# REPORT 2 - GRANGIER-ROGER-ASPECT EXPERIMENT ANALYSIS

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### Summary

The purpose of this report is twofold: in a first part a statistical analysis will be carried out on a dataset collected from an experimental setup based on Grangier-Roger-Aspect experiment [1].

In a second part, an application of photon arrival statistics is shown: using a dataset from coherent light photon detection, random integers are generated and analyzed using various visual techniques.

## 1 Photon indivisibility experiment

The experiment developed by P. Grangier, G. Roger and A. Aspect in 1986 consist in verifying, by using statistical methods on photomultipliers hits, that a single photon, after impinging on a beam splitter, is present in only one of the beams after, and so it is indivisible. The statistical outcome is expressed in terms of *correlation* between events occurences in the transmitted and reflected channels: the result highlight how a very strong *anticorrelation* between events is found.

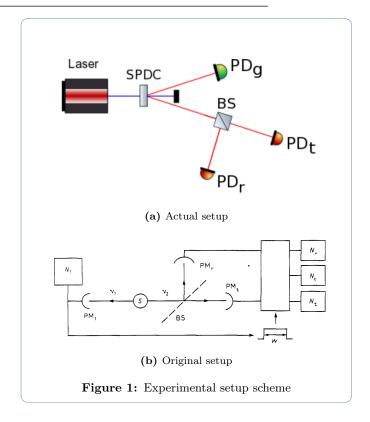
From the theoretical point of view, this experiment confirms the quanized nature of radiation, as the classical model for photodetection, which predicts correlation between detection along the two branches, is completely contradicted by the data.

### Experimental and statistical setup

Even if the description of the experiment with a single beam splitter and two detectors is straightfoward, an additional technique is needed to prevent detector noise from making the data unintelligible. So instead of a single source, a source which emits photon in couples is used, one is sent to a separate detector, and the other is sent to the setup described before. In that way the first photon triggers a gate signal that validate counts from the other detectors. Assuming a low rate emission from the source with respect to dark count rate of photodiodes, with that technique the noise is greatly reduced.

Altought in the original experiment this feature was hardwired with electronics, in our setup all events are collected regardless of their validation, and the *gate* signal is to be applied separately in post-processing.

The optical bench setup is shown in Figure 1a: all the pulses from the photodiodes  $PD_g, PD_t, PD_r$  are collected by a time-tagger on a common time scale in three different channels, respectively called  $gate\ (G)$  channel,  $transmitted\ (T)$  channel and  $reflected\ (R)$  channel.



For every gate event which is associated with at least an event in the reflected or transmitted channel (and therefore can be considered as an event not belonging to noise of the gate detector), there is a constant probability  $p_r$  and  $p_t$  to have an event in these channel.

In fact, we can define two Bernoulli random variables  $X_r \sim B(p_r)$  and  $X_t \sim B(p_t)$  which represents the result of measurement associated with each gate event. In this sense all the data collected can be represented as a stochastic process of i.i.d. variables. Each measurement will be called a *double* coincidence if only one of the two realizations is 1, and *triple* coincidence if they are both 1.

The physical problem is addressed by observing the correlation between the random variables, using the following definition of correlation coefficient:

$$\alpha = \frac{p_c}{p_r p_t} = \frac{\mathbb{E}[X_r X_t]}{\mathbb{E}[X_r] \mathbb{E}[X_t]}.$$

If  $\alpha > 1$  the variables are *correlated*, and the classical model is confirmed, indeed if  $\alpha < 1$  the variables are *anticorrelated*, and the classical model is rejected in favour of the quantum model. This follows naturally from the concept of a photon indivisibility: if the photon can't be splitted we expect to never find triple coincidences. Needless to say, we can only have an estimate of this parameter from experimental data: this is carried out as usual

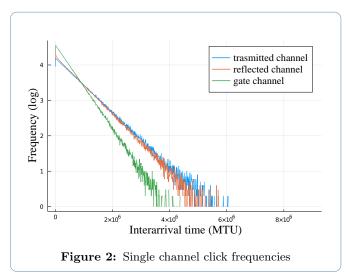
extracting a sample mean estimate using the following estimator: if  $N_1$  is the number of valid gate events,

$$\hat{\alpha} = \frac{\hat{p_c}}{\hat{p_r} \hat{p_t}} = \frac{N_1 \sum_{i=1}^{N_1} X_r X_t}{\sum_{i=1}^{N_1} X_r \sum_{i=1}^{N_1} X_t}.$$

Further comments on this estimator will be presented in the interpretation of result section.

