

Lecture 15: More on SDP and MAXCUT

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Last Time...

MAXCUT: Given $G = (V, E)$ we want to find (S, \bar{S}) so that $|E(S, \bar{S})|$ is maximized. Recall that there is a simple solution that gives a $1/2$ -approximation problem. We found that linear programming didn't beat this approximation guarantees. Spectral methods gave a $9/8$ integrality gap.

Vector Embedding

Relax: $x_i \in \mathbb{R} \rightarrow x_i \in \mathbb{R}^n$ for each vertex v . The SDP:

$$\begin{aligned} \max \quad & \frac{1}{4} \sum_{ij \in E} \|v_i - v_j\|^2 \\ \text{s.t.} \quad & \forall i \|v_i\|^2 = 1 \end{aligned}$$

for any cut S we can consider the solution:

$$v_i^{(S)} = \begin{cases} 1 & \text{if } i \in S \\ -1 & \text{if } i \notin S \end{cases}$$

we then have:

$$\text{value}(v^{(S)}) = |E(S, \bar{S})|.$$

Note that this is kind of similar to a spectral relaxation except here we have n constraints. We have that the spectral case looks like:

$$\begin{aligned} \max \quad & \frac{1}{4} \sum_{ij \in E} \|v_i - v_j\|^2 \\ \text{s.t.} \quad & \sum_i d_i \|v_i\|^2 = 2|E|. \end{aligned}$$

Goemans-Williamson Guarantees

The given spectral relaxation is called the Goemans-Williamson relaxation. Today we will prove that the Goemans-Williamson relaxation can be rounded to a 0.87856 -approximation to MAXCUT.

Rounding

Pick a direction s uniformly at random and look at the inner product of the solution vectors with s . We will assign $i \in S$ iff $\langle v_i, s \rangle \geq 0$.

Proof of the Guarantee Take a pair i, j then:

$$\Pr(ij \text{ is cut by rounding}) = \frac{\theta_{ij}}{\pi}$$

where $\theta_{i,j}$ is the angle between v_i and v_j . Note that one may only consider the projection of s onto the 2-dimensional subspace spanned by v_i and v_j . But recall:

$$\theta_{ij} = \arccos \langle v_i, v_j \rangle$$

but then:

$$\mathbb{E}[|E(S, \bar{S})|] = \sum_{\{i,j\} \in E} \arccos(\langle v_i, v_j \rangle)$$

We will compare the above expectation with the solution to the SDP that is an upperbound to the value of MAXCUT(G).

$$SDP = \frac{1}{4} \sum_{\{i,j\} \in E} \|v_i - v_j\|^2 = \frac{1}{2} \sum_{\{i,j\} \in E} (1 - \langle v_i, v_j \rangle)$$

Consider:

$$\frac{\mathbb{E}[|E(S, \bar{S})|]}{SDP} = \frac{2}{\pi} \cdot \frac{\sum_{\{i,j\} \in E} \arccos \langle v_i, v_j \rangle}{\sum_{\{i,j\} \in E} 1 - \langle v_i, v_j \rangle}$$

We have:

$$\min_{-1 \leq x \leq 1} \frac{2}{\pi} \cdot \frac{\arccos x}{1 - x} \geq 0.878...$$

where the minimum is attained at $x = -0.67$. There are also matching integrality gaps between these.

Partitioning: Minimum Conductance

Recall:

$$\min_{S \subseteq V} \frac{|E(S, \bar{S})|}{Vol(S) \cdot Vol(\bar{S})} \cdot Vol(G)$$

Cheeger:

$$\lambda_2 \leq \bar{\phi}_G \leq 2\sqrt{2\lambda_2}$$

Spectral Relaxation:

$$\begin{aligned} & \min \sum_{\{i,j\}} \|v_i - v_j\|^2 \\ \text{s.t. } & \sum_{i < j} \frac{d_i d_j}{\text{Vol}(G)} \|v_i - v_j\|^2 = 1 \end{aligned}$$

Note that this formulation might partition in the graph in two sets of very different volume.

Balanced Minimum Conductance

Divide-and-conquer: we would to get a partition where a relatively large fraction of the volume lies on each side. We define the b -balanced minimum conductance:

$$\begin{aligned} \bar{\phi}_{G,b} &= \min_{S \subseteq V} \bar{\phi}(S) \\ \text{Vol}(S) &\geq b \cdot \text{Vol}(G) \end{aligned}$$

Side Note: Integral solution to spectral relaxation:

$$(S, \bar{S})$$

we may consider the vector:

$$v_i^{(S)} = \begin{cases} \sqrt{\frac{\text{Vol}(G)}{\text{Vol}(S)\text{Vol}(\bar{S})}} & \text{if } i \in S \\ 0 & \text{if } i \in \bar{S} \end{cases}$$

Suppose now that we want to rule out cuts that are not balanced, i.e. we want to impose the constraint that:

$$\frac{\text{Vol}(S)}{\text{Vol}(G)} > b$$

or equivalently:

$$1 - \frac{\text{Vol}(S)}{\text{Vol}(G)} = \frac{\text{Vol}(\bar{S})}{\text{Vol}(G)} < 1 - b$$

in order to make things balanced we might add a constraint:

$$\|v_i\|^2 \leq \sqrt{\text{Vol}(G)} \cdot \frac{1}{b}$$

Alternatively, we may think of the complete graph K_G as the sum of a bunch of stars:

$$k_G = \frac{1}{2} \sum_{i \in V} d_i \cdot S_i^G$$

where S_i is a star graph centered at i . We may want to change the above balance constraint into a translation-invariant one:

$$d_i \sum_{j \in V} \frac{d_{i,j}}{\text{Vol}(G)} \|v_i - v_j\|^2$$

where the above is the Laplacian quadratic form of $d_i \cdot S_i$.

SDP Relaxation

$$\begin{aligned}
& \min L \cdot X \\
& \text{s.t. } L(K_G) \cdot X = 1 \\
& \quad \forall i : L(S_i) \cdot X \leq \frac{\text{Vol}(G)}{b}
\end{aligned}$$

or, equivalently:

$$\begin{aligned}
& \min L \cdot X \\
& \text{s.t. } L(K_G) \cdot X = \text{Vol}(G) \\
& \quad \forall i : d_i \cdot L(S_i) \cdot X \leq d_i \frac{1}{b}
\end{aligned}$$

and the dual gives:

$$\begin{aligned}
& \max \alpha - \sum \frac{d_i \beta_i}{b} \\
& \text{s.t. } L + \sum d_i \beta_i L(S_i) \succeq \alpha L(K_G)
\end{aligned}$$