

$$v_0 t^* = l \Rightarrow t^* = \frac{l}{v_0}$$

$$y(t) = \frac{1}{2} a t^2$$

$$d = y(t^*) = \frac{1}{2} a t^{*2} = \frac{1}{2} \left(\frac{eE}{m} \right) \left(\frac{l}{v_0} \right)^2$$

$$\Delta U_k = U_k(d) - U_k(0) = -\Delta U_e = +e \Delta V =$$

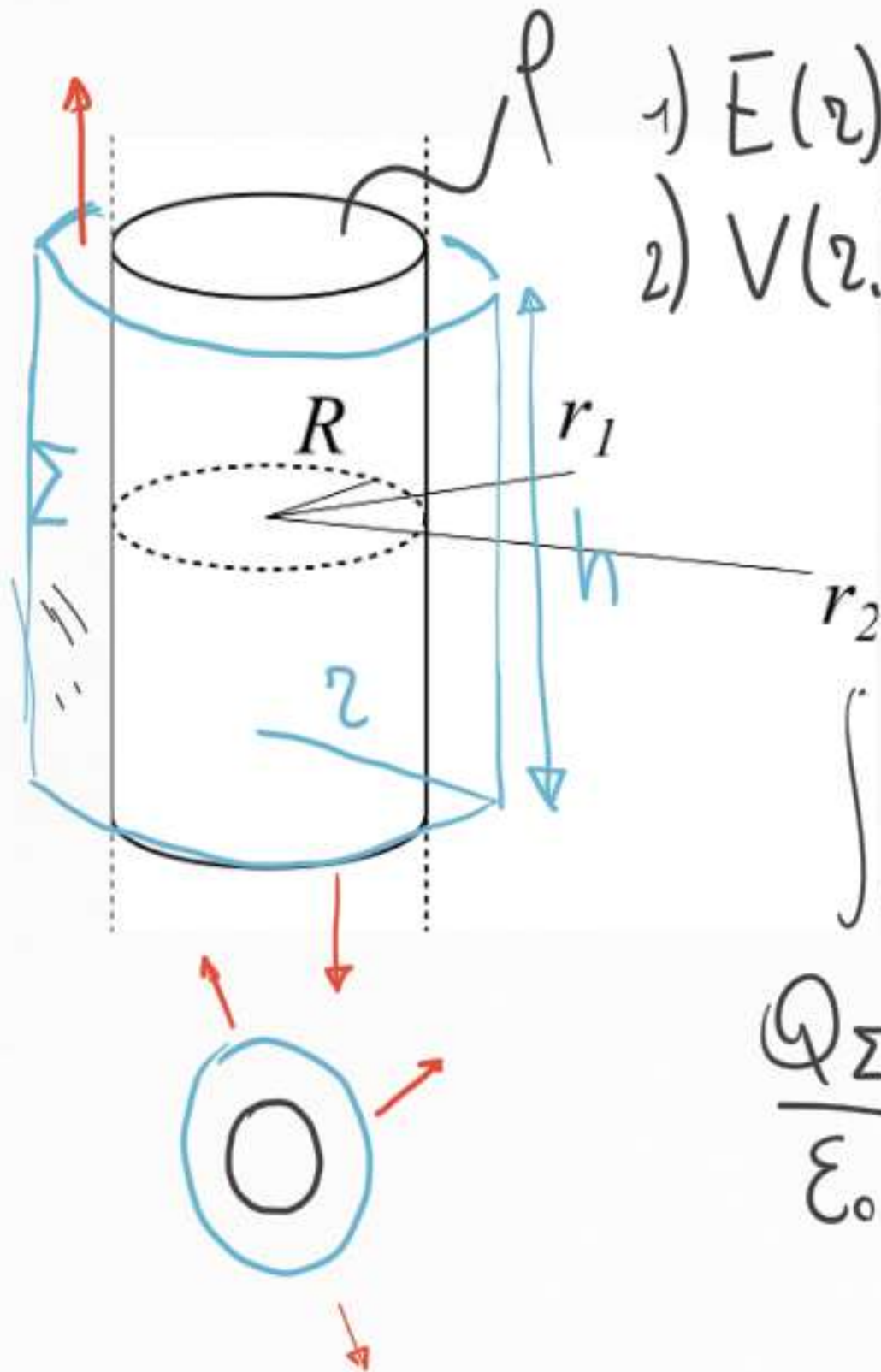
$$= \frac{1}{2} m v(t^*)^2 - \frac{1}{2} m v(0)^2 = \frac{1}{2} m (v(t^*))^2 - \frac{1}{2} m v_0^2 =$$