### **Analysis**

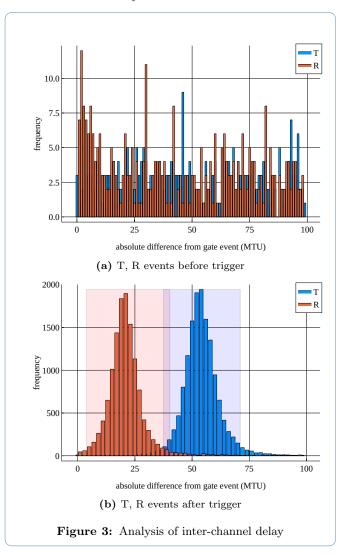
As anticipated, before counting double and triple coincidences, a preprocessing step is necessary to remove noise. First of all, we reject events on the same channel which are distanced by less than 3900 machine time units, or MTU (defined by 1MTU = 80.955ps). In fact, events whose difference in time is less than  $\approx 0.315\mu s$  could be afterpulses, artifacts of the detection devices. After this passage the interarrival time of the three channels is plotted in Figure 2, from which we can confirm that the light used is of coherent type, as it follows a Poisson arrival statistics.



In a second step, we must filter the data with a suitable *gate* function, which will be triggered by the events on the gate channel, and will detect events from the other channels which are included in a well defined *window*.

In order to build a correct gate window, we notice that the free air path of photons in the three branches of the optical setup, as well as the difference in the length of the coaxial cables connecting the detector to the time-tagger, can induce a differential time delay of events linked to the same photon pair. So we shall not limit ourselves in looking of equality of time tags as coincidences, as the reflection and/or transmission events related may occur a little time before or after each gate event. By analyzing the total distribution of every channel counts, it will be possible to deduce an estimate of the differential delay of the T and R channels with respect to the nearest gate event.

To facilitate further the recognition of delayed events, we filter the data of the transmitted and reflected channels to be in a strict interval near each gate event. In general, if we have two photons belonging to the same pair, the differential delay of two detections, on an arbitrary couple of detectors, must be less that a given time. This can be said for *physical reasons*: the pulses reach the timetagger's front end after the propagation of each photon along the optical bench, and of the signal along the RG cable. Considering the order of magnitude of the lenghts in laboratory, we deduce that the maximum time delay must be in the order of  $\sim 10ns$ , so we select only events around  $\pm 100MTU$  away from the nearest gate event. The outcome of this filtering is shown in Figure 3a for the interval [-100,0], which show only noise, and in Figure 3b for the interval [0,+100] in which bell-shaped delay curves indicates the real delayed occurences.



So we deduce that, in mean, the significant events in the channel R follows the gate event by  $\approx 22MTU$ , and the ones in the T channel follow the gate event by  $\approx 54MTU$ . In conclusion, using the hypotesis that the differential delay follows approximatively a normal distribution (which can be justified using the Central Limit Theorem), the standard deviations for each bell can be computed using the sample variance, and therefore the gate signal is tailored to be a window centered in the mean, and of width equal to a desired number of. That windows are shown in Figure 3b, and are of the form  $[(t_{Gi}+\mu)-2\sigma; (t_{Gi}+\mu)+2\sigma]$  where  $t_{Gi}$  is the time of the i-th gate event. Using the  $\pm 2\sigma$  interval, we expect to include in that way the 95%

of events. This construction of the gate window considers all the event belonging to the external of the windows as noise.

### Interpretation of results and conclusions

By filtering the events with the gate function described in the previous paragraph, we are able to measure the realization frequencies associated to the random variables  $X_r, X_t$ . The results are shown in Table 1, along with estimated errors. In order to compute the errors, the sample variance is used to deduce the standard deviation  $\hat{\sigma}_p$ . For a Bernoulli random variable of estimated probability  $\hat{p}$  it is calculated as

$$\hat{\sigma}_p = \sqrt{\frac{\hat{p}(1-\hat{p})}{N_1 - 1}}$$

using the Bessel correction at the denominator.

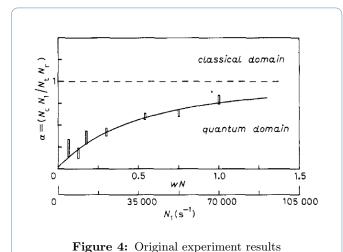
As for the error in  $\hat{\alpha}$ , a similar estimate is not readily applicable, as there is no trivial statistical description of this estimator. However, a basic error propagation extimate, using Taylor series, is carried out using the standard deviations of the probabilities.

$\hat{p}_t(\mathbf{x})$	$0.5130 \pm 0.003017$
$\hat{p}_r(\mathbf{x})$	$0.4871 \pm 0.003017$
$\hat{p}_c(\mathbf{x})$	$(3.6429 \pm 3.6429) \cdot 10^{-5}$
$\hat{\alpha}(\mathbf{x})$	$(1.458 \pm 1.476) \cdot 10^{-4}$

Table 1: Results

It may seem a problem that the estimated errors on  $\hat{p}_c$  and  $\hat{\alpha}$  are so large to be comparable to the actual magnitudes, but this is due to the poor statistics of the sample of triple coincidences: in fact, only 1 over 27451 gate events leads to a triple coincidence, and this greatly compromises the accuracy of the probability estimations.

