
INTRODUCING TYPE PROPERTIES

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ABSTRACT

Many things can be expressed by attributing some expressions to another on the static level, i.e while typing them. For instance, there are type theories that track how many times a variable is used at run-time. To achieve that, they attribute 0 , 1 , or n to the variable, stating that it is not used at all, used once, or many times, appropriately. After they assert that all variables have been used that much how they expected, the attributed data (those 0 , 1 , or n) are no longer necessary and therefore can be erased before a program is run. This was what we meant by attributions on the “static level”. Despite the number of practical ideas that can be expressed by these attributions, still, there wasn’t any programming language concept that would allow doing so. That is, to attribute arbitrary expressions to another and assign their meaning, while being fully on the static level.

In this paper, we propose *type properties* — a programming language concept, that under the hood uses *propertied types*, another notion introduced in this paper, to express them. We give its both informal description and present a simple type theory, augmented with the one.

1 Introduction

When doing some kind of a static analysis or recording information about a program, type theories usually attribute some data to their expressions statically. After the desired analysis has been performed, most of the time, these data are no longer needed and are therefore erased before a program is run.

For instance, an approach called *Quantitative Type Theory* [3] does quantitative analysis by tracking how many times a variable can be used at run-time. In this approach, variables are attributed with 0 , 1 , or n , to indicate that one is not used at run-time, used once, or used many times, appropriately. *Graded Modal Dependent Type Theory* [9] generalizes this approach to track types for their usage as well, meaning that ones need to be augmented with additional data too. [1] discusses these theories in some detail. After an assertion, during type-check, that variables have been used exactly that much how they expected to be, is made, these attributions become no longer necessary and therefore can be erased before the program goes to run-time. The assertion is made at compile-time, so the interpretation of the attributed data (those 0 , 1 , and n). This was what we meant by attributions on the “static level”.

Some type theories attribute expressions to types, rather than to terms. To illustrate, in λ_{Rust} ([7]), a reference’s type is augmented with a lifetime to indicate that the reference is valid as long as the attributed lifetime is alive. Modal types theories, in turn, to express modal necessity, supplement a type (to say, the type A) with \Box , which allows to, for instance, interpret expressions of this type as a code that will be evaluated in the future to the value of the type A ([5]).

Looking from a different perspective, an expressive power from another level of indirection can be discovered. So, even static typing itself can be seen as just a special case of these static attributions — the only thing that happens is that types are attributed to terms, a type-checking is performed, and the types are erased before a program goes to run-time.¹

The key thing is that, in common, the only thing all these powerful theories do is *attribute* some data to their expressions, assign the meaning to/interpret these data on the static level, perform an analysis/make an assertion, and erase them before the program goes to run-time since the one is just no longer needed.

¹What should be noted is that we speak about static typing in general, without covering some specific cases. For instance, in dependent type theories, since types are treated as first-class values, one is able to propagate them to run-time just like any other data.

Yet, despite the shown expressive power of these static attributions, there wasn't any programming language concept that would allow one to express them in a language itself, i.e, attribute arbitrary constant expressions to another on the static level and let a programmer decide how to interpret them, with the interpretation (meaning of them) being limited only by the other means of the language. This concept, for instance, would allow one to attribute those 0 , 1 , or n , to language expressions, while the presence of means of some kind of "overloading" of the behavior when a variable is found to be used in a term ², altogether, would give one an opportunity to express linear types as just a separate module and include them whenever needed, rather than totally refining the type system to add them. What should be noted is that it is the implementation of these static attributions that makes the expression of linear types hard in this way. It is not that hard to enlarge a theory with such a notion of "overloading", whereas obliging a type theory to somehow remember what we attributed to what, while fulfilling the requirement of being interpreted fully on the static level (which is needed to, for instance, check the same linearity laws at compile-time), is a real challenge.

In this paper, we accept this challenge. We propose *type properties* — a concept that allows one to express these static attributions. The key thing about our approach is that, for a user, it looks like the way we described — a compiler magically remembers about the attributions, while, in its implementation, we use anonymous types to express them. We also want to be clear and state that the purpose of this paper is not to show how to express things like linear types using this concept ³. The purpose of this paper is to introduce such a concept that would allow one to express static attributions, in a clear and concise way, by giving its both informal and formal presentation. It is also worth noting that the application of this concept is obviously not limited to the expression of linear types — we picked it just as an example of things, the expression of which would be really practical.

Our **contributions** are as follows:

- We first give an informal description of the concept (Section 2). While describing, we define so-called *propertied types* — exactly those anonymous types that are used to handle static attributions.
- After, we present a simple type theory, namely, λ_{\rightarrow_p} , where we formalize type properties (Section 3). Also, as those attributions must be handled at compile-time and not occur at run-time, in the same section, we introduce two phases of program execution by giving appropriate operational semantics for each of those. The first one is the phase where all static attributions are handled, which we call *transformation*. The second is the ordinary run-time program execution.
- Then we prove that, according to the rules we gave in Section 3, all static attributions are evaluated at compile-time (Section 4). We also prove that the *transformation* is deterministic, and the property of λ_{\rightarrow_p} of being type sound.
- Finally, if one still has some troubles understanding exactly how type properties are handled, we write two trivial programs and perform their step-by-step type-checking, transformation, and run-time evaluation (Section 5).

What should be noted is that the absence of such a concept doesn't mean that such static attributions weren't expressible in general — there are type theories that, in some sense, are capable of doing so. These are theories where it is possible to implement other formal logic and maybe even "embed" one in the system itself — in this case, the only thing one needs to obtain, for instance, the same linear types, is just to formalize linear logic. This, however, is not purely an expression of static attributions — it is just an expression of a whole type theory that is augmented with ones. But the real thing is that this fact, in any way, doesn't take away the need in such a concept — in contrast, such theories may just formalize our notion to obtain the ability to express them.

2 Type Properties

First of all, let's imagine a type theory where it is possible to express such static attributions and what does one must happen to have. Let's also imagine that, for now, the only expressions we can attribute to another are integer constants that we denote as n .

The first thing that must be present is obviously the attribution itself:

$$\frac{\Gamma \vdash 1 : \text{int} \quad \Gamma \vdash n : \text{int}}{\Gamma \vdash 1_n : \text{int}} \text{ Set}$$

When attributed, it is also necessary to have the ability to retrieve a static attribute back or even erase it:

²Put it simply, all we need is an opportunity to define a function that will be called when a variable is found to be used in a term.

³This is, in fact, the purpose of another upcoming research paper, on which we actively work now and for which this paper, by introducing this concept, stands as a basis.

$$\frac{\Gamma \vdash 1_n : \text{int}}{\Gamma \vdash n : \text{int}} \text{ Retrieve}$$

$$\frac{\Gamma \vdash 1_n : \text{int}}{\Gamma \vdash 1 : \text{int}} \text{ Erase}$$

Because an expression in this type theory is only optionally attributed with an integer constant, it would be preferable to have an opportunity to work with expressions, about which, during type-check, it is not yet known either they have an attributed constant or not. For instance, if we have a function's argument — x — when type-checking the body of the function, we don't know if an expression that will be used to construct the value of the argument will have one. All we need is a construction that would handle both cases — the presence and the absence of them. Let's name this construction *if-has*:

$$\frac{\Gamma \vdash x? : \text{int} \quad \Gamma, x_n : \text{int}, n : \text{int} \vdash M : T \quad \Gamma, x : \text{int} \vdash N : T \quad (x_n, x, n) \notin \Gamma}{\Gamma \vdash \text{if } x \text{ has } n \text{ then } M \text{ else } N : T}$$

Now recall that our programs do not only proceed through type-checking and run-time execution but also have a phase between them, which we will call, in Section 3, *transformation*. This is exactly the phase where all constructions that work with static attributions are handled, since, as we already pointed out many times, they must be processed before run-time.

Our new construction must be handled during this phase as well. During transformation, a thing called function monomorphization will happen, which means that we will know if the argument has an attributed expression. When the transformation will come to the construction *if-has*, the only thing it will do is to compile itself (yes, compile) to its branch *then*, if there will be an attributed constant on its argument, and to branch *else* otherwise.

Now, when we are equipped with the most basic operations on static attributions, let us try to write a trivial program in pseudo-code and see what this program is transformed into. After, we will finally discuss how we can use types to handle them.

One thing to mention — in a real programming language, most probably, you will never find an expression with subscript notation, like 1_n , so, in our pseudo-code, we replaced this notation with a more realistic one — $\text{set}(l, n)$.

```

1  greater_than_five (x : int) =
2    if x has n then n > 5
3    else x > 5
4
5  let z = 1
6  let z' = set(z, 1)
7
8  let greater_z = greater_than_five z
9  let greater_z' = greater_than_five z'
```

So, as it was pointed out in the introduction, a programmer is free to decide how to interpret these attributions. In this trivial program, we agree that if there is a statically attributed constant to an expression (such as n in x_n), then it means that, during compilation, it is known that this expression will be evaluated to the augmented constant. With this in mind, we can implement a trivial optimization in our function *greater_than_five* — that is, by the construction *if-has*, we can express that, if there's an integer constant, attributed to an expression that was used to construct the value of x , then use it and perform the comparison with respect to the constant, or to x , otherwise.

According to the logic we described, our program will be transformed into something like:

```

1  greater_than_five_1 (x : int) = x > 5
2  greater_than_five_2 (x : int) = 1 > 5
3
4  let z = 1
5  let z' = z
6
7  let greater_z = greater_than_five_1 z
8  let greater_z' = greater_than_five_2 z'
```

At this moment, we expressed a trivial optimization purely by the means of our theory.

Although it works, it's worth noting that our concept should never be used to express such optimizations in the code itself. Any modern compiler can easily apply something like *constant propagation* ([8]), an optimization that computes constant expressions at compile-time rather than at run-time, without any notion of type properties or type-theoretic static attributions and obtain even a better result. Having that static attributions have much more useful applications, some of which were listed in the introduction, we came up with this example because expressing something like from the list in the introduction is a whole separate research topic.

Now let's finally see how on earth we can use types to express static attributions and look at the real theory.

Using types to express static attributions First of all, let's make it clear what does it mean to "use types" to express these attributions. Using types to express such attributions means that, when a programmer wants to attribute one expression to another (for instance, using construction $\text{set}(x, n)$ in the previous example), rather than attributing to the term, just like we did before — $x_n : \text{int}$, we attribute it to its type.