$$= \frac{1}{2} m v_x(t^*)^2 = \frac{1}{2} m a t^{*2} = \frac{1}{2} \frac{eE}{m} \frac{l}{v_0} m = \frac{1}{2} eE \frac{l}{v_0}$$

$$\int_{\tau} \bar{F} d\tau = \int_{\tau} \bar{F} dx dy dz = \int_{\tau} \bar{F}(r, \theta, \varphi) \underbrace{r^2 \sin \theta dr d\theta d\varphi}_{\substack{\uparrow \\ r}} =$$

$$= \int_0^R \bar{F}(r) 4\pi r^2 dr$$

$$\int_{\Sigma} G(x, y) dx dy = \int_{\Sigma} G(r, \theta) r dr d\theta = \boxed{\int_{\Sigma} G(r) 2\pi r dr}$$



- 1) $\vec{E}(r) = ? \quad r > R$
- 2) $V(r_1) - V(r_2) = ?$

$$\int_{\Sigma} \vec{E} \cdot \hat{n} d\Sigma = \frac{Q_{\Sigma}}{\epsilon_0} \Rightarrow$$

$$\int_{\Sigma} \vec{E}(r) d\Sigma = E(r) \int_{\Sigma} d\Sigma = E(r) 2\pi r h$$

$$\frac{Q_{\Sigma}}{\epsilon_0} = \frac{1}{\epsilon_0} \int_{\tau_2} \rho d\tau = \frac{\rho}{\epsilon_0} \int_{\tau_2} d\tau = \frac{\rho}{\epsilon_0} \pi R^2 h \Rightarrow$$

$$\bar{E}(r) = \frac{\rho R^2}{2\epsilon_0 r}, \quad \lambda = \rho \pi R^2 \Rightarrow$$

$$\boxed{\bar{E}(r) = \frac{\lambda}{2\pi\epsilon_0 r}}$$

$$2) V(r_1) - V(r_2) = - \int_{r_2}^{r_1} \bar{E}(r) dr = - \frac{\rho R^2}{2\epsilon_0} \int_{r_2}^{r_1} \frac{dr}{r} =$$

$$= - \frac{\rho R^2}{2\epsilon_0} [\log r_1 - \log r_2] = \boxed{\frac{\rho R^2}{2\epsilon_0} \log \frac{r_2}{r_1}} \Rightarrow$$

