

$$U_e = \frac{1}{4\pi\epsilon_0} \sum_{i>j} \frac{q_i q_j}{r_{ij}} = \frac{q^2}{4\pi\epsilon_0} \left( \frac{1}{r_{12}} + \frac{1}{r_{13}} + \frac{1}{r_{23}} \right) =$$

$$= \frac{q^2}{4\pi\epsilon_0} \left( \frac{1}{L} + \frac{1}{\sqrt{2}L} + \frac{1}{L} \right)$$

$\uparrow \qquad \qquad \uparrow \qquad \qquad \uparrow$   
 $U_{12} \qquad U_{13} \qquad U_{23}$

$$q^{(12)} \quad q^{(13)} \quad \underline{W, W_{ext}}$$

$$q^{(1)} \quad q^{(4)} \cdot q_0 \quad W = -\Delta U_e = -W_{ext}$$

$$\Delta U = U_f - U_i, \quad \Delta U_e = U_e^{(4)} - U_e^{(3)}$$

$$U_e = \sum_{i>j} \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}} = U_e^{(3)} + U_e^{(14)} + U_e^{(24)} + U_e^{(34)} \Rightarrow$$

$$\Delta U_e = U_e^{(14)} + U_e^{(24)} + U_e^{(34)} = \frac{q_0 q}{4\pi\epsilon_0} \left( \frac{1}{L} + \frac{1}{L} + \frac{1}{\sqrt{2}L} \right) \Rightarrow$$

$$W = -\Delta U_e = - \frac{q q_0}{4\pi\epsilon_0} \left( \frac{2}{L} + \frac{1}{\sqrt{2}L} \right) > 0$$

$$q q_0 > 0 \Rightarrow W < 0$$

$$\vec{F} \cdot d\vec{s} < 0 \Rightarrow \Delta U_e > 0$$

$$q q_0 < 0 \Rightarrow W > 0$$

$$\vec{F} \cdot d\vec{s} > 0 \Rightarrow \Delta U_e < 0$$

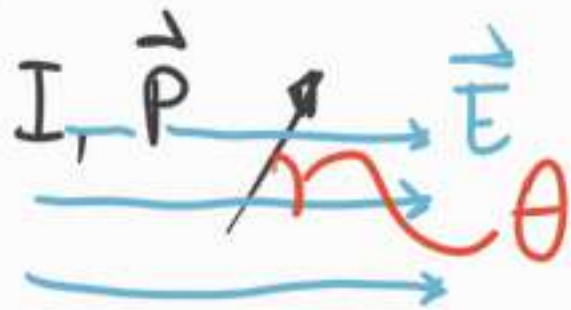
$$q q_0 > 0 \Rightarrow W_{\text{ext}} > 0$$

