

NSPDE/ANA 2022 - Lecture 1

LECTURES: 40 lectures + 8 computer sessions

2-5PM Tuesdays+Wednesday **NO LECTURES TOMORROW!**

- in person: room A-133. Wear FFP2 masks; always sanitise desk+chair
- Online: week video on; mute audio unless for asking a question

COURSE MATERIAL: see GitHub site:

<https://github.com/andreacangiani/NSPDE-ANA22>

ASSESSMENT: oral exam on course material + short presentation of coursework project.

BIBLIOGRAPHY:

- Morton & Mayers *Numerical Solution of Partial Differential Equations*. Cambridge, 1994.
- Larsson & Thomee *Partial Differential Equations with Numerical Methods*. Springer, 2009.
- Quarteroni *Numerical Models for Differential Equations*. Springer, 1994.
- Evans *Partial Differential Equations*. AMS 1997.
- Gilbert & Trudinger *Elliptic Partial Differential Equations of Second Order*. Springer, 1998.
- Own notes

(Core of course along the lines of Larsson Thomee book.)

IDEA OF THE COURSE:

present the fundamental ideas/methods and the interlink between different approaches.

- explore different problems to see that fundamental ideas are ubiquitous
- understand that appropriate numerical methods depend on the problem

Follows the Numerical Analysis course (Heltai+Rozza) and is complemented with Theory and Practice of FEM (Heltai) and Advanced FEM Techniques (Cangiani)

Practical sessions in Python and FEniCSx using
<https://colab.research.google.com/notebooks/>

PDES' Facts

- Def (PDE) :
- $\Omega \subset \mathbb{R}^d$ open "Domain of Definition"
 - PDE on Ω of order k :

$$F(x, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_d}, \dots, \frac{\partial^k u}{\partial x_d^k}) = 0 \quad (*)$$

where,
 $x = (x_1, \dots, x_d)$ ("indep. variable")
 $u: \Omega \rightarrow \mathbb{R}$ unknown k -times differentiable function
 - F given scalar function
 (systems of PDEs can also be defined, taking F as vector functions)

Def (solution) : Classical solution of $(*)$ is the family of all functions $u: \Omega \rightarrow \mathbb{R}$: that are k -times diff. ord satisfy $(*)$

Def (types of PDEs) :

- A PDE is LINEAR : coefficients in F only depend on x
- A PDE is NONLINEAR if not linear
 - ★ SEMILINEAR if coeffs of k -th order derivatives only depend on x
 - ★ QUASILINEAR if coeffs of k -th order derivatives are functions of up to the $k-1$ -th derivatives
 - ★ FULLY NONLINEAR if not quasilinear

- examples:
- Laplace (2D) $u_{xx} + u_{yy} = 0$ linear
 - inviscid Burgers : $u_t + uu_x = 0$ quasilinear
 - KdV : $u_t + uu_x + u_{xxx} = 0$ semilinear

- Monge-Ampère : $u_{xx} u_{yy} - (u_{xy})^2 = 0$ fully nonlinear

This course: mostly linear (but not only)

motivation:

- important ubiquitous ideas
- process of linearization

\leftarrow

nonlinear

example: (LT) $F(u) = \frac{\partial u}{\partial t} - \nabla \cdot (\alpha(u) \nabla u) - f(u) = 0$

in 1D $u_t - (\alpha(u) u')^l - f(u) = 0$

- linearization Picard iteration:

- Fix u^0
 - $\forall k \geq 0$, solve $\frac{\partial u^{k+1}}{\partial t} - \nabla \cdot (\alpha(u^k) u^{k+1}) - f(u^k) = 0$
- linear!