Nonetheless this great uncertainty does not invalidate the physical conclusions: this value of  $\alpha$  shows a nearperfect anticorrelation, and is in complete contradiction whith respect to the classical theory.



In addition, the result on  $\alpha$  and it's error seem to be compatible with the result obtained by Grangier et. al. shown in Figure 4. In the case of collected data, after the filtering, the average gate trigger rate is  $\approx 1$ , so it is extremely low with respect to the order of magnitude of the one of the original experiment. So the aim of the experiment is met: this experiment validate the indivisibility of the photons, and, in spite of the classical theory of EM fields, it shows a peculiar quantistic feature of reality.

### 2 Random Number Generation

In this report two methods of obtaining streams of random bits (i.e. processes of independent and identically distributed Bernoulli (p=0.5) random variables) are presented. Starting from a coherent source of light, the photon arrival times are collected by a time-tagger, so the difference between the arrivals tags represents a realization of a process of exponential random variables. The two methods differ mainly in the fact that their algorithms needs different resources: the first one can operate directly on a continuous stream of photon arrivals, whereas the second needs to scan all the sequence of arrivals before generating, in a second scan, the random bits. We will call the first one Local difference method, and the second Median, for reasons that will be clear soon.

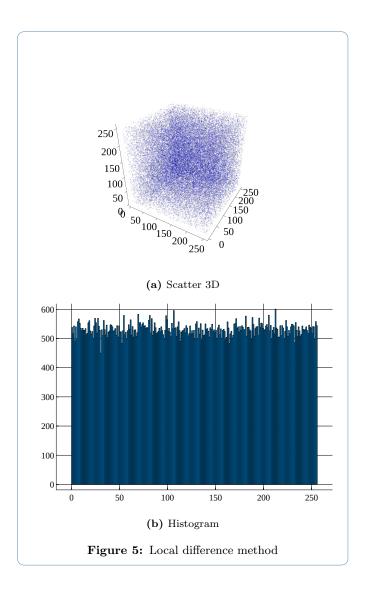
#### Local difference method

This algorithm can operate with constant memory over a stream of subsequent time tags, and works as follows:

- 1. generate from the time tags the vector of the differences between each one with the previous one (skip the first tag),
- 2. select 4 subsequent differences and group them by pairs [(1, 2); (3, 4)], and compute the difference between the second element of the pair and the first one: a sequence  $(\Delta_1, \Delta_2)$  of 2 values is obtained,
- 3. compare the values: if  $\Delta_1 \geq \Delta_2$  set the bit to 1, otherwise set the bit to 0.
- 4. iterate 2. to 3. over all the other subsequent group of 8 time tags, and save the deduced bits.

Using the vector of 4353849 time tags belonging to the Arecchi wheel experiment, we generate  $\lfloor 4353849/(4 \cdot 8) \rfloor = 136057$  bytes which represents numbers from 0 to 255.

Using them as triplets of coordinates it is possible to build a 3D scatter plot to show their uniform distribution among space. In Figure 5 this representation is shown as well as the histogram of frequencies of numbers.

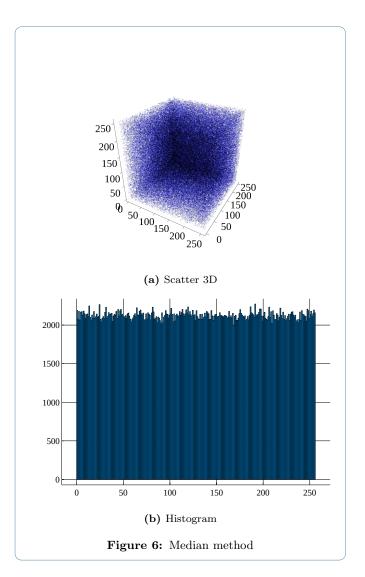


### Median method

This algorithm can operate with a double examination of the stream of the time tags, and works as follows:

- 1. generate from the time tags the vector of the differences between each one with the previous one (skip the first tag),
- 2. compute the sample median  $\widetilde{d}$  of the differences vector (or alternatively, assuming an exponential distribution, compute the sample mean and obtain the median multiplying it by ln(2)),
- 3. for each differences sample  $d_i$ , set a bit to 1 if  $d_i \ge \widetilde{d}$ , otherwise set it to 0.

This algorithm provides a generation rate of 4 times the Local difference method, at the expense of a greater computing effort, as can be noticed by the plots in Figure 6, where there are |4353849/8| = 544231 bytes.



### An even higher bit-rate proposal

If a complete statistical description of the Poisson arrival process is provided (or estimated observing the dataset), a much higher bit-rate method is easily developed: We use the theorem of Universality of uniform r.v. to obtain a continuous Uniform  $r.v. \sim U([0,1])$  from the Exponential. Once we have obtained that, we can divide the interval [0,1] in, for example, 256 sections, and consider for each hit in that section, the corresponding 8-bit number. The efficiency in this way can be scaled of a factor of 8 or higher, keeping in mind that the time-tagger has not infinite resolution, and saves the events in a fundamentally discrete space of time tags. The obvious problem in this method is that the statistical description of the incoming process can only be estimated, so the random bits will be unreliable.

