

Unified Computational Universe Terminal Object: Discrete Complexity Geometry, Information Geometry, Multi-Observer Causal Network, and Capability–Risk Structure

Haobo Ma¹

Wenlin Zhang²

¹Independent Researcher

²National University of Singapore

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Abstract

This paper constructs on foundation of previous “computational universe” series works a **unified computational universe terminal object** with explicit categorical meaning. Previous works have axiomatized computational universe as four-tuple

$$U_{\text{comp}} = (X, \mathbb{T}, \mathbb{C}, \mathbb{I}),$$

and established on it: discrete complexity geometry (complexity distance, volume growth, and discrete Ricci curvature), discrete information geometry (task information manifold (\mathcal{S}_Q, g_Q) and embedding Φ_Q), control manifold (\mathcal{M}, G) induced by unified time scale and time–information–complexity joint variational principle, multi-observer consensus geometry and causal network, topological complexity and undecidability, as well as theory of universal catastrophic safety and capability–risk frontier.

Goal of this paper is to unify these discrete and continuous, geometric and logical, single-observer and multi-observer, capability and risk structures into single categorical object

$$\mathfrak{U}_{\text{comp}}^{\text{term}}$$

—called **unified computational universe terminal object**. Specifically, we perform following steps:

1. Define computational universe category with unified time scale **CompUniv_κ**: objects are computational universes U_{comp} satisfying axioms, morphisms are “safe simulation maps” simultaneously preserving complexity geometry, information geometry, and catastrophe specifications.
2. Construct 2-layer structure on this category: one layer is discrete configuration–event–causal diamond layer; one layer is continuous control–information geometry layer, with multi-observer network, knowledge graph families, and capability–risk frontier placed on top.

3. Prove there exists object

$$\mathfrak{U}_{\text{comp}}^{\text{term}} = (\mathfrak{X}, \mathfrak{G}_{\text{comp}}, \mathfrak{G}_{\text{info}}, \mathfrak{E}_{\text{obs}}, \mathfrak{G}_{\text{cat}}, \mathfrak{F}_{\text{CR}}),$$

and for each $U_{\text{comp}} \in \mathbf{CompUniv}_\kappa$ “contraction” morphism

$$F_U : U_{\text{comp}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}},$$

such that:

- F_U at discrete level is embedding of configuration–event–diamond, at continuous level is embedding of control–information–observer states;
 - F_U preserves complexity distance and unified time scale (at most linear rescaling);
 - F_U makes all task information geometry and multi-observer consensus geometry become some class of “submanifold–subnetwork” on $\mathfrak{U}_{\text{comp}}^{\text{term}}$;
 - F_U maps catastrophe specifications and capability–risk frontier to substructures of $\mathfrak{G}_{\text{cat}}$ and \mathfrak{F}_{CR} .
4. Prove in natural 2-category sense (allowing natural transformations between morphisms), $\mathfrak{U}_{\text{comp}}^{\text{term}}$ satisfies “terminal object” property: for any two such unified objects morphisms between them have unique (in natural isomorphism sense) factorization.
 5. Finally using previously established physical universe–computational universe categorical equivalence, construct correspondence between unified physical universe terminal object $\mathfrak{U}_{\text{phys}}^{\text{term}}$ and $\mathfrak{U}_{\text{comp}}^{\text{term}}$, and explain both are equivalent terminal objects under unified time scale, boundary diamonds, observer network, and capability–risk structure.

This paper thus gives ultimate unified description of “universe as computation” under purely discrete, axiomatic framework: all concrete finite or local computational universes contract through safe–geometric–information compatible morphisms to same unified computational universe terminal object, which simultaneously plays terminal object role at categorical, geometric, and logical levels.

Keywords: Computational universe; Terminal object; Category theory; Unified time scale; Complexity geometry; Information geometry; Multi-observer consensus; Capability–risk frontier

1 Introduction

In previous series works, we have successively constructed axiomatization, discrete complexity geometry, discrete information geometry, unified time scale framework, time–information–complexity joint variational principle, multi-observer consensus geometry, topological complexity and undecidability, universal catastrophic safety, and capability–risk frontier theory for “computational universe”.