$$Q = C \Delta V \Rightarrow C = \frac{Q}{\Delta V},$$

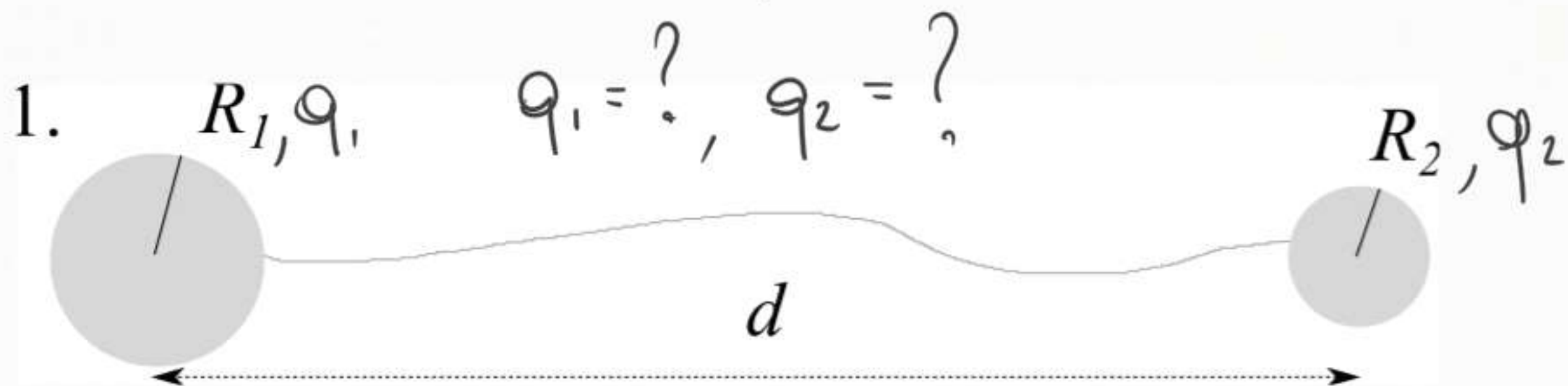
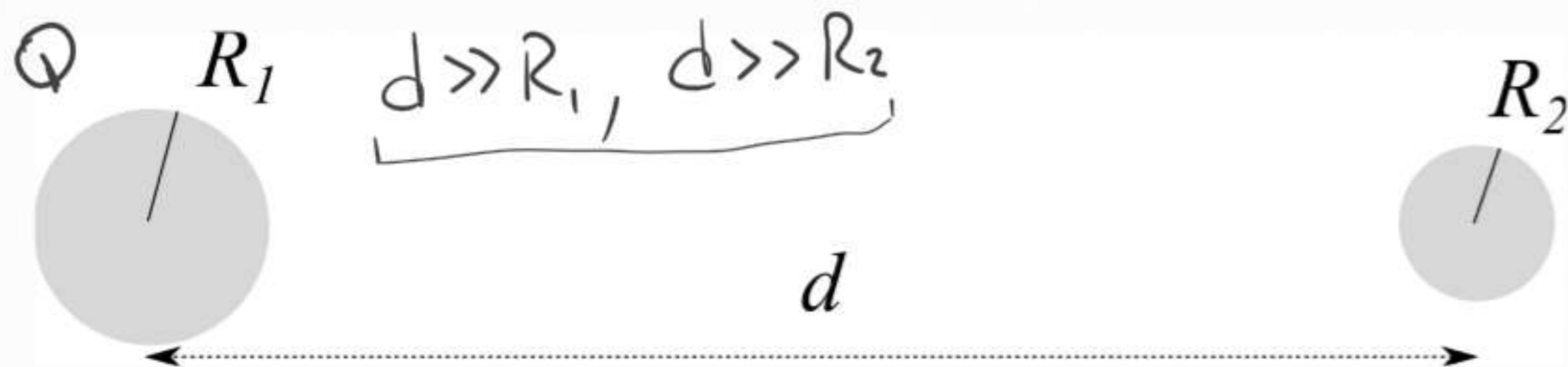
$$Q = \rho \pi R^2 h = \lambda h \Rightarrow$$

$$\Delta V = \frac{Q}{2\pi\epsilon_0 h} \log \frac{r_2}{r_1} \Rightarrow$$

$$C = \frac{Q}{\Delta V} = \frac{2\pi\epsilon_0 h}{\log\left(\frac{r_2}{r_1}\right)}$$

{ ESQNERO (DATA PAPA BILE)

