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PELCO-D PROTOCOL TUTORIAL



Pelco-D is a popular PTZ (Pan / Tilt / Zoom) camera control protocol used in the CCTV industry. (Click [here](#) to visit Pelco's website.)

This page will explain the following topics in details:

- 1) [The format of Pelco-D](#)
- 2) [How to calculate the checksum byte by using 232Analyzer](#)
- 3) [Pelco-D command string examples](#)
- 4) [How to use 232Analyzer to control the Pelco-D cameras](#)
- 5) [Have fun playing with 232Analyzer and Pelco-D cameras](#)

After reading this page and testing the camera with the 232Analyzer software , you should be able to understand the ease of using the Pelco-D protocol, and control any Pelco-D cameras in five minutes' time.

Notes:

1) Before you can control any Pelco-D cameras, you need to prepare the following items:

- A PC running 232Analyzer program
- An RS-232 port (or USB / RS-232 converter)
- An RS232 / RS485 converter

2) Make sure your COM port settings in the 232Analyzer program matches with camera's settings (Pelco-D cameras use No parity, 8 Data bits and 1 Stop bit, baud rate depends on your camera setting)

(Click [here](#) to download the 232Analyzer FREE Version. Click [here](#) to download Pelco-D / P device profiles)

1) The format of Pelco-D

Pelco-D consists of 7 hexadecimal bytes (all byte data used in this page are in Hexadecimal format unless otherwise specified).

Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
Sync	Camera Address	Command 1	Command 2	Data 1	Data 2	Checksum

- Byte 1 (Sync) - the synchronization byte, fixed to FF
- Byte 2 (Camera Address) - logical address of the camera being controlled (Address 1 is 01)
- Byte 3 & 4 (Command 1 and 2) are shown below
- Byte 5 (Data 1) - pan **speed**, range from 00 (stop) to 3F (high **speed**) and FF for "turbo" **speed** (the maximum pan **speed** that the device can go)
- Byte 6 (Data 2) - tilt **speed**, range from 00 (stop) to 3F (maximum **speed**)
- Byte 7 (Checksum) - sum of bytes (excluding the synchronization byte), then modulo 100 (Decimal code: 256)

Command 1 and 2 details

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Command 1	Sense	Reserved	Reserved	Auto / Manual Scan	Camera On/Off	Iris Close	Iris Open	Focus Near
Command 2	Focus Far	Zoom Wide	Zoom Tele	Tilt Down	Tilt Up	Pan Left	Pan Right	Fixed to 0

Example (Command 2):

Pan Left - 0 0 0 0 0 1 0 0, which equals to 04 (both hexadecimal and decimal)

Some other commands

Command	Byte 3	Byte 4	Byte 5	Byte 6



Go to Preset	00	07	00	01 to FF
Set Zoom Speed	00	25	00	00 to 33
Set Focus Speed	00	27	00	00 to 33
Alarm Ack.	00	19	00	Alarm no.

2) How to calculate the checksum byte by using 232Analyzer

Suppose you are controlling camera 1 (address 1) to pan left at high **speed**, the command string of the first 6 bytes would be: [FF 01 00 04 3F 00](#)

Step 1: Go to "Checksum Calculator" pane, choose "Hex" as "Operands format" and "+" as Operator. Then take out the first byte FF and key in all other bytes in the "Input operands" box. Remember to add "," after each byte of data. You will then get the result of "44"

Checksum Calculator

Operands format: ☒ Hex ☐ Dec ☐ Oct ☐ Bin ☐ AscII

Operator: ☐ And ☐ Or ☐ xOr ☐ Not ☐ Rev. bit order
☒ + ☐ - ☐ x ☐ \, Mod ☐ CRC-16 (Modbus)

Input operands (e.g. 10,11,):
01,00,04,3F,00,

Result: 44 Calculate

Step 2: Change Operator to "\,Mod", and key in the previous result ("44") and modulo parameter "100" in the "Input operands" box, remember to add "," after each byte of data. You will then get the result of "44" in "Remainder (Mod)" box.