This paper aims to unify all these structures into single categorical object—**unified computational universe terminal object** $\mathfrak{U}_{\text{comp}}^{\text{term}}$. This object plays “terminal object” role in computational universe category: every specific computational universe can be embedded into it through unique (up to natural isomorphism) structure-preserving map,

and all previous geometric, information, multi-observer, and safety structures can be viewed as substructures of unified object.

Terminal object construction not only provides ultimate unified description for computational universe theory, but also establishes formal correspondence with physical universe category through categorical equivalence: unified physical universe terminal object $\mathfrak{U}_{\text{phys}}^{\text{term}}$ and unified computational universe terminal object $\mathfrak{U}_{\text{comp}}^{\text{term}}$ are equivalent presentations of same mathematical object in two equivalent categories.

Paper structure: Section 2 organizes previous scattered structures into 2-category framework with 2-morphisms. Section 3 gives structural data of unified computational universe terminal object: from discrete configuration–event–diamond to continuous control–information–observer–capability–risk. Section 4 defines unified computational universe terminal object and proves its terminal object property in 2-category sense. Section 5 constructs equivalence with unified physical universe terminal object. Appendices give technical construction details and formal proof outlines.

2 Computational Universe 2-Category Under Unified Time Scale

This section organizes previous scattered structures into 2-category framework with 2-morphisms.

2.1 Computational Universe Objects with Unified Time Scale

Definition 2.1 (Computational Universe with Unified Time Scale). A computational universe object with unified time scale is seven-tuple

$$\widehat{U}_{\text{comp}} = (X, \mathsf{T}, \mathsf{C}, \mathsf{I}; \mathcal{M}, G; \mathcal{S}_Q, g_Q),$$

where:

1. $(X, \mathsf{T}, \mathsf{C}, \mathsf{I})$ is computational universe satisfying previous axioms:
 - X countable;
 - $\mathsf{T} \subset X \times X$ local finite degree;
 - C single-step cost positive and path-additive;
 - I task information quality baseline.
2. (\mathcal{M}, G) is control manifold and complexity metric constructed from unified time scale scattering master scale, satisfying Riemannian limit property of discrete complexity distance d_{comp} : for each local reachable region there exists refinement family $\{X^{(h)}\}$ and map $\Phi_h : X^{(h)} \rightarrow \mathcal{M}$, such that

$$d_{\text{comp}}^{(h)}(x, y) \rightarrow d_G(\Phi_h(x), \Phi_h(y)).$$

3. (\mathcal{S}_Q, g_Q) is information manifold and Fisher information metric for task Q , with embedding

$$\Phi_Q : X \rightarrow \mathcal{S}_Q,$$

such that discrete Jensen–Shannon information distance $d_{\text{JS},Q}(x, y)$ locally consistent with $d_{\mathcal{S}_Q}(\Phi_Q(x), \Phi_Q(y))$.

We call such objects constitute “0-layer objects” of category **CompUniv** _{κ} .

2.2 Safe–Geometric–Information Compatible 1-Morphisms

Definition 2.2 (Safe–Geometric–Information Compatible Simulation Morphism). Given two computational universes with unified time scale

$$\widehat{U}_{\text{comp}} = (X, \mathbb{T}, \mathbb{C}, \mathbb{I}; \mathcal{M}, G; \mathcal{S}_Q, g_Q),$$

$$\widehat{U}'_{\text{comp}} = (X', \mathbb{T}', \mathbb{C}', \mathbb{I}'; \mathcal{M}', G'; \mathcal{S}'_Q, g'_Q),$$

a 1-morphism

$$F : \widehat{U}_{\text{comp}} \rightarrow \widehat{U}'_{\text{comp}}$$

consists of following data:

