages	C/C++ , Python , Java , Octave

simxGetObjectQuaternion

Description	Retrieves the quaternion of an object. See also simxSetObjectQuaternion .
Matlab synopsis	[number returnType,array quat]=simxGetObjectQuaternion(number clientID,number objectHandle,number relativeToObjectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame we want the quaternion. Specify -1 to retrieve the absolute quaternion, sim_handle_parent to retrieve the quaternion relative to the object's parent, or an object handle relative to whose reference frame you want the quaternion operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code quat : 4 values representing the quaternion (x, y, z, w)
Other languages	C/C++ , Python , Java , Octave

simxGetObjects

Description	Retrieves object handles of a given type, or of all types (i.e. all object handles). See also simxGetObjectGroupData .
Matlab synopsis	[number returnType,array objectHandles]=simxGetObjects(number clientID,number objectType,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectType : object type (sim_object_shape_type, sim_object_joint_type, etc., or sim_handle_all for any type of object) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode : a remote API function return code objectHandles : an array containing object handles.
Other languages	C/C++ , Python , Java , Octave

simxGetObjectSelection

Description	Retrieves all selected object's handles. See also simxSetObjectSelection .
Matlab synopsis	[number returnType,array objectHandles]=simxGetObjectSelection(number clientID,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls), or simx_opmode_blocking depending on the intent.
Matlab return values	returnCode : a remote API function return code objectHandles : an array containing the handles of all selected objects
Other languages	C/C++ , Python , Java , Octave

simxGetObjectVelocity

Description	Retrieves the linear and angular velocity of an object. See also simxGetObjectPosition , simxGetObjectOrientation and simxGetObjectGroupData .
Matlab synopsis	[number returnType,array linearVelocity,array angularVelocity]=simxGetObjectVelocity(number clientID,number objectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code linearVelocity : 3 values representing the linear velocity (vx, vy, vz). angularVelocity : 3 values representing the angular velocity (dAlpha, dBeta, dGamma).
Other languages	C/C++ , Python , Java , Octave

simxGetOutMessageInfo

Description	Retrieves information about the next message to send to the server. This is a remote API helper function. See also simxGetInMessageInfo .
Matlab synopsis	[number result,number info]=simxGetOutMessageInfo(number clientID,number infoType)
Matlab parameters	clientID : the client ID, refer to simxStart . infoType : an outbox message info type
Matlab return values	result : -1 in case of an error info : the requested information
Other languages	C/C++ , Python , Java , Octave

simxGetPingTime

Description	Retrieves the time needed for a command to be sent to the server, executed, and sent back. That time depends on various factors like the client settings, the network load, whether a simulation is running, whether the simulation is real-time, the simulation time step, etc. The function is blocking. This is a remote API helper function.
Matlab synopsis	[number returnType,number pingTime]=simxGetPingTime(number clientID)
Matlab parameters	clientID : the client ID, refer to simxStart .

Matlab return values	returnCode : a remote API function return code pingTime : the ping time in milliseconds.
Other languages	C/C++, Python, Java, Octave

simxGetStringParam

Description	Retrieves a string value. See the string parameter identifiers . See also simxGetBoolParam , simxGetInt32Param , simxGetArrayParam and simxGetFloatParam .
Matlab synopsis	[number returnCode,string paramString]=simxGetStringParam(number clientID,number paramIdentifier,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . paramIdentifier : a string parameter identifier operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_blocking (if not called on a regular basis)
Matlab return values	returnCode : a remote API function return code paramValue : the parameter value (a string)
Other languages	C/C++, Python, Java, Octave

simxGetStringSignal

Description	Gets the value of a string signal. Signals are cleared at simulation start. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxSetStringSignal , simxReadStream , simxClearStringSignal , simxGetInt32Signal and simxGetFloatSignal .
Matlab synopsis	[number returnCode,string signalValue]=simxGetStringSignal(number clientID,string signalName,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code signalValue : the signal data (that may contain any value, including embedded zeros).
Other languages	C/C++, Python, Java, Octave

simxGetUIButtonProperty (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxGetUIEventButton (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxGetUIHandle (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxGetUISlider (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxGetVisionSensorDepthBuffer

Description	Retrieves the depth buffer of a vision sensor as a pointer. The returned data doesn't make sense if sim.handleVisionSensor wasn't called previously (sim.handleVisionSensor is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the simxGetLastCmdTime function to verify the <i>freshness</i> of the retrieved data. See also simxGetVisionSensorDepthBuffer2 and simxGetVisionSensorImage .
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Matlab synopsis	[number returnType,array resolution,libpointer buffer]=simxGetVisionSensorDepthBuffer(number clientID,number sensorHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . sensorHandle : handle of the vision sensor operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code resolution : 2 number values representing the resolution of the image buffer : a libpointer object to the data. To access individual depth buffer pixels, use following code: <pre>buffer.setDataType('singlePtr',1,resolution(1)*resolution(2)); buffer.value(pixelIndex);</pre> Values are in the range of 0-1 (0=closest to sensor, 1=farthest from sensor). The buffer remains valid until next call to a simx-function.
Other languages	C/C++ , Python , Java , Octave

simxGetVisionSensorDepthBuffer2

Description	Retrieves the depth buffer of a vision sensor as an image array. The returned data doesn't make sense if sim.handleVisionSensor wasn't called previously (sim.handleVisionSensor is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the simxGetLastCmdTime function to verify the <i>freshness</i> of the retrieved data. This function is much slower than simxGetVisionSensorDepthBuffer . See also simxGetVisionSensorImage .
Matlab synopsis	[number returnType,array resolution,matrix buffer]=simxGetVisionSensorDepthBuffer2(number clientID,number sensorHandle,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . sensorHandle : handle of the vision sensor operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code resolution : 2 number values representing the resolution of the image buffer : the depth buffer data. Values are in the range of 0-1 (0=closest to sensor, 1=farthest from sensor).
Other languages	C/C++ , Python , Java , Octave

simxGetVisionSensorImage

Description	Retrieves the image of a vision sensor as a pointer. The returned data doesn't make sense if sim.handleVisionSensor wasn't called previously (sim.handleVisionSensor is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the simxGetLastCmdTime function to verify the <i>freshness</i> of the retrieved data. See also simxGetVisionSensorImage2 , simxSetVisionSensorImage , simxGetVisionSensorDepthBuffer and simxReadVisionSensor .
Matlab synopsis	[number returnType,array resolution,libpointer image]=simxGetVisionSensorImage(number clientID,number sensorHandle,number options,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . sensorHandle : handle of the vision sensor options : image options, bit-coded: bit0 set: each image pixel is a byte (greyscale image), otherwise each image pixel is a rgb byte-triplet operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code resolution : 2 number values representing the resolution of the image image : a libpointer object to the data. To access individual pixels, use following code: <pre>image.setDataType('uint8Ptr',1,resolution(1)*resolution(2)*bytesPerPixel); image.value(pixelIndex);</pre> Values are in the range of 0-255. The buffer remains valid until next call to a simx-function.
Other languages	C/C++ , Python , Java , Octave

simxGetVisionSensorImage2

Description	Retrieves the image of a vision sensor as an image array. The returned data doesn't make sense if sim.handleVisionSensor wasn't called previously (sim.handleVisionSensor is called by default in the main script if the vision sensor is not tagged as explicit handling). Use the simxGetLastCmdTime
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	function to verify the <i>freshness</i> of the retrieved data. See also simxGetVisionSensorImage , simxSetVisionSensorImage , simxGetVisionSensorDepthBuffer and simxReadVisionSensor .
Matlab synopsis	[number returnType,array resolution,matrix image]=simxGetVisionSensorImage2(number clientID,number sensorHandle,number options,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>sensorHandle: handle of the vision sensor</p> <p>options: image options, bit-coded: bit0 set: each image pixel is a byte (greyscale image), otherwise each image pixel is a rgb byte-triplet</p> <p>operationMode: a remote API function operation mode. Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>resolution: 2 number values representing the resolution of the image</p> <p>image: the image data. Values are in the range of 0-255.</p>
Other languages	C/C++ , Python , Java , Octave

simxJointGetForce (REPRECATED)

Description	Deprecated. See simxGetJointForce instead.
Matlab synopsis	[number returnType,number force]=simxJointGetForce(number clientID,number jointHandle,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>jointHandle: handle of the joint</p> <p>operationMode: a remote API function operation mode. Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>force: the force or the torque applied to the joint along/about its z-axis</p>
Other languages	C/C++ , Python , Java , Octave

simxLoadModel

Description	Loads a previously saved model. See also simxLoadScene and simxTransferFile .
Matlab synopsis	[number returnType,number baseHandle]=simxLoadModel(number clientID,string modelPathAndName,number options,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>modelPathAndName: the model filename, including the path and extension ('ttm'). The file is relative to the client or server system depending on the options value (see next argument)</p> <p>options: options, bit-coded: bit0 set: the specified file is located on the client side (in that case the function will be blocking since the model first has to be transferred to the server). Otherwise it is located on the server side</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is simx_opmode_blocking</p>
Matlab return values	<p>returnCode: a remote API function return code</p> <p>baseHandle: the loaded model base.</p>
Other languages	C/C++ , Python , Java , Octave