While, at first, this sounds weird, this approach has some serious advantages:

- *We don't augment type theory (in the sense of the study, not a type system) with something new and complex.* In the case when we attribute expressions to term themselves, then a new kind of terms, which is different from the ordinary one, arises. Having in mind that, in the real theory, we are not restricted to attributing only integer constants and the number of attributions is not fixed, we would need to extend our meta-theory to work with these terms too. In contrast, when we attribute those to types, what we get are types parametrized with terms — and this is what we are obviously familiar with — dependent types ([10], [2],)! Of course, they are not "purely" dependent types, since they are required to capture some other data too, but instead can be seen as a special case of ones or just a similar concept.
- By attributing expressions to types rather than to terms, we also likely to get the lifting of these attributions to the static level only. This is because most type theories (if we don't cover dependent cases) erase type data before the program goes its run-time.

Now let's finally try to attribute something to a type rather than to term. From now, let's also accept the fact that we can attribute constant expressions of any type, not only integer constants, and the fact that the number of attributions is not fixed (previously we could have only one attribution). According to our logic, this would look like this:

$$\frac{\Gamma \vdash x : \text{int} \quad \Gamma \vdash n : \text{int}}{\Gamma \vdash \text{set}(1, eq, n) : [\text{int}] \langle eq \hookrightarrow n[\text{int}] \rangle}$$

First of all, because we can have arbitrarily many attributions, to later retrieve one of those, we must somehow distinguish them among themselves — from now on, each attribute will come with a name. Second, we have to use a new notation to perform attribution — we write $\text{set}(1, eq, n)$ to statically attribute an expression n to 1, and give the name eq .

Types that are constructed when one tries to perform attributions in the rest of the paper will be called *propertied types*. Their notation — $[T] \langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle$ — merely means that the original type of the term was T and that one has static attributions in form of $p \hookrightarrow e[P]$, where p , e , and P , indicate the name, expression, and type of the attribute, appropriately. In this case, the type T is said to be the base type of the propertied one.

But now we are in a trouble. The thing is, our function *greater_than_five*, expects an argument of the type *int*, while we, from now, on line 9 in the previous example, pass an argument of a different type — of a propertied one, that is based on *int*. This means that the program won't even type-check.

For this to work, we have to make our functions to be *polymorphic with respect to type properties*. This means that if a function accepts an argument of the type T , then it also must accept an argument of a propertied type that is based on T . This also means that to work as expected we have to provide an efficient framework of function recompilation and monomorphization. This is because if we place a construction like *if-has* inside the body of a function, that will inspect type type (since attributes are now kept in types) of the function's argument (as we did in *greater_than_five*), then the body of the function will depend on the type of the passed argument, which is not known since functions are polymorphic. We can't go the simple way and do the inspection at run-time ([6], [4]) since we promised that static attributions do not occur at one — so, we are left only with one choice — to provide an efficient framework of function recompilation and monomorphization.

As the reader is already familiar with nearly what one has to expect from the rest of the chapters, we think it is exactly the time to start the presentation of the real theory altogether with things like the above-mentioned framework.

3 The system $\lambda_{\rightarrow p}$: Formalization of Type Properties

In this section, we present a simple system augmented with the notion of type properties. This system was originally based on *Simply Typed Lambda Calculus*, but the augmentation of type properties has eliminated almost all observable similarities. We call this system $\lambda_{\rightarrow p}$.

3.1 Syntax

The concrete syntax of $\lambda_{\rightarrow p}$ is defined as follows:

(typing contexts)	$\Gamma ::=$	$ \Gamma, x : T$
(types)	$T, P ::=$	$\text{int} \mid \text{unit} \mid T_1 \rightarrow T_2$
(expressions)	$F, M, N, L, e, t ::=$	$\text{func } f x : T \text{ with } M \text{ in } N \mid \text{let } x = e \text{ in } L$ $\mid \text{if-has } L p : T \text{ bind-as } x \text{ in } M \text{ else } N$ $\mid \text{extract}(M) \mid \text{set}(M, p, e) \mid \text{get}(M, p)$ $\mid \text{erase}(M, p) \mid M N \mid e_1 + e_2 \mid e_1 - e_2$ $\mid x \mid n$
(identifiers and variables)	x, y, p	
(integer constants)	n, k	

The system has two base types — *int* and *unit*, one compound — the function type, and a family of types that is not present in the syntax — the family of *propertied types*.

In contrast with *STLC*, this system does not have lambdas. Instead, it has the construction *func* that introduces a function in the scope of its continuation, where one is able to refer to the former with a specific name. The reason for having this will be made clear when we will start exploring how the system processes type properties. The expressions *set* and *get* are responsible for setting and retrieving properties from and to types.

The next interesting one is the expression *if-has* — it checks if a type has some property of a specific type and binds the value of the one to the identifier that follows the keyword *bind-as*, and executes the corresponding code. Finally, the constructions *erase* and *extract* erase certain property of a type and extract the underlying value, one that was given during formation, appropriately.

3.2 Typing Rules

Type formation judgment rules are as follows:

$$\begin{array}{c}
 \frac{}{\Gamma \vdash \text{unit}} \text{F-Unit} \\
 \\
 \frac{}{\Gamma \vdash \text{int}} \text{F-Int} \\
 \\
 \frac{\Gamma \vdash T_1 \quad \Gamma \vdash T_2}{\Gamma \vdash T_1 \rightarrow T_2} \text{F-Func} \\
 \\
 \frac{\Gamma \vdash T_1}{\Gamma \vdash [T_1]\langle \rangle} \text{F-Prop-1} \\
 \\
 \frac{\Gamma \vdash [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle \quad \Gamma \vdash e : P \quad (p_1 \neq p, \dots, p_n \neq p)}{\Gamma \vdash [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n], p \hookrightarrow e[P] \rangle} \text{F-Prop-2} \\
 \\
 \frac{\Gamma \vdash [T]\langle \text{props}_1, p \hookrightarrow e[P], \text{props}_2 \rangle \quad \Gamma \vdash e' : P'}{\Gamma \vdash [T]\langle \text{props}_1, p \hookrightarrow e'[P'], \text{props}_2 \rangle} \text{F-Prop-3}
 \end{array}$$

Here, $[T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle$ represents a propertied type, which is based on the type T and has properties in form of $p \hookrightarrow e[P]$, where p is an identifier that is used to refer to the property, and e is the corresponding expression of the property with the type P . The notation $(p_1 \neq p, \dots, p_n \neq p)$ in the rule *F-Prop-2* denotes that p

must not be already present in the properties. The rule *F-Prop-3* states that we can update the expression of a specific property in a propertied type. In this rule, we wrote $props_1$ for all properties $p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n]$ that come before the property with the name p , and $props_2$ for all that come after. We also implicitly assume that every rule in this section operates only on well-formed contexts.

The introduction rules go next:

$$\begin{array}{c}
 \frac{}{\vdash () : \text{unit}} \text{I-Unit} \\
 \\
 \frac{}{\vdash n : \text{int}} \text{I-Int} \\
 \\
 \frac{\Gamma \uplus \{x : T_1\} \vdash M : T_2 \quad \Gamma, f : T_1 \rightarrow T_2 \vdash e : T_e \quad (T_2 \neq [T]\langle \dots \rangle) \wedge (T_2 \neq P_1 \rightarrow P_2)}{\Gamma \vdash (\text{func } f x : T_1 \text{ with } M \text{ in } e) : T_e} \text{I-Func} \\
 \\
 \frac{\Gamma \vdash M : T_1 \quad \Gamma \vdash e : T_2}{\Gamma \vdash \text{set}(M, p, e) : [T_1]\langle p \hookrightarrow e[T_2] \rangle} \text{I-Prop-1} \\
 \\
 \frac{\Gamma \vdash M : [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle \quad \Gamma \vdash e : P \quad (p_1 \neq p, \dots, p_n \neq p)}{\Gamma \vdash \text{set}(M, p, e) : [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n], p \hookrightarrow e[P] \rangle} \text{I-Prop-2} \\
 \\
 \frac{\Gamma \vdash M : [T]\langle props_1, p \hookrightarrow e[P], props_2 \rangle \quad \Gamma \vdash e' : P'}{\Gamma \vdash \text{set}(M, p, e) : [T]\langle props_1, p \hookrightarrow e'[P'], props_2 \rangle} \text{I-Prop-3}
 \end{array}$$

The notation $(T_2 \neq [T]\langle \dots \rangle)$ indicates that the return type, namely, T_2 , cannot be a propertied type. In other words, we cannot return a value of a propertied type from a function. Notice that we can't make our function accept values of ones too — there is no conventional syntax for propertied types so that they exist only in our derivation rules. The notation $\Gamma \uplus \{x : T_1\}$ means that we're adding the judgment $x : T_1$ in the context Γ if $x \notin \Gamma$, and shadowing old with the new one otherwise.