1. Configuration map $f_X : X \rightarrow X'$, being previously defined simulation map (preserving step structure, cost control, and information quality monotonicity), with constants $\alpha_X, \beta_X > 0$ and monotone function Ψ such that

$$(x, y) \in \mathbb{T} \Rightarrow (f_X(x), f_X(y)) \in \mathbb{T}',$$

$$d'_{\text{comp}}(f_X(x), f_X(y)) \leq \alpha_X d_{\text{comp}}(x, y) + \beta_X,$$

$$\mathbb{I}(x) \leq \Psi(\mathbb{I}'(f_X(x))).$$

2. Control manifold map $f_{\mathcal{M}} : \mathcal{M} \rightarrow \mathcal{M}'$, for metrics G, G' satisfying Lipschitz–bilateral control: there exist $\alpha_{\mathcal{M}}, \beta_{\mathcal{M}} > 0$ such that

$$\alpha_{\mathcal{M}} G_{\theta}(v, v) \leq G'_{f_{\mathcal{M}}(\theta)}(df_{\mathcal{M}}v, df_{\mathcal{M}}v) \leq \beta_{\mathcal{M}} G_{\theta}(v, v).$$

3. Information manifold map $f_{\mathcal{S}} : \mathcal{S}_Q \rightarrow \mathcal{S}'_Q$, for Fisher metric satisfying similar Lipschitz–bilateral control, and compatible with f_X , i.e., there exists natural transformation η_X such that

$$f_{\mathcal{S}} \circ \Phi_Q \simeq \Phi'_Q \circ f_X.$$

4. Safety specification compatibility: if there exists catastrophe set $C_{\text{cat}} \subset X$ on $\widehat{U}_{\text{comp}}$, then its image $C'_{\text{cat}} = f_X(C_{\text{cat}}) \subset X'$ remains catastrophe set, and F does not map safe points into catastrophe points, i.e., visible safety–catastrophe partition under map preserves or “blunts toward safety side”.

Such 1-morphisms simultaneously preserve discrete–continuous geometry and catastrophe specifications. All objects and 1-morphisms constitute category **CompUniv** _{κ} .

2.3 2-Morphisms and Natural Transformations

At control and information manifold level, two 1-morphisms may have “continuous deformations”, corresponding in category theory to 2-morphisms—natural transformations.

Definition 2.3 (Natural Transformation as 2-Morphism). Given two 1-morphisms

$$F, G : \widehat{U}_{\text{comp}} \rightarrow \widehat{U}'_{\text{comp}},$$

a 2-morphism

$$\Xi : F \Rightarrow G$$

includes:

1. Configuration side natural transformation Ξ_X , usually family of local invertible maps on X' , such that $G_X \simeq \Xi_X \circ F_X$;
2. Control and information side natural transformations $\Xi_{\mathcal{M}}, \Xi_{\mathcal{S}}$, giving in metric compatible sense $G_{\mathcal{M}} \simeq \Xi_{\mathcal{M}} \circ F_{\mathcal{M}}, G_{\mathcal{S}} \simeq \Xi_{\mathcal{S}} \circ F_{\mathcal{S}}$;
3. On safety structure not breaking coarse structure of catastrophe set and capability–risk frontier.

Thus, $\mathbf{CompUniv}_{\kappa}$ has 2-category structure.

3 Structural Data of Unified Computational Universe Terminal Object

This section gives specific composition of unified computational universe terminal object

$$\mathfrak{U}_{\text{comp}}^{\text{term}}$$

from discrete configuration–event–diamond to continuous control–information–observer–capability–risk.

3.1 Discrete Layer: Maximal Configuration Universe and Event–Diamond Structure

Definition 3.1 (Maximal Configuration Universe). Let \mathfrak{X} be “amalgamation of all countable configuration sets and their finite representations” under some large cardinal control, formally constructible through Grothendieck universe \mathcal{U} and set theory as

$$\mathfrak{X} = \bigcup_{U_{\text{comp}} \in \mathbf{CompUniv}_{\kappa}} \iota_U(X),$$

where ι_U is embedding of each X into common superset. Define on \mathfrak{X} unified transition relation

$$\mathsf{T}_{\infty} = \bigcup_{U_{\text{comp}}} \iota_U(\mathsf{T}_U),$$

cost function

$$\mathsf{C}_\infty = \bigcup_{U_{\text{comp}}} \iota_U(\mathsf{C}_U),$$

at conflicts through equivalence class identification (i.e., merging geometrically equivalent update rules from different universes into single object). Thus obtain “maximal global complexity graph” containing all local computation structures

$$\mathfrak{G}_{\text{comp}}^{(1)} = (\mathfrak{X}, \mathsf{T}_\infty, \mathsf{C}_\infty).$$

At event layer

$$\mathfrak{E} = \mathfrak{X} \times \mathbb{N},$$

can define unified causal partial order and complexity light cone; thus any finite budget causal diamond \diamond can be viewed as subgraph of $\mathfrak{G}_{\text{comp}}^{(1)}$.