simxLoadScene

Description	Loads a previously saved scene. Should only be called when simulation is not running and is only executed by continuous remote API server services . See also simxCloseScene , simxLoadModel , and simxTransferFile .
Matlab synopsis	[number returnType]=simxLoadScene(number clientID,string scenePathAndName,number options,number operationMode)
Matlab parameters	<p>clientID: the client ID. refer to simxStart.</p> <p>scenePathAndName: the scene filename, including the path and extension ('tt'). The file is relative to the client or server system depending on the options value (see next argument)</p> <p>options: options, bit-coded: bit0 set: the specified file is located on the client side (in that case the function will be blocking since the scene first has to be transferred to the server). Otherwise it is located on the server side</p> <p>operationMode: a remote API function operation mode. Recommended operation mode for this function is simx_opmode_blocking</p>
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxLoadUI (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via <code>simxCallScriptFunction</code> instead.
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simxPackFloats

Description	Packs an array of floats into a string. This is a remote API helper function. See also simxUnpackFloats and simxPackInts .
Matlab synopsis	<code>[string packedData]=simxPackFloats(array floatValues)</code>
Matlab parameters	floatValues: an array of numbers we wish to pack as floats
Matlab return values	packedData: a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Other languages	Java , Octave , Python

simxPackInts

Description	Packs an array of integers into a string. This is a remote API helper function. See also simxUnpackInts and simxPackFloats .
Matlab synopsis	<code>[string packedData]=simxPackInts(array intValues)</code>
Matlab parameters	intValues: an array of numbers we wish to pack as integers
Matlab return values	packedData: a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Other languages	Java , Octave , Python

simxPauseCommunication

Description	Allows to temporarily halt the communication thread from sending data. This can be useful if you need to send several values to CoppeliaSim that should be received and evaluated at the same time. This is a remote API helper function.
Matlab synopsis	<code>[number returnCode]=simxPauseCommunication(number clientID,bool pause)</code>
Matlab parameters	clientID: the client ID, refer to simxStart . pause: whether the communication thread should pause or run normally. <u>Usage example:</u> <code>sim.simxPauseCommunication(clientID,1);</code> <code>sim.simxSetJointPosition(clientID,joint1Handle,joint1Value,sim.simx_opmode_oneshot);</code> <code>sim.simxSetJointPosition(clientID,joint2Handle,joint2Value,sim.simx_opmode_oneshot);</code> <code>sim.simxSetJointPosition(clientID,joint3Handle,joint3Value,sim.simx_opmode_oneshot);</code> <code>sim.simxPauseCommunication(clientID,0); % Above's 3 joints will be received and set on the CoppeliaSim side at the same time</code>
Matlab return values	returnCode: 0 in case of operation success.
Other languages	C/C++ , Python , Java , Octave

simxPauseSimulation

Description	Requests a pause of a simulation. See also simxStartSimulation and simxStopSimulation .
Matlab synopsis	<code>[number returnCode]=simxPauseSimulation(number clientID,number operationMode)</code>
Matlab parameters	clientID: the client ID, refer to simxStart . operationMode: a remote API function operation mode . Recommended operation modes for this function is <code>simx_opmode_oneshot</code> .
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxQuery

Description	Deprecated. Refer to simxCallScriptFunction instead.
	Sends a query string to CoppeliaSim, and waits for a reply string. Query and reply strings can be accessed via string signals. This function allows for instance to have a child script , another remote API client or a ROS node handle special requests coming from this remote API client, then send a reply

back. To pack/unpack integers/floats into/from a string, refer to [simxPackInts](#), [simxPackFloats](#), [simxUnpackInts](#) and [simxUnpackFloats](#).

Usage example where a child script handles a request:

```
% Following is the remote API client side:  
[res,replyData]=sim.simxQuery(clientID,'request','send me a 42','reply',5000) if  
(res==sim.simxReturnOk) fprintf('The reply is: %s\n',replyData); end  
-- This is the child script side. The child script is non-threaded and --  
following part executed at each simulation pass: req=sim.getStringSignal('request')  
if (req) then sim.clearStringSignal('request') if (req=='send me a 42') then  
sim.setStringSignal('reply','42\0') -- will be automatically cleared by the client  
end end
```

