

**Umeå University**  
Department of Computing Science

**Parallel Programming 7.5 p**  
**5DV152**

**Exercises, Chapter/Topic 1**

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## 1 Introduction

This report is part of the mandatory coursework. It describes the solutions for several chosen exercises from the course book [1].

### 2 1.1 - Formulas for block partitioning

The overwhelming idea is to load balance  $p$  number of cores with  $n$  tasks. Here, we use two functions to obtain block partitioning using a `for` loop:

```
for (my_i = my_first_i; my_i < my_last_i; my_i++)
```

The functions `my_first_i` and `my_last_i` are used to set the limits in the loop. Besides  $n$ ,  $i$  and  $p$  we also need an index for the actual core:  $k$ . It is understood that indices  $i$  and  $k$  start at 0. The book text hints to start with the case when  $n$  is evenly divisible by  $p$ :

```
my_first_i = k * n / p
my_last_i = (k + 1) * n / p
```

Testing this expression for  $n = 10$ ,  $p = 5$ ,  $k = \{0, 1, \dots, 4\}$  seems to be correct. Now when  $n$  is not even divisible by  $p$ , one has to distribute the  $n \bmod p$  tasks for example on the first  $n \bmod p$  cores:

```
my_first_i = k * n / p + (k < n mod p ? k : n mod p)
my_last_i = (k + 1) * n / p + (k + 1 < n mod p ? k + 1 : n mod p)
```

Testing this expression for  $n = 9$ ,  $p = 5$ ,  $k = \{0, 1, \dots, 4\}$  gives the correct results.

### 3 1.2 - Modify 1.1 with non-uniform costs

In my opinion, this question can be understood in several different ways:

#### 3.1 First attempt

Let there be 10 tasks ( $n$ ) that take 2, 4, ..., 20 ms to finish, and there are 3 cores ( $p$ ). So one could try to distribute the tasks onto the cores that the standard deviation of total runtimes for all cores is as little as possible. A possible solution for the above described actual setting would be:

$i_9$  to  $k_0$ ,  $i_8$  to  $k_1$ ,  $i_7$  to  $k_2$ . Then,  $i_0$  to  $k_0$ ,  $i_1$  to  $k_1$ ,  $i_2$  to  $k_2$ . And  $i_6$  to  $k_0$ ,  $i_5$  to  $k_1$ ,  $i_4$  to  $k_2$ . Finally,  $i_3$  to  $k_0$ . This somehow works, makes sense and I guess it would be possible to devise a general formula for this.

However, it does not adhere to the actual question: *How would you change your answer to the preceding question if ....* And the preceding question is: *Devise formulas for the functions that calculate 'my\_first\_i' and 'my\_last\_i' in the global sum example.* Hence, to make formulas for first  $i$  and last  $i$  the tasks should be assigned to the cores in a consecutive sequence. Therefore, second attempt:

#### 3.2 Second attempt

If the tasks have to be in a consecutive order, I would calculate the total amount of time all tasks together will take. That should be  $n^2 + n$ . This can be divided by the number of

cores available  $\frac{n^2+n}{p} = r$ . Now I would write an algorithm that iterates through  $n$  and assigns the tasks to the cores until  $r$  is 'reached'. Probably, there would be some edge case handling needed and it could make sense to iterate from high to low  $i$ 's.

To come up with a non-iterative approach for `my_first_i` and `my_last_i` formulas will be more mathematically involved. I could think of an approach where one needs to solve partial integrals of total time elapsed.

However, this way of asking the question somehow does not make much sense: The solution will be less optimal than the one devised in the first idea. So I read again the question and came up with again another interpretation:

### 3.3 Third attempt

The question states  $i = k$  requires  $k + 1$  times as much time than call  $i = 0$ . Somehow this does not make sense. Because in this formula, to define the time, there need to be equal indices  $k$  as indices  $i$ . That would mean that the problem is by definition embarrassingly parallel.

From the wording of the question in the second part *the first call takes..., the second call requires...* etc., I conclude that the author means that every time the algorithm is executed it will take inherently (in the current case) 2 milliseconds longer to finish. Maybe it should not be  $k$ , as index for cores, but just an arbitrary index to construct a number series. This brings me to the fourth and last idea:

### 3.4 Fourth attempt

If every call to the algorithm takes inherently longer, the task's  $i$  are actually independent of the time it takes to run and one can not start executing the 'long running'  $i$ 's as described in attempt 1 and 2. In this case, it's obvious that the solution for 1.1 is also valid here.

