

# NSPDE/ANA 2022 - Lecture 10

Last lecture:

- The generalised Galerkin method
- Advection-dominated Advection-diffusion problems

Today:

- Strongly consistent FEM for advection-dominated problems
- Intro to Parabolic problems

References:

- Quarteroni
- Larsson-Thomee

Seen last week: for

$$\begin{cases} -\alpha u'' + b u' = 0 & \text{in } \Omega = (0, 1) \\ u(0) = 0; u(1) = 1 \end{cases}$$

exact solution of  $u(x) = \frac{e^{bx/\alpha} - 1}{e^{b/\alpha} - 1}$  monotone!

FEM/FD solution:  $U_j = \frac{1 - \left(\frac{1 + \text{Pe}_h}{1 - \text{Pe}_h}\right)^j}{1 - \left(\frac{1 + \text{Pe}_h}{1 - \text{Pe}_h}\right)^M}$   $\forall j$

oscillatory if  $\text{Pe}_h > 1$

$\text{Pe}_h := \frac{bh}{2\alpha}$  mesh Péclet number

(similar issues for reaction-dominated reaction-diffusion problems, see eg Quarteroni)

Towards a cure of numerical "instability"

generic equation of our FEM/FD scheme  
 $(k=1)$

$$-\alpha \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + b \frac{u_{i+1} - u_{i-1}}{2h} = 0$$

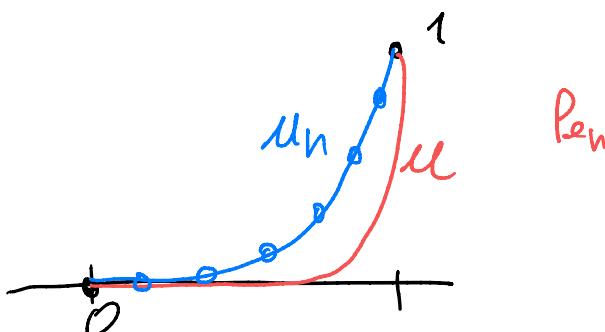
$$-\underbrace{\alpha u''}_{\text{small}} + b u' = 0$$

alternatively, use **UPWIND** difference for the advection term ? ( $b > 0$ )

$$-\alpha \frac{U_{i+1} - 2U_i + U_{i-1}}{h^2} + b \frac{U_j - U_{j-1}}{h} = 0$$

solution :

$$U_j = \frac{(1+2Pe_h)^7 - 1}{(1+2Pe_h)^4 - 1} \quad \text{monotone ?}$$



upwind solution is over diffusive.

$$6 \frac{U_8 - U_{8-1}}{h} = 6 \frac{U_8 - \frac{1}{2}U_{8-1} - \frac{1}{2}U_{7-1} + \frac{1}{2}U_{8+1} - \frac{1}{2}U_{7+1}}{h}$$

| ||  
 $\underbrace{\quad}_{\text{control FD}}$        $\underbrace{\quad}_{\text{centre FD for } \frac{bh}{2} u''}$

operator for  $-\alpha u'' + bu' = 0$  written as CD

for  $-(\alpha + \frac{6h}{2})u'' + bu' = 0$

$\underbrace{\alpha_h}_{\downarrow}$

$$\text{Pe}_h = \frac{bh}{2\alpha_h} = \frac{\text{Pe}}{1+\text{Pe}} < 1$$

OPWHD  $\equiv$  numerical / artificial diffusion / viscosity

Adding viscosity/diffusion  $\Rightarrow$  reduction in consistency

Perhaps accuracy can be raised by optimizing the amount of artificial diffusion:

In general, define

$$Q_h := \varrho (1 + \phi(P_{\text{Re}}))$$

for example:

• Upwind :  $\phi(t) = t \rightarrow O(h)$  scheme

• Schaffettel-Gummel :  $\phi(t) = t - 1 + B(2t)$

$$\begin{aligned} B(t) &= \begin{cases} \frac{t}{e^t - 1} & \text{if } t > 0 \\ -1 & \text{if } t = 0 \end{cases} \\ \text{Bernoulli} \\ \text{function} \end{aligned}$$

$\rightarrow O(h^2)$  scheme

analysis of the octahedral diffusion scheme

we have  $R_h(u, v) = \int_{\Omega} \partial_n u' v' \, , \text{ so}$

by Strong

$$\begin{aligned} \|u - u_h\|_{H^1} &\leq \inf_{v_h \in V_h} \left\{ \left(1 + \frac{\varrho}{\varrho_{0,h}}\right) \|u - v_h\|_{H^1} \right. \\ &\quad \left. + \frac{1}{\varrho_{0,h}} \sup_{\substack{w_h \in V_h \\ w_h \neq 0}} \frac{|f(v_h, w_h) - R_h(v_h, w_h)|}{\|w_h\|_{H^1}} \right\} \\ &\quad (\text{quaternion}) \end{aligned}$$

for FOF  
degree k

$$\leq C \frac{h^k}{\varrho(1 + \phi(\text{Re}))} \|u\|_{H^{k+1}} + \frac{\phi(\text{Re})}{1 + \phi(\text{Re})} \|u\|_{L^2}$$

$\text{for } k=1, \text{ upwind } O(h)$   
 SG  $O(h^2)$  (more for  $k > 1$ )

What about multidim problems?