- Newton iteration:

- Fix u^0
- define $u^{k+1} = u^k + \delta u^k$ where u^k solves linear PDE:

$$F'(u^k) \delta u^k = -F(u^k)$$

$$(u^{k+1} = u^k - \frac{f(u^k)}{F'(u^k)})$$

- $\frac{\partial u^{k+1}}{\partial t} = \frac{\partial u^k}{\partial t} + \frac{\partial \delta u^k}{\partial t}$

- $-f(u^{k+1}) \approx -f(u^k) - F'(u^k) \delta u^k$

$$\bullet \quad \varrho(u^{k+1}) \approx \varrho(u^k) + \varrho'(u^k) \delta u^k$$

$$\nabla \cdot \varrho(u^{k+1}) \nabla u^{k+1} \approx -(\varrho(u^k) + \varrho'(u^k) \delta u^k) (\nabla u^k + \nabla \delta u^k)$$

$$= -\varrho(u^k) \nabla u^k - \varrho(u^k) \nabla \delta u^k - \varrho'(u^k) \delta u^k (\nabla u^k + \nabla \delta u^k)$$

higher-order

$$\parallel F(u^k)$$

$$\frac{\delta u^k}{\delta t} = \nabla \cdot (\varrho(u^k) \nabla \delta u^k) - \nabla \cdot (\varrho'(u^k) (\delta u^k) \nabla u^k)$$

$$- f'(u^k) \delta u^k = F(u^k)$$

$$= F'(u^k) \delta u^k$$

LINEAR PDEs OF 1st AND 2nd ORDER

① transport equation

$$\text{ex: } u_x + u_y = 0$$

can be solved by "method of characteristics"

$$\begin{cases} \xi = x + \gamma \\ \gamma = y - x \end{cases} \quad v(\xi, \gamma) = u(x(\xi, \gamma), y(\xi, \gamma))$$

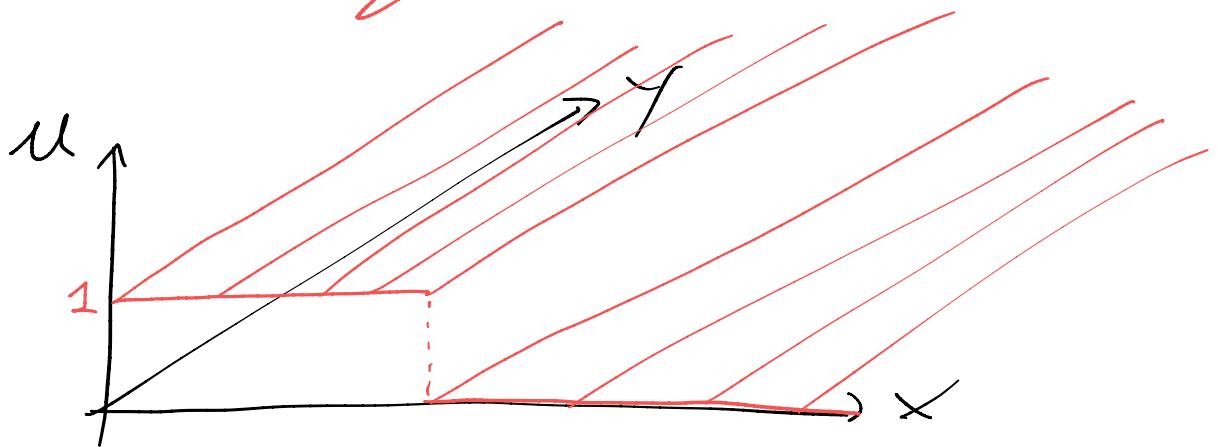
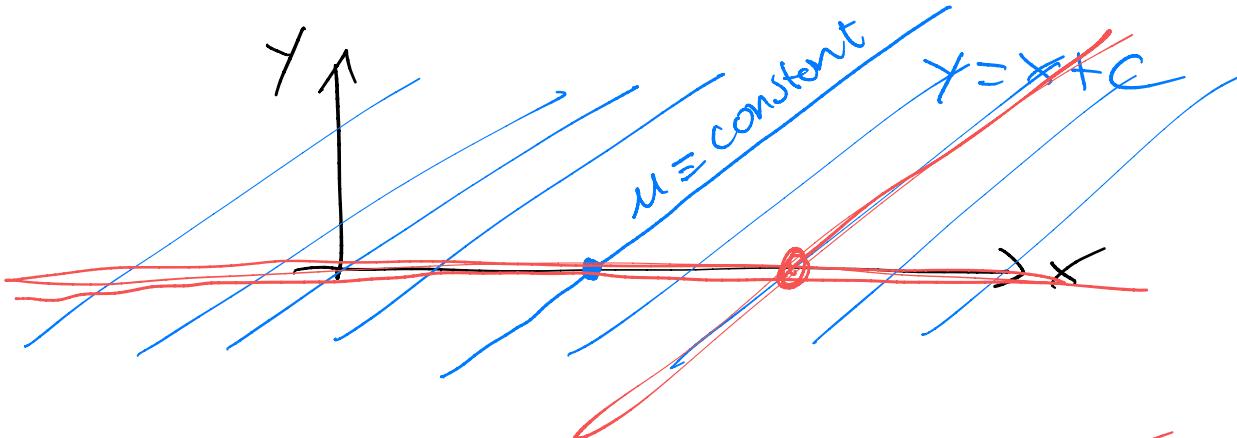
$$\downarrow \quad v_\xi = 0 \quad \xrightarrow{\text{integrate}} \quad v(\xi, \gamma) = f(\gamma)$$