Rules that cover the rest of the expressions are present below.

$$\begin{array}{c}
 \frac{\Gamma \vdash t_1 : T_1 \rightarrow T_2 \quad \Gamma \vdash t_2 : T_1}{\Gamma \vdash t_1 t_2 : T_2} \text{E-App-1} \\
 \\
 \frac{\Gamma \vdash t_1 : T_1 \rightarrow T_2 \quad \Gamma \vdash t_2 : [T_1]\langle \dots \rangle}{\Gamma \vdash t_1 t_2 : T_2} \text{E-App-2} \\
 \\
 \frac{\Gamma, x : T_1 \vdash M : T_2 \quad \Gamma \vdash N : T_1 \quad (T_2 \neq [T]\langle \dots \rangle) \wedge (T_2 \neq P_1 \rightarrow P_2)}{\Gamma \vdash \text{let } x = N \text{ in } M : T_2} \text{E-Let} \\
 \\
 \frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}} \text{E-Plus} \\
 \\
 \frac{\Gamma \vdash e_1 : [\text{int}]\langle \dots \rangle \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 + e_2 : \text{int}} \text{E-P-Plus-1} \\
 \\
 \frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : [\text{int}]\langle \dots \rangle}{\Gamma \vdash e_1 + e_2 : \text{int}} \text{E-P-Plus-2} \\
 \\
 \frac{\Gamma \vdash e_1 : [\text{int}]\langle \dots \rangle \quad \Gamma \vdash e_2 : [\text{int}]\langle \dots \rangle}{\Gamma \vdash e_1 + e_2 : \text{int}} \text{E-P-Plus-3} \\
 \\
 \frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 - e_2 : \text{int}} \text{E-Minus}
 \end{array}$$

$$\begin{array}{c}
 \frac{\Gamma \vdash e_1 : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash e_2 : \text{int}}{\Gamma \vdash e_1 - e_2 : \text{int}} \text{ E-P-Minus-1} \\
 \\
 \frac{\Gamma \vdash e_1 : \text{int} \quad \Gamma \vdash e_2 : [\text{int}] \langle \dots \rangle}{\Gamma \vdash e_1 - e_2 : \text{int}} \text{ E-P-Minus-2} \\
 \\
 \frac{\Gamma \vdash e_1 : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash e_2 : [\text{int}] \langle \dots \rangle}{\Gamma \vdash e_1 - e_2 : \text{int}} \text{ E-P-Minus-3} \\
 \\
 \frac{\Gamma \vdash M : [T] \langle \dots, p \hookrightarrow e[P], \dots \rangle}{\Gamma \vdash \text{get}(M, p) : P} \text{ E-Get-Prop} \\
 \\
 \frac{\begin{array}{c} \Gamma, L : T_L \vdash T_x \quad \Gamma, L : [T_L] \langle \rangle \vdash N : T \\ \Gamma \uplus \{x : T_x\}, L : [T_L] \langle p \hookrightarrow x[T_x] \rangle \vdash M : T \quad (e \notin \Gamma) \wedge (T_L \neq [T'] \langle \rangle) \end{array}}{\Gamma, L : T_L \vdash \text{if-has } L \text{ } p : T_x \text{ bind-as } x \text{ in } M \text{ else } N : T} \text{ E-If-Has-1} \\
 \\
 \frac{\begin{array}{c} \Gamma, L : [T_L] \langle \text{props} \rangle \vdash T_x \quad \Gamma, L : [T_L] \langle \text{props} \setminus p \rangle \vdash N : T \\ \Gamma \uplus \{x : T_x\}, L : [T_L] \langle \text{props} \setminus p, p \hookrightarrow x[T_x] \rangle \vdash M : T \quad (e \notin \Gamma) \end{array}}{\Gamma, L : [T_L] \langle \text{props} \rangle \vdash \text{if-has } L \text{ } p : T_x \text{ bind-as } x \text{ in } M \text{ else } N : T} \text{ E-If-Has-2} \\
 \\
 \frac{\Gamma \vdash M : [T] \langle \dots \rangle}{\Gamma \vdash \text{extract}(M) : T} \text{ E-Ext} \\
 \\
 \frac{\Gamma \vdash M : [T] \langle \text{props}_1, p \hookrightarrow e[P], \text{props}_2 \rangle}{\Gamma \vdash \text{erase}(M, p) : [T] \langle \text{props}_1, \text{props}_2 \rangle} \text{ E-Erase}
 \end{array}$$

One may notice that the rule *E-Let* prohibits its continuation to be of a propertied or function type. The reason for that will be made clear when we will explore how the system processes type properties. The rule *E-App-2* is one of the main rules that make functions be polymorphic with respect to propertied types. Namely, it states that if a function accepts an argument of the type T_1 , then it also accepts an argument of a propertied type that is based on T_1 . Another interesting rule is the rule *E-If-Has-1* — it states that if one tries to check if a property is assigned on even non-propertied type, then the expression is still well-typed. This is because when one checks if the body of a function is well-typed and tries to check if a type has an assigned property, the type of the argument itself may not be a propertied one, but instead the base type of the one.

Finally, the structural rules are:

$$\begin{array}{c}
 \frac{}{\Gamma, x : T, \Gamma' \vdash x : T} \text{ S-Var} \\
 \\
 \frac{\Gamma \vdash L : T_L \quad \Gamma \vdash T_x \quad (x \notin \Gamma)}{\Gamma, x : T_x \vdash L : T_L} \text{ S-Weak} \\
 \\
 \frac{\Gamma, \Gamma' \vdash L : T_L}{\Gamma', \Gamma \vdash L : T_L} \text{ S-Exchange}
 \end{array}$$

3.3 Processing type properties

As said in Section 2, type properties must live only in compile-time. This means that we must somehow evaluate them, and this evaluation must be processed right before a program is passed to the run-time. For this purpose, we introduce a new judgment — the judgment \rightarrow_p , which is a big-step operational semantics judgment that only evaluates stuff with type properties. In the rest of this paper, this form of evaluation will be called *transformation*.

An efficient implementation of type properties would utilize effective means of function recompilation. In order to perform any recompilation stuff, we must somehow save bodies and information of functions defined, so we introduce a context that serves the desired purpose. We call this context *functional context* Δ and define it as follows:

$$\Delta ::= \mid \Delta, f :: x : T_1 . M : T_2 \mid \Delta, f [n] \triangleright x : T_1 . M : T_2$$

Since functions in our system are not anonymous, to associate something with a specific function, it is enough to associate it with its name. If our language would instead have *ordinary lambdas* (or any other type of anonymous functions), other facilities for body propagation, which would, by chance, be more complicated than just named functions, must be utilized.

$f :: x : T_1 . M : T_2$ indicates that f is a function that takes x of the type T_1 as an argument, its body is M , and the resulting type is T_2 . It stands for a function that contains a raw code (not transformed yet) and therefore cannot be propagated to a run-time call. $f [n] \triangleright x : T_1 . M : T_2$, where n is any natural number, stands for a monomorphized version of f , meaning that its body has already gone through transformation and it is ready to be called. n here just stands for distinguishing different monomorphizations of the function f .

Below we list some notations that we'll use in this section

- $f \notin \Delta$ — there is no entry $f :: x : T_1 . M : T_2$, where T_1 and T_2 match *arbitrary* types and M matches *any* term, in the context Δ .
- $f [n] \notin \Delta$ — there is no entry $f [k] \triangleright x : T_1 . M : T_2$, where T_1 and T_2 match *arbitrary* types, M matches *any* term, and k matches the specific number n , in the context Δ .
- $f [n] \triangleright x : T_1 . M : T_2 \notin \Delta$ — there is no entry exactly this entry in the context Δ .

Functional contexts are processed by the new judgment, while the latter itself works under a typing one:

$$\Gamma ::= \mid \Gamma, x : T \mid \Gamma, \langle \Delta_1; t_1 \rangle \rightarrow_p \langle \Delta_2; t_2 \rangle : T$$

To illustrate, the judgment $\Gamma \vdash \langle \Delta_1; t_1 \rangle \rightarrow_p \langle \Delta_2; t_2 \rangle : T$ merely means that the program t_1 , under the functional context Δ , is transformed to the program t_2 , the functional context became Δ' , and the type of both t_1 and t_2 is T .

We also extend structural rules that work on typing context to cover the transformation judgment as follows:

$$\begin{array}{c} \frac{}{\Gamma, \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T, \Gamma' \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T} \text{R-S-Red} \\[10pt] \frac{\Gamma \vdash M : T_M \quad \Gamma \vdash T_L \quad \Gamma \vdash L : T_L \quad \Gamma \vdash L' : T_L \quad (\langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle \notin \Gamma)}{\Gamma, \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L \vdash M : T_M} \text{R-S-Weak-1} \\[10pt] \frac{\begin{array}{c} (\langle \Delta_L; L \rangle \rightarrow_p \langle \Delta'_L; L' \rangle \notin \Gamma) \quad \Gamma \vdash L : T_L \\ \Gamma \vdash \langle \Delta_M; M \rangle \rightarrow_p \langle \Delta'_M; M' \rangle : T_M \quad \Gamma \vdash L' : T_L \quad \Gamma \vdash T_L \end{array}}{\Gamma, \langle \Delta_L; L \rangle \rightarrow_p \langle \Delta'_L; L' \rangle : T_L \vdash \langle \Delta_M; M \rangle \rightarrow_p \langle \Delta'_M; M' \rangle : T_M} \text{R-S-Weak-2} \\[10pt] \frac{\Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L \quad \Gamma \vdash T_x \quad (x \notin \Gamma)}{\Gamma, x : T_x \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L} \text{R-S-Weak-3} \\[10pt] \frac{\Gamma, \Gamma' \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L}{\Gamma', \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L} \text{R-S-Exchange} \\[10pt] \frac{}{\Gamma, \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T, \Gamma' \vdash L' : T} \text{R-S-Var} \\[10pt] \frac{\begin{array}{c} (f \notin \Delta \cup \Delta') \quad \Gamma, x : T_x \vdash M : T_M \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L \quad \Gamma, x : [T_x] \langle \rangle \vdash M : T_M \end{array}}{\Gamma \vdash \langle \Delta, f :: x : T_x . M : T_M; L \rangle \rightarrow_p \langle \Delta', f :: x : T_x . M : T_M; L' \rangle : T_L} \text{R-S-Weak-Delta-1} \\[10pt] \frac{\begin{array}{c} (f [n] \notin \Delta \cup \Delta') \quad \Gamma, x : T_x \vdash M : T_M \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta'; L' \rangle : T_L \quad \Gamma, x : [T_x] \langle \rangle \vdash M : T_M \end{array}}{\Gamma \vdash \langle \Delta, f [n] \triangleright x : T_x . M : T_M; L \rangle \rightarrow_p \langle \Delta', f [n] \triangleright x : T_x . M : T_M; L' \rangle : T_L} \text{R-S-Weak-Delta-2} \end{array}$$

$$\frac{\Gamma \vdash \langle \Delta_1, \Delta_2; L \rangle \rightarrow_p \langle \Delta'_1, \Delta'_2; L' \rangle : T_L}{\Gamma \vdash \langle \Delta_2, \Delta_1; L \rangle \rightarrow_p \langle \Delta'_1, \Delta'_2; L' \rangle : T_L} \text{ R-S-Exchange-Delta}$$

Constants and literals have nothing to do with type properties, so they are transformed into themselves:

$$\frac{}{\vdash \langle ; () \rangle \rightarrow_p \langle ; () \rangle : \text{unit}} \text{ R-V-Unit}$$

$$\frac{}{\vdash \langle ; n \rangle \rightarrow_p \langle ; n \rangle : \text{int}} \text{ R-V-Int}$$

$$\frac{}{\vdash \langle f :: x : T_1 . M : T_2; f \rangle \rightarrow_p \langle f :: x : T_1 . M : T_2; f \rangle : T_1 \rightarrow T_2} \text{ R-V-Func}$$