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$$V(1) = V(2), \quad V(1) = \frac{q_1}{4\pi\epsilon_0 R_1} \Rightarrow$$

q_1, R_1



$$V(2) = \frac{q_2}{4\pi\epsilon_0 R_2}$$

$$\frac{q_1}{R_1} = \frac{q_2}{R_2}, \quad q_1 + q_2 = Q \Rightarrow$$

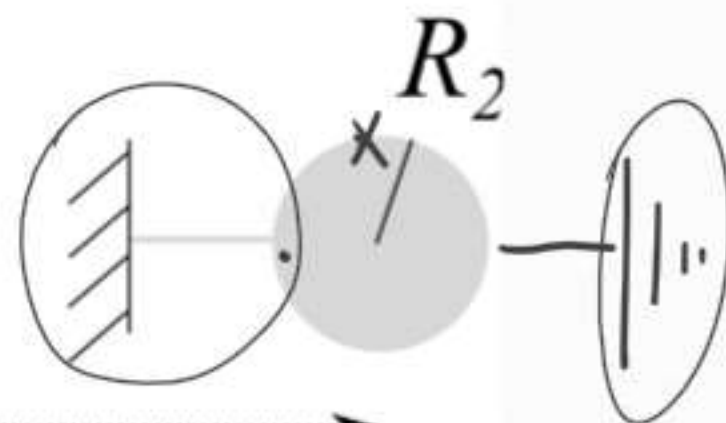
$$\frac{Q - q_2}{R_1} = \frac{q_2}{R_2} \Rightarrow q_2 \left(\frac{1}{R_2} + \frac{1}{R_1} \right) = \frac{Q}{R_1} \Rightarrow$$

$$q_2 = \frac{QR_2}{R_1 + R_2}, \quad q_1 = Q - q_2 = \frac{QR_1}{R_1 + R_2}$$

2. R_1, Q



d



$$V(2) = 0 \Rightarrow$$

$$V(2) = \frac{Q_2}{4\pi\epsilon_0 R_2} + \frac{Q}{4\pi\epsilon_0 (d-R_2)} \approx \frac{Q_2}{4\pi\epsilon_0 R_2} + \frac{Q}{4\pi\epsilon_0 d} = 0 \Rightarrow$$

