**annex** safety {\*\*

**fault** SensorPedalPosition\_ErroneousData "Inverted boolean fault" **:** faults.inverted\_fail **{**

**inputs:** val\_in **<-** elec\_pedal\_position**;**

**outputs:** elec\_pedal\_position **<-** val\_out**;**

**probability:** 5.0E-6 **;**

**duration: permanent;**

**}**

};