Can we have a strongly consistent method  
(inconsistency term also of  $O(k)$ )

Model problem:  $-a \Delta u + b \cdot \nabla u = f$

$$\begin{aligned}
 u_h \in V_h : A(u_h, v_h) &= l(v_h) \\
 &\quad \leftarrow \text{PDE + BC} \\
 &+ \sum_T \frac{h}{b} \int_T (a \Delta u + b \cdot \nabla u - f) (b \cdot \nabla v) \\
 &\quad \left( \begin{array}{l} \text{orthogonal} \\ \text{diffusion} \\ \text{scheme} \end{array} \right. \\
 &\quad \left. \begin{array}{l} \nabla v \\ \nabla u \end{array} \right) \\
 &\quad \text{streamline-diffusion} \\
 &\quad \text{scheme} \\
 &\quad \text{stabilizing term} \\
 &\quad \underbrace{\qquad\qquad\qquad}_{\text{for strong consistency}}
 \end{aligned}$$

$\Rightarrow$  Streamline-diffusion method  
 [Hughes-Brooks 1979]

$$B_h(u_h, v_h) := \sum_T \frac{\delta h_T}{b} \int_T (-\alpha \Delta u_h + b \cdot \nabla u_h) \cdot (b \cdot \nabla v_h)$$

find  $u_h \in V_h$ :  $\int_T f v_h$

$$R(u_h, v_h) + B_h(u_h, v_h) = l(v_h) + \sum_T \int_T \frac{h}{b} f (b \cdot \nabla v_h) \quad \forall v_h \in V_h$$

another interpretation: Petrov-Galerkin  
scheme ( $\equiv$  test space  $\neq$  trial space)

$$\mathcal{T}_T := \frac{\delta h_T}{b} \quad \text{streamline-diffusion parameter}$$

# Analysis of SD - FEM

note :

- $H^1$  norm is not the right norm or we do not have stabilization in such norm
- Instead : SD - norm :

$$\|v\|_{SD} = \left( \alpha \|v\|_1^2 + \sum_{T \in \mathcal{G}_h} \zeta_T \|b \cdot \nabla v\|_{L^2(T)}^2 \right)^{1/2}$$

(stability)

Lemma : If  $0 < \zeta_T < \frac{h_T^2}{2\alpha \mu_I}$ ,  $\mu_I > 0$

constant (from  $\|\Delta v_h\|_{0,T}^2 \leq \mu_I h_T^{-2} \|v\|_{1,T}^2$ )

then  $A(v_h, v_h) + B_h(v_h, v_h) \geq \frac{1}{2} \|v_h\|_{SD}^2$

Theorem : If  $\sigma_h = \begin{cases} \delta_0 h_T & \text{if } Pe_h > 1 \text{ (conv)} \\ \delta_1 \frac{h_T^2}{\alpha} & \text{if } Pe_h \leq 1 \text{ (diff dom noted)} \end{cases}$

for  $\delta_0, \delta_1 > 0$ , then

$$\|u - u_h\|_{SD} \leq c(\alpha^{1/2} + h^{1/2}) h^k \|u\|_{k+1}$$

$$( \|u - u_h\|_{H^1}^2 + \sum_T \zeta_T \|b \cdot \nabla(u - u_h)\|^2 )^{1/2}$$

$\uparrow$  diffusion dom. core

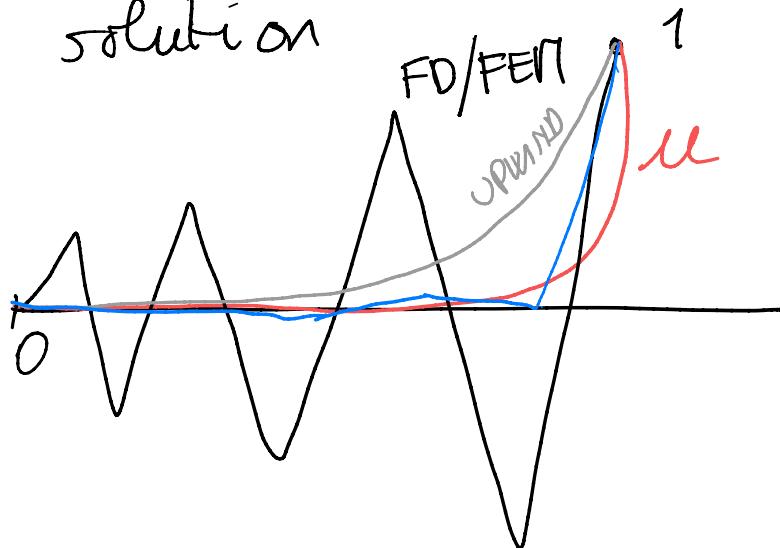
$\Rightarrow$   $\underbrace{\alpha h^{1/2}}$