### References

- [1] P.Grangier, G.Roger, A.Aspect Experimental evidence for a photon anticorrelation effects on a beam splitter: a new light on single-photon interferences (Europhys. Lett., 1 (4), pp. 173-179, 1986)
- [2] R.V.Hogg, J.W.McKean, A.T.Craig, *Introduction to mathematical statistics* (Pearson, 2019)

#### Code

The code is written in Julia Programming Language.

1. Analysis of photon indivisibility experiment

```
module Analyzer
   using Plots
using Printf
import Plotly
   import PGFPlots
   import
            Statistics
   import ProgressMeter

single_chan_stat, config
10
   default(show = true)
11
   const machine_time = 80.955e-12
12
13
14
   function loader(;aft_filter = true)
        println("Loading...")
15
        s = "./tags.txt"
16
        a = readlines(s)
17
18
         for y in a
19
              filter(x -> !isspace(x), y)
20
         end
21
         i=0
        b = Array{Int, 2}(undef, 2, length(a))
22
23
        b[1, :] = [parse(Int, split(x, ";")[1]) for x in a]
24
        b[2, :] = [parse(Int, split(x, ";")[2])  for x in a]
25
26
27
28
         tags = Array{Int, 2}(undef, 3, length(b))
        fill!(tags, 0)
29
         println(typeof(tags))
30
        \bar{k} = Array\{\bar{I}nt, 1\}(\bar{u}ndef, 3) \# k[i]  will be the total count of trigger \ensuremath{\mathcal{L}} events on channel i
31
         fill!(k, 1)
32
33
         i=0
34
         cnt = 0
         aft = Array{Int, 1}(undef, 3)
35
         fill!(aft, 0)
36
            (aft_filter)
aft_const = 3900
37
38
39
         else
40
              aft_const = 0
41
42
         for i = 1:length(a)
                  (i<8 | tags[b[2, i]-1, k[b[2, i]-1] - 1] + aft_const < b[1, i] ) tags[b[2, i]-1, k[b[2, i]-1]] = b[1, i]
43
44
                   k[b[2, i] - 1] += 1
45
              else
46
47
                   aft[b[2, i] - 1] +=1
              end
48
49
         end
         println("Number of valid hits")
51
         @printf("\t n. of transmitted hits
@printf("\t n. of reflected hits
                                                       : %6d \n", k[1])
: %6d \n", k[2])
: %6d \n", k[3])
52
53
         @printf("\t n. of gate hits
54
         println("T+R = ", k[1]+k[2], ", G = ", k[3])
55
56
         println("Number of afterpulses:")
                                                        : %6d \n", aft[1])
: %6d \n", aft[2])
: %6d \n", aft[3])
         @printf("\t chan 1 - transmitted (2) :
57
         @printf("\t chan 2 - reflected (3)
58
59
         @printf("\t chan 3 - gate (4)
         println("Percentage of afterpulses")
60
                                                          %4.1f %% \n", aft[1]/k[1] * 100)
%4.1f %% \n", aft[2]/k[2] * 100)
%4.1f %% \n", aft[3]/k[3] * 100)
         @printf("\t chan 1 - transmitted (2)
@printf("\t chan 2 - reflected (3)
61
                                                        :
62
         @printf("\t chan 3 - gate (4)
63
         return (tags, k);
64
65
66
   end
   function delay_estimator((tags, k); mode = "gate_first")
67
68
         println("Analyzing...")
```

```
69
          machine\_time = 80.955e-12
          diff1 = Array{Int, 1}(undef, k[1])
diff2 = Array{Int, 1}(undef, k[2])
70
71
          fill!(diff1, 0)
72
          fill!(diff2, 0)
if mode == "gate_last"
73
74
               g1 = -1
75
76
               g2 = tags[3, 1]
               \tilde{n} = 1
77
               # Retarded gate method - positive diff
78
               for i = 2:k[3]
79
                     while (tags[1, n] < g2 && n < k[1])
80
81
                          diff1[n] = g2 - tags[1, n]
82
                          n += 1
83
                     end
                     g2 = tags[3, i]
84
85
86
               end
               g1 = -1
87
88
               g2 = tags[3, 1]
               \tilde{n} = 1
89
               for i = 2:k[3]
90
                     while (tags[2, n] < g2 && n < k[2])</pre>
91
                          diff2[n] = g2 - tags[2, n]
92
93
                     end
94
95
                     g2 = tags[3, i]
96
          elseif mode == "gate_first"
97
               # Anticipated gate method - positive diff
98
99
               g1 = -1
               g2 = tags[3, 1]
100
               \tilde{n} = 8
101
102
               for i = 2:k[3]
                     while (tags[1, n] < g2 && n < k[1])</pre>
103
                          diff1[n] = tags[1, n] - g1
104
105
                     end
106
                     g1 = g2
107
                     g2 = tags[3, i]
108
109
               end
               diff1 = diff1[8:length(diff1)]
110
111
               g1 = -1
112
               g2 = tags[3, 1]
113
               \tilde{n} = 8
114
               for i = 2:k[3]