## 4 1.3 - Tree-structured global sum

The aim was to write pseudo code that calculates the tree structured global sum described on page 5. The book hints to use a variable called `divisor` that is initialized with the value 2 and another variable called `core_difference` that is initialized with the value 1. It was proposed that `divisor` is doubled in each iteration and that  $n \bmod \text{divisor}$  is used to determine `send = 0` and `receive = 1`. From figure 1.1 in the book, one can see that this rule works. Note especially that  $\text{core } k = 0$  will read in each iteration as  $0 \bmod x = 0$  is true for any  $x$ . Further, the book proposes that `core_diff`, when doubled in each iteration, can be used to describe the difference in value between a core pair that is involved in a 'send/receive' operation. The correctness of this can also be verified in figure 1.1 of the book.

Assuming that  $k$  is the core index, this allows already to write the main part of the algorithm:

```
if( k % divisor == 0 )
    receive and add from k + core_diff
else
    send to k - core_diff
    break
```

From figure 1.1, it can also be seen that `send` is the last operation a core does. Afterwards, it can terminate. This is solved here with a `break` statement after `send`. Further, there need to be some control structure to know when to finish. Here it was decided to use a `while` loop with the comparison `core_diff < p`, where `p` is the number of cores in the system. In each iteration `divisor` and `core_diff` are doubled. Moreover, before exit, the core `k = 0` should return the result. Below is the complete code listing that incorporates the the described features:

```
divisor = 2
core_diff = 1

while(core_diff < p){
    if( k % divisor == 0 )
        receive and add from k + core_diff
    else
        send to k - core_diff
        break

    divisor * 2
    core_diff * 2
}

if( k == 0 )
    return final result
```

## 5 1.4 - Alternative algorithm for 1.3

Here the aim was to modify the pseudo code from 1.3 to use bit-wise operators, basically to obtain `k` indices for `send` and `receive`. In the book, the idea is visually described using a table (page 13, exercise 1.4). The bitwise `Xor` operator is applied to a binary `bitmask` with the initial value  $001_2$  and the binary value of each `k`. This will flip the last bit in every `k` value, resulting in two `k`'s exchanging their initial value with each other. This can be exploited to use the core `k` whose value becomes lower by the bitshift as the sender and the other one in the 'flipping pair' as receiver. After the first iteration, the `bitmask` is bit-shifted to the left, hence  $001_2$  becomes  $010_2$ . Now follows the next iteration round with applying `Xor` to all remaining `k`'s.

Here the value of the `bitmask` itself can be used in a `while` loop to determine the end of the iteration using the comparison: `bitmask <= p`. Also in this version, after the `while` loop the core `k = 0` needs to return the result.

```
bitmask = 1

while ( bitmask <= p ){
    if(k bitwiseXor bitmask > k)
        receive and add from k bitwiseXor bitmask
    else
        send to k bitwiseXor bitmask
        break
```

4(5)

```
        bitwiseLeft bitmask
    }

    if( k == 0)
        return final result
```

## 6 1.5 - Generalization of 1.3 and 1.4

Here it was required to modify 1.3 and 1.4 to a more generalized form that could also handle the case when  $p$  is not a power of two value. Basically the same code could be maintained with just an additional `if` control sequence around the ‘receive’ statement that handles the case when there is no neighbour in the graph that could send the result.

### 6.1 Generalized form or 1.3

```
divisor = 2
core_diff = 1

while(core_diff < p){
    if(k % divisor == 0)
        if (k + core_diff < p)
            receive and add from k + core_diff
        else
            send to k - core_diff
            break

    divisor * 2
    core_diff * 2
}

if( k == 0 )
    return final result
```

### 6.2 Generalized form of 1.4

```
bitmask = 1

while ( bitmask =< p ){
    if(k bitwiseXor bitmask > k)
        if (k bitwiseXor bitmask < p)
            receive and add from k bitwiseXor bitmask
        else
            send to k bitwiseXor bitmask
            break

    bitwiseLeft bitmask
}
```

```
if( k == 0)
    return final result
```

## **7 1.6 - Cost analysis of global sum algorithms**

The number of receives and additions for core 0 is in the original ‘pseudo-code global sum’  $p-1$  and in the tree-structured global sum  $\text{ceiling}(\log_2(p))$ .

## **References**

- [1] P.S. Pacheco. *An Introduction to Parallel Programming*. Morgan Kaufman, 2011.