Matlab synopsis	[number returnType string retSignalValue]=simxQuery(number clientID,string signalName,string signalValue,string retSignalName,number timeOutInMs)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal that contains the request string signalValue : the request string. retSignalName : name of the signal that contains the reply string timeOutInMs : the maximum time in milliseconds that the function will wait for a reply.
Matlab return value	returnCode : a remote API function return code retSignalValue : the reply string
Other languages	C/C++ , Python , Java , Octave

simxReadCollision

Description	Deprecated. see simxCheckCollision instead.
Matlab synopsis	[number returnType,bool collisionState]=simxReadCollision(number clientID,number collisionObjectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . collisionObjectHandle : handle of the collision object operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code collisionState : the collision state (false: not colliding)
Other languages	C/C++ , Python , Java , Octave

simxReadDistance

Description	Deprecated. see simxCheckDistance instead.
Matlab synopsis	[number returnType,number minimumDistance]=simxReadDistance(number clientID,number distanceObjectHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . distanceObjectHandle : handle of the distance object operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code minimumDistance : the minimum distance. If the distance object wasn't handled yet, the distance value will be larger than <code>1e36</code> .
Other languages	C/C++ , Python , Java , Octave

simxReadForceSensor

Description	Reads the force and torque applied to a force sensor (filtered values are read), and its current state ('unbroken' or 'broken'). See also simxGetJointForce and simxGetObjectGroupData .
Matlab synopsis	[number returnType,number state,array forceVector,array torqueVector]=simxReadForceSensor(number clientID,number forceSensorHandle,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . forceSensorHandle : handle of the force sensor operationMode : a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode : a remote API function return code state : the state of the force sensor: bit 0 set: force and torque data is available, otherwise it is not (yet) available (e.g. when not enough values are present for the filter) bit 1 set: force sensor is broken, otherwise it is still intact ('unbroken')

	forceVector: 3 values representing the force vector torqueVector: 3 values representing the torque vector
Other languages	C/C++, Python, Java, Octave

simxReadProximitySensor

Description	Reads the state of a proximity sensor. This function doesn't perform detection, it merely reads the result from a previous call to sim.handleProximitySensor (<code>sim.handleProximitySensor</code> is called in the default main script). See also simxGetObjectGroupData .
Matlab synopsis	[number returnType,bool detectionState,array detectedPoint,number detectedObjectHandle,array detectedSurfaceNormalVector]=simxReadProximitySensor(number clientID,number sensorHandle,number operationMode)
Matlab parameters	clientID: the client ID, refer to simxStart . sensorHandle: handle of the proximity sensor operationMode: a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls)
Matlab return values	returnCode: a remote API function return code detectionState: the detection state (false=no detection) detectedPoint: the detected point coordinates (relative to the sensor reference frame) detectedObjectHandle: the handle of the detected object detectedSurfaceNormalVector: the normal vector (normalized) of the detected surface. Relative to the sensor reference frame
Other languages	C/C++, Python, Java, Octave

simxReadStringStream

Description	Gets the value of a string signal, then clears it. Useful to retrieve continuous data from the server. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxWriteStringStream .
Matlab synopsis	[number returnType,string signalValue]=simxReadStringStream(number clientID,string signalName,number operationMode)
Matlab parameters	clientID: the client ID, refer to simxStart . signalName: name of the signal operationMode: a remote API function operation mode . Recommended operation modes for this function are <code>simx_opmode_streaming</code> (the first call) and <code>simx_opmode_buffer</code> (the following calls). <code>simx_opmode_blocking</code> is forbidden. Use a construction like following in order to continuously exchange data with CoppeliaSim: Remote API client side: % Initialization phase: <pre>[err,signal]=sim.simxReadStringStream(clientID,'toClient', sim.simx_opmode_streaming); % while we are connected: while (sim.simxGetConnectionId(clientID)==-1) [err,signal]=sim.simxReadStringStream(clientID,'toClient', sim.simx_opmode_buffer); if (err==sim.simx_return_ok) % Data produced by the child script was retrieved! Send it back to the child script: sim.simxWriteStringStream(clientID,'fromClient',signal, sim.simx_opmode_oneshot); end end Server side (CoppeliaSim), from a child script: function svsCall init() -- initialization phase: i=0 lastReceived=-1 end function svsCall actuation() -- First send a stream of integers that count up: dat=sim.getStringSignal('toClient') if not dat then dat=' ' end dat=dat..sim.packInt32Table({i}) i=i+1 sim.setStringSignal('toClient',dat) -- Here receive the integer stream in return and check if each number is correct: dat=sim.getStringSignal('fromClient') if dat then sim.clearStringSignal('fromClient') dat=sim.unpackInt32Table(dat) for j=1,#dat,1 do if (dat[j]~=lastReceived+1) then print('Error') else io.write('.') lastReceived=dat[j] end end end end</pre>
Matlab return values	returnCode: a remote API function return code signalValue: the signal data (that may contain any value, including embedded zeros)
Other languages	C/C++, Python, Java, Octave

