

Computational Electrical Engineering - Optimization Assignment for the Numerical Lab

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1 Comparison of Gradient-Based and Stochastic Algorithms

We are asked to compare the Gradient-Based and Stochastic Optimization scheme to find the minimum of a function.

1.1 Plot of the objective function

The test is performed on the Rastrigin function

$$f(x_1, \dots, x_n) = An + \sum_{i=1}^n (x_i^2 - A \cos(2\pi x_i)),$$

for $n = 2$ and $A = 10$. The Rastrigin function is a common benchmark for optimization algorithm as it exhibits many local minima and its global minimum is exactly the origin $\mathbf{0}$, as we may notice in Figure 1.

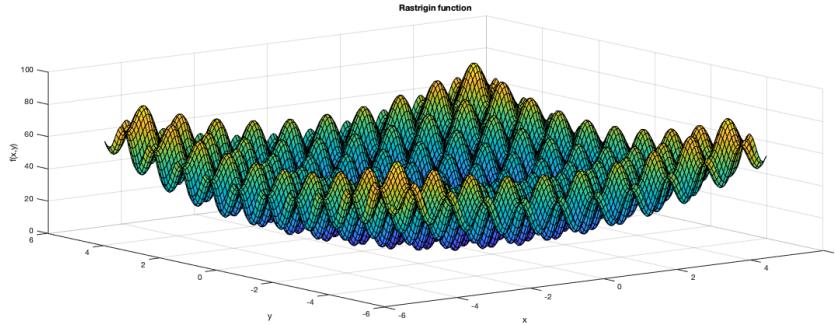


Figure 1: Rastrigin function in the range $[-5.12, 5.12] \times [-5.12, 5.12]$.

1.2 Visual Comparison and Statistics

We rely on the built-in Matlab functions `fminunc` for the gradient-based method and the genetic algorithm `ga` for the stochastic approach. Since the gradient-based method requires an initial value for \mathbf{x} , for every run the initial value is obtained as

```
x = 2*(rand(2,1)-.5)*bound;
```

that is a random 2D point in $\text{bound} * ([-1, 1] \times [-1, 1])$, with $\text{bound} = 5.12$. For a visual comparison, we run $N = 40$ times each algorithm and we plot the resulting computed optimal solution on the contour plot of the function.

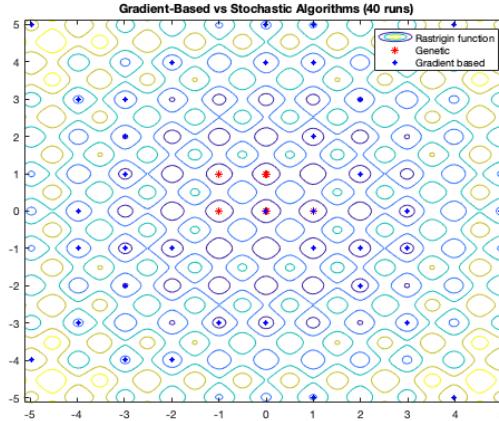


Figure 2: Contour plot of the Rastrigin function with computed optimal solutions for `ga` and `fminunc`.

Figure 2 highlights that the stochastic approach is able to reach consistently the region near the origin where the function is lower, while the gradient-based method is heavily dependent on the initial values and it gets stuck on local minima.

We record statistics by running again the two methods for $N = 1000$ times. The obtained results are summarized in Table 1. Table 1 shows how, even though the gradient-based method is able to find the lowest minimum in a single run, it often easily gets stuck in suboptimal minima and it performs worse than the stochastic approach in mean, standard deviation and maximum. On the other hand the genetic algorithm is able to find points near the global minima reliably and with low standard deviation. Also, its worst case scenario is one order of magnitude better than the one with the gradient based approach.