Now we present the rules that work with type properties directly so that they somehow transform the expressions they operate on. Rules for the expressions that are used to set properties go first.

$$\frac{\Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T \quad \Gamma \vdash \langle \Delta_M; e \rangle \rightarrow_p \langle \Delta'; e' \rangle : P \quad (T \neq [T']\langle \dots \rangle)}{\Gamma \vdash \langle \Delta; \text{set}(M, p, e) \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle p \hookrightarrow e'[P] \rangle} \text{ R-Set-1}$$

$$\frac{\Gamma \vdash \langle \Delta_M; e \rangle \rightarrow_p \langle \Delta'; e' \rangle : P \quad (p_1 \neq p, \dots, p_n \neq p) \quad \Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; \text{propertied}[M'] \rangle : [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle}{\Gamma \vdash \langle \Delta; \text{set}(M, p, e) \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n], p \hookrightarrow e[P] \rangle} \text{ R-Set-2}$$

$$\frac{\Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; \text{propertied}[M'] \rangle : [T]\langle \text{props}_1, p \hookrightarrow e[P], \text{props}_2 \rangle \quad \Gamma \vdash \langle \Delta_M; e \rangle \rightarrow_p \langle \Delta'; e' \rangle : P}{\Gamma \vdash \langle \Delta; \text{set}(M, p, e) \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle \text{props}_1, p \hookrightarrow e[P'], \text{props}_2 \rangle} \text{ R-Set-3}$$

The rules all transform their expressions to `propertied[...]`, which we will use to intermediately (during compile-time program transformation) represent any value of a `propertied` type, with the underlying value x . For instance, if we would set a property `equal_to` to the integer constant 5, then we would get the term `propertied[5] : [int](equal_to \hookrightarrow 5[int])`.

Next go the rules for retrieving and erasing type properties, as well as extracting underlying values:

$$\frac{\Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : [T]\langle \dots, p \hookrightarrow e[P], \dots \rangle \quad \Gamma \vdash \langle \Delta_M; e \rangle \rightarrow_p \langle \Delta_e; e' \rangle : P}{\Gamma \vdash \langle \Delta; \text{get}(M, p) \rangle \rightarrow_p \langle \Delta_e; e' \rangle : P} \text{ R-Get}$$

$$\frac{\Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle \dots \rangle}{\Gamma \vdash \langle \Delta; \text{extract}(M) \rangle \rightarrow_p \langle \Delta'; M' \rangle : T} \text{ R-Ext}$$

$$\frac{\Gamma \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle \text{props}_1, p \hookrightarrow e[P], \text{props}_2 \rangle}{\Gamma \vdash \langle \Delta; \text{erase}(M, p) \rangle \rightarrow_p \langle \Delta'; \text{propertied}[M'] \rangle : [T]\langle \text{props}_1, \text{props}_2 \rangle} \text{ R-Erase}$$

Notice that the expression `get`, in contrast to `if-has` works only on expressions of `propertied` types. This means that we are unable to retrieve a property from a function's argument without checking that it is present, since it is impossible for a function to work only on `propertied` types — they must work on their base types too.

$$\frac{\begin{array}{c} (T_L \neq [T']\langle \dots \rangle) \wedge (E \notin \Gamma) \wedge (\langle \Delta_1; E \rangle \rightarrow_p \langle \Delta_2; E' \rangle : T_E \notin \Gamma) \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta_L; L' \rangle : T_L \end{array}}{\Gamma \vdash \langle \Delta; E \rangle \rightarrow_p \langle \Delta_L; \text{propertied}[L'] \rangle : [T_L]\langle \rangle \vdash \langle \Delta_L; N[L/E] \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T_N} \text{ R-If-Has-1}$$

$$\frac{\Gamma \vdash \langle \Delta_L; N \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T_N \quad (p_1 \neq p, \dots, p_n \neq p) \quad \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta_L; L' \rangle : [T]\langle p_1 \hookrightarrow e_1[P_1], \dots, p_n \hookrightarrow e_n[P_n] \rangle}{\Gamma \vdash \langle \Delta; \text{if-has } L \text{ } p : T_x \text{ bind-as } x \text{ in } M \text{ else } N \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T_N} \text{ R-If-Has-2}$$

$$\frac{\begin{array}{c} \Gamma \vdash \langle \Delta_L; N \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T_N \quad (P \neq T_x) \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta_L; L' \rangle : [T] \langle \dots, p \hookrightarrow e[P], \dots \rangle \end{array}}{\Gamma \vdash \langle \Delta; \text{if-has } L \text{ } p : T_x \text{ bind-as } x \text{ in } M \text{ else } N \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T_N} \text{R-If-Has-3}$$

$$\frac{\begin{array}{c} \Gamma \vdash \langle \Delta_L; e \rangle \rightarrow_p \langle \Delta_e; e' \rangle : P \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta_L; L' \rangle : [T] \langle \dots, p \hookrightarrow e[P], \dots \rangle \\ \Gamma \uplus \{ \langle \Delta_L; x \rangle \rightarrow_p \langle \Delta_e; x \rangle : P \} \vdash \langle \Delta_e; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\ (P \neq T_1 \rightarrow T_2) \wedge (T_M \neq T_1 \rightarrow T_2) \wedge (T_M \neq [T_P] \langle \dots \rangle) \end{array}}{\Gamma \vdash \langle \Delta; \text{if-has } L \text{ } p : P \text{ bind-as } x \text{ in } M \text{ else } N \rangle \rightarrow_p \langle \Delta_M; \text{let } x = e' \text{ in } M' \rangle : T_M} \text{R-If-Has-4}$$

$$\frac{\begin{array}{c} \Gamma \vdash \langle \Delta_L; e \rangle \rightarrow_p \langle \Delta_e; e' \rangle : P \\ \Gamma \vdash \langle \Delta; L \rangle \rightarrow_p \langle \Delta_L; L' \rangle : [T] \langle \dots, p \hookrightarrow e[P], \dots \rangle \\ \Gamma \uplus \{ \langle \Delta_L; x \rangle \rightarrow_p \langle \Delta_e; e' \rangle : P \} \vdash \langle \Delta_e; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\ (P = T_1 \rightarrow T_2) \vee (T_M = T_1 \rightarrow T_2) \vee (T_M = [T_P] \langle \dots \rangle) \end{array}}{\Gamma \vdash \langle \Delta; \text{if-has } L \text{ } p : P \text{ bind-as } x \text{ in } M \text{ else } N \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M} \text{R-If-Has-5}$$

The rules above define the transformation of the expression *if-has*. To work as expected, the value of L , whether it is of a propertied type or not, must enter the branch *else* with the same type. Because of that, in the rule *R-If-Has-1*, we made L be transformed to the value of a propertied type with the base type of T_L and without any properties. Then, L , whether from the rule *R-If-Has-1*, *R-If-Has-2* or *R-If-Has-3*, always enters the branch *else* being of a propertied type.

The transformation rule for function definition expression is as follows:

$$\frac{\Gamma \uplus \{x : T_1\} \vdash M : T_2 \quad \Gamma \uplus \{f : T_1 \rightarrow T_2\} \vdash \langle \Delta, f :: x : T_1 . M : T_2; e \rangle \rightarrow_p \langle \Delta'; e' \rangle : T_e}{\Gamma \vdash \langle \Delta; \text{func } f \text{ } x : T_1 \text{ with } M \text{ in } e \rangle \rightarrow_p \langle \Delta'; e' \rangle : T_e} \text{R-Func}$$

The requirement on the typing judgment $\Gamma \uplus \{x : T_1\} \vdash M : T_2$ is only needed to infer the type T_2 , not to ensure that the body is well-typed. This is due to the fact that before transformation, we expect the program to pass the type-checker. The rules below are the main rules that allow functions to be polymorphic with respect to type properties.

$$\frac{\begin{array}{c} (f[k] \notin \Delta \cup \Delta_x) \\ (\Delta_f \equiv f :: x : T_1 . M : T_2) \\ (\Delta_{f[k]} \equiv f[k] \triangleright x : T_1 . M' : T_2) \\ \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : T_1 \rightarrow T_2 \\ \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_x, \Delta_f; \text{propertied}[y] \rangle : [T_1] \langle \text{props} \rangle \\ \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_x; \text{propertied}[x] \rangle : [T_1] \langle \text{props} \rangle \} \vdash \langle \Delta_x; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_2 \end{array}}{\Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] y \rangle : T_2} \text{R-App-Compile-Prop-1}$$

$$\frac{\begin{array}{c} (\Delta_f \equiv f :: x : T_1 . M : T_2) \\ (\Delta_{f[k]} \equiv f[k] \triangleright x : T_1 . M' : T_2) \\ \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : T_1 \rightarrow T_2 \\ \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_x, \Delta_f, \Delta_{f[k]}; \text{propertied}[y] \rangle : [T_1] \langle \text{props} \rangle \\ \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_x; \text{propertied}[x] \rangle : [T_1] \langle \text{props} \rangle \} \vdash \langle \Delta_x; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_2 \end{array}}{\Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] y \rangle : T_2} \text{R-App-Ready-Prop-1}$$

$$\frac{\begin{array}{c} (f[k] \notin \Delta \cup \Delta_{f'}) \\ (\Delta_f \equiv f :: x : P_1 \rightarrow P_2 . M : T_M) \\ (\Delta_{f[k]} \equiv f[k] \triangleright x : P_1 \rightarrow P_2 . M' : T_M) \\ \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : (P_1 \rightarrow P_2) \rightarrow T_M \\ \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_{f'}, \Delta_f; \text{propertied}[f'] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \\ \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_{f'}; \text{propertied}[f'] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \} \vdash \langle \Delta_{f'}; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \end{array}}{\Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] f' \rangle : T_M} \text{R-App-Compile-Prop-2}$$