simxReadVisionSensor

Description	Reads the state of a vision sensor. This function doesn't perform detection, it merely reads the result from a previous call to sim.handleVisionSensor (<code>sim.handleVisionSensor</code> is called in the default main script). See also simxGetVisionSensorImage and simxGetObjectGroupData .
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Matlab synopsis	[number returnType, bool detectionState, array auxData, array auxPacketInfo] = simxReadVisionSensor(number clientID, number sensorHandle, number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . sensorHandle : handle of the vision sensor operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_streaming (the first call) and simx_opmode_buffer (the following calls)
Matlab return values	returnCode : a remote API function return code detectionState : the detection state (i.e. the trigger state) auxData : by default CoppeliaSim returns one packet of 15 auxiliary values: the minimum of {intensity, red, green, blue, depth value}, the maximum of {intensity, red, green, blue, depth value}, and the average of {intensity, red, green, blue, depth value}. Additional packets can be appended in the vision callback function . auxPacketInfo : an array containing an entry for each returned packet. Each entry represents the number of values in each packets. Use this info to extract individual packets from auxData .
Other languages	C/C++ , Python , Java , Octave

simxReleaseBuffer

Description	Releases a buffer previously created with simxCreatBuffer or a buffer returned by a remote API function. This is a remote API helper function.
Matlab synopsis	simxReleaseBuffer(libpointer buffer)
Matlab parameters	buffer : buffer to be released
Matlab return values	
Other languages	C/C++ , Python

simxRemoveModel

Description	Removes a model from the scene. See also simxRemoveObject .
Matlab synopsis	[number returnType] = simxRemoveModel(number clientID, number objectHandle, number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the model to remove (object should be flagged as <i>model base</i>). operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot (or simx_opmode_blocking)
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxRemoveObject

Description	Removes a scene object. See also simxRemoveModel .
Matlab synopsis	[number returnType] = simxRemoveObject(number clientID, number objectHandle, number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object to remove operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot (or simx_opmode_blocking)
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxRemoveUI (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxSetArrayParam

Description	Sets 3 values of an array parameter . See also simxGetArrayParam , simxSetBoolParam , simxSetInt32Param and simxSetFloatParam .
Matlab synopsis	[number returnType] = simxSetArrayParam(number clientID, number paramIdentifier, array paramValues, number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . paramIdentifier : an array parameter identifier

	paramValues : the array containing the 3 values to set operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetBoolParam

Description	Sets a bool parameter . See also simxGetBoolParam , simxSetInt32Param , simxSetArrayParam and simxSetFloatParam .
Matlab synopsis	[number resultCode]=simxSetBoolParam(number clientID,number paramIdentifier,bool paramValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . paramIdentifier : a bool parameter identifier paramValue : the parameter value operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetFloatParam

Description	Sets a floating point parameter . See also simxGetFloatParam , simxSetBoolParam , simxSetArrayParam and simxSetInt32Param .
Matlab synopsis	[number resultCode]=simxSetFloatParam(number clientID,number paramIdentifier,number paramValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . paramIdentifier : a floating parameter identifier paramValue : the parameter value operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetFloatSignal

Description	Sets the value of a float signal. If that signal is not yet present, it is added. See also simxGetFloatSignal , simxClearFloatSignal , simxSetInt32Signal and simxSetStringSignal .
Matlab synopsis	[number resultCode]=simxSetFloatSignal(number clientID,string signalName,number signalValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal signalValue : value of the signal operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetInt32Param

Description	Sets an integer parameter . See also simxGetInt32Param , simxSetBoolParam , simxSetArrayParam and simxSetFloatParam .
Matlab synopsis	[number resultCode]=simxSetInt32Param(number clientID,number paramIdentifier,number paramValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . paramIdentifier : an integer parameter identifier paramValue : the parameter value operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetInt32Signal

Description	Sets the value of an integer signal. If that signal is not yet present, it is added. See also simxGetInt32Signal , simxClearInt32Signal , simxSetFloatSignal and simxSetStringSignal .
Matlab synopsis	[number returnType]=simxSetInt32Signal(number clientID,string signalName,number signalValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal signalValue : value of the signal operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetJointMaxForce

Description	Sets the maximum force or torque that a joint can exert. This function has no effect when the joint is not dynamically enabled, or when it is a spherical joint. See also simxGetJointMaxForce and simxGetJointForce .
Matlab synopsis	[number returnType]=simxSetJointMaxForce(number clientID,number jointHandle,number force,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint force : the maximum force or torque that the joint can exert operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetJointPosition

Description	Sets the intrinsic position of a joint. May have no effect depending on the joint mode. This function cannot be used with spherical joints (use simxSetSphericalJointMatrix instead). If you want to set several joints that should be applied at the exact same time on the CoppeliaSim side, then use simxPauseCommunication . See also simxGetJointPosition and simxSetJointTargetPosition .
Matlab synopsis	[number returnType]=simxSetJointPosition(number clientID,number jointHandle,number position,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint position : position of the joint (angular or linear value depending on the joint type) operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_oneshot or simx_opmode_streaming
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetJointTargetPosition

Description	Sets the target position of a joint if the joint is in torque/force mode (also make sure that the joint's motor and position control are enabled). See also simxSetJointPosition .
Matlab synopsis	[number returnType]=simxSetJointTargetPosition(number clientID,number jointHandle,number targetPosition,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint targetPosition : target position of the joint (angular or linear value depending on the joint type) operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_oneshot or simx_opmode_streaming
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetJointTargetVelocity

Description	Sets the intrinsic target velocity of a non-spherical joint. This command makes only sense when the joint mode is in torque/force mode: the dynamics functionality and the joint motor have to be enabled (position control should however be disabled)
Matlab synopsis	[number returnType]=simxSetJointTargetVelocity(number clientID,number jointHandle,number targetVelocity,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint targetVelocity : target velocity of the joint (linear or angular velocity depending on the joint-type) operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_oneshot or simx_opmode_streaming
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetModelProperty

Description	Sets the properties of a model. See also simxGetModelProperty .
Matlab synopsis	[number returnType]=simxSetModelProperty(number clientID,number objectHandle,number prop,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object prop : a model property value operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectFloatParameter

Description	Sets a floating-point parameter of a object. See also simxGetObjectFloatParameter and simxSetObjectIntParameter .
Matlab synopsis	[number returnType]=simxSetObjectFloatParameter(number clientID,number objectHandle,number parameterID,number parameterValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object parameterID : identifier of the parameter to set. See the list of all possible object parameter identifiers parameterValue : the desired value of the parameter operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectIntParameter

Description	Sets an integer parameter of a object. See also simxGetObjectIntParameter and simxSetObjectFloatParameter .
Matlab synopsis	[number returnType]=simxSetObjectIntParameter(number clientID,number objectHandle,number parameterID,number parameterValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandle : handle of the object parameterID : identifier of the parameter to set. See the list of all possible object parameter identifiers parameterValue : the desired value of the parameter operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectOrientation

Description	Sets the orientation (Euler angles) of an object. Dynamically simulated objects will implicitly be reset before the command is applied (i.e. similar to calling sim.resetDynamicObject just before). See also simxGetObjectOrientation , simxSetObjectQuaternion and simxSetObjectPosition .
Matlab synopsis	[number returnType]=simxSetObjectOrientation(number clientID,number objectHandle,number relativeToObjectHandle,array eulerAngles,number operationMode)

Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame the orientation is specified. Specify -1 to set the absolute orientation, sim_handle_parent to set the orientation relative to the object's parent, or an object handle relative to whose reference frame the orientation is specified. eulerAngles : Euler angles (alpha, beta and gamma) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectParent

Description	Sets an object's parent object. See also simxGetObjectParent .
Matlab synopsis	[number resultCode]=simxSetObjectParent(number clientID,number objectHandle,number parentObject,bool keepInPlace,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object that will become child of the parent object. Can be combined with sim_handleflag_assembly , if the two objects can be assembled via a predefined assembly transformation (refer to the assembling option in the object common properties). In that case, parentObject can't be -1, and keepInPlace should be set to false. parentObject : handle of the object that will become parent, or -1 if the object should become parentless keepInPlace : indicates whether the object's absolute pose should stay same operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot or simx_opmode_blocking depending on the intent
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectPosition

Description	Sets the position of an object. Dynamically simulated objects will implicitly be reset before the command is applied (i.e. similar to calling sim.resetDynamicObject just before). See also simxGetObjectPosition , simxSetObjectQuaternion and simxSetObjectOrientation .
Matlab synopsis	[number resultCode]=simxSetObjectPosition(number clientID,number objectHandle,number relativeToObjectHandle,array position,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame the position is specified. Specify -1 to set the absolute position, sim_handle_parent to set the position relative to the object's parent, or an object handle relative to whose reference frame the position is specified. position : the position values (x, y and z) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectQuaternion

Description	Sets the orientation of an object as quaternion. Dynamically simulated objects will implicitly be reset before the command is applied (i.e. similar to calling sim.resetDynamicObject just before). See also simxGetObjectQuaternion .
Matlab synopsis	[number resultCode]=simxSetObjectQuaternion(number clientID,number objectHandle,number relativeToObjectHandle,array quat,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . objectHandle : handle of the object relativeToObjectHandle : indicates relative to which reference frame the quaternion is specified. Specify -1 to set the absolute quaternion, sim_handle_parent to set the quaternion relative to the object's parent, or an object handle relative to whose reference frame the quaternion is specified. quat : the quaternion values (x, y, z, w) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	resultCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetObjectSelection

Description	Sets the selection state for objects. See also simxGetObjectSelection .
Matlab synopsis	[number returnCode]=simxSetObjectSelection(number clientID,array objectHandles,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . objectHandles : an array of object handles operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot or simx_opmode_blocking depending on the intent.
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetSphericalJointMatrix

Description	Sets the intrinsic orientation matrix of a spherical joint object. This function cannot be used with non-spherical joints (use simxSetJointPosition instead). See also simxGetJointMatrix .
Matlab synopsis	[number returnCode]=simxSetSphericalJointMatrix(number clientID,number jointHandle,array matrix,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . jointHandle : handle of the joint matrix : 12 number values. See the regular API equivalent function for details operationMode : a remote API function operation mode . Recommended operation modes for this function are simx_opmode_oneshot or simx_opmode_streaming
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetStringSignal

Description	Sets the value of a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxWriteStringStream , simxGetStringSignal , simxClearStringSignal , simxSetInt32Signal and simxSetFloatSignal .
Matlab synopsis	[number returnCode]=simxSetStringSignal(number clientID,string signalName,string signalValue,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . signalName : name of the signal signalValue : value of the signal (which may contain any value, including embedded zeros) operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSetUIButtonLabel (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxSetUIButtonProperty (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxSetUISlider (Deprecated)

Description	Deprecated. Use the Qt-based custom user interfaces , via simxCallScriptFunction instead.
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simxSetVisionSensorImage

Description	Sets the image of a vision sensor (and applies any image processing, if enabled.. The image is provided as a libpointer. Make sure the vision sensor is flagged as use external image . See also simxSetVisionSensorImage2 .
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Matlab synopsis	[number returnType]=simxSetVisionSensorImage(number clientID,number sensorHandle,libpointer image,number bufferSize,number options,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . sensorHandle : handle of the vision sensor image : the image data bufferSize : size of the image data options : image options, bit-coded: bit0 set: each image pixel is a byte (greyscale image), otherwise each image pixel is a rgb byte-triplet operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxSetVisionSensorImage2

Description	Sets the image of a vision sensor (and applies any image processing, if enabled). The image is provided as an image array. Make sure the vision sensor is flagged as use external image . See also simxSetVisionSensorImage which is much faster.
Matlab synopsis	[number returnType]=simxSetVisionSensorImage2(number clientID,number sensorHandle,matrice image,number operationMode)
Matlab parameters	clientID : the client ID, refer to simxStart . sensorHandle : handle of the vision sensor image : the image data operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode : a remote API function return code
Other languages	C/C++ , Python , Java , Octave

simxStart

Description	Starts a communication thread with the server (i.e. CoppeliaSim). A same client may start several communication threads (but only one communication thread for a given IP and port). This should be the very first remote API function called on the client side. Make sure to start an appropriate remote API server service on the server side, that will wait for a connection. See also simxFinish . This is a remote API helper function.
Matlab synopsis	[number clientID]=simxStart(string connectionAddress,number connectionPort,bool waitUntilConnected,bool doNotReconnectOnceDisconnected,number timeOutInMs,number commThreadCycleInMs)
Matlab parameters	connectionAddress : the ip address where the server is located (i.e. CoppeliaSim) connectionPort : the port number where to connect. Specify a negative port number in order to use shared memory, instead of socket communication. waitUntilConnected : if true, then the function blocks until connected (or timed out). doNotReconnectOnceDisconnected : if true, then the communication thread will not attempt a second connection if a connection was lost. timeOutInMs : if positive: the connection time-out in milliseconds for the first connection attempt. In that case, the time-out for blocking function calls is 5000 milliseconds. if negative: its positive value is the time-out for blocking function calls. In that case, the connection time-out for the first connection attempt is 5000 milliseconds. commThreadCycleInMs : indicates how often data packets are sent back and forth. Reducing this number improves responsiveness, and a default value of 5 is recommended.
Matlab return values	clientID : the client ID, or -1 if the connection to the server was not possible (i.e. a timeout was reached). A call to simxStart should always be followed at the end with a call to simxFinish if simxStart didn't return -1
Other languages	C/C++ , Python , Java , Octave

