

EE636: Matrix Computations

Lecture 3

Debasattam Pal

EE Department,
Indian Institute of Technology Bombay,
Mumbai, India.

IIT Bombay
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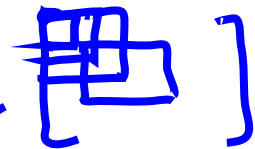


- How a computer solves

$$Ax = b, \quad \min \|Ax - b\|, \quad Ax = \lambda x, \quad Av = \sigma u$$

where $\sigma \geq 0$, $\{u_1, u_2, \dots, u_m\} \subseteq \mathbb{R}^m$, $\{v_1, v_2, \dots, v_n\} \subseteq \mathbb{R}^n$ are orthonormal.

- The effect of **round off error**.
- When a solution can be trusted.
- FLOPS** to measure computation time.
- Counted the FLOPS for basic matrix multiplication: $2mn$ for a matrix of size $m \times n$ and a vector of size n .
- How to solve linear systems of equations: triangular systems.
- The (almost) general case: Gaussian elimination.
- Gaussian elimination (without pivoting) is possible if and only if the **leading principal minors** of A are non-zero.
- Gaussian elimination without pivoting results in the **LU decomposition** of A : that is $A = LU$, where U is an **upper triangular matrix** and L is a **unity lower triangular matrix**.
- The L and U in the LU decomposition is unique.



FLOPs count of LU decomposition

$$\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -m_{21} & 1 & 0 & \cdots & 0 \\ -m_{31} & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ -m_{n1} & 0 & 0 & \cdots & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ 0 & a_{22}^{(1)} & a_{23}^{(1)} & \cdots & a_{2n}^{(1)} \\ 0 & a_{32}^{(1)} & a_{33}^{(1)} & \cdots & a_{3n}^{(1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & a_{n2}^{(1)} & a_{n3}^{(1)} & \cdots & a_{nn}^{(1)} \end{bmatrix}$$

- $(n-1)$ FLOPs for divⁿ to get m_{ij} s.
- $(n-1)^2 + \boxed{(n-1)}$ FLOPs for multⁿ.
 \rightarrow augmented
- $(n-1)^2 + \boxed{(n-1)}$ FLOPs for addⁿ.

$$2(n-1)^2 + 2(n-1) + (n-1)$$

$$(n-1)[2(n-1) + 3]$$

$$= (n-1)[2n+1] \approx 2n^2$$

$$= \underline{\underline{(2n^2 - n - 1)}} \quad @ \text{ the end of step 1.}$$

$$\text{Total FLOPS} = 2n^2 + 2(n-1)^2 + 2(n-2)^2 + \dots \approx O(n^3)$$

Special case: symmetric positive definite matrices

$$A = A^T$$

Definition (symmetric positive definite matrices)

A symmetric matrix $A = A^T \in \mathbb{R}^{n \times n}$ is said to be **positive definite (PD)** if $x^T A x > 0$ for all $x \in \mathbb{R}^n \setminus \{0\}$.

- Geometry of quadratic forms.

$$x \in \mathbb{R}^n \quad "x^T A x" \in \mathbb{R}.$$

$$x^T A x > 0 \quad \forall x \in \mathbb{R}^n \setminus \{0\}$$

$$\underline{A} x = b \quad \text{PD.}$$

$$\{x \in \mathbb{R}^n \mid \underline{x^T A x} = c\} = \text{level sets of } x^T A x$$

Special case: symmetric positive definite matrices

Theorem

$A = A^T$ is PD if and only if every eigenvalue of A is positive. 

I PD? 

$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ PD? 

$$\underline{x_1^2 + 2x_2^2} > 0$$

$$\forall x_1, x_2 \neq 0$$

$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ PD?
 $x_1^2 - x_2^2 =$

Special case: symmetric positive definite matrices

$$\underline{A = A^T} \Rightarrow \exists Q \in \mathbb{R}^{n \times n}, Q^T Q = Q Q^T = I, \\ \text{s.t.}$$

$$Q^T A Q = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \quad \text{SPECTRAL THEOREM.}$$

$$A = Q \Lambda Q^T \quad y := Q^T x$$

$$x^T A x = x^T Q \Lambda Q^T x = \frac{y^T \Lambda y}{\forall y \in \mathbb{R}^n} \\ \forall x \in \mathbb{R}^n \quad (=)$$

$$y^T A y = y_1^2 \lambda_1 + \dots + y_n^2 \lambda_n \geq 0 \quad \forall y$$

$$\Leftrightarrow \underline{\lambda_i \geq 0} \text{ PSD}$$

$$\lambda_i > 0, \text{ PD}$$

$$x_1^2 + x_2^2 = c$$



GEOMETRY
when A PSD.

What if $A \neq A^T$?

Special case: symmetric positive definite matrices

Theorem

$A = A^T$ is PD if and only if every leading principal submatrix of A is PD.



$$\begin{bmatrix} & & \\ & & \\ & & \end{bmatrix} \succ 0 \Leftrightarrow A_1 \succ 0, A_2 \succ 0, \dots, A_n \succ 0.$$



$$\Rightarrow A \not\succ 0 \Rightarrow \exists \xi \in \mathbb{R}^n \text{ s.t. } \xi^T A \xi < 0$$
$$\begin{bmatrix} \xi \\ 0 \end{bmatrix}^T A \begin{bmatrix} \xi \\ 0 \end{bmatrix} = \xi^T A \xi < 0 \Rightarrow A \not\succ 0.$$

Special case: symmetric positive definite matrices

Lemma

If $A = A^T$ is PD then $\det A > 0$.

The Schur complement

The Schur complement

Special case: symmetric positive definite matrices

Theorem

Let $A = A^T$ be PD, then A admits an LU factorization.

LU decomposition of symmetric PD matrices: Cholesky factorization

LU decomposition of symmetric PD matrices: Cholesky factorization

LU decomposition of symmetric PD matrices: Cholesky factorization

Thank you