	Gradient Based	Genetic Algorithm
mean	16.015	0.32535
std	11.785	0.60883
min	1.4211e-14	2.7583e-11
max	60.692	4.9748

Table 1: Statistics on $f(\mathbf{x}_{\text{opt}})$ found by 1000 runs of the two methods for the Rastrigin function.

1.3 A table with the solutions (x vector) computed with the gradient-based and the stochastic approach

Table 2 includes the coordinate \mathbf{x} of the found minima and their corresponding f value for 10 runs of the gradient based and genetic algorithm each.

run	Gradient Based			Genetic Algorithm		
	x_{opt}	y_{opt}	$f(x_{\text{opt}}, y_{\text{opt}})$	x_{opt}	y_{opt}	$f(x_{\text{opt}}, y_{\text{opt}})$
1	2.5064e-08	1.9899	3.9798	-1.1519e-06	1.877e-05	7.0159e-08
2	0.99496	-0.99496	1.9899	2.4912e-05	2.5959e-05	2.5682e-07
3	-1.9899	2.9849	12.934	-1.205e-07	2.5853e-06	1.3289e-09
4	-1.9899	-1.9899	7.9597	4.4799e-07	4.4188e-07	7.8554e-11
5	-3.9798	1.9899	19.899	2.8582e-06	2.4343e-06	2.7963e-09
6	0.99496	7.0329e-09	0.99496	-1.744e-06	7.4266e-06	1.1546e-08
7	-0.99496	1.9899	4.9748	-0.99496	-0.99496	1.9899
8	-1.9899	-1.9899	7.9597	-2.9914e-06	5.9759e-06	8.8601e-09
9	-0.99496	-3.9798	16.914	1.2764e-06	1.0668e-05	2.2902e-08
10	0.99496	4.9747	25.869	1.8154e-06	-2.4552e-06	1.8498e-09

Table 2: Ten runs found minima and corresponding f value for the gradient based and genetic algorithm.

1.4 The trend of f_{best} during the iterations of the stochastic approach

Figure 3 includes the trend of f_{best} during the iterations of the one genetic algorithm run.

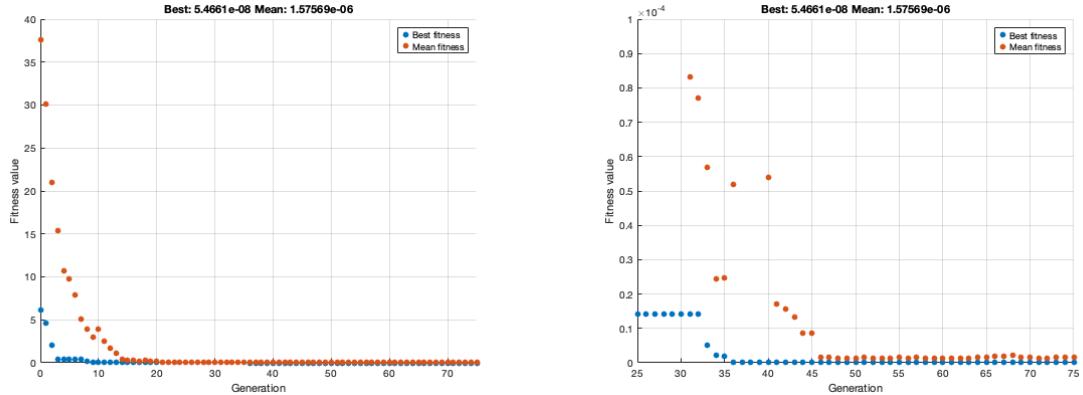


Figure 3: Trend of f_{best} on a genetic algorithm run. On the right, zoom for Generation > 25 .

For the first generations the population is largely diversified as the Mean fitness is far from the best fitness. Later, by recombining the good features in the different individual of the population, the algorithm is able to improve the best fitness gradually yet keeping the population diverse enough. Finally the algorithm stops when the whole population converges to the same point (or individual), as the mean approaches the best fitness, because there is no more possibility to recombine diverse features.