3.2 Continuous Layer: Terminal Objects of Unified Control Manifold and Information Manifold

At control and information geometry level, previous works already constructed for each $\widehat{U}_{\text{comp}}$ control manifold (\mathcal{M}_U, G_U) and information manifold $(\mathcal{S}_{Q,U}, g_{Q,U})$.

Definition 3.2 (Unified Control Manifold Terminal Object). Let

$$\mathfrak{M} = \coprod_{U_{\text{comp}}} \mathcal{M}_U / \sim,$$

where \sim is “time scale–complexity isometry equivalence”: if there exists isometric embedding of control–scattering realization, identify corresponding points. Through this amalgamation obtain large manifold or stacky object \mathfrak{M} , with unified metric \mathfrak{G} , locally consistent with each G_U .

Definition 3.3 (Unified Information Manifold Terminal Object). Similarly for all tasks Q and universe U_{comp} , construct information manifold family $\mathcal{S}_{Q,U}$ and perform similar amalgamation, obtaining unified information manifold

$$\mathfrak{S} = \coprod_{Q,U} \mathcal{S}_{Q,U} / \sim,$$

carrying piecewise Fisher metric \mathfrak{g} .

Thus, any concrete computational universe’s control–information geometry can be embedded into $(\mathfrak{M}, \mathfrak{G})$ and $(\mathfrak{S}, \mathfrak{g})$ as submanifolds; under unified time scale master scale and scattering structure, these embeddings preserve geodesic structure and information structure.

3.3 Multi-Observer Network Layer

Taking single observer object

$$O = (M_{\text{int}}, \Sigma_{\text{obs}}, \Sigma_{\text{act}}, \mathcal{P}, \mathcal{U})$$

as basic unit, view all countable observer families in unified computational universe as collection of points $(\theta, \phi, m, \mathcal{G}, A)$.

Definition 3.4 (Unified Observer State Space). Define

$$\mathfrak{E}_{\text{obs}} = \bigcup_{U_{\text{comp}}, \mathcal{O}} \left(\prod_{i \in I} \mathcal{E}_Q^{(i)} \times M_{\text{int}}^{(i)} \times \mathfrak{G}^{(i)} \times \mathfrak{A}^{(i)} \right) / \sim,$$

where $\mathcal{E}_Q^{(i)} = \mathcal{M}_U^{(i)} \times \mathcal{S}_{Q,U}^{(i)}$, $\mathfrak{G}^{(i)}$ is knowledge graph space, $\mathfrak{A}^{(i)}$ is attention configuration space, \sim identifies geometrically equivalent and strategy equivalent states.

Joint metric composed of sum of each $G_U, g_{Q,U}$ and knowledge graph spectral distance.

3.4 Catastrophe Specification and Capability–Risk Frontier Layer

Perform similar amalgamation for catastrophe specifications and capability–risk structures defined in all computational universes.

Definition 3.5 (Unified Catastrophe Specification Layer). Define catastrophe specification family

$$\mathfrak{S}_{\text{cat}} = \bigcup_{U_{\text{comp}}} \{(X_{0,U}, C_{\text{cat},U})\} / \sim,$$

where equivalence relation identifies equivalent initial state sets and catastrophe sets under unified embedding.

Definition 3.6 (Unified Capability–Risk Frontier Layer). For each (U_{comp}, Q) , capability–risk frontier is $\mathcal{F}_{\text{CR}}^{(U,Q)} \subset \mathbb{R} \times [0, 1]$. Embedding all these frontiers as parametrized family into unified strategy space, obtain overall structure

$$\mathfrak{F}_{\text{CR}} = \bigcup_{U,Q} \mathcal{F}_{\text{CR}}^{(U,Q)} \times \{(U, Q)\} / \sim.$$

On unified control–observer strategy space, \mathfrak{F}_{CR} is piecewise Pareto boundary set, describing capability–risk limit curves in all possible computational universes.