$$q q_0 < 0 \Rightarrow W_{\text{ext}} < 0$$

$$\text{III } W : q = 2 \cdot 10^{-7} \text{ C}$$

$$q_0 = -10^{-8} \text{ C}$$

$$L = 5 \text{ cm}$$

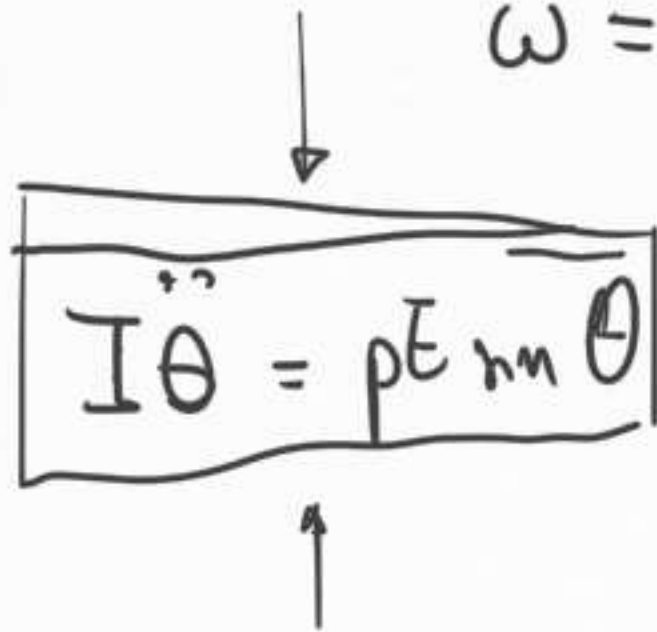


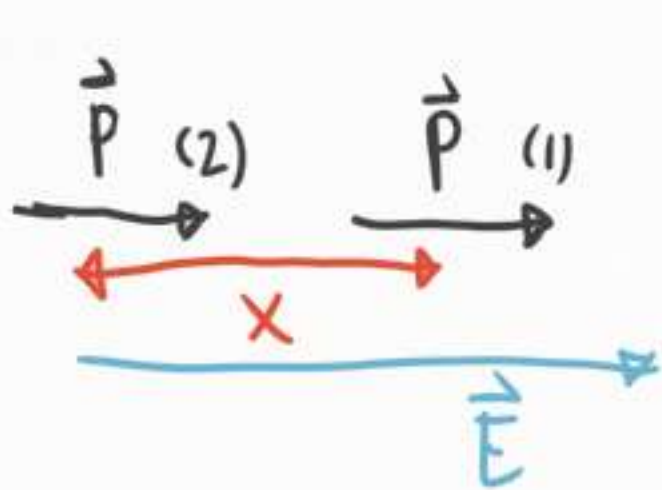
1)  $\omega = ?$  quando  $\theta = 0$ ,  $U_e = -\vec{p} \cdot \vec{E}$

$$U_e^{(i)} = -p\bar{E} \cos \theta = U_{\text{TOT}}^{(i)}$$

$$U_{\text{TOT}}^{(f)} = -p\bar{E} + \boxed{\frac{1}{2} I \omega^2} = U_{\text{TOT}}^{(i)} = -p\bar{E} \cos \theta \Rightarrow$$

$$\omega = \sqrt{\frac{2p\bar{E}(1 - \cos \theta)}{I}}$$





$$2) U_e = ?$$

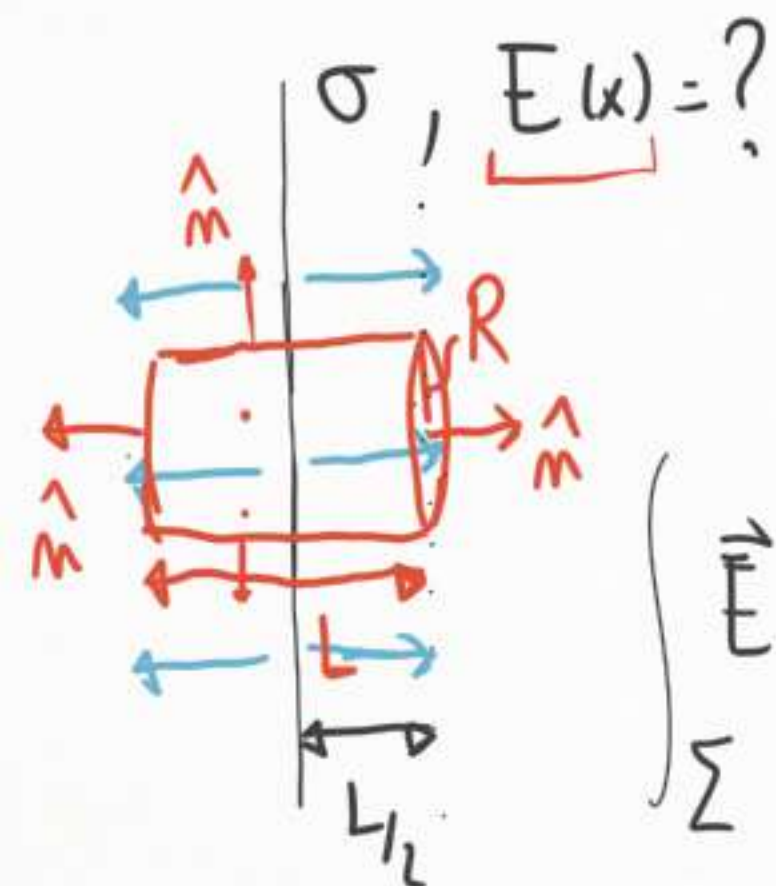
$$U_e^{(1)} = -\vec{p} \cdot \vec{E}_{\text{tot}} = -\vec{p} \cdot (\vec{E} + \vec{E}_d) =$$