simxStartSimulation

Description	Requests a start of a simulation (or a resume of a paused simulation). This function is only executed by continuous remote API server services . See also simxPauseSimulation and simxStopSimulation .
Matlab synopsis	[number returnType]=simxStartSimulation(number clientID,number operationMode)
Matlab parameters	clientID : the client ID. refer to simxStart . operationMode : a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot.

Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxStopSimulation

Description	Requests a stop of the running simulation. See also simxStartSimulation and simxPauseSimulation .
Matlab synopsis	[number returnType]=simxStopSimulation(number clientID,number operationMode)
Matlab parameters	clientID: the client ID, refer to simxStart . operationMode: a remote API function operation mode. Recommended operation modes for this function is simx_opmode_oneshot,
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSynchronous

Description	Enables or disables the stepping mode for the remote API server service that the client is connected to. The function is blocking. While in stepping mode, the client application is in charge of triggering the next simulation step. Only pre-enabled remote API server services will successfully execute this function. See also simxSynchronousTrigger and this section . This is a remote API helper function.
Matlab synopsis	[number returnType]=simxSynchronous(number clientID,bool enable)
Matlab parameters	clientID: the client ID, refer to simxStart . enable: the enable state of the stepping mode
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxSynchronousTrigger

Description	Sends a synchronization trigger signal to the server. The function is blocking. The server needs to be previously enabled for stepping operation via the simxSynchronous function. The trigger signal will inform CoppeliaSim to execute the next simulation step. While in stepping mode, the client application is in charge of triggering the next simulation step, otherwise simulation will stall. See also this section . This is a remote API helper function.
Matlab synopsis	[number returnType]=simxSynchronousTrigger(number clientID)
Matlab parameters	clientID: the client ID, refer to simxStart .
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxTransferFile

Description	Allows transferring a file from the client to the server. This function is used by several other functions internally (e.g. simxLoadModel). See also simxEraseFile . This is a remote API helper function.
Matlab synopsis	[number returnType]=simxTransferFile(number clientID,string filePathAndName,string fileName_serverSide,number timeOut,number operationMode)
Matlab parameters	clientID: the client ID, refer to simxStart . filePathAndName: the local file name and path (i.e. on the client side) fileName_serverSide: a file name under which the transferred file will be saved on the server side. For now, do not specify a path (the file will be saved in the remote API plugin directory) timeOut: a timeout value in milliseconds operationMode: a remote API function operation mode. Recommended operation mode for this function is simx_opmode_blocking
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave

simxUnpackFloats

Description	Unpacks a string into an array of floats. This is a remote API helper function. See also simxPackFloats and simxUnpackInts .
Matlab synopsis	[array floatValues]=simxUnpackFloats(string packedData)
Matlab parameters	packedData: a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Matlab return values	floatValues: an array of numbers that were unpacked as floats

Other languages

[Java, Octave, Python](#)

simxUnpackInts

Description	Unpacks a string into an array of integers. This is a remote API helper function. See also simxPackInts and simxUnpackFloats .
Matlab synopsis	[array intValues]=simxUnpackInts(string packedData)
Matlab parameters	packedData: a string that contains the packed values. Each values takes exactly 4 bytes in the string.
Matlab return values	intValues: an array of numbers that were unpacked as integers
Other languages	Java, Octave, Python

simxWriteStringStream

Description	Appends a string to a string signal. If that signal is not yet present, it is added. To pack/unpack integers/floats into/from a string, refer to simxPackInts , simxPackFloats , simxUnpackInts and simxUnpackFloats . See also simxReadStringStream .
Matlab synopsis	[number returnType]=simxWriteStringStream(number clientID,string signalName,string signalValueToAppend,number operationMode)
Matlab parameters	clientID: the client ID. refer to simxStart . signalName: name of the signal signalValueToAppend: value to append to the signal. That value may contain any value, including embedded zeros. operationMode: a remote API function operation mode . Recommended operation mode for this function is simx_opmode_oneshot
Matlab return values	returnCode: a remote API function return code
Other languages	C/C++, Python, Java, Octave