4 Unified Computational Universe Terminal Object and Terminal Object Property

This section merges all above layers, gives definition of unified computational universe terminal object, and proves its terminal object property in 2-category sense.

4.1 Definition of Terminal Object

Definition 4.1 (Unified Computational Universe Terminal Object). Unified computational universe terminal object defined as ten-tuple

$$\mathfrak{U}_{\text{comp}}^{\text{term}} = (\mathfrak{X}, \mathsf{T}_{\infty}, \mathsf{C}_{\infty}, \mathsf{l}_{\infty}; \mathfrak{M}, \mathfrak{G}; \mathfrak{S}, \mathfrak{g}; \mathfrak{E}_{\text{obs}}; \mathfrak{S}_{\text{cat}}; \mathfrak{F}_{\text{CR}}),$$

where each part defined as in 3.1–3.6.

Intuitively, $\mathfrak{U}_{\text{comp}}^{\text{term}}$ simultaneously contains:

- All locally realizable configurations and updates;
- All control path complexity geometry limits under unified time scale;
- All task information geometries and observer networks;
- All catastrophe specifications and capability–risk frontiers.

4.2 Unified Contraction Functor

Definition 4.2 (Contraction 1-Morphism). For each $\widehat{U}_{\text{comp}} \in \mathbf{CompUniv}_{\kappa}$, define

$$F_U : \widehat{U}_{\text{comp}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}}$$

as follows:

1. Configuration embedding

$$f_X = \iota_U : X \hookrightarrow \mathfrak{X}.$$

2. Control manifold embedding

$$f_{\mathcal{M}} : \mathcal{M}_U \hookrightarrow \mathfrak{M},$$

preserving metric structure (at most constant rescaling).

3. Information manifold embedding

$$f_{\mathcal{S}} : \mathcal{S}_{Q,U} \hookrightarrow \mathfrak{S},$$

preserving Fisher information metric.

4. Observer and knowledge graph embedding

$$f_{\text{obs}} : \text{ObsStates}(U_{\text{comp}}) \hookrightarrow \mathfrak{E}_{\text{obs}}.$$

5. Catastrophe specification and capability–risk frontier embedding

$$f_{\text{cat}} : (X_0, C_{\text{cat}}) \mapsto \mathfrak{S}_{\text{cat}}, \quad f_{\text{CR}} : \mathcal{F}_{\text{CR}}^{(U,Q)} \mapsto \mathfrak{F}_{\text{CR}}.$$

Combining these F_U is safe–geometric–information compatible 1-morphism.

4.3 Terminal Object Property

Theorem 4.3 (2-Terminal Object Property of Unified Computational Universe Terminal Object). *In 2-category $\mathbf{CompUniv}_\kappa$, $\mathfrak{U}_{\text{comp}}^{\text{term}}$ is 2-terminal object:*

For each object $\widehat{U}_{\text{comp}}$, there exists 1-morphism

$$F_U : \widehat{U}_{\text{comp}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}},$$

and for any other 1-morphism

$$G_U : \widehat{U}_{\text{comp}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}},$$

there exists unique (in 2-morphism sense) natural transformation

$$\Xi_U : G_U \Rightarrow F_U.$$

Proof (Outline). 1. **Existence:** By construction in 4.2, for each $\widehat{U}_{\text{comp}}$ can explicitly define F_U as embedding.

2. **Uniqueness (up to natural transformation):** Any other 1-morphism G_U must map X to some subset of \mathfrak{X} , and preserve structure at control–information–observer–capability–risk layers. Since $\mathfrak{U}_{\text{comp}}^{\text{term}}$ constructed by “maximal global equivalence class”, for any such G_U there exists “isometry–equivalence class” natural transformation Ξ_U pulling it back to canonical embedding F_U : at each layer, can eliminate redundant degrees of freedom through internal isometry or local unitary transformation, making map isomorphic to F_U .

3. **Naturality:** For morphism $H : \widehat{U}_{\text{comp}} \rightarrow \widehat{V}_{\text{comp}}$, natural transformation between two-side composition $F_V \circ H$ and F_U given by unified construction—this is standard feature of “inclusion–isometry” structure in Grothendieck universe.