$$\begin{array}{c}
 (\Delta_f \equiv f :: x : P_1 \rightarrow P_2 . M : T_M) \\
 (\Delta_{f[k]} \equiv f[k] \triangleright x : P_1 \rightarrow P_2 . M' : T_M) \\
 \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : (P_1 \rightarrow P_2) \rightarrow T_M \\
 \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_{f'}, \Delta_f, \Delta_{f[k]}; \text{propertied}[f'] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \\
 \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_{f'}; \text{propertied}[f'] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \} \vdash \langle \Delta_{f'}; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\
 \hline
 \Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] f' \rangle : T_M \quad \text{R-App-Ready-Prop-2}
 \end{array}$$

$$\begin{array}{c}
 (f[k] \notin \Delta \cup \Delta_{f'}) \\
 (\Delta_f \equiv f :: x : P_1 \rightarrow P_2 . M : T_M) \\
 (\Delta_{f[k]} \equiv f[k] \triangleright x : P_1 \rightarrow P_2 . M' : T_M) \\
 \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_{f'}, \Delta_f; f' \rangle : P_1 \rightarrow P_2 \\
 \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : (P_1 \rightarrow P_2) \rightarrow T_M \\
 \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_{f'}; f' \rangle : P_1 \rightarrow P_2 \} \vdash \langle \Delta_{f'}; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\
 \hline
 \Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] f' \rangle : T_M \quad \text{R-App-Compile-Func}
 \end{array}$$

$$\begin{array}{c}
 (\Delta_f \equiv f :: x : P_1 \rightarrow P_2 . M : T_M) \\
 (\Delta_{f[k]} \equiv f[k] \triangleright x : P_1 \rightarrow P_2 . M' : T_M) \\
 \Gamma \vdash \langle \Delta, \Delta_f; N \rangle \rightarrow_p \langle \Delta_{f'}, \Delta_f, \Delta_{f[k]}; f' \rangle : P_1 \rightarrow P_2 \\
 \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : (P_1 \rightarrow P_2) \rightarrow T_M \\
 \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_{f'}; f' \rangle : P_1 \rightarrow P_2 \} \vdash \langle \Delta_{f'}; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\
 \hline
 \Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta_M, \Delta_f, \Delta_{f[k]}; f[k] f' \rangle : T_M \quad \text{R-App-Ready-Func}
 \end{array}$$

$$\begin{array}{c}
 (\Delta_{f[k]} \equiv f[k] \triangleright x : T_1 . M : T_2) \quad \Gamma \vdash \langle \Delta, \Delta_{f[k]}; N \rangle \rightarrow_p \langle \Delta, \Delta_{f[k]}; N' \rangle : T_1 \\
 \hline
 \Gamma \vdash \langle \Delta, \Delta_{f[k]}; f[k] N \rangle \rightarrow_p \langle \Delta, \Delta_{f[k]}; f[k] N' \rangle : T_2 \quad \text{R-App-Compiled}
 \end{array}$$

The rules *R-App-Compile-** compile raw functions, i.e monomorphize them according to the passed argument. The rules *R-App-Ready-** are applied when an appropriate monomorphization is already present in the context. When one is present, there is no need to create an extra one so that the resulting call references the found monomorphization.

The rules above cover four different types of applications. The first is when a function is applied with a value of a propertied type that is not a function. It propagates the propertied value to the raw body of the function and replaces its underlying value by the name of the argument since the underlying value is received at run-time. In this case, the function application is transformed into the application of the monomorphized function and the value of a propertied type is replaced with its underlying value. The second is when a function is applied with a value of a propertied type that is a function. In our system, functions are just names that refer to entries in a functional context, so because it is required to know the name of the function at compile-time to transform the function application, the underlying value cannot be received at run-time. The third one is when a function is applied to a function. For the same reason as in the previous rule, the name of the function is the argument's position is propagated to the compiling function. The last one is when the function application was already transformed to a monomorphized version so that it is just transformed to itself.

As the argument of a propertied type in function application is transformed into its underlying value, the expression *let*, for type properties to be fully erased at run-time, must do the same if it gets an expression of a propertied type.

$$\begin{array}{c}
 (T \neq P_1 \rightarrow P_2) \\
 \Gamma \vdash \langle \Delta; N \rangle \rightarrow_p \langle \Delta_N; \text{propertied}[y] \rangle : [T] \langle \text{props} \rangle \\
 \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_N; \text{propertied}[x] \rangle : [T] \langle \text{props} \rangle \} \vdash \langle \Delta_N; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\
 \hline
 \Gamma \vdash \langle \Delta; \text{let } x = N \text{ in } M \rangle \rightarrow_p \langle \Delta_M; \text{let } x = y \text{ in } M' \rangle : T_M \quad \text{R-Let-Prop-1}
 \end{array}$$

$$\begin{array}{c}
 \Gamma \vdash \langle \Delta; N \rangle \rightarrow_p \langle \Delta_N; \text{propertied}[f] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \\
 \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_N; \text{propertied}[f] \rangle : [P_1 \rightarrow P_2] \langle \text{props} \rangle \} \vdash \langle \Delta_N; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \\
 \hline
 \Gamma \vdash \langle \Delta; \text{let } x = N \text{ in } M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \quad \text{R-Let-Prop-2}
 \end{array}$$

$$\frac{\Gamma \vdash \langle \Delta; F \rangle \rightarrow_p \langle \Delta_F; f \rangle : T_1 \rightarrow T_2 \quad \Gamma \uplus \{ \langle \Delta; x \rangle \rightarrow_p \langle \Delta_F; f \rangle : T_1 \rightarrow T_2 \} \vdash \langle \Delta_F; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M}{\Gamma \vdash \langle \Delta; \text{let } x = F \text{ in } M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M} \text{ R-Let-Func}$$

The rest of the rules are those which don't transform/evaluate their expressions but rather propagate the transformation of their subexpressions:

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; e'_1 \rangle : \text{int} \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_2 \rangle : \text{int}}{\Gamma \vdash \langle \Delta; e_1 + e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_1 + e'_2 \rangle : \text{int}} \text{ R-P-Plus}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; e'_1 \rangle : \text{int} \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_2 \rangle : \text{int}}{\Gamma \vdash \langle \Delta; e_1 - e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_1 - e'_2 \rangle : \text{int}} \text{ R-P-Minus}$$

$$\frac{\begin{array}{c} (T \neq [T'] \langle \dots \rangle) \wedge (T \neq P_1 \rightarrow P_2) \\ \Gamma \vdash \langle \Delta; N \rangle \rightarrow_p \langle \Delta_N; N' \rangle : T \\ \Gamma \uplus \{ \langle ; x \rangle \rightarrow_p \langle ; x \rangle : T \} \vdash \langle \Delta_N; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_M \end{array}}{\Gamma \vdash \langle \Delta; \text{let } x = N \text{ in } M \rangle \rightarrow_p \langle \Delta_M; \text{let } x = N' \text{ in } M' \rangle : T_M} \text{ R-P-Let}$$

$$\frac{\begin{array}{c} (f[k] \notin \Delta) \\ (T_1 \neq [T] \langle \dots \rangle) \wedge (T_1 \neq P_1 \rightarrow P_2) \\ (\Delta_{f[k]} \equiv f[k] \triangleright x : T_1 . M' : T_2) \\ (\Delta_f \equiv f :: x : T_1 . M : T_2) \end{array} \quad \begin{array}{c} \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f; f \rangle : T_1 \rightarrow T_2 \\ \Gamma \vdash \langle \Delta_M, \Delta_f, \Delta_{f[k]}; N \rangle \rightarrow_p \langle \Delta'; N' \rangle : T_1 \\ \Gamma \uplus \{ \langle ; x \rangle \rightarrow_p \langle ; x \rangle : T_1 \} \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_2 \end{array}}{\Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta'; f[k] N' \rangle : T_2} \text{ R-App-Compile}$$

$$\frac{\begin{array}{c} (T_1 \neq [T] \langle \dots \rangle) \wedge (T_1 \neq P_1 \rightarrow P_2) \\ (\Delta_{f[k]} \equiv f[k] \triangleright x : T_1 . M' : T_2) \\ (\Delta_f \equiv f :: x : T_1 . M : T_2) \\ \Gamma \vdash \langle \Delta_M, \Delta_f, \Delta_{f[k]}; N \rangle \rightarrow_p \langle \Delta'; N' \rangle : T_1 \\ \Gamma \vdash \langle \Delta_i; F \rangle \rightarrow_p \langle \Delta, \Delta_f, \Delta_{f[k]}; f \rangle : T_1 \rightarrow T_2 \\ \Gamma \uplus \{ \langle ; x \rangle \rightarrow_p \langle ; x \rangle : T_1 \} \vdash \langle \Delta; M \rangle \rightarrow_p \langle \Delta_M; M' \rangle : T_2 \end{array}}{\Gamma \vdash \langle \Delta_i; FN \rangle \rightarrow_p \langle \Delta'; f[k] N' \rangle : T_2} \text{ R-App-Ready}$$

And, finally, the rules that make ordinary expressions that work on base data types work on propertied ones:

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; \text{propertied}[L_1] \rangle : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; \text{propertied}[L_2] \rangle : [\text{int}] \langle \dots \rangle}{\Gamma \vdash \langle \Delta; e_1 + e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; L_1 + L_2 \rangle : \text{int}} \text{ R-P-Plus-1}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; \text{propertied}[L_1] \rangle : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_2 \rangle : \text{int}}{\Gamma \vdash \langle \Delta; e_1 + e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; L_1 + e'_2 \rangle : \text{int}} \text{ R-P-Plus-2}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; e'_1 \rangle : \text{int} \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; \text{propertied}[L_2] \rangle : [\text{int}] \langle \dots \rangle}{\Gamma \vdash \langle \Delta; e_1 + e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_1 + L_2 \rangle : \text{int}} \text{ R-P-Plus-3}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; \text{propertied}[L_1] \rangle : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; \text{propertied}[L_2] \rangle : [\text{int}] \langle \dots \rangle}{\Gamma \vdash \langle \Delta; e_1 - e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; L_1 - L_2 \rangle : \text{int}} \text{ R-P-Minus-1}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; \text{propertied}[L_1] \rangle : [\text{int}] \langle \dots \rangle \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_2 \rangle : \text{int}}{\Gamma \vdash \langle \Delta; e_1 - e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; L_1 - e'_2 \rangle : \text{int}} \text{ R-P-Minus-2}$$

$$\frac{\Gamma \vdash \langle \Delta; e_1 \rangle \rightarrow_p \langle \Delta_{e_1}; e'_1 \rangle : \text{int} \quad \Gamma \vdash \langle \Delta_{e_1}; e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; \text{propertied}[L_2] \rangle : [\text{int}] \langle \dots \rangle}{\Gamma \vdash \langle \Delta; e_1 - e_2 \rangle \rightarrow_p \langle \Delta_{e_2}; e'_1 - L_2 \rangle : \text{int}} \text{R-P-Minus-3}$$

3.4 Operational Semantics

Now it's time to use the judgment \rightarrow_p and give a semantics for expressions that are intended to be evaluated at run-time. Just as in the previous section, we need to save bodies of functions somewhere. For this purpose, we introduce a new context, the context Φ :

$$\Phi ::= \mid \Phi, f[n] :: x \otimes M$$

Since everything is type-checked at compile-time, there is no need to track type information about bodies and arguments.

