Lorenzo Sforni

Personal Details

AFFILIATION: Department of Electrical, Electronic and Information Engineering

"G. Marconi", Alma Mater Studiorum Università di Bologna, viale del

Risorgimento 2, 40136, Bologna, Italy

EMAIL: lorenzo.sforni@unibo.it

Date of Birth: September 7, 1996

CURRENT POSITION

1 Nov 2020 – current | Ph.D. Candidate in Systems and Control Engineering

Department of Electrical, Electronic and Information Engineering "G. Marconi", Alma Mater Studiorum Università di Bologna, Italy

EDUCATION

9 Oct 2020 | Master degree in Automation Engineering (LM-25), Alma Mater

Studiorum Università di Bologna, Italy 110/110 cum laude, GPA: 30.0/30.0

Advisor: G. Notarstefano

Thesis: A closed-loop methodology for discrete-time nonlinear optimal

control.

26 Jul 2018 | Bachelor degree in Automation Engineering (L-8), Alma Mater

Studiorum Università di Bologna, Italy

110/110 cum laude Advisor: A. Zucchelli

Thesis: Development of a nanofiber piezoelectric sensor for composite

structures.

Positions Held

1 Mar 2023 – 4 Sep 2023 | Visiting Researcher at California Institute of Technology (Pasadena,

CA, USA)

Advisor: A.D. Ames

Project: Development of optimal-control-based safe controllers for

robotic systems.

RESEARCH PROJECTS PARTICIPATION

Nov 2023 - current | AlmaValue: scouting of Alma Mater's search results and support

for market enhancement. University of Bologna internal funding for candidate spinoff projects. Supported by Next Generation EU.

Project: DiscreetAI

Principal Investigator: G. Notarstefano

Position: Member of the development team (4 people)

Nov 2023 – current | PRIN 2022 – Next Generation EU

Project: ECODREAM

Project Coordinator: L. Glielmo, Universitá del Sannio

Position: Ph.D. Student, member of the University of Bologna group

Nov 2022 – current

Italy-Brasil cooperation project funded by the Italian Ministry of

Foreign Affairs and International Cooperation

Project: Distributed Optimization for Cooperative Machine Learning

in Complex Networks

Principal Investigator: G. Notarstefano

Position: Ph.D. Student

Nov 2020 - Sep 2021

ERC Starting Grant OPT4SMART

Project: Distributed Optimization Methods for Smart Cyber-Physical

Networks

Principal Investigator: G. Notarstefano

Position: Ph.D. Student

AWARDS

May 2020

Scholarship for outstanding academic achievements from Alma Mater Studiorum Università di Bologna.

Scholarship for outstanding academic achievements – GPA 30.0/30.0

Sep 2018

Total merit-based exemption from Alma Mater Studiorum Università di Bologna.

Total exemption from enrolment fees if students obtained the first cycle degree during 2017/18 a.y. at the University of Bologna, by 31 July 2018, within their course's established time period and with a degree mark of no less than 110/110

Teaching

A.Y. 2023/2024

Teaching assistant for "Optimal Control - M", 30h, Master Degree in Automation Engineering, Alma Mater Studiorum Università di Bologna, held by prof. G. NOTARSTEFANO.

A.Y. 2022/2023

Teaching assistant for "Optimal Control - M", 30h, Master Degree in Automation Engineering, Alma Mater Studiorum Università di Bologna, held by prof. G. NOTARSTEFANO.

A.Y. 2021/2022

Teaching assistant for "Optimal Control - M", 30h, Master Degree in Automation Engineering, Alma Mater Studiorum Università di Bologna, held by prof. G. NOTARSTEFANO.

Teaching assistant for "Robust H_{∞} Control, Topic Highlight - M", 30h, Master Degree in Automation Engineering, Alma Mater Studiorum Università di Bologna, held by prof. L. MIRKIN, *Technion - Israel Institute of Technology*.

A.Y. 2020/2021

Teaching assistant for "Model Predictive Control, Topic Highlight - M", 30h, Master Degree in Automation Engineering, Alma Mater Studiorum Università di Bologna, held by prof. M. MUELLER, *Leibniz University Hannover*.

MENTORING EXPERIENCE AND STUDENT SERVICE

2023 – current | Co-supervision of the master thesis in Automation Engineering at ETH Zürich : Giulia Cutini (2023)

2020 – current

Co-supervision of the master theses in Automation Engineering at University of Bologna: F. Sartori (collab. with SACMI, 2023), A. Tramaloni (collab. with SACMI, 2022), S. Baroncini (2022), E. Pianazzi (2022), F. Pretini (2022), G. Gaddoni (collab. with Istituto Ortopedico Rizzoli, 2021), L. Fiocchi (2021), L. Sarti (2021), E. Guerra (collab. with Thales Alenia Space, 2021)

Talks

Dec 2022 | I attended the Intern. Conference on Decision and Control (CDC22) in Cancún (Mexico) and presented the paper "Structured-policy Q-

in Cancun (Mexico) and presented the paper "Structured-policy Q-learning: an LMI-based Design Strategy for Distributed Reinforcement Learning".

Dec 2021 | I attended virtually the Intern. Conference on Decision and Control (CDC21) in Austin (TX, USA) and presented the paper "Learning-driven Nonlinear Optimal Control via Gaussian Process Regression".

JOURNAL PUBLICATIONS PREPRINTS

- [J1] L. Sforni, G. Carnevale, G. Notarstefano "A Distributed Feedback-based Framework for Nonlinear Aggregative Optimal Control", *IEEE Transactions on Automatic Control* (under review second round), 2023.
- [J2] L. Sforni, S. Spedicato, I. Notarnicola, G. Notarstefano "GoPRONTO: a Feedback-based Framework for Nonlinear Optimal Control", IEEE Transactions on Automatic Control (under review third round), 2021.

Conference Proceedings

- [C1] L. Sforni, G. Carnevale, I. Notarnicola, G. Notarstefano "On-Policy Data-Driven Linear Quadratic Regulator Via Combined Policy Iteration and Recursive Least Squares", in IEEE 62nd Conf. on Decision and Control, (Marina Bay, Singapore), 2023.
- [C2] L. Pichierri, G. Carnevale, L. Sforni, A. Testa, G. Notarstefano "A Distributed Online Optimization Strategy for Cooperative Robotic Surveillance", in *IEEE International Conference on Robotics and Automation*, (London, UK), pp. 5537–5543, 2023.
- [C3] L. Sforni, A. Camisa, G. Notarstefano "Structured-policy Q-learning: an LMI-based Design Strategy for Distributed Reinforcement Learning", in *IEEE 61st Conf. on Decision and Control*, (Cancún, Mexico), pp. 4059–4064, 2022.
- [C4] L. Sforni, I. Notarnicola, G. Notarstefano "Learning-driven Nonlinear Optimal Control via Gaussian Process Regression", in *IEEE 60th Conf. on Decision and Control*, (Austin, TX, USA), pp. 4406–4411, 2021.

In compliance with the Italian Legislative Decree no. 196 dated 30/06/2003, I hereby authorize the recipient of this document to use and process my personal details for the purpose of recruiting and selecting staff and I confirm to be informed of my rights in accordance to art. 7 of the above mentioned decree.

Bologna, November 27, 2023

Lorenzo Sforni