

# *Transparent* causal inference for observational epidemiology

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# Who am I?

- Final-year\* PhD student at the Barcelona Institute for Global Health (ISGlobal).
  - Google Scholar: <https://shorturl.at/IJCU8>
  - CV: <https://shorturl.at/N3YeP>
  - Code: <https://github.com/lorenzoFabbri>

Today's talk

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- *Prenatal and childhood exposure to mixtures of non-persistent endocrine disrupting chemicals (EDC) and adolescence neurodevelopment: a triangulation study.*

Vrijheid, M., Basagaña, X., Gonzalez, J.R., Jaddoe, V.W., Jensen, G., Keun, H.C., McEachan, R.R., Porcel, J., Siroux, V., Swertz, M.A. and Thomsen, C., 2021. Advancing tools for human early lifecourse exposome research and translation (ATHLETE): Project overview. *Environmental Epidemiology*, 5(5), p.e166.

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# Today's talk

- ***Prenatal** and **childhood** exposure to mixtures of non-persistent endocrine disrupting chemicals (EDC) and **adolescence** neurodevelopment: a **triangulation** study.*

Approaching the question



# Some notation

- I will make use of the following notation:
  - $A$  will be our (vector of) exposure(s).
  - $W$  will be our vector of *a priori* selected confounders.
  - $C$  is an indicator variable for censoring ( $C = 1$  indicating censored).
  - $Y$  will be our outcome.
  - The potential outcomes will be indicated with  $Y^{\{a\}}$ .

# Approaching the question

1. Start with a well-defined **causal question**, and define the **causal estimand** and **model** (e.g., DAG):

$$\Psi^* = E[Y^{\{a=a^*, c=0\}}] - E[Y^{\{a=a^{nc}, c=0\}}]$$

# Intermezzo: causal policies / shift functions

- Binary exposures (presence/absence, treated/untreated):  $Y^{\{a=1\}} - Y^{\{a=0\}}$ .
- Categorical exposures:  $Y^{\{a=a_5\}} - Y^{\{a=a_0\}}$ .
- Continuous exposures: ?
  - $Y^{\{a=avg(a)\}} - Y^{\{a=nc\}}$ .
  - $Y^{\{a=75^{th}\}} - Y^{\{a=25^{th}\}}$ .
  - MTP: if  $a \geq 0.5$  and  $bw < 70$  then  $a^g = a * 0.1$ , else  $a^g = a$ .
  - ...
- A zoo of interventions: static, dynamic, MTPs, deterministic, stochastic...

# Approaching the question

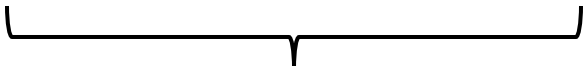
1. Start with a well-defined causal **question**, and define the causal **estimand** and **model** (e.g., DAG).
2. Consider the **observed** data and **identifiability** conditions. Define the **statistical** estimand:

$$\Psi = E_W[E[Y|W, A = a^*, C = 0] - E[Y|W, A = a^{nc}, C = 0]]$$

# Approaching the question

3. Choose the *best* **statistical estimator**:

$$Y \sim A_1 + A_2 + \dots + A_p + W$$

  
Components of mixture  $i$

How to get the *best* estimator?

# How to get the *best* estimator

- To summarize:
  1. Define your causal estimand.
  2. *Derive* the associated statistical estimand.
  3. Estimate the so-called *nuisance functions*.
  4. Estimate your effect of interest.

# How to get the *best* estimator: g-formula

Remember:  $E[Y|W, A = a^*, C = 0]$

$$\Psi^g = \int_A \int_W E[Y|A = a, W = w] f^g(A|W) f(W) da dw$$



# How to get the *best* estimator: g-formula

$$\Psi^g = \int_A \int_W E[Y|A = a, W = w] f^g(A|W) f(W) da dw$$

# How to get the *best* estimator: EIF

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# How to get the *best* estimator: EIF

$$\Psi^g = \int_A \int_W E[Y|A=a, W=w] f^g(A|W) f(W) da dw$$

$$\begin{aligned} IF_1 &= \int_A \int_W \frac{I(A=a, W=w)}{f(A=a, W=w)} \{Y - E[Y|A, W]\} f^g(A|W) f(W) da dw \\ &= \frac{f^g(A|W)}{f(A|W)} \{Y - E[Y|A, W]\}. \end{aligned}$$