In order to ensure that the real program evaluation can be started *only* after stuff with type properties has been carried out at compile-time, we give this Φ context to programs only after a successful transformation and type-check:

$$\frac{\vdash t_1 : T \quad \vdash \langle ; t_1 \rangle \rightarrow_p \langle \Delta; t_2 \rangle : T \quad (T \neq [T'] \langle \dots \rangle) \quad \Phi \equiv \{(f[n] \triangleright x : T_1 . M : T_2) \in \Delta \mid f[n] :: x \otimes M\}}{\Phi \triangleright \langle ; t_2 \rangle} \text{Ready}$$

The rule above states that if, under empty typing context, the program t_1 is well-typed, transformed to t_2 and t_2 is not a value of a propertied type, then the program t_2 is ready to be executed and is given a Φ -context. We call the program t_1 *well-transformed* if it satisfies the conditions above. The restriction with t_2 not being a value of a propertied type is required because we prohibit all that stuff with type properties to occur in run-time. In the next section, we will prove that this is the only source of them.

A context that will keep track of variables and their corresponding values is defined as follows:

$$\sigma ::= \mid \sigma, x \hookrightarrow v$$

The structural rules for the Φ context are:

$$\frac{\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle \quad (f[n] \notin \Phi)}{\Phi, f[n] :: x \otimes M \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle} \text{Phi-Weak-1}$$

$$\frac{\Phi \triangleright e \text{ val} \quad (f[n] \notin \Phi)}{\Phi, f[n] :: x \otimes M \triangleright e \text{ val}} \text{Phi-Weak-2}$$

$$\frac{\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle \quad \Phi \triangleright v \text{ val} \quad (x \hookrightarrow v \notin \sigma \cup \sigma')}{\Phi \triangleright \langle \sigma, x \hookrightarrow v; e \rangle \mapsto \langle \sigma', x \hookrightarrow v; e' \rangle} \text{Sigma-Weak}$$

$$\frac{\Phi, \Phi' \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle}{\Phi', \Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle} \text{Phi-Exchange-1}$$

$$\frac{\Phi, \Phi' \triangleright e \text{ val}}{\Phi', \Phi \triangleright e \text{ val}} \text{Phi-Exchange-2}$$

$$\frac{\Phi \triangleright \langle \sigma_1, \sigma_2; e \rangle \mapsto \langle \sigma'_1, \sigma'_2; e' \rangle}{\Phi \triangleright \langle \sigma_2, \sigma_1; e \rangle \mapsto \langle \sigma'_1, \sigma'_2; e' \rangle} \text{Sigma-Exchange}$$

Obtaining a Φ context for an expression ensures that the program is ready to process its computation, so every transition rule implicitly assumes that its source has one. Since the resulting expression, in order to proceed with the computation, must have the one too, we added a rule that does just that:

$$\frac{\Phi \triangleright \langle \sigma; e \rangle \quad \Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle}{\Phi \triangleright \langle \sigma'; e' \rangle} \text{Phi-Preserve}$$

We also add two more expressions to the language, which are not present in the language itself but are responsible for dropping or retrieving previous values of variables:

$$e ::= \dots \mid \text{drop } x \text{ after } e \mid \text{retrieve } x = v \text{ after } e$$

Closed values are evaluated by the following rules:

$$\frac{}{\triangleright () \text{ val}} \text{V-Unit}$$

$$\frac{}{\triangleright n \text{ val}} \text{V-Int}$$

$$\frac{}{f[n] :: x \otimes M \triangleright f[n] \text{ val}} \text{V-Func}$$

And, finally, the transition rules are:

$$\frac{}{\Phi \triangleright \langle x \hookrightarrow v; x \rangle \mapsto \langle x \hookrightarrow v; v \rangle} \text{Var}$$

$$\frac{\Phi \triangleright \langle \sigma; e_1 \rangle \mapsto \langle \sigma'; e'_1 \rangle}{\Phi \triangleright \langle \sigma; e_1 e_2 \rangle \mapsto \langle \sigma'; e'_1 e_2 \rangle} \text{App-P-1}$$

$$\frac{\Phi \triangleright e_1 \text{ val} \quad \Phi \triangleright \langle \sigma; e_2 \rangle \mapsto \langle \sigma'; e'_2 \rangle}{\Phi \triangleright \langle \sigma; e_1 e_2 \rangle \mapsto \langle \sigma'; e_1 e'_2 \rangle} \text{App-P-2}$$

$$\frac{\Phi, f[n] :: x \otimes M \triangleright v \text{ val} \quad (x \notin \sigma)}{\Phi, f[n] :: x \otimes M \triangleright \langle \sigma; f[n] v \rangle \mapsto \langle \sigma, x \hookrightarrow v; \text{drop } x \text{ after } M \rangle} \text{App-1}$$

$$\frac{\Phi, f[n] :: x \otimes M \triangleright v \text{ val}}{\Phi, f[n] :: x \otimes M \triangleright \langle \sigma, x \hookrightarrow v_{\text{prev}}; f[n] v \rangle \mapsto \langle \sigma, x \hookrightarrow v; \text{retrieve } x = v_{\text{prev}} \text{ after } M \rangle} \text{App-2}$$

$$\frac{}{\Phi, g[k] :: y \otimes M_g, f[n] :: x \otimes M_f \triangleright \langle \sigma; f[n] g \rangle \mapsto \langle \sigma; M_f \rangle} \text{App-With-Func}$$

$$\frac{\Phi \triangleright \langle \sigma; n_1 \rangle \mapsto \langle \sigma'; n'_1 \rangle}{\Phi \triangleright \langle \sigma; n_1 + n_2 \rangle \mapsto \langle \sigma'; n'_1 + n_2 \rangle} \text{Plus-P-1}$$

$$\frac{\Phi \triangleright n_1 \text{ val} \quad \Phi \triangleright \langle \sigma; n_2 \rangle \mapsto \langle \sigma'; n'_2 \rangle}{\Phi \triangleright \langle \sigma; n_1 + n_2 \rangle \mapsto \langle \sigma'; n_1 + n'_2 \rangle} \text{Plus-P-2}$$

$$\frac{\Phi \triangleright n_1 \text{ val} \quad \Phi \triangleright n_2 \text{ val} \quad (n_1 + n_2 = n)}{\Phi \triangleright \langle ; n_1 + n_2 \rangle \mapsto \langle ; n \rangle} \text{Plus}$$

$$\frac{\Phi \triangleright \langle \sigma; n_1 \rangle \mapsto \langle \sigma'; n'_1 \rangle}{\Phi \triangleright \langle \sigma; n_1 - n_2 \rangle \mapsto \langle \sigma'; n'_1 - n_2 \rangle} \text{Minus-P-1}$$

$$\frac{\Phi \triangleright n_1 \text{ val} \quad \Phi \triangleright \langle \sigma; n_2 \rangle \mapsto \langle \sigma'; n'_2 \rangle}{\Phi \triangleright \langle \sigma; n_1 - n_2 \rangle \mapsto \langle \sigma'; n_1 - n'_2 \rangle} \text{Minus-P-2}$$

$$\begin{array}{c}
 \frac{\Phi \triangleright n_1 \text{ val} \quad \Phi \triangleright n_2 \text{ val} \quad (n_1 - n_2 = n)}{\Phi \triangleright \langle ; n_1 - n_2 \rangle \mapsto \langle ; n \rangle} \text{Minus} \\
 \\
 \frac{\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle}{\Phi \triangleright \langle \sigma; \text{let } x = e \text{ in } M \rangle \mapsto \langle \sigma'; \text{let } x = e' \text{ in } M \rangle} \text{Let-P} \\
 \\
 \frac{\Phi \triangleright v \text{ val} \quad (x \notin \sigma)}{\Phi \triangleright \langle \sigma; \text{let } x = v \text{ in } M \rangle \mapsto \langle \sigma, x \hookrightarrow v; \text{drop } x \text{ after } M \rangle} \text{Let-1} \\
 \\
 \frac{\Phi \triangleright v \text{ val}}{\Phi \triangleright \langle \sigma, x \hookrightarrow v_{\text{prev}}; \text{let } x = v \text{ in } M \rangle \mapsto \langle \sigma, x \hookrightarrow v; \text{retrieve } x = v_{\text{prev}} \text{ after } M \rangle} \text{Let-2} \\
 \\
 \frac{\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle}{\Phi \triangleright \langle \sigma; \text{drop } x \text{ after } e \rangle \mapsto \langle \sigma'; \text{drop } x \text{ after } e' \rangle} \text{Drop-After-1} \\
 \\
 \frac{\Phi \triangleright v \text{ val}}{\Phi \triangleright \langle \sigma, x \hookrightarrow v_x; \text{drop } x \text{ after } v \rangle \mapsto \langle \sigma; v \rangle} \text{Drop-After-2} \\
 \\
 \frac{\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle}{\Phi \triangleright \langle \sigma; \text{retrieve } x = v \text{ after } e \rangle \mapsto \langle \sigma'; \text{retrieve } x = v \text{ after } e' \rangle} \text{Retrieve-After-1} \\
 \\
 \frac{\Phi \triangleright v \text{ val}}{\Phi \triangleright \langle \sigma, x \hookrightarrow v_x; \text{retrieve } x = v_{\text{prev}} \text{ after } v \rangle \mapsto \langle \sigma, x \hookrightarrow v_{\text{prev}}; v \rangle} \text{Retrieve-After-2}
 \end{array}$$

4 Properties of λ_{\rightarrow_p}

In this section, we are going to explore some important properties of λ_{\rightarrow_p} . We start with the properties of compile-time program transformation.

