**Senza filtrare le misure (con d = 10cm e inizioPruning = 200)**

Errore assoluto finale stima landmark [cm]:

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | Tag 1 | Tag 2 | Tag 3 | Tag 4 |
| Robot 1 | 14 | 17 | 24 | **16** |
| Robot 2 | 122 | 220 | 245 | 251 |
| Robot 3 | 58 | 45 | 83 | 131 |
| Insieme | **8** | **9** | **12** | 22 |

Distanze robot-landmark [cm]

|  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | R1-L1 | R1-L2 | R1-L3 | R1-L4 | R2-L1 | R2-L2 | R2-L3 | R2-L4 | R3-L1 | R3-L2 | R3-L3 | R3-L4 |
| R1 | 106 | 233 | **320** | 253 |  |  |  |  |  |  |  |  |
| R2 |  |  |  |  | **204** | 192 | 189 | 231 |  |  |  |  |
| R3 |  |  |  |  |  |  |  |  | **252** | 247 | 136 | 155 |
| Tutti | **119** | **229** | 305 | **254** | 199 | **194** | **192** | **214** | 241 | **249** | **153** | **160** |
| **GT** | **114** | **227** | **320** | **259** | **205** | **201** | **202** | **221** | **259** | **259** | **152** | **168** |

Distanze tra i robot [cm]

|  |  |  |  |
| --- | --- | --- | --- |
|  | R1-R2 | R1-R3 | R2-R3 |
| Stima | 134 | 153 | 55 |
| **GT** | **135** | **170** | **61** |