$$u(x, y) = f(\gamma(x, y)) = f(y - x)$$

u is constant \leftarrow for \parallel

$$Y - X = C$$

Characteristics of the PDE



Note that the "red function" satisfies the PDE. In particular this function is discontinuous across some characteristics

More in general, take $a, b, c, f : \mathbb{R}^2 \rightarrow \mathbb{R}$, $a, b \in C^1(\mathbb{R}^2)$

$$\nabla \cdot \begin{pmatrix} a & b \\ f & 0 \end{pmatrix} = 0$$

$$a(x, y) u_x + b(x, y) u_y + c(x, y) u = f(x, y) \quad \text{in } \mathbb{R}^2$$

As before can we method of charact.

① characteristic curves $\gamma^{y=y(x)}$: solution of

$$-a \frac{dy}{dx} + b = 0$$

② Second order linear PDEs in \mathbb{R}^2

$a, b, c, d, e, f, g: \Omega \rightarrow \mathbb{R}, \Omega = \mathbb{R}^2$

$$a u_{xx} + 2b u_{xy} + c u_{yy} + du_x + eu_y + fu = g$$

class of 2nd order linear PDEs

Def (Discriminant): $D = D(\underline{x}) = b^2 - ac$ is the DISCRIMINANT of the 2nd order PDE.

- $D > 0$ at \underline{x} , the PDE is hyperbolic at \underline{x}
- $D = 0$ " , " parabolic "
- $D < 0$ " , " elliptic "

The PDE is said hyperbolic, etc if it is such in the Whole of Ω .

note: lower order terms are irrelevant for this characterisation of 2nd order PDEs.

- examples:
- hyperbolic: $u_{tt} + cu_{xx} = 0$ ($c < 0$) wave eq.
 - parabolic: $u_t + \alpha u_{xx} = 0$ ($\alpha < 0$) heat (or diffusion) eq.
 - elliptic: $\underbrace{u_{xx} + u_{yy}}_{\Delta u} = 0$ Laplace eq.

"Physically" these examples reflect the general character of each class:

- elliptic eq. \rightarrow time indep
- parabolic eq. \rightarrow time-dep diffusion phenomena

- hyperbolic eq. \rightarrow transport wave-like phenomena with finite speed propagation.

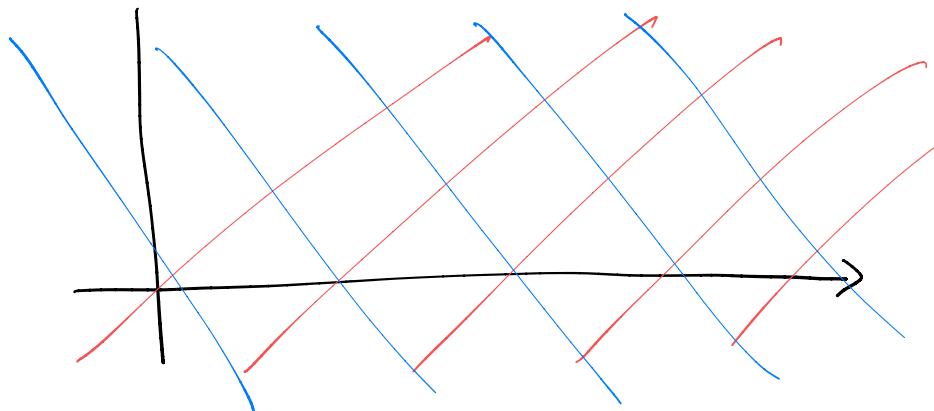
Theorem: (invariance of type): The sign D of a 2nd order linear PDE is invariant under smooth non-singular transformation of coordinates (change of variables).