4.1 Program transformation properties

One of the important claims that we made in previous sections was that no values of propertied types and propertied types themselves are present at run-time. That is, everything related to them must be carried out at compile-time. We start with the lemma that states just that.

Lemma 4.1 *If $\Gamma \vdash t_1 : T$ and $\Gamma \vdash \langle \Delta'; t_2 \rangle \rightarrow_p \langle \Delta'; t_2 \rangle : T$, then either T is of the form or no subexpression in t_2 is of a type $[T']\langle \dots \rangle$. What's more, for every function $f[n] \triangleright x : T_1 . M : T_2$ in Δ' , neither T_1, T_2 , nor any subexpression of M is of the form $[T']\langle \dots \rangle$.*

The allowance for t_2 be a value of a propertied type is justified by the rule *Ready* from the previous section, since no Φ context, which is required for an expression to be passed to run-time, is given for one.

Proof 4.1 *By induction on the derivation rules of the judgment \rightarrow_p and the typing rules from Section 3.2.*

The proof of the fact that neither T_1 nor T_2 of $f[n] \triangleright x : T_1 . M : T_2$ may be of the form $[T']\langle \dots \rangle$ is immediate by the typing rule I-Func, which states that in order to form a function, the resulting type must not be a propertied one. T_1 a priori cannot be a propertied type since there is no conventional syntax for them in the language.

For the rules that act on values — *R-V-Unit* and *R-V-Int* — the proof is immediate since they are transformed into themselves. The rules that act on the expression *set* make it be of type $[T']\langle \dots \rangle$, so the proof is immediate too. Next, the rules *R-Get* and *R-Ext* transform their expressions into their subexpressions, which are, by induction, assumed to have the desired property.

The proof that the same holds for every function in the context Δ' is obtained by the induction on the rules that perform monomorphization and add them to functional contexts.

What's interesting are the rules *R-App-Prop-1* — when the argument of the function application is of a propertied type, the expression is transformed into a run-time application with the argument being the underlying value. Since

that, we got rid of the propertied type in the argument. The same situation is found with the rules that act on the expression *if-has* — there are special rules that cover cases when the property being extracted is of a propertied type — they just transform them to their underlying values.

Proofs for the rest of the rules follow the same structure and are obtained by using the same techniques. So, in order not to litter this paragraph, we omitted them here.

The next important property of the \rightarrow_p -transformation is that it must be deterministic, since none of our compile-time constructions is expected to do something that causes non-deterministic behavior.

Lemma 4.2 *If $\Gamma \vdash \langle \Delta; t_1 \rangle \rightarrow_p \langle \Delta_1; t_2 \rangle : T$ and $\Gamma \vdash \langle \Delta; t_1 \rangle \rightarrow_p \langle \Delta_2; t'_2 \rangle : T'$, then $\Delta_1 = \Delta_2$, $t_2 = t'_2$ and $T = T'$*

We didn't define equality judgment for types, terms, and contexts, so what we meant is the ordinary syntactic one.

Proof 4.2 *By induction on the derivation rules of the judgment \rightarrow_p .*

The proof has a similar structure to the one of the *Lemma 4.1* — for some expressions, there is only one rule defining their transformations, so assuming that all subexpressions are deterministic makes the proof for them.

Other rules explore the structure of their subexpressions so that no expression can be transformed by two rules simultaneously. For instance, let's take a look at the rules *R-Let-Prop-1*, *R-Let-Prop-2*, *R-Let-Func*, and *R-P-Let*. They all operate on an expression *let x = N in M*, but:

- *R-Let-Prop-2* works only when *N* is of a propertied type, and the underlying value is of a function one.
- *R-Let-Prop-1* works only when *N* is of a propertied type too, but the underlying value is *not* of a function type, thus covering all cases that *R-Let-Prop-2* excludes.
- *R-Let-Func* works only when *N* is transformed to a function.
- *R-P-Let* works only when *N* is neither transformed to a function, nor to a value of a propertied type.

thus mutually excluding each other.

4.2 Type soundness

Now, when it was shown that the compile-time part has the properties we needed, we are able to prove one of the most important properties of a programming language — the property of being *type sound*. The *type soundness* theorem states that if a program passes its programming language's type checker, then it is guaranteed that it has a well-defined behavior when executed. It consists of two theorems — the first, called the *progress* theorem, which states that if an expression *e* is well-typed (and, in our case, well-transformed under \rightarrow_p) then either it is already a value, or we can process its computation. And the second, called the *preservation* theorem, which states that if an expression *e* has type *T* and $\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle$, then *e'* is of type *T* too.

Lemma 4.3 (Progress) *If $\Phi \triangleright \langle \sigma; e \rangle$, then either $\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle$ or $\Phi \triangleright e \text{ val}$*

Proof 4.3 *By induction on the rules given in Section 3.4*

The proof for expressions that represent values is immediate. Next, one must observe that the semantics is defined for all expressions except ones that carry out stuff with type properties, such as *set*, *get*, etc. But since we proved (the lemma 4.1) that all stuff related to them is carried out at compile-time, no expression like *set* and *get* can occur at run-time, so the assumption is justified.

Lemma 4.4 (Preservation) *if $\Gamma \vdash e : T$ and $\Phi \triangleright \langle \sigma; e \rangle \mapsto \langle \sigma'; e' \rangle$, then $\Gamma \vdash e' : T$*

Proof 4.4 *By induction on the typing rules from Section 3.2 and the rules given in Section 3.4*

5 Programming in λ_{\rightarrow_p}

In this section, we are going to write two trivial programs in λ_{\rightarrow_p} and prove that they evaluate to some specific expressions. This section intends to make the processing of type properties more clear for those who didn't catch it in previous sections, by performing a step-by-step type-checking, transformation, and run-time evaluation of the programs. The reader is free to skip this section.

We start with a very simple program to make the reader familiar with the structure of the proofs.

Lemma 5.1 *Let L be the program*

```

1  let y = 5 in
2  func f x : int with
3      x + y in
4  f 1
    
```

L evaluates to 6.

Formally, if a program L evaluates to an expression L' , then it means that L is well-typed, well-transformed, and $\Phi \triangleright \langle ; L \rangle \mapsto^* \langle \sigma; L' \rangle$, where $\Phi \triangleright \langle ; L \rangle \mapsto^* \langle \sigma; L' \rangle$ stands for $\Phi \triangleright \langle ; L \rangle \mapsto \langle \sigma_1; e_1 \rangle$, $\Phi \triangleright \langle \sigma_1; e_1 \rangle \mapsto \langle \sigma_2; e_2 \rangle$, ..., $\Phi \triangleright \langle \sigma_n; e_n \rangle \mapsto \langle \sigma; L' \rangle$ with $n \geq 0$, so we reformulate our lemma as follows:

Given the program L , L is well-typed, well-transformed, and $\Phi \triangleright \langle ; L \rangle \mapsto^ \langle \sigma; 6 \rangle$.*

Proof 5.1 We first start with proof that the program is well-typed. Basically, what we want is to derive the judgment

$$\vdash \text{let } y = 5 \text{ in func } f \ x : \text{int with } x + y \text{ in } f \ 1 : \text{int}$$

According to the rule *E-Let*, this can be derived if we have the following judgments entailed:

$$\begin{aligned} y : \text{int} \vdash \text{func } f \ x : \text{int with } x + y \text{ in } f \ 1 : \text{int} \\ \vdash 5 : \text{int} \end{aligned}$$

The second rule is derived immediately by the rule *I-Int*. The first, according to the rule *I-Func*, is obtained when we have that

$$\begin{aligned} y : \text{int}, x : \text{int} \vdash x + y : \text{int} \\ y : \text{int}, x : [\text{int}] \langle \rangle \vdash x + y : \text{int} \\ y : \text{int}, f : \text{int} \rightarrow \text{int} \vdash f \ 1 : \text{int} \end{aligned}$$

which are all easily obtained by *E-Plus*, *E-App-I*, and some structural rules so that the proof is completed.

What we need to prove next is that this program is well-transformed, which is expressed by obtaining the judgment

$$\vdash \langle ; L \rangle \twoheadrightarrow_p \langle \Delta; t_2 \rangle : \text{int}$$

By the rule *R-P-Let*, if the type of y is not a propertyed or function one (which is exactly the case here, since y is of type int), $\langle ; \text{let } y = 5 \text{ in } M \rangle$ is transformed into $\langle \Delta; \text{let } y = N' \text{ in } M' \rangle$, where N' , M' , and Δ are:

$$\begin{aligned} \vdash \langle ; 5 \rangle \twoheadrightarrow_p \langle \Delta_1; N' \rangle : \text{int} \\ \langle ; y \rangle \twoheadrightarrow_p \langle ; y \rangle : \text{int} \vdash \langle \Delta_1; \text{func } f \ x : \text{int with } x + y \text{ in } f \ 1 \rangle \twoheadrightarrow_p \langle \Delta; M' \rangle : \text{int} \end{aligned}$$

For the first judgment, by the rule *R-P-Int* and the fact that transformations under \twoheadrightarrow_p are deterministic (which was proven in the previous section), it must be the case that N' is 5.

