

# PROJECT #7

## UAV FOLLOWER

Exploiting localization capabilities provided by UWB radios, the main goal of this project is to develop a smart robot swarm that track and follow a leader.

Starting from a working UWB localization system, you will have to undertake all the necessary step to control the dynamic of the robot, integrating the UWB system into the navigation functionalities of your unmanned vehicle

Contact reference:

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