$$= -p(\bar{E} + \bar{E}_d)$$

$$E_d(x) = \frac{p}{2\pi\epsilon_0} \frac{1}{x^3} \Rightarrow U_e^{(1)} = -p\bar{E} - \boxed{\frac{p^2}{2\pi\epsilon_0} \frac{1}{x^3}}$$

$$U_e = -p\bar{E} - p\bar{E} - \frac{p^2}{2\pi\epsilon_0} \frac{1}{x^3}$$





$$\int_{\Sigma} \vec{E} \cdot \hat{n} d\Sigma = \frac{Q_{\Sigma}}{\epsilon_0}$$

$$\int_{\Sigma} \vec{E} \cdot \hat{n} d\Sigma = \int_{B_1} \vec{E} \cdot \hat{n} d\Sigma + \int_{B_2} \vec{E} \cdot \hat{n} d\Sigma + \int_{\Sigma} \vec{E} \cdot \hat{n} d\Sigma =$$

$$= E \int_{B_1} d\Sigma + E \int_{B_2} d\Sigma = E 2\pi R^2 = \frac{Q_{\Sigma}}{\epsilon_0}$$

$$Q_{\Sigma} = \int_{\tau_{\Sigma}} dq = \int_{\Sigma} \sigma d\Sigma = \sigma \int_{\Sigma} d\Sigma \quad \text{PROX PAGINA}$$

$$Q_{\Sigma} = \int_{\hat{\Gamma}_{\Sigma}} dq = \int_{\Sigma} \sigma d\Sigma = \sigma \int_{\Sigma} d\Sigma = \sigma \pi R^2 \Rightarrow$$

$$2\pi R^2 E = \frac{\sigma \pi R^2}{\epsilon_0} \Rightarrow E = \frac{\sigma}{2\epsilon_0}$$



 $1) \sigma$ 
$$E(z) \quad p \in \mathbb{R} \quad z \in \mathbb{R}$$

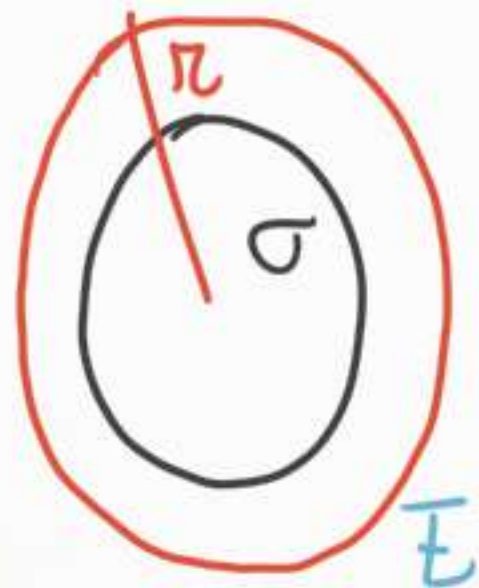
$$\int_{\Sigma} \vec{E}(\underline{r}) \cdot \hat{n} d\Sigma = \int_{\Sigma} E(r) d\Sigma = E(r) \int_{\Sigma} d\Sigma = E(r) 4\pi r^2$$

