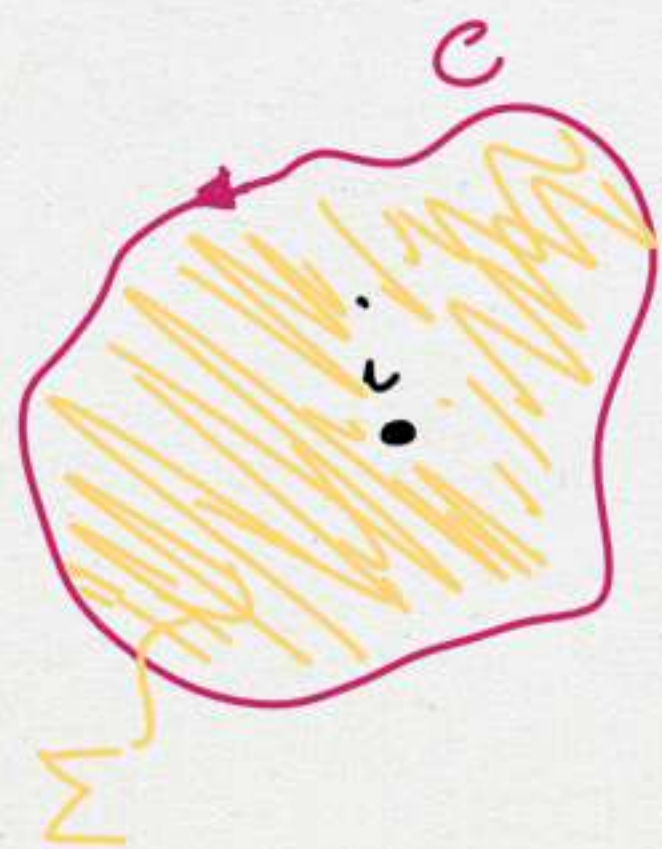


$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 \sum_K i_K$$

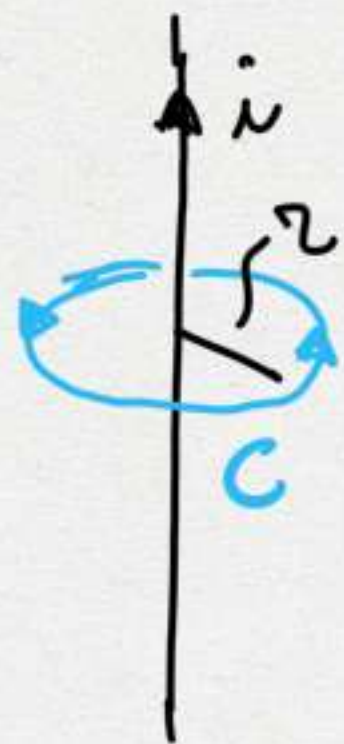


$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 i = \mu_0 \int_{\Sigma} \vec{j} \cdot \hat{n} d\Sigma$$

$$\oint_C \vec{B} \cdot d\vec{s} \underset{\substack{\uparrow \\ \text{STOKES}}}{=} \int_{\Sigma(C)} \overbrace{\vec{\nabla} \times \vec{B}}^{\vec{j}} \cdot \hat{n} d\Sigma = \int_{\Sigma(C)} \overbrace{\mu_0 \vec{j}}^{\vec{j}} \cdot \hat{n} d\Sigma \Rightarrow$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{j}$$

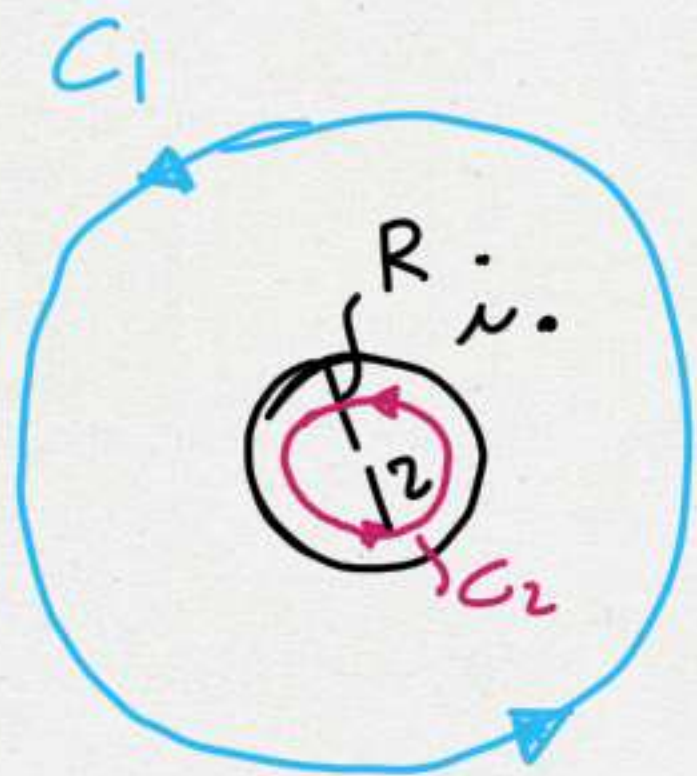
$$\vec{\nabla} \times \vec{E} = 0$$



$$\vec{B}(\vec{r}) = \frac{\mu_0 i}{2\pi r} \hat{\varphi}$$

$$\oint_C \vec{B} \cdot d\vec{s} = \oint_C B ds = B \oint_C ds = B 2\pi r = \mu_0 i \Rightarrow$$