# How to get the *best* estimator: EIF

$$\Psi^g = \int_A \int_W E[Y|A=a, W=w] f^g(A|W) f(W) da dw$$

$$\begin{aligned} IF_2 &= \int_A \int_W E[Y|A, W] f^g(A|W) \{I(W=w) - f(W=w)\} da dw \\ &= \int_A E[Y|A, W] f^g(A|W) da - \Psi \\ &= \int_A E[Y(A^*, W)] f(A|W) f^+(A|W) da - \Psi \end{aligned}$$

# How to get the *best* estimator: EIF

$$\Psi^g = \int_A \int_W E[Y|A=a, W=w] f^g(A|W) f(W) da dw$$

$$EIF = \frac{f^g(A|W)}{f(A|W)} \{Y - E[Y|A, W]\} + E[Y|A^g, W] - \Psi$$

- One possible way to use the EIF to estimate the parameter of interest is by **plugging in** estimates of the individual components and averaging over the sample (AIPW).

# How to get the *best* estimator: nuisance functions

- $\Psi_{AIPW}^g = avg(\widehat{EIF})$   
$$= \frac{1}{n} \sum_i \frac{f^g(A_i|W_i)}{f(A_i|W_i)} \{Y_i - E[Y_i|A_i, W_i]\} + E[Y_i|A_i^g, W_i]$$
- We combine 2 nuisance functions (double-robustness): the **propensity score** and the **outcome model**.
- For my project, probably using Imtp R package:  
<https://github.com/nt-williams/Imtp>. Works also with multiple exposures. Implements parametric g-computation, IPW, TML, and SDR estimators. Static, dynamic, and MT policies.

# Why that?

- Literature on mixtures (environmental epidemiology): quantile g-computation, BKMR, BWQS...
  - Parametric models.
  - No causal “background”.
  - Discretization of exposures that are continuous in nature.

# Triangulation and open questions

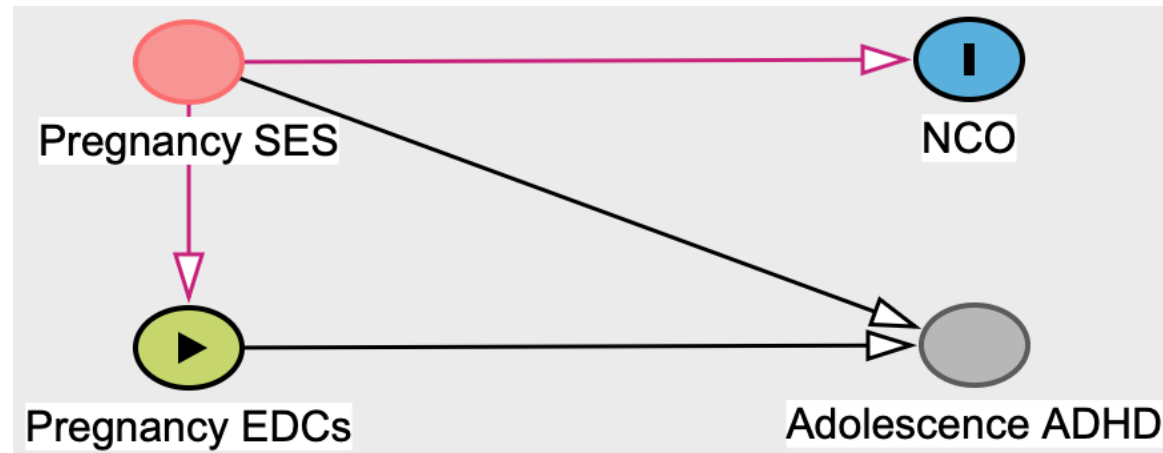


# Triangulation and open questions

- Observational studies are subject to **bias** (many).
- We can strengthen our conclusions by combining different data sources and methods:
  - Negative controls (exposure and/or outcome).
  - Cross-cohort comparisons.
  - Genetic variants (MR), although different estimand.
  - ...

