

```
In [1]: import os
import pandas as pd
import numpy as np
from matplotlib import pyplot as plt
from sklearn.preprocessing import LabelEncoder

import torch
import torch.utils.data as data
import torch.optim as optim
import torch.nn as nn
```

Select run configurations

```
In [2]: # 'MF' - baseline ... just standard Matrix Factorization
# 'NCF' - collaborative ... using NeuMF (GMF==MF + MLP) architecture according to
# 'hybrid' - final model ... duplicated NCF with one branch using pretrained book embeddings
architecture = "hybrid"

# 'colab' vs 'paperspace'
environment = "paperspace"
```

Load data

```
In [3]: if environment == "colab":
    from google.colab import drive
    drive.mount("/content/drive", force_remount=True)
    data_path = "/content/drive/Shared drives/KNN-Recommendors/data/"
else:
    data_path = "/notebooks/data/"

df = pd.read_csv(data_path + "book_interactions_comics_graphic.csv")
df.head()
```

Out[3]:

	user_id	book_id	rating
0	6	16002136	5
1	6	17277800	4
2	6	19358975	5
3	6	17131869	4
4	6	15704307	4

It's necessary to transform ids to labels as they can have higher values than their count (index errors)

```
In [4]: labelEncoder = LabelEncoder()
df["user_label"] = labelEncoder.fit_transform(df["user_id"])
df["book_label"] = labelEncoder.fit_transform(df["book_id"])

df.head()
```

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Out[4]:
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	user_id	book_id	rating	user_label	book_label
0	6	16002136	5	0	33421
1	6	17277800	4	0	35164
2	6	19358975	5	0	39973
3	6	17131869	4	0	34643
4	6	15704307	4	0	32092

Basic statistics

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In [5]: num_users = df["user_id"].unique().shape[0]
num_books = df["book_id"].unique().shape[0]
df_len = df.shape[0]
print("Users: {}".format(num_users))
print("Books: {}".format(num_books))
print("Interactions: {}".format(df_len))
print("Density: {}/{} ... {} %".format(df_len, num_users*num_books, round(100*df_len/(num_users*num_books), 4)))