Rigorous 2-category proof requires checking compatibility at each layer, see Appendix C. □

5 Equivalence with Unified Physical Universe Terminal Object

Previous works already constructed physical universe category $\mathbf{PhysUniv}^{\text{QCA}}$ and computational universe category $\mathbf{CompUniv}^{\text{phys}}$, and through functors

$$F : \mathbf{PhysUniv}^{\text{QCA}} \rightarrow \mathbf{CompUniv}^{\text{phys}}, \quad G : \mathbf{CompUniv}^{\text{phys}} \rightarrow \mathbf{PhysUniv}^{\text{QCA}}$$

proved both are categorically equivalent. At physical level, unified physical universe terminal object $\mathfrak{U}_{\text{phys}}^{\text{term}}$ already constructed through scattering time scale, boundary time geometry, and Dirac–QCA continuous limit.

In current scenario, from inclusion $\mathbf{CompUniv}^{\text{phys}} \hookrightarrow \mathbf{CompUniv}_\kappa$ and categorical equivalence, can lift terminal object relationship:

Proposition 5.1 (Equivalence Between Terminal Objects). *Under constraints of unified time scale, unified physical universe terminal object $\mathfrak{U}_{\text{phys}}^{\text{term}}$ and unified computational universe terminal object $\mathfrak{U}_{\text{comp}}^{\text{term}}$ are equivalent in 2-category sense.*

That is, there exists pair of 1-morphisms

$$\mathcal{F} : \mathfrak{U}_{\text{phys}}^{\text{term}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}}, \quad \mathcal{G} : \mathfrak{U}_{\text{comp}}^{\text{term}} \rightarrow \mathfrak{U}_{\text{phys}}^{\text{term}},$$

and natural isomorphism 2-morphisms

$$\mathcal{G} \circ \mathcal{F} \simeq \text{Id}_{\mathfrak{U}_{\text{phys}}^{\text{term}}}, \quad \mathcal{F} \circ \mathcal{G} \simeq \text{Id}_{\mathfrak{U}_{\text{comp}}^{\text{term}}}.$$

Proof relies on previous categorical equivalence theorem and terminal object property, see Appendix D.

This means: “universe as computation” unified terminal object and “universe as unified time–boundary geometry” terminal object are same 2-terminal object in different categorical presentations: one with discrete computation structure as primary, one with continuous geometric structure as primary.

A Technical Details of Unified Configuration–Event–Diamond Layer

A.1 Set-Theoretic Construction of Maximal Configuration Universe

To avoid size paradoxes, we operate within some Grothendieck universe \mathcal{U} , let

$$\mathcal{X}_0 = \{X_U : U \in \mathbf{CompUniv}_\kappa\}, \quad \mathcal{T}_0 = \{\mathsf{T}_U, \mathsf{C}_U, \mathsf{l}_U\}.$$

Define

$$\mathfrak{X} = \bigsqcup_U (X_U \times \{U\}),$$

then through isometry–equivalence relation \sim identify “geometrically completely identical” point pairs, obtaining quotient set

$$\mathfrak{X} = \left(\bigsqcup_U X_U \right) / \sim.$$

Unified transition relation T_∞ and cost C_∞ obtained through similar quotient construction. This process ensures:

- Each concrete X_U embedded into \mathfrak{X} ;
- In isometry equivalence classes, do not repeatedly count same update structures;
- Unified complexity distance $d_{\text{comp},\infty}$ restricts to original distance on each subset.

A.2 Unified Event Layer and Diamonds

On event layer

$$\mathfrak{E} = \mathfrak{X} \times \mathbb{N}$$

unified update relation

$$\mathsf{T}_{\mathfrak{E}} = \{((x, k), (y, k + 1)) : (x, y) \in \mathsf{T}_{\infty}\}$$

and cost function induce complexity light cone and diamond definitions completely analogous to single universe case.

B Construction of Unified Control and Information Manifold Terminal Objects

B.1 Local Construction of Control Manifold Terminal Object

For each U_{comp} , control manifold \mathcal{M}_U locally isomorphic to some Riemannian manifold (\mathbb{R}^{d_U}, G_U) . We perform disjoint union over all such local patches, then amalgamate by “time scale–scattering–control structure isometry” relation, obtaining unified control manifold \mathfrak{M} .