example: $u_{xx} - u_{yy} = 0$

$$\begin{cases} \xi = x + y \\ \eta = y - x \end{cases} \rightarrow \nabla_{\xi\eta} = 0 \rightarrow \nabla(\xi, \eta) = F(\xi) + G(\eta)$$

$\forall F, G \in C^2(\mathbb{R})$

$$\rightarrow u(x, y) = \underbrace{F(x+y)}_{C_1 \in \mathbb{R}} + \underbrace{G(y-x)}_{C_2 \in \mathbb{R}}$$



these two families of characteristic curves are found in the solution of ODE

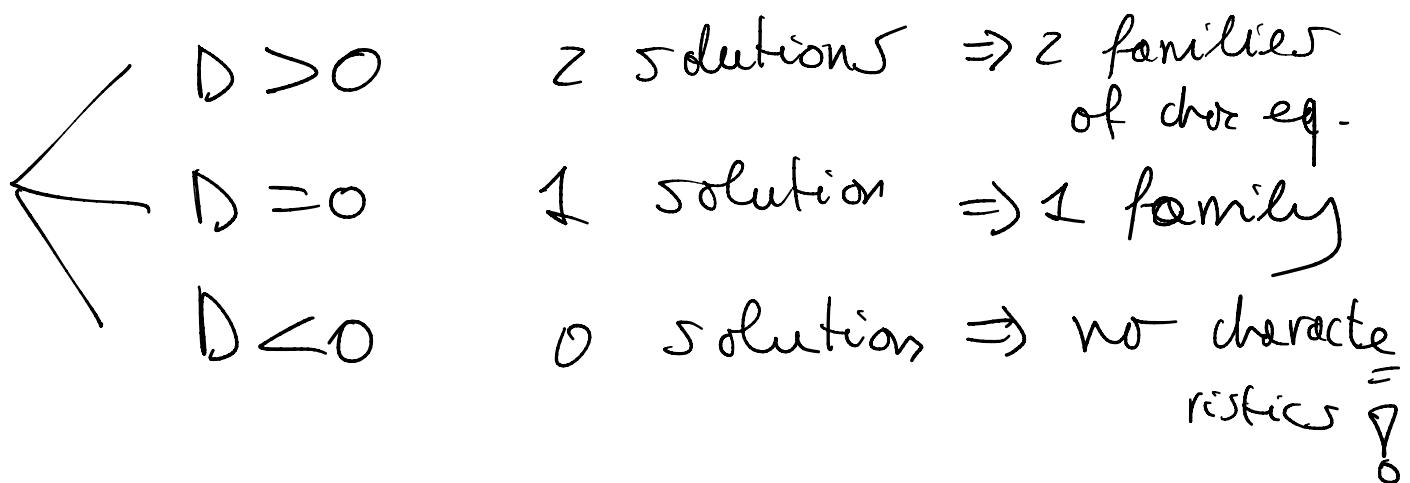
$$\frac{dy}{dx} = \frac{b \pm \sqrt{D}}{a} = \pm 1 \quad (a=1, b=0, c=-1)$$

In general, for $a u_{xx} + 2bu_{xy} + cu_{yy} + \dots = 0$, we get the characteristic eq.

$$a \left(\frac{dy}{dx} \right)^2 + b \frac{dy}{dx} + c = 0$$

→ with roots

$$\frac{dy}{dx} = \frac{-b \pm \sqrt{D}}{2a}$$



Remark: all this still valid for semi-linear PDEs?

Now, let's "fix the constants".

Def (Cauchy Problem): Let $F(x, u, \dots) = 0$ given PDE of order k .

Let S be a surface in \mathbb{R}^d , $n=n(x)$ its normal.