115
                     while (tags[2, n] < g2 && n < k[1])</pre>
116
                          diff2[n] = tags[2, n] - g1
117
118
119
                     end
                     g1 = g2
120
                     g2 = tags[3, i]
121
122
               diff2 = diff2[8:length(diff2)]
123
124
          else
               # Minimum distance method
125
               g1 = -100000000
126
               g2 = tags[3, 1]
127
               \tilde{n} = 1
128
               for i = 2:k[3]
129
                    while (tags[1, n] < g2 && n < k[1])
   if ((tags[1, n] - g1) < (g2 - tags[1, n]))
      diff1[n] = tags[1, n] - g1</pre>
130
131
132
133
                               diff1[n] = tags[1, n] - g2
134
                          end
135
                          n += 1
136
                     end
137
138
                    g1 = g2
                    g2 = tags[3, i]
139
140
               end
               g1 = -100000000
141
               g2 = tags[3, 1]
142
               \tilde{n} = 1
143
```

```
144
             for i = 2:k[3]
                  while (tags[2, n] < g2 && n < k[1])
   if ((tags[2, n] - g1) < (g2 - tags[2, n]))
      diff2[n] = tags[2, n] - g1</pre>
145
146
147
148
149
                            diff2[n] = tags[2, n] - g2
                       end
150
                       n += 1
151
                  end
152
                  g1 = g2
153
                  g2 = tags[3, i]
154
155
             end
         end
156
157
         max\_clicks = 100
         max_delay = max_clicks * machine_time / 1e-9
158
         @printf("PRE-filtering at max delay = %d ns \n ", max_delay)
159
         filter!(x-> (x < max_clicks), diff1)
160
         filter!(x-> (x< max_clicks), diff2)
161
162
163
         difference_info(diff1, diff2, k)
         mu_1 = Statistics.mean(diff1)
164
         mu_2 = Statistics.mean(diff2)
165
         sigma_1 = sqrt(Statistics.var(diff1 .- mu_1))
166
167
         sigma_2 = sqrt(Statistics.var(diff2 .- mu_2))
168
169
         return [mu_1, sigma_1, mu_2, sigma_2]
170
    end
171
172
    function difference_info(diff1, diff2, k)
         machine\_time = 80.955e-12
173
         println("Difference Info...")
174
         max_diff1 = maximum(diff1)
175
176
         min_diff1 = minimum(diff1)
         max_diff2 = maximum(diff2)
177
         min_diff2 = minimum(diff2)
178
                                                   : %10d \n", max_diff1)
: %10d \n", min_diff1)
         Oprintf("1) maximum difference
179
         Oprintf("1) minimum difference
180
         @printf("1) maximum time difference (ns)
                                                          : %10.4f \n", max_diff1 * \2
181
             \ machine_time * 1e9)
         @printf("1) minimum time difference (ns) : %10.4f \n", min_diff1 √
182
             \ *machine_time * 1e9)
183
                                                   : %10d \n", max_diff2)
: %10d \n", min_diff2)
         @printf("2) maximum difference
184
         @printf("2) minimum difference
185
         @printf("2) maximum time difference
                                                          : %10.4f \n", 2
                                                   (ns)
186
             \ max_diff2*machine_time * 1e9)
         Oprintf("2) minimum time difference
                                                    (ns) : %10.4f \ln n', 2
187

min_diff2*machine_time * 1e9)
188
         Qprintf("1) Fraction of accepted hits : %d / %d = %4.2f \n", 2
189

    length(diff1), k[1], length(diff1)/k[1])

         Qprintf("2) Fraction of accepted hits : %d / %d = %4.2f\n", \ensuremath{\mathcal{L}}
190

    length(diff2), k[2], length(diff2)/k[2])

191
192
         mod = Int(ceil(maximum([length(diff1), length(diff2)]) / 1e4))
193
         # plot clicks
194
195
         x_delays1 = (min_diff1:mod:max_diff1)
196
         x_delays2 = (min_diff2:mod:max_diff2)
197
         bin_num1 = Int(floor((max_diff1-min_diff1) / mod)) + 1
println("bins 1: ", bin_num1)
198
199
         bias1 = Int(floor(-min_diff1/mod))
200
         hist1 = Array{Int, 1}(undef, bin_num1)
201
202
         fill!(hist1, 0)
203
         while (i <= length(diff1))</pre>
204
             hist1[Int(floor((diff1[i] - min_diff1) / mod))+1] += 1
205
206
207
208
         bin_num2 = Int(floor((max_diff2-min_diff2) / mod)) + 1
209
210
         bias2 = Int(floor(-min_diff2/mod))
         println("bins 2: ", bin_num2)
hist2 = Array{Int, 1}(undef, bin_num2)
211
212
```

```
213
         fill!(hist2, 0)
214
         i = 1
         while (i <= length(diff2))</pre>
215
              hist2[Int(floor((diff2[i] - min_diff2) / mod))+1] += 1
216
217
218
         end
