# Probabilistic Graphical Models

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February 26, 2018

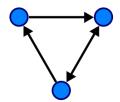
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#### Outline

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# What is graph

- vertices or nodes or points
- edag, arcs or lines
- direction



## Graph is everywhere in the field of computer science

- all the trees(avl tree, binary search tree, red-black tree...)
- dijkstra's algorithm, maximum flow algorithm...
- deep learning computing framework: Mxnet, Tensorflow

## What is probability graph

- a graph comprises nodes (also called vertices) connected by links (also known as edges or arcs).
- each node represents a random variable (or group of random variables), and the links express probabilistic relation- ships between these variables
- the graph then captures the way in which the joint distribution over all of the random variables can be decomposed into a product of factors each depending only on a subset of the variables.

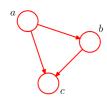
## Why we need to study probability graph

- It provide a simple way to visualize the structure of a probabilistic model and can be used to design and motivate new models
- insights into the properties of the model, including conditional independence properties, can be obtained by inspection of the graph
- complex computations, can be expressed in terms of graphical manipulations, in which underlying mathematical expressions are carried along implicitly.

# Bayesian network(directed graph)

- the links of the graph have a particular directionality indicated arrows
- useful to expressing the causal relationships between random variables
- apply the product rule to the joint distribution over three variables p(a, b, c) = p(c|a, b)p(b|a)p(a)

Figure: the directed graph model of joint distribution p(a, b, c)



#### A example

ploynoimal regression:

$$p(\mathbf{t}, \mathbf{w}) = p(\mathbf{w}) \prod_{n=1}^{N} p(t_n | w)$$
 (1)

make the parameters of a model, as well as its stochastic variables, explicit

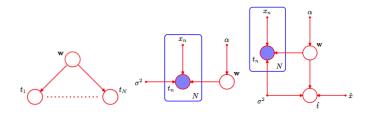
$$p(\mathbf{t}, w|x, \alpha, \sigma^2) = p(w|\alpha) \prod_{n=1}^{N} p(t_n|w, x_n, \sigma^2)$$
 (2)

where x is input the data, t is the observed data,  $\alpha$  is the gaussian prior and  $\sigma^2$  is the noise variance.

the form with prediction value:

$$p(\hat{t}, \mathbf{t}, w | \hat{x}, \mathbf{x}, \alpha, \sigma^2) = p(w | \alpha) p(\hat{t} | \hat{x}, w, \sigma^2) \left[ \prod_{n=1}^{N} p(t_n | w, x_n, \sigma^2) \right]$$
(3)

# corresponding graph model



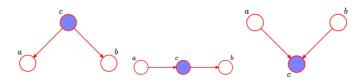
# Conditional independence

defination: p(a|b,c) = p(a|c),  $a \perp b|c$ 

- it is very important for simplifying computation
- using D-sparation in directed graph, undirected graph however, it's easier to judage than the directed graph
- **KEY IDEA**: to see wether a variable is "blocked"

## three example graphs

- tail-to-tail  $a \perp \!\!\!\perp b \mid c$
- head-to-tail  $a \perp \!\!\!\perp b \mid c$
- head-to-head  $a \perp\!\!\!\perp b \mid c$  not hold



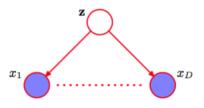
## Example

Naive Bayes:

$$p(D|\mu) = \prod_{n=1}^{N} p(x_n|\mu)$$
 (4)

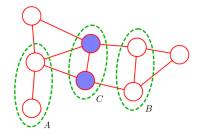
where  $\mu$  is the prior

Figure: probalisic graph expression of naive bayes



# Markov random fields(Undirected graph)

• conditional independence properties:  $A \perp\!\!\!\perp B \mid C$ , whether all paths that connect nodes in set A to nodes in the set B.



#### Factorization properties

- clique: which is defined as a subset of the nodes in a graph such that there exists link between all pairs of nodes in the subset. The set of nodes in a clique is fully connected.
- maximal clique: is a clique such that it is not possible to include any other nodes from the graph
- the joint distribution is written as a product of potential functions  $\psi(\mathcal{C})$  over the maximal cliques of the graph

$$p(x) = \frac{1}{Z} \prod_{C} \psi(C)(x_{C})$$

where  $x_C$  denote the node in the clique, and we do not restrict the choice of it. Z is the partition function, give by

$$Z = \sum_{X} \prod_{C} \psi(C)(X_{C})$$



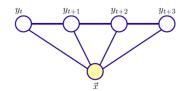
## Example: CRF

- CRF(Conditional Random Field) is just a version of an MRF where all the clique poentials are conditioned on input features
- CRF can be any kind of structure, but usually we use a linear chain structure.

$$p(y|x) = \frac{1}{Z(x)} \prod_{j=1} \psi_j(y,x)$$

where we define the poential function to be:

$$\psi_j(x,y) = \exp(\sum_{i=1}^m \lambda_i f_i(y_{j-1},y_j,x,j))$$



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#### Inference

- exact inference and approximation method.
- exact inference: sum-product, max-sum algorithm
- approximation: variational methods and sampling methds etc.

# Reference and further reading I



Bishop 2006

Pattern Recognition and Machine Learning. Springer, 2009.

more about CRF and HMM see this material:

http://www.eng.utah.edu/~cs6961/papers/jerryzhu-crfs.pdf