Grenoble | images | parole | signal | automatique | laboratoire

# Optimal Laplacian regularization for sparse spectral community detection



ICASSP 2020

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UMR 5216





#### Community detection

The non-backtracking matrix







## Community detection

### Problem position

The non-backtracking matrix







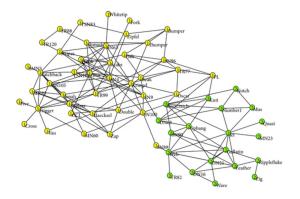


Figure: A representation of the dolphin network (Lusseau 2003)

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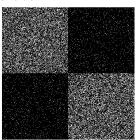
# More formally

Given a graph  $\mathcal{G}(\mathcal{V}, \mathcal{E})$  with  $|\mathcal{V}| = n$  nodes and k communities, assign to each node the correct class label.

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The problem



A representation of the adjacency matrix  $A_{ii} = 0$  (black) if i, jare not connected and  $A_{ii} = 1$  (white) if they are connected

### Community detection

### Spectral clustering

The non-backtracking matrix







Node embedding to low dimensional space

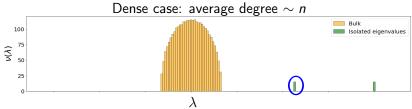
Node embedding to low dimensional space  $\rightarrow$  *k-means* 

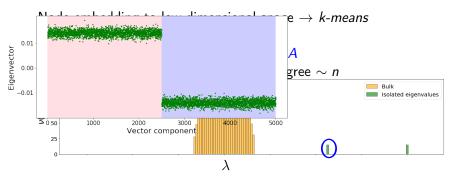
Node embedding to low dimensional space  $\rightarrow$  *k-means*  $D = \operatorname{diag}(A\mathbf{1})$ 

Node embedding to low dimensional space  $\rightarrow k$ -means

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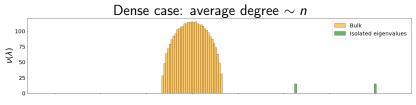
# Spectrum of $D^{-1}A$

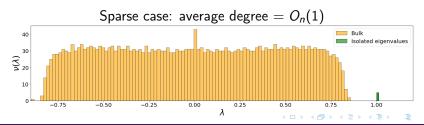




Node embedding to low dimensional space  $\rightarrow$  *k-means*  $D = \operatorname{diag}(A1)$ 

### Spectrum of $D^{-1}A$





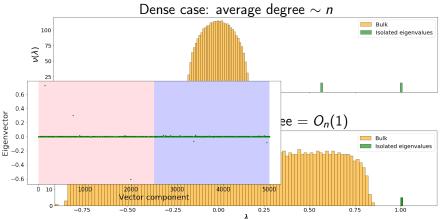




Node embedding to low dimensional space  $\rightarrow$  *k-means* 

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Spectrum of  $D^{-1}A$ 







#### Community detection

The generative model

The non-backtracking matrix







Dealing with sparsity and heterogeneous degree distributions

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Degree-corrected stochastic block model

$$\mathbb{P}(A_{ij} = 1 | \theta_i, \theta_j, \sigma_i, \sigma_j) = \theta_i \theta_j \frac{C_{\sigma_i, \sigma_j}}{n}$$





#### Theoretical bounds

#### Define

- $ightharpoonup c = \frac{c_{\rm in} + c_{\rm out}}{2}$ , expected average degree
- $\Phi = \sum_{i} \theta_{i}^{2}$

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- $\Phi = \sum_{i} \theta_{i}^{2}$

#### Detectability threshold

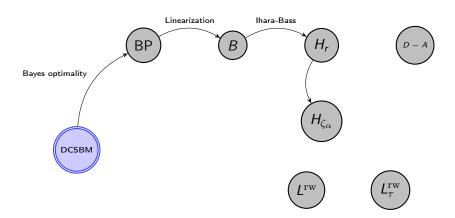
Non-trivial reconstruction iff  $\alpha = \frac{c_{\rm in} - c_{\rm out}}{\sqrt{c}} > \frac{2}{\sqrt{b}}$ .