$$Q_\Sigma = 0 \Rightarrow E(r) = 0$$



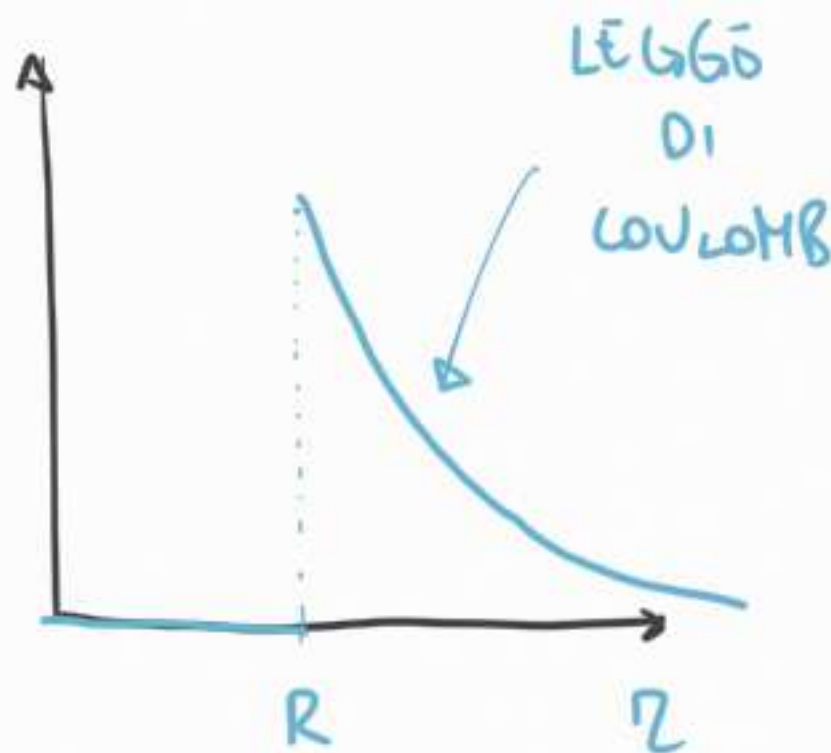


$$E(r) > R$$



$$\oint_{\Sigma} \vec{E}(r) \cdot \hat{n} d\Sigma = \bar{E}(r) 4\pi r^2, \quad Q_{\Sigma} = \sigma 4\pi R^2 = q$$

$$\Rightarrow E(r) = \frac{q}{4\pi\epsilon_0 r^2} = \frac{\sigma 4\pi R^2}{4\pi\epsilon_0} \frac{1}{r^2}$$



II  $\rho$ ,  $\boxed{dq = \rho d\tau}$   
 $r < R$

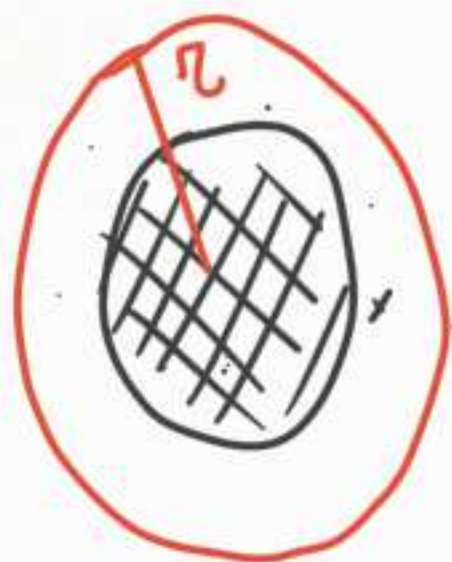


$$E(r) 4\pi r^2 = \frac{Q_{\Sigma}}{\epsilon_0}$$

$$Q_{\Sigma} = \int_{\tau_{\Sigma}} \rho d\tau = \rho \int_{\tau_{\Sigma}} d\tau = \frac{4}{3} \pi \rho r^3$$

$$\Rightarrow E(r) = \frac{\rho}{3\epsilon_0} r$$

$r > R$



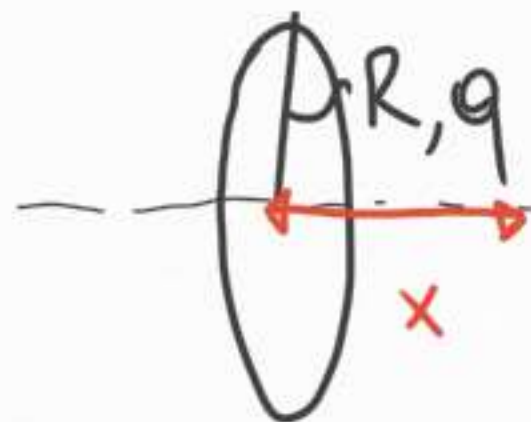
$$E(r) 4\pi r^2 = \frac{Q_{\Sigma}}{\epsilon_0}$$

$$Q_{\Sigma} = \int_{\tau_{\Sigma}} \rho d\tau = \frac{4}{3} \pi \rho R^3 = \textcircled{9} \Rightarrow$$

$$\boxed{E(r) = \frac{\textcircled{9}}{4\pi\epsilon_0} \frac{1}{r^2}}$$

$$3) \rho(z) = Az^2, z < R$$


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$$1) V(x) = ?$$

$$2) V(x) \rightarrow \vec{E}(x, 0, 0)$$

ESEMPIO 2.6  
(MNV)

SOLUZIONI  
SUL SITO