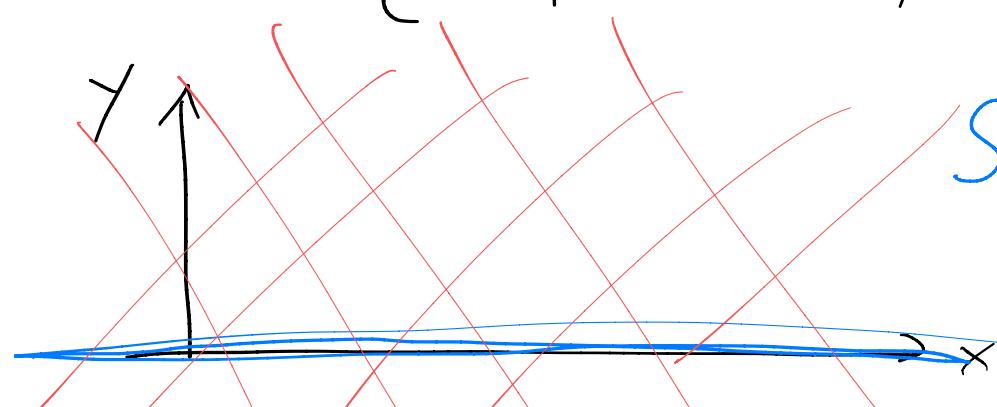
and suppose that $\forall x \in S$, the "INITIAL CONDITIONS"

$$u(x) = f_0(x), \frac{\partial u}{\partial n}(x) = f_1(x), \dots, \frac{\partial^{k-1} u}{\partial n^{k-1}}(x) = f_{k-1}(x)$$

are given. The Cauchy problem: find the solutions of the PDE satisfying the I.C.

example: $\begin{cases} u_{xx} - u_{yy} = 0 \\ u(x, 0) = \sin x; u_y(x, 0) = 0 \end{cases}$

Cauchy
Pbm



$$S = \{(x, y) : y=0\}$$

solution: take gen. sol. $u(x, y) = F(x+y) + G(y-x)$

apply the I.C., gives

$$u(x, y) = \frac{1}{2} (\sin(x+y) + \sin(x-y))$$

∴ solution of the Cauchy problem!

Theorem (Cauchy-Kovalevskaya):

Given 2nd order linear PDE and an initial surface S with initial data f_i , and given $x_0 \in S$. Suppose that:

- S is analytic
- S is not a characteristic surface at x_0
- data all analytic (coeffs, f_i)

Then, Cauchy problem has a solution in a neighbourhood of x_0 (local result!)

which is analytic.

Comments

- * general but "limited" to analytic data
- * gives a result about $\exists!$, this does not imply that the solution is "well behaved"

Def: A PDE problem is WELL POSED in the sense of Hadamard if

- it has a unique solution
- the solution depends continuously on the PDE coeffs and the problem's data

see provided example for Laplace eq. showing $\exists!$ of a Cauchy problem for which a small perturbation of data \Rightarrow exponentially large change in solution !

\rightsquigarrow Cauchy problem "wrong" for Laplace !

Why numerical methods?

- Theory of PDEs: study of well-posedness of PDE problems, rarely can write down the solutions
- Numerical methods look for approximate solutions that can be computed in practice

(Quarteroni), sol data

Let $P(u, g) = 0$ be a PDE problem

$$P_N(u_N, g_N) = 0$$

dimension of discrete problem

Def: A numerical method $P_N(u_N, g_N)$ is

* CONVERGENT: if $\|u - u_N\| \xrightarrow{N \rightarrow \infty} 0$
↑ some norm

* CONSISTENT: if $P_N(u, g) \xrightarrow{N \rightarrow +\infty} 0$

STRONGLY CONSISTENT $P_N(u, g) = 0 \forall N$

* STABLE: if small perturbations in

δ_H results in small perturbation in resulting numerical solution

$$S_0 - \delta_H \rightarrow S_H + \delta S_H$$

so
where $P_H(\underbrace{u_H + \delta u_H}_{\in \mathcal{E}}, S_H + \delta S_H) = 0$

$$\forall \epsilon > 0 \exists \delta \in \mathcal{E} : \text{ if } \| \delta S_H \| < \epsilon$$

$$\text{then } \| \delta u_H \| \leq \epsilon \quad \forall H.$$

Theorem (Lax-Richtmyer equivalence) :

Consistency + Stability \Rightarrow convergent