Users: 100950
Books: 59196
Interactions: 4190598
Density: 4190598/5975836200 ... 0.0701 %
```

In case of final hybrid model, load also the pretrained book embeddings

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In [6]: def csv_embedding_to_dict(filename):
df_embed = pd.read_csv(data_path + filename)
df_embed.set_index("book_id", inplace=True)
return {book_id_to_label[id]:row.values.tolist() for id, row in df_embed.iterrows()}

if architecture == "hybrid":
    book_id_to_label = {row["book_id"]:row["book_label"] for i, row in df.drop_duplicates().iterrows()}
    pretrained_book_embeddings = csv_embedding_to_dict("book_embedding_comics_graph.csv")
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Use GPU if possible

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In [7]: device = "cuda" if torch.cuda.is_available() else "cpu"
device
```

```
Out[7]: 'cuda'
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Prepare torch dataloaders for the training

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In [8]: class DataSet(data.Dataset):
""" Base dataset for data loaders """
def __init__(self, users, books, ratings):
super(DataSet, self).__init__()
self.users = torch.tensor(users, dtype=torch.long, device=device)
self.items = torch.tensor(books, dtype=torch.long, device=device)
self.ratings = torch.tensor(ratings, dtype=torch.float, device=device)

def __len__(self):
return len(self.users)

def __getitem__(self, idx):
return self.users[idx], self.items[idx], self.ratings[idx]
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In [9]: batch_size = 256 # proposed in NCF paper + lower doesn't have better results, just

# split to train, validation, test datasets ... 70-20-10
if not os.path.exists(data_path + "train-df.csv"):
    train_df, valid_df, test_df = np.split(df.sample(frac=1), [int(.7 * df_len), int(.8 * df_len)])
    # session may be terminated, so to remember
    train_df.to_csv(data_path + "train-df.csv", index=False)
    valid_df.to_csv(data_path + "valid-df.csv", index=False)
    test_df.to_csv(data_path + "test-df.csv", index=False)
else:
    train_df = pd.read_csv(data_path + "train-df.csv")
    valid_df = pd.read_csv(data_path + "valid-df.csv")
    test_df = pd.read_csv(data_path + "test-df.csv")

# create datasets
train_dataset = DataSet(train_df["user_label"].values, train_df["book_label"].values)
valid_dataset = DataSet(valid_df["user_label"].values, valid_df["book_label"].values)
test_dataset = DataSet(test_df["user_label"].values, test_df["book_label"].values)

# create dataloaders
train_dataloader = data.DataLoader(train_dataset, batch_size=batch_size, shuffle=True)
valid_dataloader = data.DataLoader(valid_dataset, batch_size=batch_size, shuffle=True)

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Model - definition and training

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In [10]: # model path for saving for given architecture
model_path = "{}-model".format(data_path, architecture)

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In [11]: # inspired by https://github.com/guoyang9/NCF/blob/master/model.py
class Model(nn.Module):
    def __init__(self, user_num, book_num, embedding_dim=32, num_of_layers=3):
        super(Model, self).__init__()

        # baseline MF embeddings
        self.embed_user_GMF = nn.Embedding(user_num, embedding_dim)
        self.embed_book_GMF = nn.Embedding(book_num, embedding_dim)
        if architecture == "MF":
            self.create_predict_layer_and_init_weights(embedding_dim)
            return

        # added MLP branch of NCF architecture
        embed_mul_lambda = lambda x: 2 ** (num_of_layers - x)
        self.embed_user_MLP = nn.Embedding(user_num, embedding_dim * embed_mul_lambda(1))
        self.embed_book_MLP = nn.Embedding(book_num, embedding_dim * embed_mul_lambda(1))

        MLP_layers = []
        dropouts = [0.5] + [0.3] * (num_of_layers - 1)
        for i in range(num_of_layers):
            dim = embedding_dim * embed_mul_lambda(i)
            MLP_layers.append(nn.Dropout(p=dropouts[i]))
            MLP_layers.append(nn.Linear(dim, dim // 2))
            MLP_layers.append(nn.ReLU())

        self.MLP_layers = nn.Sequential(*MLP_layers)
        if architecture == "NCF":
            self.create_predict_layer_and_init_weights(2 * embedding_dim) # GMF + MLP
            return

        # to NeuMF is concatenated pretrained book embedding of the same size
        self.create_predict_layer_and_init_weights(4 * embedding_dim)

    def create_predict_layer_and_init_weights(self, dimension):
        """ Helper method for creating last prediction layer and

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        initializing weights as different architectures are supported.
        """

        self.predict_layer = nn.Linear(dimension, 1)
        self.init_weights()

    def init_weights(self):
        """ Initializes model according to original NCF paper. """

        # Xavier for prediction - in paper they used kaiming but we don't have sign
        nn.init.xavier_uniform_(self.predict_layer.weight)

        # embeddings from normal distribution
        standard_deviation = 0.01
        nn.init.normal_(self.embed_user_GMF.weight, std=standard_deviation)
        nn.init.normal_(self.embed_book_GMF.weight, std=standard_deviation)
        if architecture == "MF":
            return

        nn.init.normal_(self.embed_user_MLP.weight, std=standard_deviation)
        nn.init.normal_(self.embed_book_MLP.weight, std=standard_deviation)

        # use Xavier for the MLP network
        for layer in [x for x in self.MLP_layers if isinstance(x, nn.Linear)]:
            nn.init.xavier_uniform_(layer.weight)

    def forward(self, users, books):
        """ Implementation of pytorch nn.Module forward method == computation. """

        output_GMF = self.embed_user_GMF(users) * self.embed_book_GMF(books)
        if architecture == "MF":
            return self.predict_layer(output_GMF.view(-1))

        output_MLP = self.MLP_layers(torch.cat([self.embed_user_MLP(users), self.embed_book_MLP(books)], 1))
        if architecture == "NCF":
            return self.predict_layer(torch.cat((output_GMF, output_MLP), -1).view(-1))

        pretrained_embeddings = [pretrained_book_embeddings[label] for label in books]
        pretrained_embeddings = torch.tensor(pretrained_embeddings, device=device)
        return self.predict_layer(torch.cat((pretrained_embeddings, output_GMF, output_MLP), -1).view(-1))

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In [12]: class ModelTrainer:
        """ Class responsible for training the model. """

        def __init__(self, model, train_dataloader, valid_dataloader):
            self.model = model
            self.train_data = train_dataloader
            self.valid_data = valid_dataloader
            self.batch_iters = {"Train": len(train_dataloader), "Valid": len(valid_dataloader)}
            self.epochs = 1
            self.loss_values = {"Train": [], "Valid": []}
            self.best_loss = 1e6
            self.criterion = nn.MSELoss()
            self.optimizer = optim.Adam(model.parameters(), lr=1e-3)

        def train(self, epochs=6):
            """ Standard model training. In each batch are updated statistics.
            At the end of each epoch the current model is saved and validation run
            """

            self.epochs = epochs
            for epoch in range(1, epochs + 1):

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        self.model.train()

        # Adam overfits extremely quickly here (almost done after first epoch)
        if epoch == 2:
            self.optimizer = optim.SGD(model.parameters(), lr=5e-4)

        loss_sum = 0
        for users, books, ratings in self.train_data:
            self.optimizer.zero_grad()

            predictions = self.model(users, books)
            loss = self.criterion(predictions, ratings)
            loss_sum += loss.item()

            loss.backward()
            self.optimizer.step()

        self.eval_epoch(loss_sum, "Train", epoch)
        self.validate(epoch)

    def validate(self, epoch):
        """ Validates the model after each epoch on validation dataset. """

        self.model.eval()
        loss_sum = 0
        for users, books, ratings in self.valid_data:
            predictions = self.model(users, books)
            loss = self.criterion(predictions, ratings)
            loss_sum += loss.item()

        self.eval_epoch(loss_sum, "Valid", epoch)

    def eval_epoch(self, loss_sum, phase, epoch):
        """ Helper method for finalizing and printing epoch statistics. """

        data = self.train_data if phase == "Train" else self.valid_data
        count = len(data.dataset.items)
        loss = loss_sum / self.batch_iters[phase]
        self.loss_values[phase].append(loss) # update for plot

        # save the best in case we overtrain - quite fast in collaborative filtering
        if phase == "Valid" and loss < self.best_loss:
            self.best_loss = loss
            self.save_model(model_path)

        print_stats = [phase, epoch, self.epochs, loss]
        print("{}: Epoch: [{} / {}] Loss: {:.6f} ".format(*print_stats))

    def plot_loss(self):
        """ Plots loss during training and validation. """

        plt.plot(self.loss_values["Train"], label = "Train")
        plt.plot(self.loss_values["Valid"], label = "Val")
        plt.legend()
        plt.show()

    def save_model(self, location="model"):
        """ Saves model to specified location. """

        torch.save(self.model.state_dict(), location)

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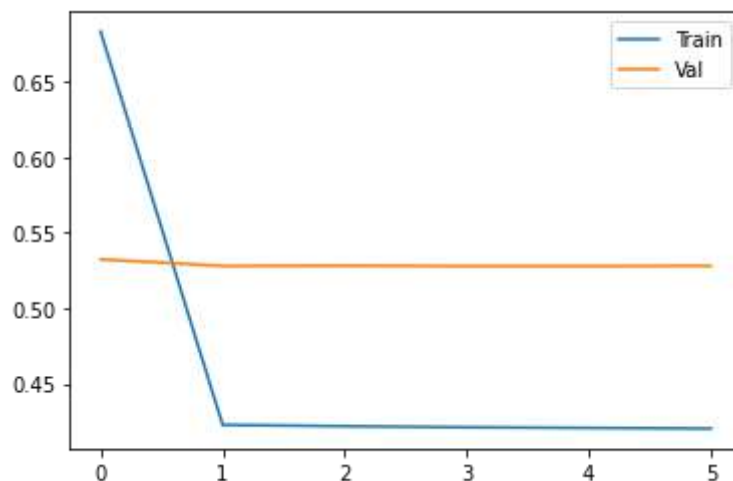
In [13]: model = Model(num_users, num_books).to(device)
         trainer = ModelTrainer(model, train_dataloader, valid_dataloader)

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trainer.train()
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Train: Epoch: [1/6] Loss: 0.683251
Valid: Epoch: [1/6] Loss: 0.532458
Train: Epoch: [2/6] Loss: 0.422792
Valid: Epoch: [2/6] Loss: 0.527994
Train: Epoch: [3/6] Loss: 0.421902
Valid: Epoch: [3/6] Loss: 0.528177
Train: Epoch: [4/6] Loss: 0.421187
Valid: Epoch: [4/6] Loss: 0.527940
Train: Epoch: [5/6] Loss: 0.420771
Valid: Epoch: [5/6] Loss: 0.527935
Train: Epoch: [6/6] Loss: 0.420353
Valid: Epoch: [6/6] Loss: 0.528065
```

```
In [14]: trainer.plot_loss()
```