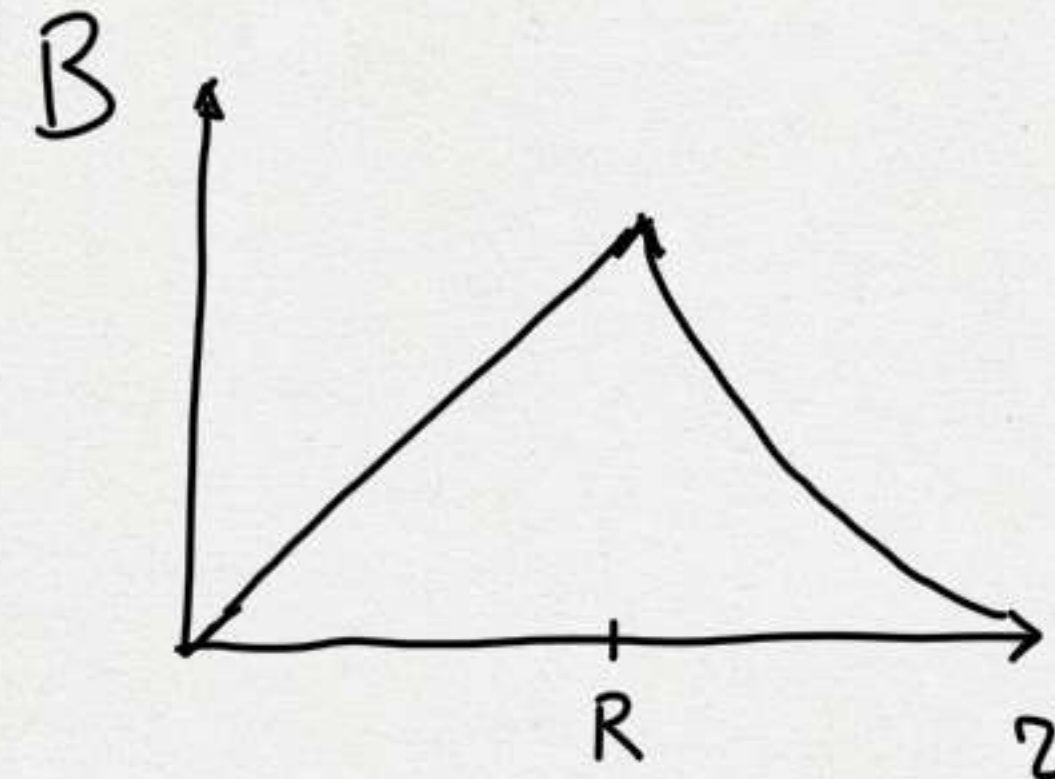
$$B = \frac{\mu_0 i}{2\pi r} \quad \text{LEGGE DI BIOT-SAVART}$$