         mu_1 = Statistics.mean(diff1)
219
         mu_2 = Statistics.mean(diff2)
220
         sigma_1 = sqrt(Statistics.var(diff1 .- mu_1))
221
         sigma_2 = sqrt(Statistics.var(diff2 .- mu_2))
222
223
         if (length(hist1) < 600 && length(hist2) < 600)
    println("Plotting...")</pre>
224
225
              # fig = Plotly.figure()
226
              n_sigma_ = 2
227
228
              fig = Plots.bar(x_delays1,
229
                                  hist1
                                  show=true,
xlabel = "absolute difference from gate event (MTU)",
230
231
                                  ylabel = "frequency",
232
                                  label = "T"
233
                                  size = (600, 400))
234
              Plots.bar!(x_delays2, hist2, label = "R")
235
              rectangle(w, h, x, y) = Plots.Shape(x .+ [0,w,w,0], y .+ [0,0,h,h])
236
237
              recr = rectangle(2*n_sigma_*sigma_1, maximum([maximum(hist1), \( \varrho\)
238

    maximum(hist2)]), mu_1-n_sigma_*sigma_1, 0)

              rect = rectangle(2*n_sigma_*sigma_2, maximum([maximum(hist1), ∠
239

    maximum(hist2)]), mu_2-n_sigma_*sigma_2, 0)

              # Plots.plot!(recr, linewidth = 2, opacity = 0.1, color=:blue, \angle
240

    label=nothing)

              # Plots.plot!(rect, linewidth = 2, opacity = 0.1, color=:red, \angle
241
                  242
243
              display(fig)
              savefig("./images/delays.pdf")
244
         else
245
             println("Too long to plot...")
246
247
         end
    end
248
249
    function gated_counter((tags, k), params; mode = "confidence")
250
251
         println("Gated counting...")
252
         mu_1 = params[1]
         sigma_1 = params[2]
253
254
         mu_2 = params[3]
         sigma_2 = params[4]
255
256
                              nsmitted : %6.4f \n", params[1])
nsmitted : %6.4f \n", params[2])
reflected : %6.4f \n", params[3])
reflected : %6.4f \n", params[4])
         @printf("mean tramsmitted
257
         @printf("stdd tramsmitted
258
         @printf("mean
259
         @printf("stdd
260
261
         N_1 = 0
         intervals = [2]
262
         for n_sigma_ in intervals
263
              max_clicks = 100
264
              x = 1
265
              r_hit = false
266
              refl = 0
267
              multiple_refl = 0
268
              y = 1
269
              t_hit = false
270
              tran = 0
271
              multiple_tran = 0
272
              coincidences = 0
if (mode == "confidence")
273
274
                   for i=1:length(tags[3, :])-1
275
                       r_hit = false
276
                       t_hit = false
277
                               tags[1, x] < -n_sigma_*sigma_1 + tags[3, i] + mu_1
278
                       while
                            x +=
279
280
                       while -n_sigma_*sigma_1 + tags[3, i] + mu_1 <= tags[1, x] < 2
281
                            \hookrightarrow +n_sigma_*sigma_1 + tags[3, i] + mu_1 && tags[1, x] < \swarrow
                            \hookrightarrow tags[3, i+1]
```

```
282
                           t_hit = true
283
                      end
284
                      if t_hit
285
286
                           tran += 1
                      end
287
288
289
                      while
                             tags[2, y] < -n_sigma_*sigma_2 + tags[3, i] + mu_2
290
                      end
291
                      while -n_sigma_*sigma_2 + tags[3, i] + mu_2 <= tags[2, y] < 2
292
                          \rightarrow +n_sigma_*sigma_2 + tags[3, i] + mu_2 && tags[2, y] < \nearrow
                          \searrow tags[3, i+1]
293
                           r_hit = true
                           y += 1
294
295
                       end
                      if r_hit
296
                           refl += 1
297
                      end
298
                      if r_hit && t_hit
299
300
                           coincidences += 1
301
                      if r_hit || t_hit
302
                           N_1 += 1
303
                      end
304
305
                  end
             else
306
307
                  for i=1:length(tags[3, :])-1
                      r_hit = false
t_hit = false
308
309
                      while tags[1, x] < tags[3, i]
310
311
                           x += 1
                      end
312
                      while tags[3, i] <= tags[1, x] < tags[3, i] + max_clicks</pre>
313
314
                           t_hit = true
315
316
                       end
                      if t_hit
317
                           tran += 1
318
                      end
319
320
                      while tags[2, y] < tags[3, i]</pre>