convection dom. core

$O(h^k)$  for  $H^1$  norm

$O(h^k)$  for  $\|b \cdot \nabla u\|$  norm

typical solution



SD solution is  $O(h^k)$  accurate but not monotone.

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## PARABOLIC PROBLEMS

In general, a parabolic equation in  $\mathbb{R}^d$ ,

$$u_t + \mathcal{L}u = f$$

with  $\mathcal{L}$  linear elliptic 2<sup>nd</sup> order operator

$$\left( \frac{\partial}{\partial t} + \mathcal{L} = \text{"parabolic op."} \right)$$

(Larson-Thorne) example:  $\Omega \subset \mathbb{R}^d$  bounded

$$(P_0) \begin{cases} u_t - \Delta u = 0 & \text{in } \Omega \times \mathbb{R}^+ \\ u = 0 & \text{on } \partial\Omega \times \mathbb{R}^+ \\ u(\cdot, 0) = u_0 & \text{in } \Omega \end{cases} \quad \begin{array}{l} (\text{heat equation}) \\ (\text{boundary cond.}) \\ (\text{initial cond.}) \end{array}$$

with  $u_0 \in L^2(\Omega)$ .

Proposition:  $\exists$  a countable set of smooth eigenfunctions  $\{\varphi_i\}_{i=1}^{+\infty}$  and eigenvalues  $\{\lambda_i\}_{i=1}^{+\infty}$

of the Laplace operator, i.e.

$$\begin{cases} -\Delta \varphi_i = \lambda_i \varphi_i & \text{in } \Omega \\ \varphi_i = 0 & \text{on } \partial\Omega \end{cases}$$

and  $\{\varphi_i\}_{i=1}^{+\infty}$  is a basis of  $L^2(\Omega)$ .

Moreover,  $0 < \lambda_1 \leq \lambda_2 \dots \leq \lambda_i \leq \dots$ , and  $\lim_{i \rightarrow \infty} \lambda_i = +\infty$

and  $\int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j = \lambda_i \delta_{ij}$

→ we fit in separation of variables ∴ seek sol.  $(P_0)$  in the form:

$$u(x, t) = \sum_{i=1}^{+\infty} \hat{u}_i(t) \varphi_i(x)$$

$\uparrow \hat{u}_i: \mathbb{R}^+ \rightarrow \mathbb{R}$  to be determined

Inserting such  $u$  in  $(P_0)$  gives:

$$\sum_{i=1}^{+\infty} (\hat{u}'_i(t) + \lambda_i \hat{u}_i(t)) \varphi_i(x) = 0 \quad \text{in } \Omega \times \mathbb{R}^+$$

basis for  $L^2$

$$\Rightarrow \hat{u}_i'(t) + \lambda_i \hat{u}_i(t) = 0 \quad \forall i, t \in \mathbb{R}^+$$

with sol.  $\hat{u}_i(t) = \hat{u}_i(0) e^{-\lambda_i t}$

$\uparrow$  const. of int. to be determined using the

initial cond:

$$= u_0(x) = u(x, 0) = \sum_{i=1}^{+\infty} \hat{u}_i(0) \varphi_i(x)$$

$$\stackrel{L^2}{\Rightarrow} \sum_{i=1}^{+\infty} u_0^i \varphi_i(x) \quad \exists u_0^i \quad i=1, \dots, +\infty$$

$$\Rightarrow u(x, t) = \sum_i u_0^i \underbrace{e^{-\lambda_i t}}_{\text{exponential decay in time}} \varphi_i(x)$$

$$\|u(\cdot, t)\|_{L^2(\Omega)} \leq C \|u_0\|_{L^2(\Omega)} \quad \begin{matrix} (\text{proof}) \\ (\text{Parseval}) \\ (\text{relation}) \end{matrix}$$

$$\Rightarrow u(\cdot, t) \in L^2(\Omega)$$

For nonhomogeneous problem:  $= [0, T]$

$$(P) \begin{cases} u_t - \Delta u = f & \text{in } \Omega \times I \\ u = 0 & \text{on } \partial\Omega \times I \\ u(x, 0) = u_0 & \text{in } \Omega \end{cases}$$

Denote by  $E(t)u_0$  the solution operator of the homog. problem  $(P_0)$ .