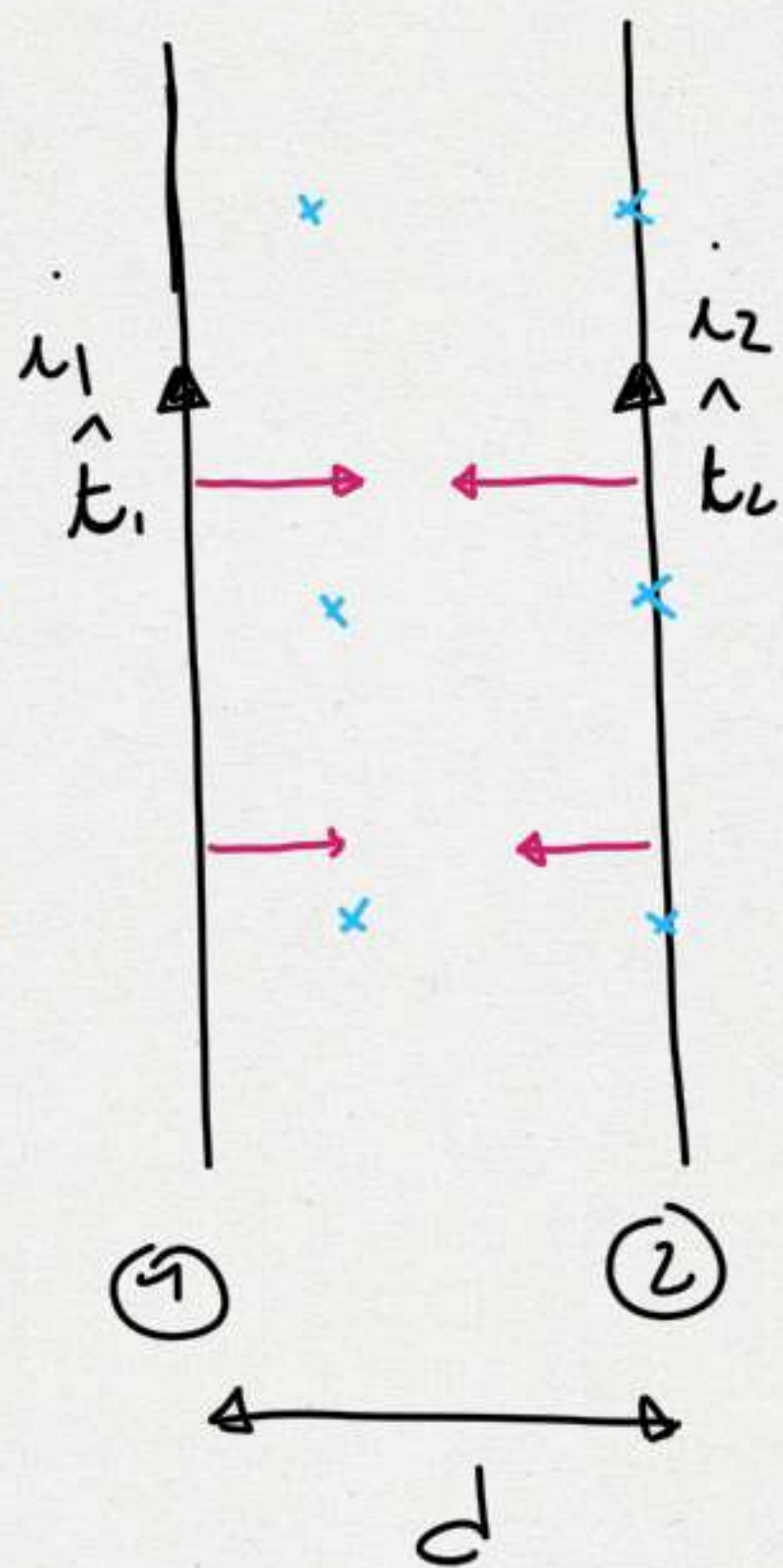


$$\oint_{C_1} \vec{B} \cdot d\vec{s} = \mu_0 i \Rightarrow B(r > R) = \frac{\mu_0 i}{2\pi r}$$

$$J = \frac{i}{\Sigma} = \frac{i}{\pi R^2}, \quad i(r) = J \Sigma(r) = J \pi r^2 = \frac{i r^2}{R^2} \Rightarrow$$

$$B 2\pi r = \mu_0 \left(\frac{i r^2}{R^2} \right) \Rightarrow B(r < R) = \frac{\mu_0 i r}{2\pi R^2}$$



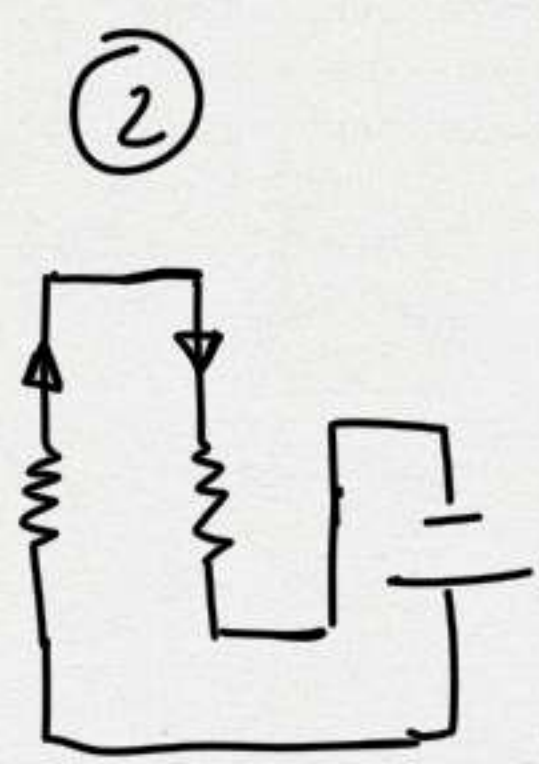
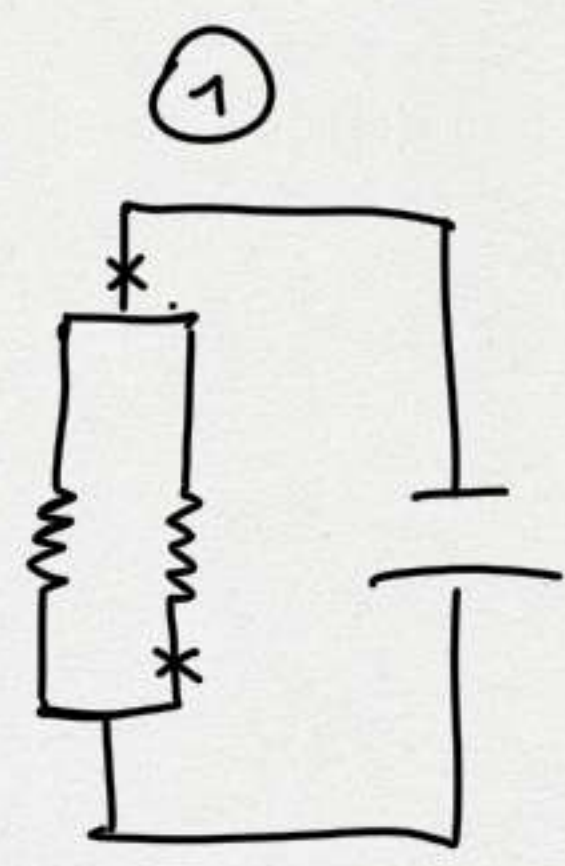


$$d\vec{F} = i d\vec{l} \times \vec{B} = i dl \hat{t} \times \vec{B}$$

$$d\vec{F}_{12} = i_2 dl_2 \hat{t}_2 \times \vec{B}_1$$

$$\vec{f}_{12} \equiv \frac{d\vec{F}_{12}}{dl} = i_2 \hat{t}_2 \times \vec{B}_1, \quad f_{12} = i_2 B_1 = \frac{\mu_0 i_1 i_2}{2\pi d}$$