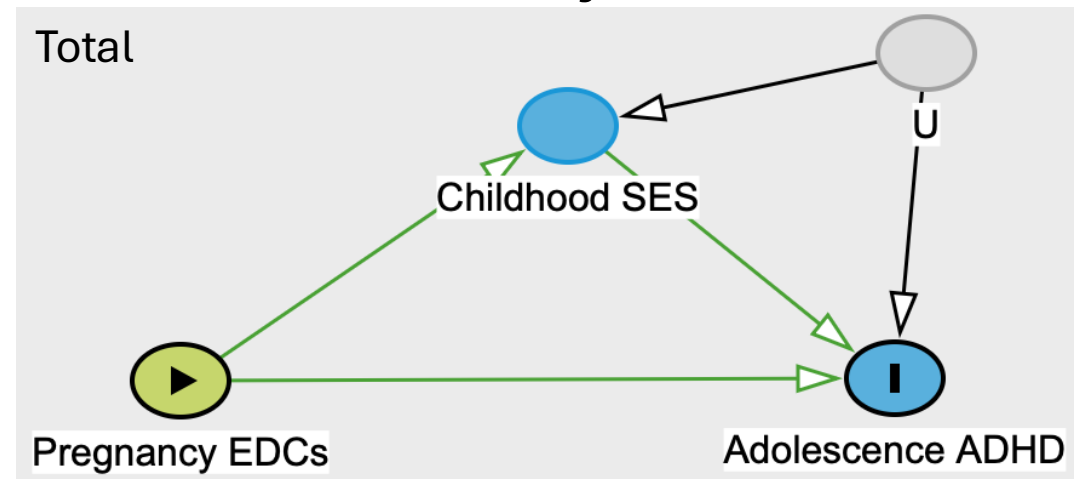
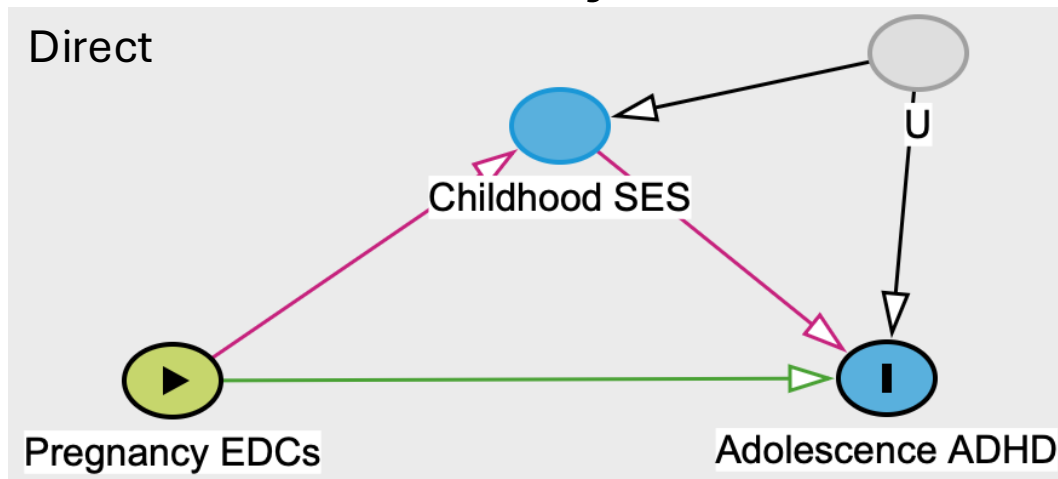
# Triangulation and open questions

- Observational studies are subject to **bias** (many).
- We can strengthen our conclusions by combining different data sources and methods:
  - Negative control outcome, assuming “SES” is main culprit.



# Triangulation and open questions

- **Direct or total effects:** “...when there is an unmeasured common cause of the intermediate and the outcome, associations adjusted for the intermediate are subject to bias.”



- What if there is no arrow between EDCs and SES?

Thank you for your attention!

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