321
322
                      end
323
                      while tags[3, i] <= tags[2, y] < tags[3, i] + max_clicks</pre>
324
                           r_hit = true
326
                      end
327
328
                      if r_hit
329
                           refl += 1
330
                       end
331
                      if r_hit && t_hit
                           coincidences += 1
332
                      end
333
334
                      if r_hit || t_hit
                           N_1 += 1
335
336
                      end
                  end
337
             end
338
             Oprintf("Measurement with As sigma_ confidence \n")
339
             println("sigma = ", n_sigma_)
prob_refl = refl / N_1
340
341
             prob_tran = tran / N_1
342
             prob_triple = coincidences / N_1
343
             344
                                                   %9d \n", N_1)
%9d \n", refl)
%9d \n", train
345
             @printf("\t reflected
346
                                          hits :
             @printf("\t transmitted hits:
347
             @printf("\t coincidences hits :
                                                  %9d \n", coincidences)
348
             @printf(" -----\n")
349
             @printf("\t P[double]
                                               : \%9.8f \n", prob_refl + prob_tran - 2 \nearrow
350
                 *prob_triple)
             @printf("\t P[triple]
                                                : %9.8f \n", prob_triple)
351
             @printf("\t Alpha
                                                : %9.8f \n", alpha)
352
353
354
             sigma_r = sqrt(prob_refl*(1-prob_refl)/(N_1-1))
```

```
sigma_t = sqrt(prob_tran*(1-prob_tran)/(N_1-1))
355
356
               sigma_c = sqrt(prob_triple*(1-prob_triple)/(N_1-1))
              @printf("p_r variance: %9.8f \n", sigma_r)
@printf("p_t variance: %9.8f \n", sigma_t)
@printf("p_c variance: %9.8f \n", sigma_c)
357
358
359
               @printf(" variance: %9.8f \n", sigma_c/(prob_refl*prob_tran) +
360
                         sigma_r * prob_triple/(prob_refl^2*prob_tran) +
361
362
                         sigma_t * prob_triple/(prob_refl*prob_tran^2))
         end
363
    end
364
365
366
    function config()
         Plots.plotly()
367
368
         Plots.default(size=(600, 400),
         guidefont=("times", 14)
369
         legendfont=("times", 14),
370
         tickfont=("times", 14)
371
372
373
    end
374
    function single_chan_stat((tags, k))
375
         machine_time = 80.955e-12
bin_num = 1000
376
377
378
         hist = Array{Int, 2}(undef, 3, bin_num)
         fill!(hist, 0)
bin_step = Array{Int}(undef, 3)
379
380
381
         diff = Array{Int, 2}(undef, 3, maximum(k)-1)
         fill!(diff, 0)
382
         println(length(tags[3, :]), k)
383
         maxx = 0
384
385
         for chan in [1, 2, 3]
              series = tags[chan,
386
               for i = 1:k[chan]-1
387
                    diff[chan, i] = series[i+1] - series[i]
388
              end
389
              filter!(z \rightarrow (z>0), diff[chan, :])
390
              max_diff = maximum(diff[chan, :])
391
              if max_diff>maxx
392
393
                    maxx = max_diff
394
               end
395
         end
396
         x_axis = 0:bin_num:maxx
         bin_size = maxx/bin_num
397
         i = 1
398
         for chan = [1, 2, 3]
  filter!(z -> (z>0), diff[chan, :])
399
400
               for i = 1:k[chan]-2
401
402
                    hist[chan, Int(ceil(diff[chan, i]/bin_size))] += 1
403
               end
         end
405
         fig = Plots.plot((0:bin_num-1)*bin_size,
406
407
                               [log10(x) for x in hist[1, :]]
                               label = string("trasmitted channel"),
408
                               show=true,
xlabel = "Interarrival time (MTU)",
409
410
                               ylabel = "Frequency (log)",
411
                               size = (600, 400))
412
413
         Plots.plot!((0:bin_num-1)*bin_size,
414
                         [log10(x) for x in hist[2, :]],
415
                         label = string("reflected channel"))
416
417
         Plots.plot!((0:bin_num-1)*bin_size
418
                         [log10(x) for x in hist[3, :]],
419
                         label = string("gate channel"))
420
         @printf("Sum 1 : %5.4f \n", sum(hist[1, :]/sum(hist[1, :])))
@printf("Sum 2 : %5.4f \n", sum(hist[2, :]/sum(hist[2, :])))
@printf("Sum 3 : %5.4f \n", sum(hist[3, :]/sum(hist[3, :])))
421
422
423
424
425
         savefig(string("./images/single_chan.pdf"))
426
    end
427
428
    end
```