$$f_{21} = i_1 B_2 = \frac{\mu_0 i_2 i_1}{2\pi d}$$

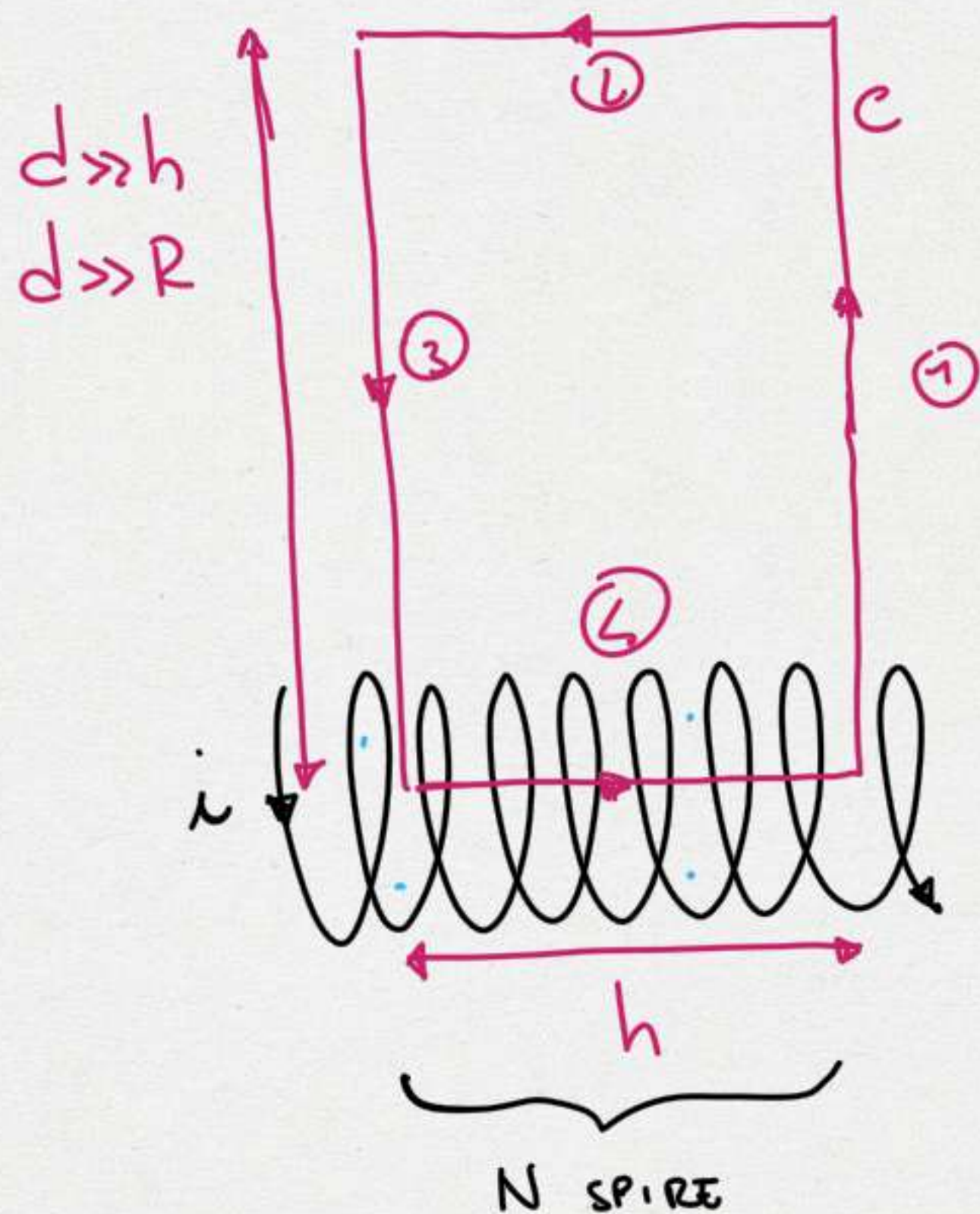


SOLENOID \vec{E}



$$\oint_C \vec{B} \cdot d\vec{s} = \int_{(1)} + \int_{(2)} + \int_{(3)} + \int_{(4)} = \cancel{\int_{(1)}} + \cancel{\int_{(3)}} + \int_{(4)} =$$