Then

$$u(\cdot, t) (= u(t)) = E(t)u_0 + \int_0^t E(t-s)f(s)ds$$

Duhamel Principle

(Proof in LT)

and

$$\|u(t)\|_0 \leq \|u_0\|_0 + \int_0^t \|f(s)\| ds$$

stability

$\Rightarrow$  uniqueness +  
cont. dependence  
on data follows

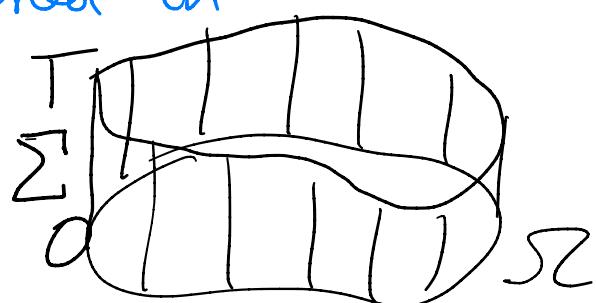
Moreover we have maximum principle:

$u_t - Au \leq 0$  smooth in  $\Omega \times (0, T]$ , Then

the max. of  $u$  is obtained in

$$\Omega \times \{0\} \cup \Sigma$$

$$\Sigma \supset \Omega \times (0, T]$$



$$\frac{\|u\|}{C(\bar{\Omega} \times \bar{I})} \leq \max \left\{ \frac{\|u\|}{C(\Sigma)}, \frac{\|u_0\|}{C(\bar{\Omega})} \right\} + C \frac{\|f\|}{C(\bar{\Omega} \times \bar{I})}$$

### Weak formulation

for  $\begin{cases} u_t - \Delta u = f & \text{in } \Omega \times I \\ u = 0 & \text{in } \Sigma \\ u(\Sigma, 0) = u_0 & \text{in } \Omega \end{cases}$

$\forall t \quad v \in H_0^1(\Omega)$  test and integrate:

$$\frac{d}{dt} \int_{\Omega} u v + \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} f v \quad \forall v \in H_0^1(\Omega)$$

$$\begin{matrix} !! \\ (u, v) \end{matrix} \quad \begin{matrix} !! \\ A(u, v) \end{matrix}$$

$$\frac{d}{dt} (u, v) + A(u, v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

$$u(\cdot, t) = u(t) : I \longrightarrow V$$

$$t \longrightarrow u(t)$$

right setting :

$$u \in L^2(I; H_0^1(\Omega)) \cap C^0(\bar{I}; L^2(\Omega))$$

where,

$$u \in L^2(I; H_0^1(\Omega)) \text{ if } u = u(t) \in H_0^1(\Omega) \text{ and}$$

$$\int_I \|u(t)\|_{H_0^1}^2 dt < \infty$$

$$u \in C^0(\bar{I}; L^2(\Omega)) \text{ if } \forall t \in \bar{I},$$

$$\lim_{s \rightarrow t} \|u(s) - u(t)\|_{L^2(\Omega)} = 0$$

### Well-posedness

Consider the problem: find  $u \in L^2(I; H_0^1) \cap C^0(\bar{I}; L^2)$ :

$$(P_w) \begin{cases} \frac{d}{dt}(u(t), v) + \mathcal{R}(u(t), v) = F(t, v) & t \in I \\ u(0) = u_0 \in L^2(\Omega) \end{cases}$$

$$\text{with } \mathcal{R}(u, v) = (\alpha \nabla u, \nabla v) - (\underline{b} u, \nabla v) + (c u, v)$$

is well-posed? Yes if:

- $\mathcal{R}$  is continuous
- if  $\mathcal{R}$  is coercive

Actually, the coercivity requirement can be relaxed somehow. It is enough to require the validity of

e.g.  $H^1_0$

Def:  $A$  is weakly coercive in  $V$  if  $\exists \alpha > 0, \lambda \geq 0 : \forall v \in V$

$$A(v, v) + \lambda \|v\|_{L^2(\Omega)}^2 \geq \alpha \|v\|_V^2$$

(Gording inequality)

(see Quarteroni),

otherwise, in case of Gording look here ( $V = H^1_0$ )

Theorem: if  $A$  is cont. and coercive in  $V \times V$ ,

$f \in L^2(I; L^2(\Omega))$ ,  $u_0 \in L^2(\Omega)$ . Then

$\exists! u \in L^2(I; V) \cap C^0(I; L^2)$  sol. of  $(P_w)$

and

$$u_t \in L^2(I; V')$$

$$\max_{t \in I} \|u(t)\|_0^2 + \int_I \|u(t)\|_V^2 \leq \|u_0\|_{L^2(\Omega)}^2 + \frac{1}{\alpha} \int_I \|f(t)\|^2$$

norm of

norm of

"energy estimate"

that is, the problem is well-posed ?