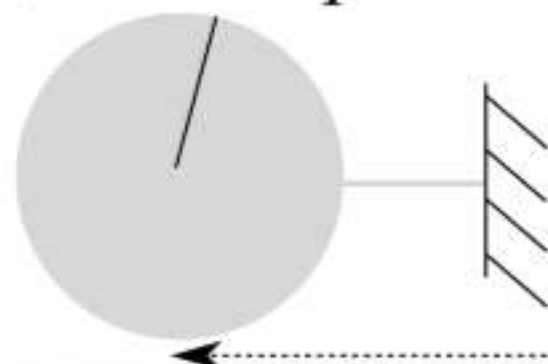
$$Q_2 = - \frac{QR_2}{d}$$

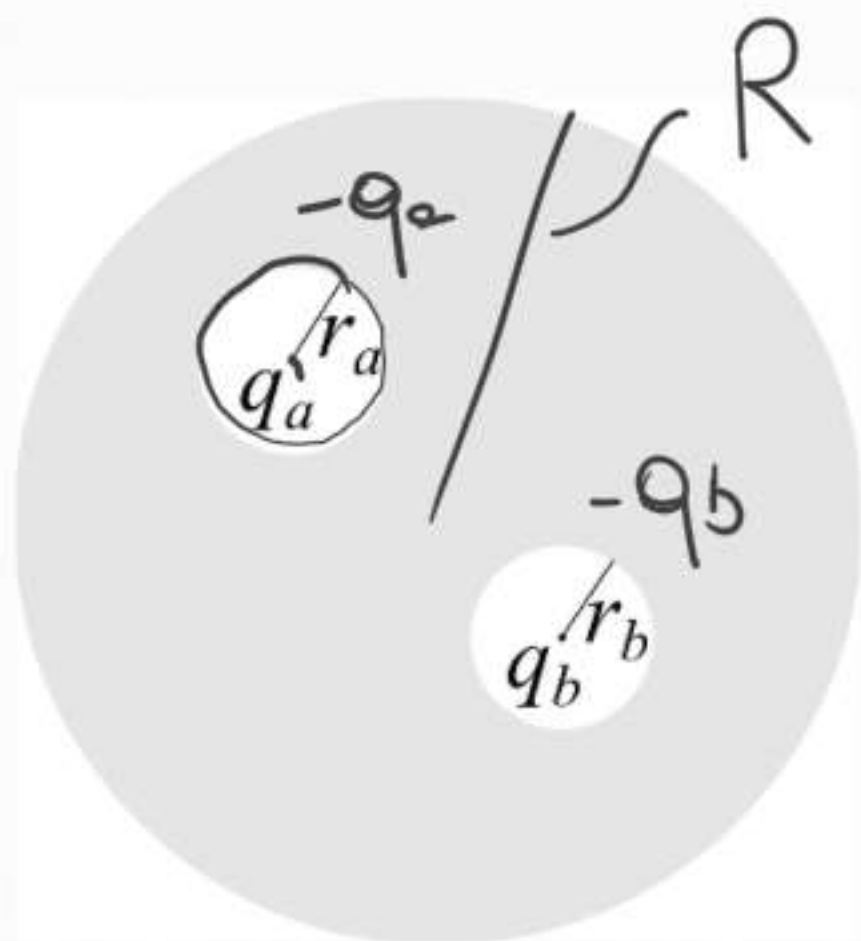
3.