$$= \int_{(4)} \vec{B} \cdot d\vec{s} = B \int_{(4)} ds = Bh$$

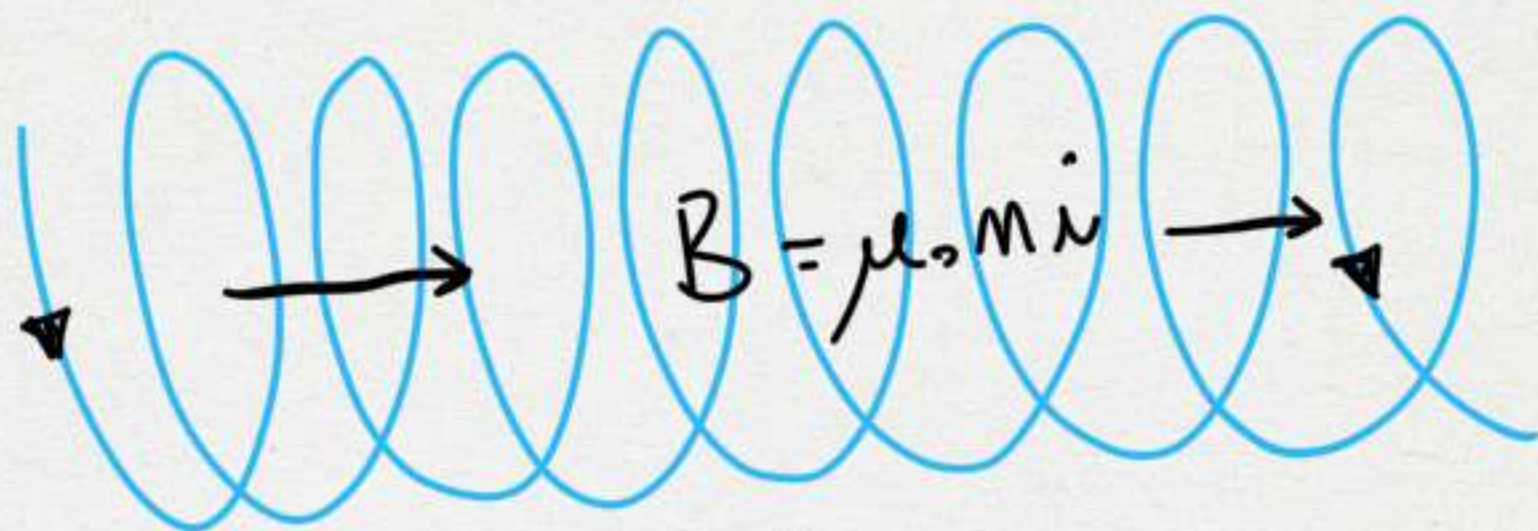


$$\mu_0 \sum_k i_k = \mu_0 N i \Rightarrow$$

