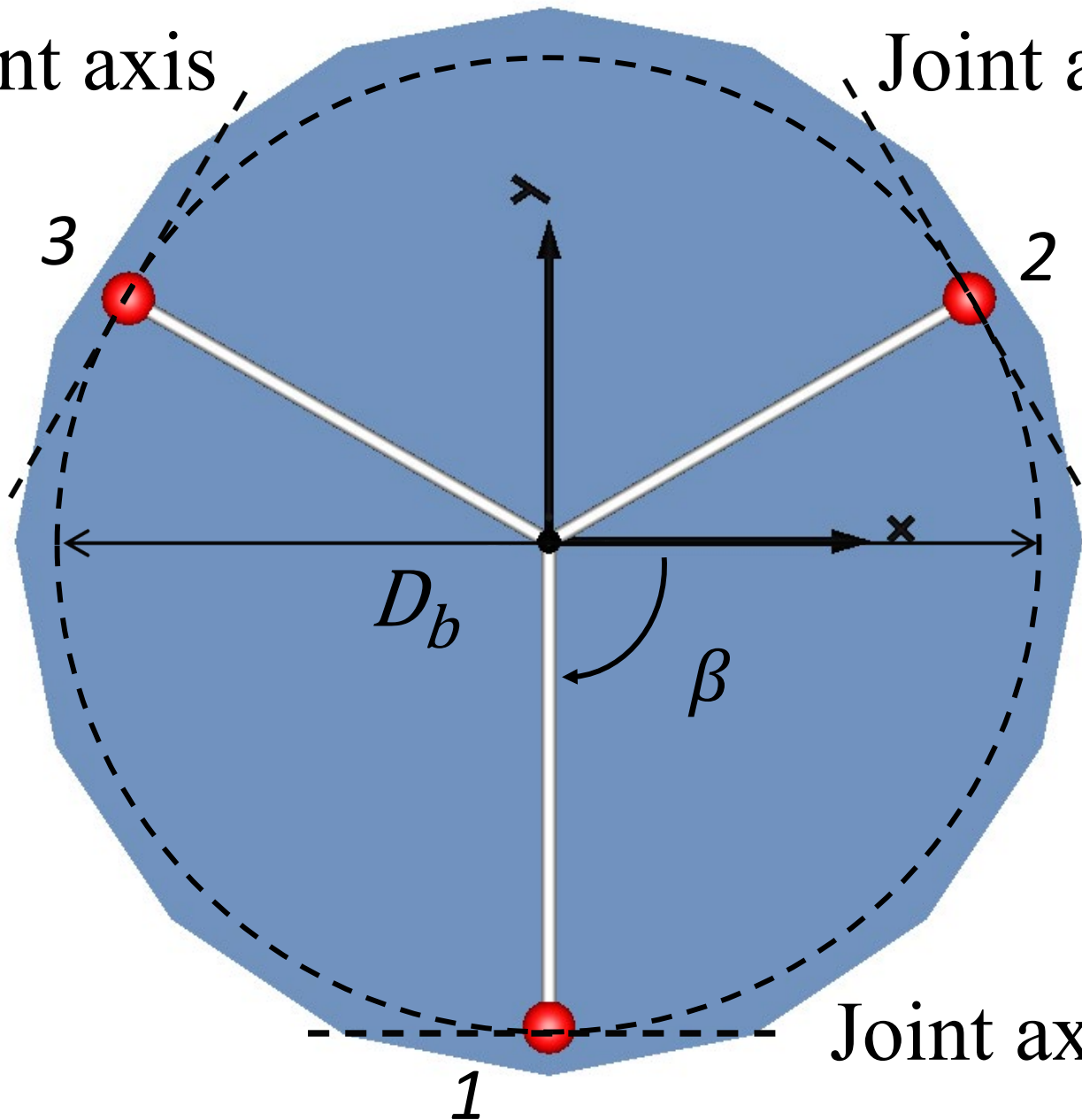


Joint axis

Joint axis



Joint axis

1

2

3

$D_b$

$\beta$