The second is obtained by the rule *R-Func*, which requires us to show that

$$\begin{aligned} \langle ; y \rangle \twoheadrightarrow_p \langle ; y \rangle : \text{int}, x : \text{int} \vdash x + y : \text{int} \\ \langle ; y \rangle \twoheadrightarrow_p \langle ; y \rangle : \text{int}, f : \text{int} \rightarrow \text{int} \vdash \langle f :: x : \text{int} . x + y : \text{int}; f \ 1 \rangle \twoheadrightarrow_p \langle \Delta; M' \rangle : \text{int} \end{aligned}$$

The first is obtained easily obtained by the rules *R-S-Var* and *E-Plus*. Let:

$$\begin{aligned} \Gamma &\equiv \langle ; y \rangle \twoheadrightarrow_p \langle ; y \rangle : \text{int}, f : \text{int} \rightarrow \text{int}, \\ \Delta_f &\equiv f :: x : \text{int} . x + y : \text{int}, \\ \Delta_{f[1]} &\equiv f [1] \triangleright x : \text{int} . x + y : \text{int} \end{aligned}$$

Then, the required premiss is itself easily obtained by the rule *R-App-Compile*:

$$\begin{array}{c}
 \Gamma \vdash \langle \Delta_f; f \rangle \twoheadrightarrow_p \langle \Delta_f; f \rangle : \text{int} \rightarrow \text{int} \\
 \Gamma \vdash \langle \Delta_f, \Delta_{f[1]}; 1 \rangle \twoheadrightarrow_p \langle \Delta_f, \Delta_{f[1]}; 1 \rangle : \text{int} \\
 \Gamma \uplus \{ \langle ; x \rangle \twoheadrightarrow_p \langle ; x \rangle : \text{int} \} \vdash \langle ; x + y \rangle \twoheadrightarrow_p \langle ; x + y \rangle : \text{int} \\
 \hline
 \Gamma \vdash \langle \Delta_f; f \ 1 \rangle \twoheadrightarrow_p \langle \Delta_f, \Delta_{f[1]}; f \ [1] \ 1 \rangle : \text{int}
 \end{array}$$

As the required premises are obtained easily, the proof is completed. The final transformation judgment is:

$$\vdash \langle ; \text{let } y = 5 \text{ in func } f \ x : \text{int with } x + y \text{ in } f \ 1 \rangle \twoheadrightarrow_p \langle \Delta_f, \Delta_{f[1]}; \text{let } y = 5 \text{ in } f \ [1] \ 1 \rangle : \text{int}$$

Since *int* is not a propertied type, this completes the proof and justifies the assumption that the program is well-transformed.

Now, all is left is to prove that under the operational semantics we gave in section 3.4, this program is evaluated to the term 6. First, we need to obtain a Φ context for our program, which is, by the rule *Ready*, easily obtained under the assumption that our program is well-typed and well-transformed:

$$\frac{\vdash L : \text{int} \quad \vdash \langle ; L \rangle \twoheadrightarrow_p \langle \Delta; t_2 \rangle : \text{int}}{\Phi \triangleright \langle ; t_2 \rangle} \text{ Ready}$$

where Φ , in our case, is just $f \ [1] :: x \otimes x + y$.

When the ready context is obtained, the evaluation of the program proceeds as follows:

$$\begin{array}{c}
 \overline{\Phi \triangleright 5 \text{ val}} \\
 \hline
 \Phi \triangleright \langle ; \text{let } y = 5 \text{ in } f \ [1] \ 1 \rangle \mapsto \langle y \hookrightarrow 5; \text{drop } y \text{ after } f \ [1] \ 1 \rangle \quad \overline{\Phi \triangleright 1 \text{ val}} \\
 \hline
 f \ [1] :: x \otimes x + y \triangleright \langle y \hookrightarrow 5; f \ [1] \ 1 \rangle \mapsto \langle y \hookrightarrow 5, x \hookrightarrow 1; \text{drop } x \text{ after } x + y \rangle \\
 \hline
 \sigma \equiv y \hookrightarrow 5, x \hookrightarrow 1 \\
 \hline
 \Phi \triangleright \langle \sigma; x \rangle \mapsto \langle \sigma; 1 \rangle \\
 \hline
 \Phi \triangleright \langle \sigma; x + y \rangle \mapsto \langle \sigma; 1 + y \rangle \\
 \hline
 \Phi \triangleright \langle \sigma; y \rangle \mapsto \langle \sigma; 5 \rangle \\
 \hline
 \Phi \triangleright \langle \sigma; 1 + y \rangle \mapsto \langle \sigma; 1 + 5 \rangle \\
 \hline
 \Phi \triangleright \langle ; 1 + 5 \rangle \mapsto \langle ; 6 \rangle \\
 \hline
 \Phi \triangleright \langle \sigma; 1 + 5 \rangle \mapsto \langle \sigma; 6 \rangle \\
 \hline
 \overline{\Phi \triangleright 6 \text{ val}} \\
 \hline
 \Phi \triangleright \langle \sigma; \text{drop } x \text{ after } x + y \rangle \mapsto^* \langle \sigma; \text{drop } x \text{ after } 6 \rangle \\
 \hline
 \Phi \triangleright \langle y \hookrightarrow 5, x \hookrightarrow 1; \text{drop } x \text{ after } 6 \rangle \mapsto \langle y \hookrightarrow 5; 6 \rangle \\
 \hline
 \Phi \triangleright \langle y \hookrightarrow 5; \text{drop } y \text{ after } f \ [1] \ 1 \rangle \mapsto^* \langle y \hookrightarrow 5; \text{drop } y \text{ after } 6 \rangle \\
 \hline
 \Phi \triangleright \langle y \hookrightarrow 5; \text{drop } y \text{ after } 6 \rangle \mapsto \langle ; 6 \rangle
 \end{array}$$

This completes the proof of the *lemma 5.1*.

Now we shall explore more complicated programs. Let L be the program:

```

1  func f x : int with
2    if-has x c : int bind-as c in
3      c + 1
4    else extract(x) in
5    let y = set(5, c, 5) in
6    f y
    
```

Lemma 5.2 *L is well-typed, well-transformed, and $\Phi \triangleright \langle ; L \rangle \mapsto^* \langle \sigma; 6 \rangle$.*

Proof 5.2 We left the proof that the program is well-typed to the reader, since it is pretty trivial and follows the same strategy as the one of the *lemma 5.1*.

What we want to focus on now is the property of the program of being well-transformed — since the program utilizes type properties, exploring the property will make it clear how exactly they are carried out at compile-time. In particular, just as with the *lemma 5.1*, all we want is to derive the judgment

$$\vdash \langle ; L \rangle \twoheadrightarrow_p \langle \Delta; L' \rangle : T$$

and ensure that T is not a propertied type.

The program L contains 6 lines of code, so repeatedly writing its parts every time a new assumption arises would be quite unreadable and space-consuming, so it would be reasonable to name distinct parts of the program and refer to them when we do our proof.

$$\begin{aligned} L &\equiv \text{func } f \ x : \text{int with } L_1 \text{ in } L_2 \\ L_1 &= \text{if-has } x \ c : \text{int bind-as } c \text{ in } c + 1 \text{ else extract}(x) \\ L_2 &= \text{let } y = \text{set}(5, c, 5) \text{ in } f \ y \end{aligned}$$

The only rule that can be applied to the program L is the rule *R-Func*, which says that to obtain the judgment

$$\vdash \langle ; \text{func } f \ x : \text{int with } L_1 \text{ in } L_2 \rangle \twoheadrightarrow_p \langle \Delta; L'_2 \rangle : T,$$

it is enough to show that

$$\begin{aligned} x : \text{int} &\vdash L_1 : T_2 \\ x : [\text{int}] \langle \rangle &\vdash L_1 : T_2 \\ f : T_1 \rightarrow T_2 &\vdash \langle f :: x : T_1 . L_1 : T_2; L_2 \rangle \twoheadrightarrow_p \langle \Delta; L'_2 \rangle : T \end{aligned}$$

The first two are easily obtained by the rules *E-If-Has-1* *E-If-Has-2*. Let $\Gamma \equiv f : T_1 \rightarrow T_2$ and $\Delta_1 \equiv f :: x : T_1 . L_1 : T_2$.

To obtain the second, according to the rule *R-Let-Prop-1*, it is enough to show that:

$$\begin{aligned} \Gamma &\vdash \langle \Delta_1; \text{set}(5, c, 5) \rangle \twoheadrightarrow_p \langle \Delta_1; \text{propertied}[5] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle \\ \Gamma \uplus \{ \langle \Delta_1; y \rangle \twoheadrightarrow_p \langle \Delta_1; \text{propertied}[y] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle \} &\vdash \langle \Delta_1; f \ y \rangle \twoheadrightarrow_p \langle \Delta; F' \rangle : T \end{aligned}$$

The first is immediate by the rules *R-Set-1*, *R-V-Int*, and corresponding structural ones. Let

$$\Gamma' \equiv \Gamma, \langle \Delta_1; y \rangle \twoheadrightarrow_p \langle \Delta_1; \text{propertied}[y] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle$$

Then, the second is easily obtained by the rule *R-App-Compile-Prop-1*:

$$\Gamma' \vdash \langle \Delta_1; f \ y \rangle \twoheadrightarrow_p \langle \Delta_1, f \ [1] \triangleright x : \text{int} . L'_1 : T_2; f \ [1] \ y \rangle : T_2$$

which requires us to show that

$$\begin{aligned} \Gamma' &\vdash \langle \Delta_1; f \rangle \twoheadrightarrow_p \langle \Delta_1; f \rangle : \text{int} \rightarrow T_2 \\ \Gamma' &\vdash \langle \Delta_1; y \rangle \twoheadrightarrow_p \langle \Delta_1; \text{propertied}[y] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle \\ \Gamma' \uplus \{ \langle ; x \rangle \twoheadrightarrow_p \langle ; \text{propertied}[x] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle \} &\vdash \langle ; L_1 \rangle \twoheadrightarrow_p \langle ; L'_1 \rangle : T_2 \end{aligned}$$

where T_1 becomes int .

The first two are trivial. Let

$$\Gamma'' \equiv \Gamma', \langle ; x \rangle \twoheadrightarrow_p \langle ; \text{propertied}[x] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle$$

The last one, according to the rule *R-If-Has-4*, can be obtained by obtaining:

$$\begin{aligned}\Gamma'' &\vdash \langle ; x \rangle \rightarrow_p \langle ; \text{propertied}[x] \rangle : [\text{int}] \langle c \hookrightarrow 5[\text{int}] \rangle \\ \Gamma'' &\vdash \langle ; 5 \rangle \rightarrow_p \langle ; 5 \rangle : \text{int} \\ \Gamma'', \langle ; c \rangle &\rightarrow_p \langle ; c \rangle : \text{int} \vdash \langle ; c + 1 \rangle \rightarrow_p \langle ; c + 1 \rangle : \text{int}\end{aligned}$$

which are all obtained pretty easily and where T_2 become int. The final transformation judgment is:

$$\vdash \langle ; L \rangle \rightarrow_p \langle \Delta; \text{let } y = 5 \text{ in } f[1] \ y \rangle : \text{int}$$

with Δ being $f :: x : \text{int} . L_1 : \text{int}, f[1] \triangleright x : \text{int} . \text{let } c = 5 \text{ in } c + 1 : \text{int}$.

Now all is left is to prove that L' evaluates to 6. Since after transformation, the program became no more complicated than the one from the lemma 5.1, we left it to the reader.

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