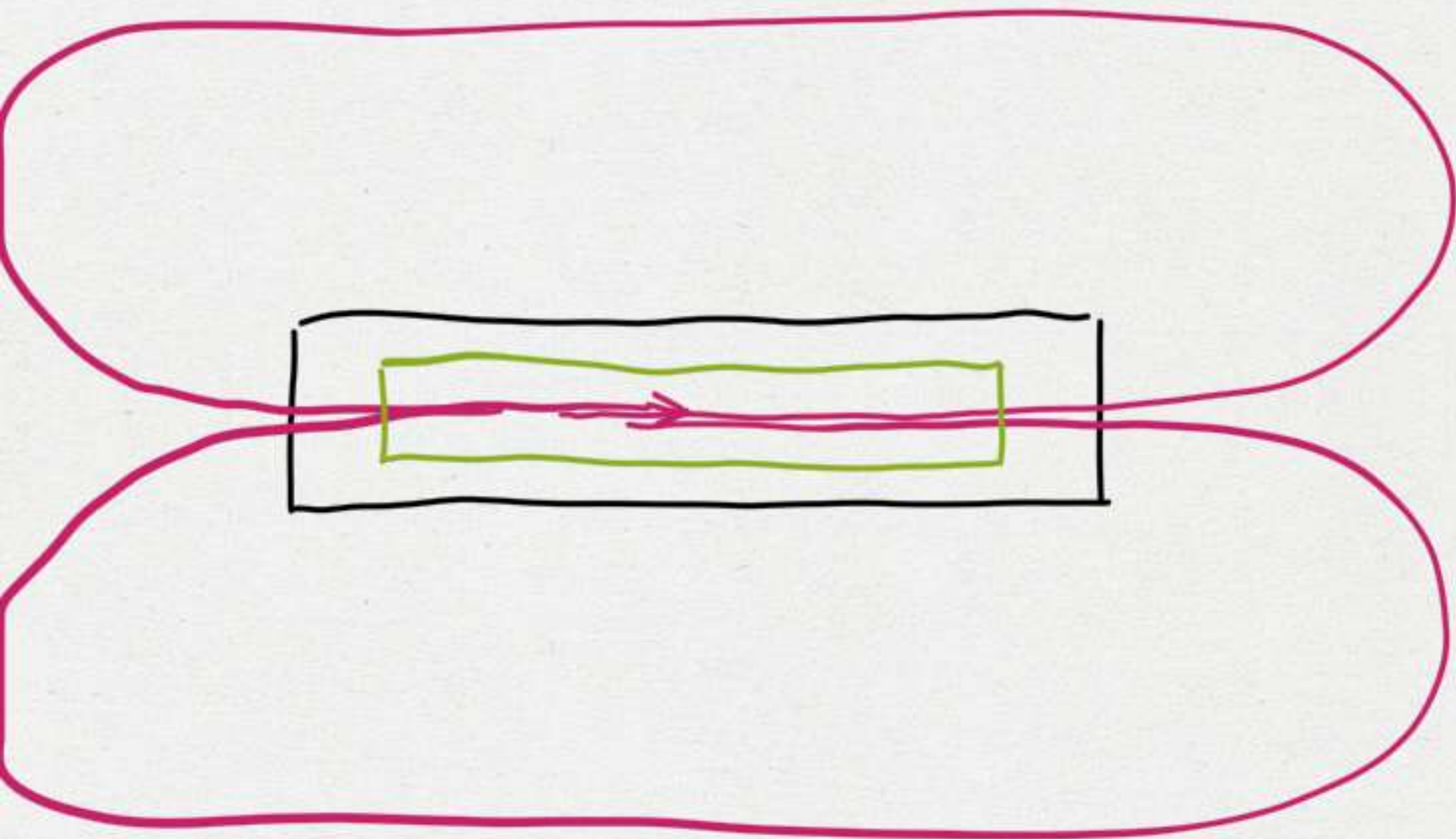
$$[m] = \frac{1}{m}$$

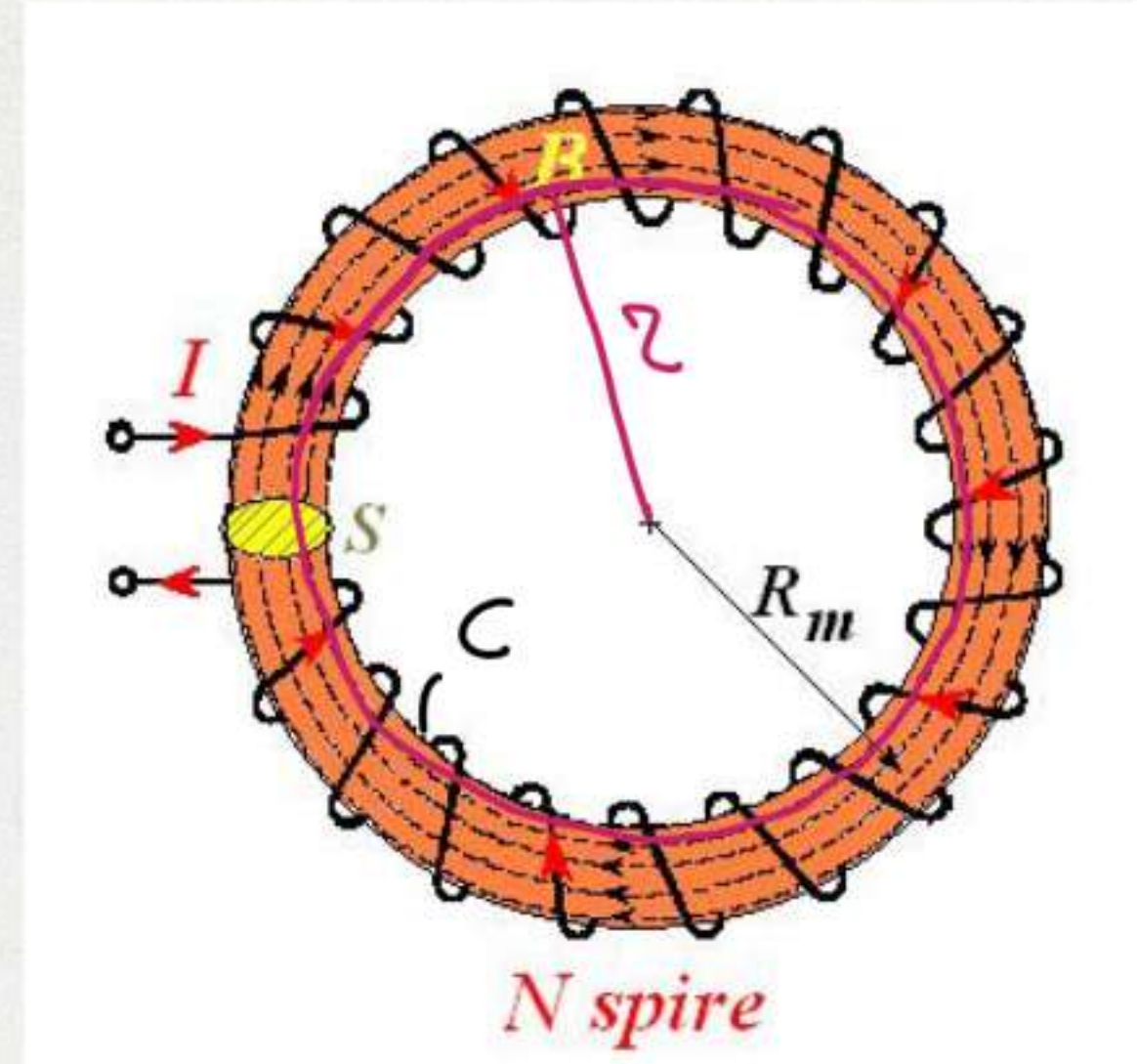
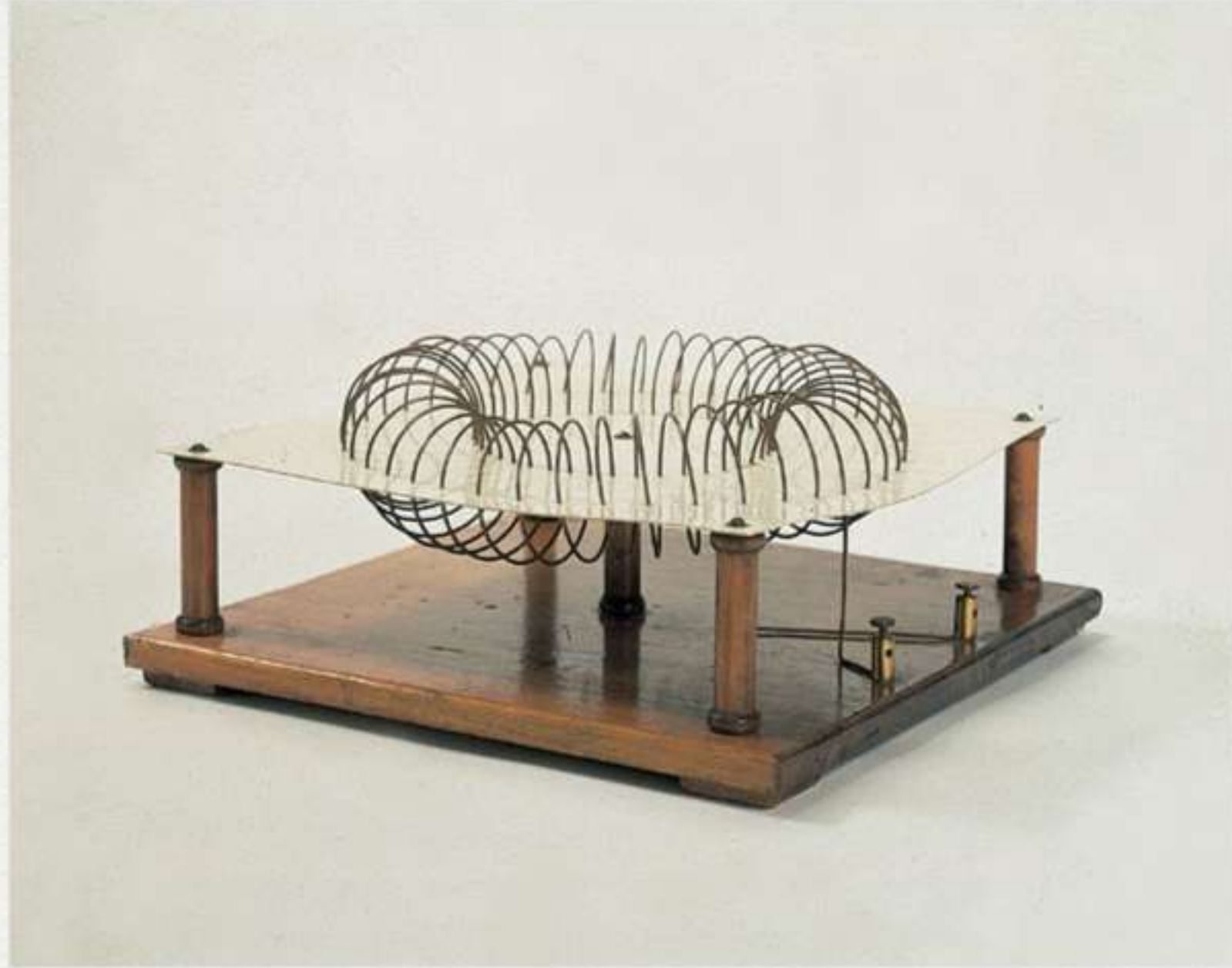
$$B = \frac{\mu_0 N i}{h} \equiv \mu_0 n i$$