R_1

R_2 Q_2

d





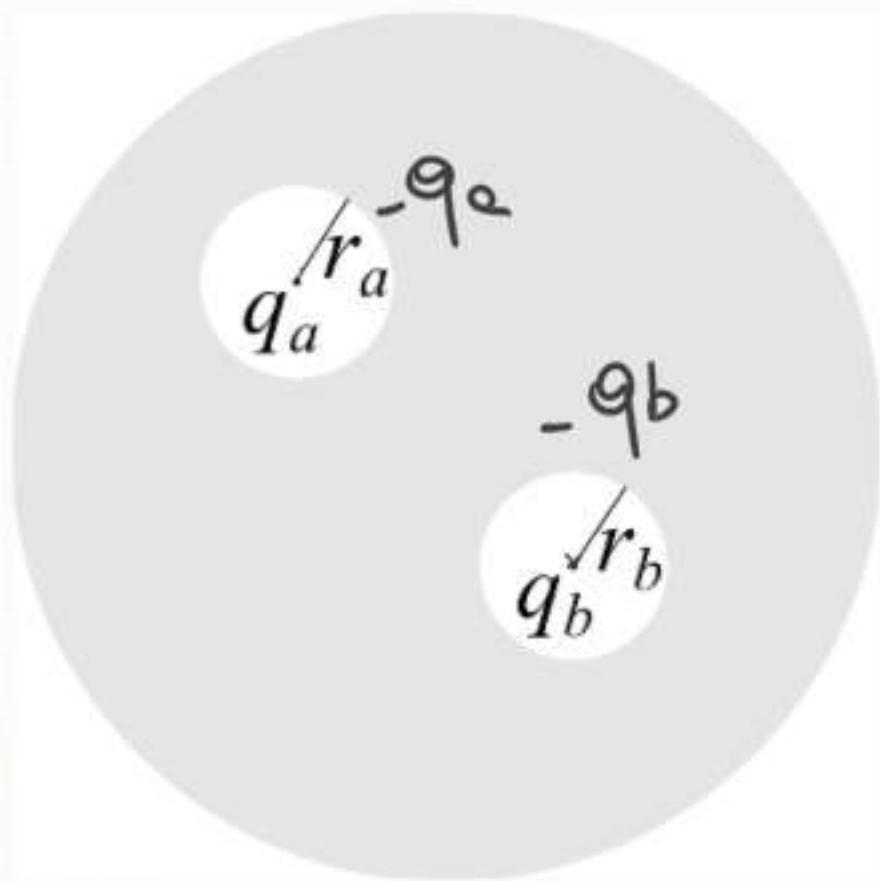
$$1) \sigma_R, \sigma_a, \sigma_b$$

$$2) \bar{E}(z), z > R$$

$$q_a + q_b$$

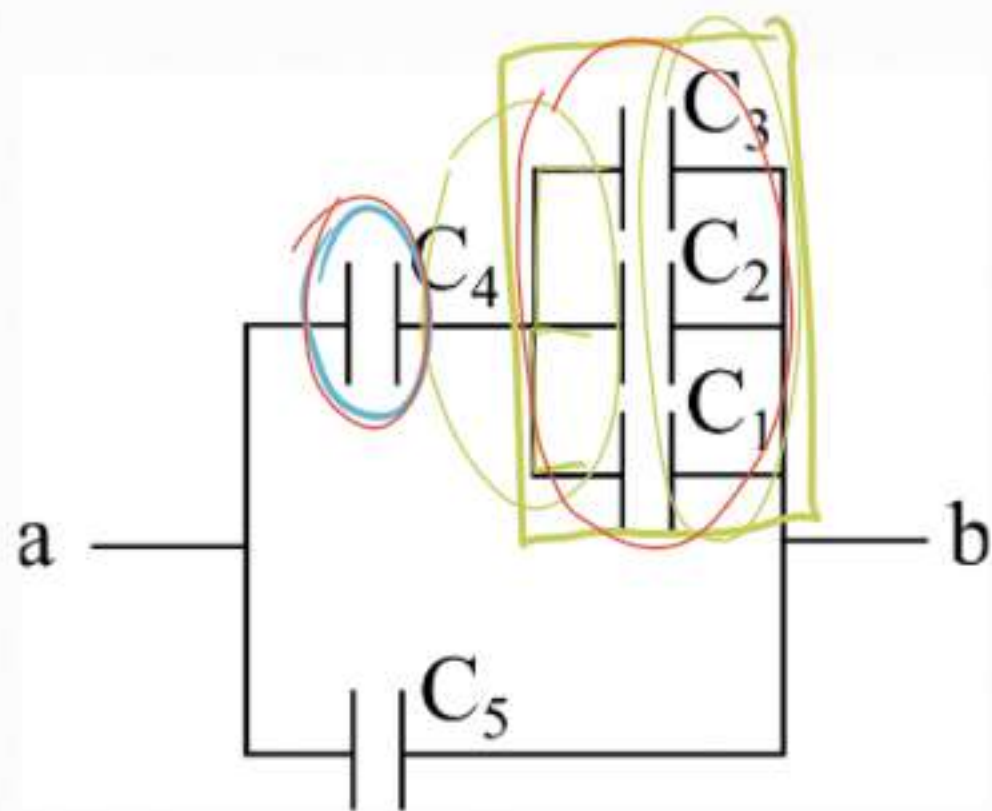
$$\sigma_R = \frac{q_a + q_b}{4\pi R^2}, \quad \sigma_a = -\frac{q_a}{4\pi r_a^2}, \quad \sigma_b = -\frac{q_b}{4\pi r_b^2}$$

$$\boxed{\bar{E}(z) = \frac{q_a + q_b}{4\pi \epsilon_0} \frac{1}{z^2}}$$



$$F_{eb} = ?$$

$$F = q_e E_e$$



$$\Delta V_{ab} = V(a) - V(b)$$

$$1) C_{eq} = ?$$

$$2) q_i, \Delta V_i, \quad i \in \{1, 2, 3, 4, 5\}$$

PARALLELO

$$C_{eq} = \sum_i C_i$$

SERIE

$$\frac{1}{C_{eq}} = \sum_i \frac{1}{C_i}$$

$$C_{eq} = \left(\frac{1}{C_1} \right) + \frac{1}{C_2}$$