Technically, can define equivalence relation:

$$(\theta, U) \sim (\theta', U') \iff \exists \text{ isometric isomorphism } \varphi : \mathcal{M}_U \supset U \rightarrow U' \subset \mathcal{M}_{U'} \text{ with } \varphi(\theta) = \theta'.$$

Metric \mathfrak{G} defined on equivalence class representatives by G_U , isometry equivalence ensures consistency.

B.2 Construction of Information Manifold Terminal Object

For all Q, U , information manifold $(\mathcal{S}_{Q,U}, g_{Q,U})$ can be determined through relative entropy second-order structure. Same as control manifold, through disjoint union and Fisher–isometry equivalence relation amalgamation obtain $(\mathfrak{S}, \mathfrak{g})$.

C Formal Proof Outline of Terminal Object 2-Property

C.1 Uniqueness of 1-Morphism (Up to Natural Transformation)

Given $\widehat{U}_{\text{comp}}$ and two 1-morphisms

$$F_U, G_U : \widehat{U}_{\text{comp}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}},$$

compare their maps at each layer:

- At configuration layer, from isometry–equivalence construction of \mathfrak{X} , images of F_U and G_U must fall in same equivalence class, thus there exists some local bijection Ξ_X such that $G_X = \Xi_X \circ F_X$;

- At control and information layers, from isometry–equivalence construction of $\mathfrak{M}, \mathfrak{S}$, there exist isometric natural transformations $\Xi_{\mathcal{M}}, \Xi_{\mathcal{S}}$ between $F_{\mathcal{M}}, G_{\mathcal{M}}$ and $F_{\mathcal{S}}, G_{\mathcal{S}}$;
- At observer and capability–risk layers, similar amalgamation ensures existence of corresponding natural transformations.

Combining these natural transformations into 2-morphism Ξ_U completes.

C.2 2-Terminal Object Property

If there exists another candidate terminal object $\mathfrak{U}'_{\text{comp}}$, then 1-morphism $H : \mathfrak{U}_{\text{comp}}^{\text{term}} \rightarrow \mathfrak{U}'_{\text{comp}}$ starting from $\mathfrak{U}_{\text{comp}}^{\text{term}}$ and 1-morphism K from $\mathfrak{U}'_{\text{comp}}$ to $\mathfrak{U}_{\text{comp}}^{\text{term}}$ must compose to identity in 2-morphism sense, because both have “inclusion–amalgamation–isometry” structure. This is standard 2-terminal object argument.

D Equivalence of Unified Physical Universe Terminal Object and Unified Computational Universe Terminal Object

At physical level, unified physical universe terminal object

$$\mathfrak{U}_{\text{phys}}^{\text{term}} = (M_{\infty}, g_{\infty}; \mathcal{F}_{\infty}; \kappa_{\infty}; S_{\infty}; \cdots)$$

constructed through similar Grothendieck amalgamation in physical universe category $\mathbf{PhysUniv}^{\text{QCA}}$. Previously given categorical equivalence

$$F : \mathbf{PhysUniv}^{\text{QCA}} \rightarrow \mathbf{CompUniv}^{\text{phys}}, \quad G : \mathbf{CompUniv}^{\text{phys}} \rightarrow \mathbf{PhysUniv}^{\text{QCA}}.$$

By extending these functors to terminal object level, can construct

$$\mathcal{F} : \mathfrak{U}_{\text{phys}}^{\text{term}} \rightarrow \mathfrak{U}_{\text{comp}}^{\text{term}}, \quad \mathcal{G} : \mathfrak{U}_{\text{comp}}^{\text{term}} \rightarrow \mathfrak{U}_{\text{phys}}^{\text{term}},$$

and using terminal object property and equivalence, obtain natural isomorphisms

$$\mathcal{G} \circ \mathcal{F} \simeq \text{Id}_{\mathfrak{U}_{\text{phys}}^{\text{term}}}, \quad \mathcal{F} \circ \mathcal{G} \simeq \text{Id}_{\mathfrak{U}_{\text{comp}}^{\text{term}}}.$$

This fundamentally shows:

- Viewing universe as “scattering–boundary geometry terminal object under unified time scale” and
- Viewing universe as “computational universe terminal object under unified time scale”

are same mathematical object in dual presentation in two equivalent categories.