$$\vec{B} = 0$$



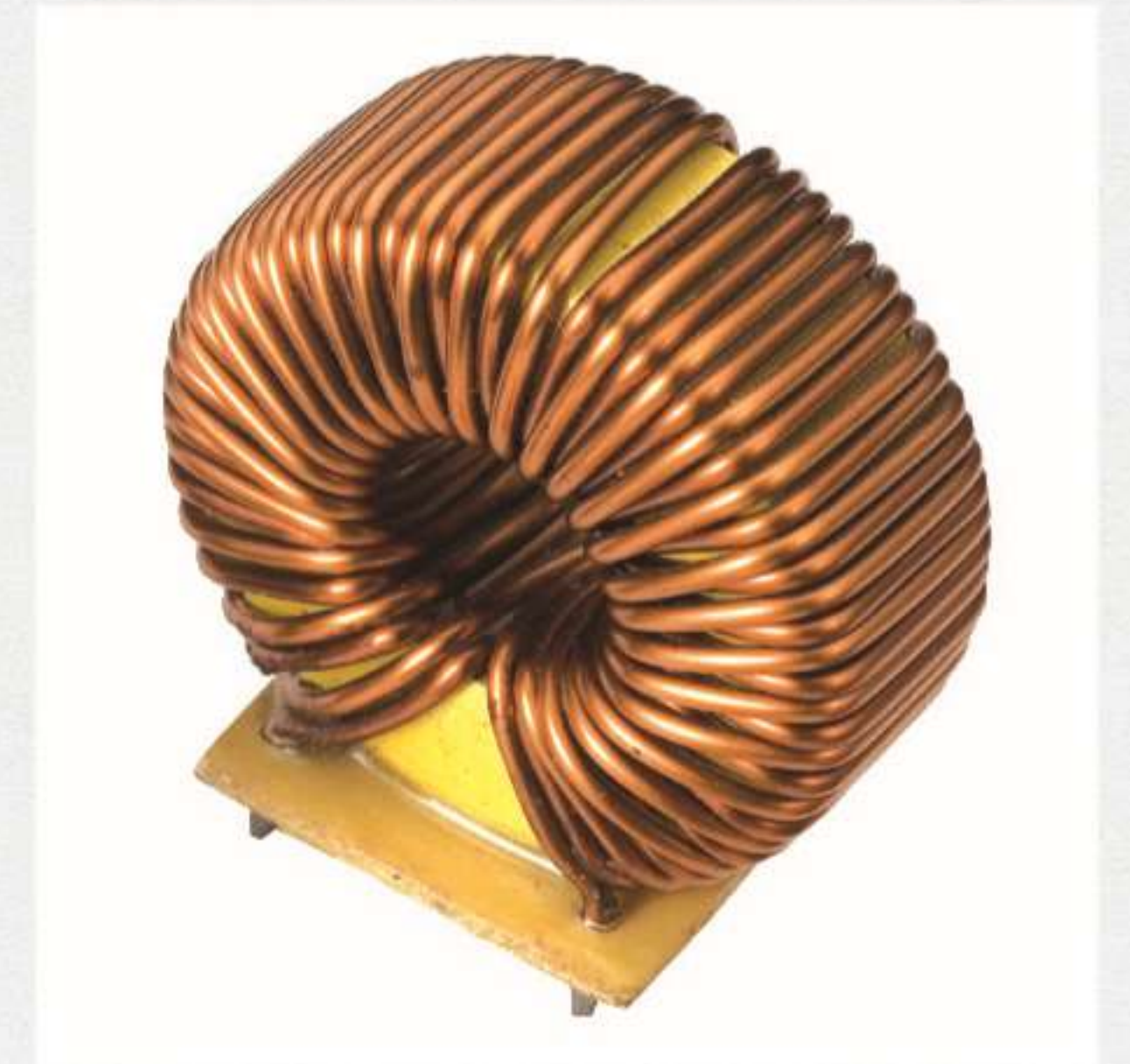
$$\vec{B} = 0$$

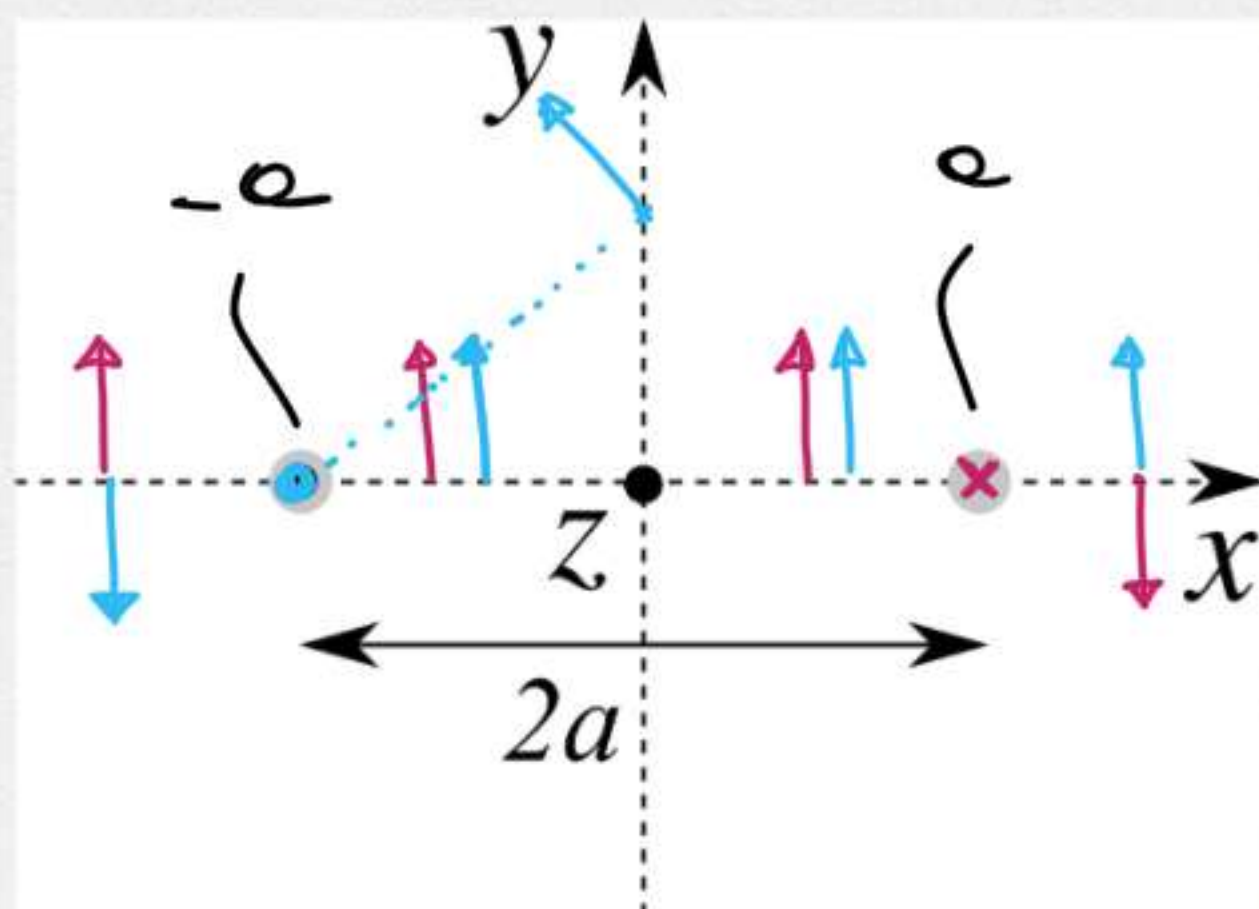




N SPIRE

$$\oint_c \vec{B} \cdot d\vec{s} = B \oint_c ds = B 2\pi r = \mu_0 N i \Rightarrow B = \frac{\mu_0 N i}{2\pi r}$$





① CALCOLARE $\vec{B}(x, 0, 0)$

② CALCOLARE $\vec{B}(0, y, 0)$

③ RIFARE I PUNTI ① E ② SE I FILI SONO EQUIVOCI

$$\vec{B} = \vec{B}_s + \vec{B}_o, \quad B(r) = \frac{\mu_0 i}{2\pi r}$$

$$r_s = x - (-a) = x + a$$

$$B_s = \frac{\mu_0 i}{2\pi |r_s|}, \quad \hat{B}_s = \hat{t} \times \hat{r}_s = \hat{t} \times \frac{\vec{r}_s}{r_s} = \pm \hat{y}$$

$$r_o = x - a$$

$$B_o = \frac{\mu_0 i}{2\pi |r_o|}, \quad \hat{B}_o = \hat{t} \times \hat{r}_o = \hat{t} \times \frac{\vec{r}_o}{r_o} = \pm \hat{y}$$

$$\vec{B}_s = \frac{\mu_0 i}{2\pi} \frac{\hat{y}}{x+a}$$

$$\vec{B}_o = -\frac{\mu_0 i}{2\pi} \frac{\hat{y}}{x-a}$$

$$\begin{aligned} \vec{B}_{\text{TOT}} &= \vec{B}_s + \vec{B}_o = \vec{B}_{\text{TOT}}(x, 0, 0) = \\ &= \frac{\mu_0 i \hat{y}}{2\pi} \left(\frac{1}{x+a} - \frac{1}{x-a} \right) \end{aligned}$$