"44" would be the result of checksum, now the full string of pan left at high **speed** command would be [FF 01 00 04 3F 00 44](#)

Checksum Calculator

Operands format: ☒ Hex ☐ Dec ☐ Oct ☐ Bin ☐ AscII

Operator: ☐ And ☐ Or ☐ xOr ☐ Not ☐ Rev. bit order
☐ + ☐ - ☐ x ☒ \, Mod ☐ CRC-16 (Modbus)

Input operands (e.g. 10,11,):
44,100,

Result: 0 44 Calculate

Quotient (\) Remainder (Mod)

3) Pelco-D command string examples

Camera Address: 1

Pan Left at high **speed**: [FF 01 00 04 3F 00 44](#)

Pan Right at medium **speed**: [FF 01 00 02 20 00 23](#)

Tilt Up at high **speed**: [FF 01 00 08 00 3F 48](#)

Tilt Down at medium **speed**: [FF 01 00 10 20 00 31](#)

Stop all actions (Pan / Tilt / Zoom / Iris etc.): [FF 01 00 00 00 00 01](#)

Note: there will be no response from cameras in Pelco-D protocol

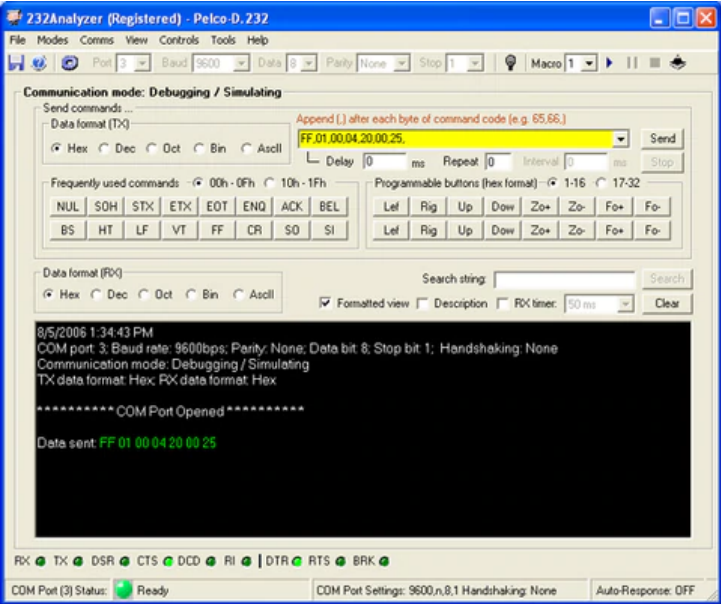
4) How to use 232Analyzer to control the Pelco-D cameras

Suppose you are controlling camera address no. 1 to pan left at medium **speed** (command string: [FF 01 00 04 20 00 25](#))

Way 1: From the command pane - choose "Hex" as the TX data format and key in the command string "FF,01,00,04,20,00,25," in the input box as shown below. Then click on the "Send" button. The command will then be sent out immediately and you will notice the camera panning left continuously.

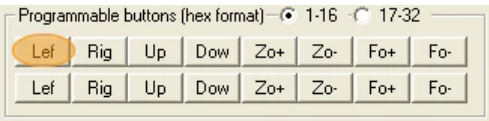
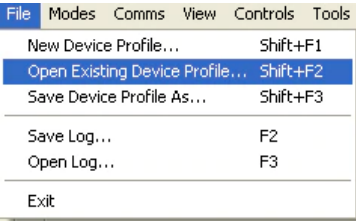
Note: If you are using the FREE Version, choose "Dec" as TX data format and key in "255,1,0,4,32,0,37,"





Way 2: From Programmable buttons

Download and unzip the [Pelco-DP.zip](#) file, then open "Pelco-D.232" file from 232Analyzer program. When you click on the first button "Lef", the command will be sent out after 500ms.



5) Have fun playing with 232Analyzer and Pelco-D cameras

The programmable buttons 1 to 8 will trigger the camera's action continuously. To stop, you have to send out the "Stop" command "FF 01 00 00 00 00 01" (or "255 01 00 00 00 00 01" Decimal format) to the camera.







"Pelco-DP.zip" file allows you to send two (2) commands with the click of a button, e.g. when you click on "Lef" button on the second row (button no. 9), the camera will pan left for 500ms and then stop. This is because button no. 9 is linked to button 17, which stores the "Stop" command. (Note: Programmable buttons 9 to 16 will trigger the camera's action for 500ms and will stop automatically).

You may program it in such a way that the camera pans left for 500ms, stops, tilts up for 1000ms, stops, tilts down for 500ms, and then pans right continuously. All sorts of actions can be done through "Programmable Buttons" or "Macros" functions.

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- Download 232Analyzer »

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