2. Functions involved in generation and analysis of random data

```
function random(tags; mode="naif")
2
       data = diff(tags[1])
       data_diff = diff(data)[1:2:length(data)]
       println("Generating with ", mode, " rule, over ", length(tags[1]) , " \checkmark
4
            + tags stream...")
       println("Diffs length:
                                ", length(data), " \nDiffs_of_diffs length: ", \rangle
5
           \( length(data_diff))
             Statistics.mean(data)
6
7
       lambda = 1/mu
       median = Statistics.median(data)
9
       sigma = sqrt(Statistics.var(data))
10
       byte_stream = Array{UInt8}(undef, Int(floor(length(data)/8))-1)
       if mode == "naif
11
            stream = BitArray(undef, length(data))
12
            for i = 1:length(data)
13
                if data[i] < median</pre>
14
                    stream[i] = 1
15
                else
16
                    stream[i] = 0
17
                end
18
            end
19
20
           byte_stream = Array{UInt8}(undef, Int(floor(length(stream)/8)))
21
            for i = 1:length(byte_stream)-1
22
                byte_stream[i]
                1*stream[8*i]+2*stream[8*i+1]+4*stream[8*i+2]+8*stream[8*i+3]+
23
                16*stream[8*i+4]+32*stream[8*i+5]+64*s[8*i+6]+128*stream[8*i+7]
24
            end
25
       elseif mode == "high-rate"
26
           uniform_events = Array{Float64}(undef, length(data))
27
28
            for i = 1:length(data)
29
                uniform_events[i] = exp(-data[i] * lambda) - 1
30
            end
31
            byte_stream = Array{UInt8}(undef, length(data))
32
           for i = 1:length(byte_stream)
33
34
                byte_stream[i] = -Int(floor(255 * uniform_events[i]))
35
            end
36
       elseif mode == "diff"
            stream = BitArray(undef, length(data_diff))
37
            for i =1:length(data_diff)-1
38
39
                if data_diff[i] < data_diff[i+1]</pre>
                    stream[i] = 1
40
41
                else
42
                    stream[i] = 0
                end
43
            end
44
45
            byte_stream = Array{UInt8}(undef, Int(ceil(length(stream)/8)))
           for i = 1:length(byte_stream)-1
46
47
                byte_stream[i]
48
                1*stream[8*i]+2*stream[8*i+1]+4*stream[8*i+2]+8*stream[8*i+3]+
                16*stream[8*i+4]+32*stream[8*i+5]+64*s[8*i+6]+128*stream[8*i+7]
49
           end
50
       elseif mode == "diff-2"
51
            stream = BitArray(undef, Int(ceil(length(data_diff))/2))
52
53
           fill!(stream, 0)
54
           k = 1
55
            for i =1:2:length(data_diff)-2
                  data_diff[i] < data_diff[i+1]
56
                    stream[k] = 1
57
                else
58
59
                    stream[k] = 0
                end
60
                k+=1
61
            end
62
           byte_stream = Array{UInt8}(undef, Int(ceil(length(stream)/8)))
63
64
           fill!(byte_stream, 0)
                i = 1:length(byte_stream)-1
65
66
                byte_stream[i]
67
                1*stream[8*i]+2*stream[8*i+1]+4*stream[8*i+2]+8*stream[8*i+3]+
                16*stream[8*i+4]+32*stream[8*i+5]+64*s[8*i+6]+128*stream[8*i+7]
68
69
            end
       end
70
       println("Byte stream generated")
71
```

```
72
73
        println("mean: ", Statistics.mean(byte_stream))
74
        rnd_tester(byte_stream)
75
        return byte_stream
76
77
   \verb"end"
78
    function rnd_tester(byte_stream)
        samples = length(byte_stream)-9
79
80
        while samples % 3 != 0
81
             samples -= 1
82
        println("Analyzing ", samples, " UInt8 numbers...")
83
        # 3D Scatter
84
85
        fig1 = Plots.scatter3d(byte_stream[1:3:samples], ∠
            \hookrightarrow byte_stream[2:3:samples], byte_stream[3:3:samples],
                                  markercolor = :blue,
86
87
                                  markershape = :cross,
                                  markersize = 0 opacity = 0.1, label= nothing,
                                               = 0.5,
88
89
90
                                  tickfont=("times", 12),
91
                                   size = (1024, 768)
92
93
        # Histogram
94
        fig2 = Plots.histogram(byte_stream, bins = 256, label= nothing)
95
        # Random walk
96
        x = Array{Float64}(undef, samples)
97
        fill!(x, 0)
98
99
        mu = Statistics.mean(byte_stream)
        println("Statistical mean of byte_stream: ", mu)
100
101
        for i=2:samples
             x[i] = x[i-1] + byte_stream[i] - 127.5
102
103
        end
        fig3 = Plots.plot(1:samples, x, label= nothing, size = (1024, 768))
104
105
        display(fig1)
106
                        "./random_img/scatter3d.pdf")
107
        savefig(fig1,
        display(fig2)
108
        savefig(fig2,
                        "./random_img/histogram.pdf")
109
110
        display(fig3)
        savefig(fig3, "./random_img/random_walk.pdf")
111
112
    end
```