Evaluate the model on the test dataset

```
In [15]: class ModelTester:
        """ Loads a trained model and runs it against test dataset. """

        def __init__(self, model, location):
            self.model = model.to(device)
            self.model.load_state_dict(torch.load(location))
            self.model.eval()
            self.criterion = nn.MSELoss()
            self.stats = {}
            self.predictions = []

        def test(self, test_dataset, test_df):
            """ Tests the model against given data """

            self.stats = {"loss": 0, "hits": 0}
            self.predictions = []

            for user, book, rating in test_dataset:
                # make prediction
                prediction = self.model(torch.reshape(user, (-1,)), torch.reshape(book, (-1,)))
                self.predictions.append(prediction.item())

                # compute statistics
                self.stats["loss"] += self.criterion(prediction.squeeze(), rating).item()
                if rating == round(prediction.item()):
                    self.stats["hits"] += 1

            # print results
            count = len(test_dataset.items)
```

```
print("Test dataset metrics: ")
print("Loss: {:.6f}".format(self.stats["loss"] / count ))
print("Hit acc: {:.3f} %".format(100 * self.stats["hits"] / count))
```

```
In [16]: tester = ModelTester(Model(num_users, num_books), model_path)
tester.test(test_dataset, test_df)
```

Test dataset metrics:

Loss: 0.525940

Hit acc: 55.853 %