## DL concepts:

Concept	Description	Effect	Notes
Covariance Shift	General: Change in the distribution of data.	Makes learning slower, requiring smaller α	Apply BN
	In DL: Change in the distribution of activations of layer <i>n</i> due to change in weights of previous layers.	Can cause saturation in some units, which can stop learning completely	
Co-adaptation	Some neurons become very dependent on others.	Over-fitting	Apply Dropout
	Deeper layers learn to correct errors from earlier layers.		

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Early stopping	Stop training if <b>validation</b> loss does not improve after <i>n</i> iterations	Prevent overfitting	
Batch Norm	Without BN, layers are constantly learning normalization, and changes in early layers screw deeper layers expectations  Idea: Normalize data between network layers  Idea: Have specific parameters for normalization mean and std, so weights don't have to perform the normalization	More stable learning, even with larger α  Small regularization effect (adds noise to activations). Less dropout needed	Can be applied to all types of layers  Learnable shift and scale are per feature
Adagrad	Per-weight adaptive LR, with larger LR for sparser	Works well on sparse data when sparse	

	parameters.	features are informative	
RMSprop	Per-weight adaptive learning rate, divided by a moving average of gradient.  Extends Rprop to mini-batch training scenarios.	Faster learning	
Adam	Per-weight adaptive learning rate, divided by a moving average of gradient and gradient second moment (variance).  Extends RMSprop by also using second moment.	Faster learning	
Leaky ReLU PReLU	Leaky ReLU produces non-zero gradient in the negative domain  PReLU makes the slope in the negative domain a learnable parameter.	Avoid zero gradient when x < 0.	
Dropout	During training, randomly drop some neuron activations.  Similar to training multiple networks in parallel and averaging their outputs, which reduces variance (over-fitting).	Regularizes, preventing over fitting.	Mostly for dense layers

Model overfit	Get more data	Get more data for real  Image data augmentation  Smote -like  Data augmentation with generative models	
	Reduce model capacity / complexity (reduce variance)	Reduce network's layers and nodes	
		Early stop	
		Regularize  Average several	L1 & L2 regularization  Momentum, Smaller batch size  Dropout  Batch Normalization  Use larger learning rate
	B 1 : .	models	
	Regularize less		
Model underfit	Increase model capacity	More layers, more nodes	