<sup>1</sup>Gulikers et.al., An impossibility result for reconstruction in the degree-corrected stochastic block model





### State of the art



#### A unified framework

The non-backtracking matrix





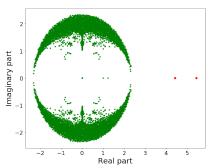
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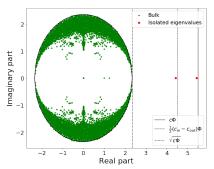


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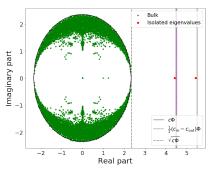
$$B_{(ij),(kl)} = \delta_{jk}(1 - \delta_{il}), \quad \forall \ (ij),(kl) \in \mathcal{E}^d$$



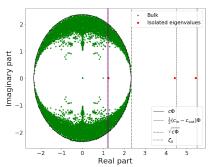
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#### Linearization of BP

$$B\boldsymbol{\delta} = \zeta_{\alpha}\boldsymbol{\delta} \tag{1}$$

$$\zeta_{\alpha} = \frac{c_{\text{in}} + c_{\text{out}}}{c_{\text{in}} - c_{\text{out}}} = \frac{2\sqrt{c}}{\alpha}$$
 (2)





# To recap

✓ Detects communities down to the threshold



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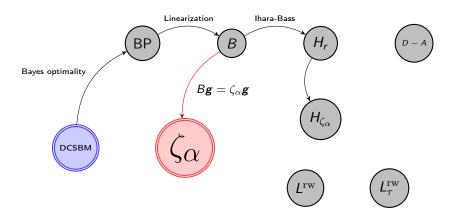
- ✓ Detects communities down to the threshold
- ✓ An informative eigenvalue *inside* the bulk of B



# To recap

- ✓ Detects communities down to the threshold
- ✓ An informative eigenvalue *inside* the bulk of B Introduces the parameter  $\zeta_{\alpha}$

### A unified framework



#### A unified framework

The non-backtracking matrix

The Bethe-Hessian matrix







### The Bethe-Hessian matrix

#### Ihara-Bass formula

$$B\mathbf{g} = \zeta_{\alpha}\mathbf{g}$$
$$[(\zeta_{\alpha}^{2} - 1)I_{n} + D - \zeta_{\alpha}A]\mathbf{x} = 0$$

### The Bethe-Hessian matrix

### Ihara-Bass formula

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### The Bethe-Hessian matrix

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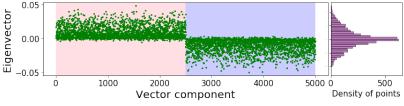
We showed, for all D

$$\mathbb{E}[x] = \sigma$$

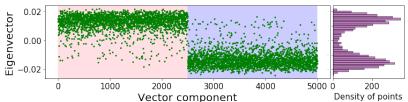








Optimal value 
$$r = \zeta_{\alpha} = \frac{c_{\rm in} + c_{\rm out}}{c_{\rm in} - c_{\rm out}}$$



<sup>&</sup>lt;sup>6</sup>Saade (2014) Spectral clustering of graphs with the Bethe Hessian  $\triangleright$   $\triangleleft$   $\bigcirc$   $\triangleright$   $\triangleleft$   $\bigcirc$   $\triangleright$   $\triangleleft$ 







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 $H_{\zeta_{\alpha}}$ 

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# $H_{\zeta_{\alpha}}$

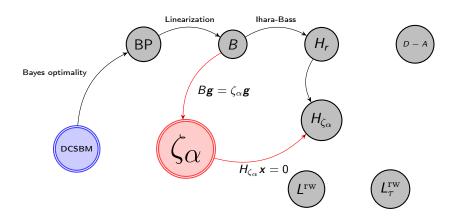
- ✓ The second smallest eigenvalue is zero and is informative
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# To recap

# $H_{\zeta_{\alpha}}$

- ✓ The second smallest eigenvalue is zero and is informative
- ✓ Detects communities down to the threshold
- ✓ The eigenvector is resilient to the degree distribution

### A unified framework



$$L_{\tau} = D_{\tau}^{-1/2} A D_{\tau}^{-1/2}$$
  
 $L_{\tau}^{\text{rw}} = D_{\tau}^{-1} A$ 

Where  $D_{\tau} = D + \tau I_n$ .

 $<sup>^{1}\</sup>mathrm{Qin}$  (2013) Regularized spectral clustering under the degree-corrected stochastic blockmodel







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From  $H_{C_{\alpha}}$  to  $L_{\tau}$ 

$$H_{\zeta_{\alpha}} \mathbf{x} = [(\zeta_{\alpha}^2 - 1)I_n + D - \zeta_{\alpha}A]\mathbf{x} = 0$$
$$[D + (\zeta_{\alpha}^2 - 1)I_n]^{-1}A\mathbf{x} = \frac{1}{\zeta_{\alpha}}\mathbf{x}$$

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So

$$\tau = \zeta_{\alpha}^2 - 1 \le c\Phi - 1 \approx c$$

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$$L^{\mathrm{rw}}_{\zeta^2_{\alpha}-1}$$

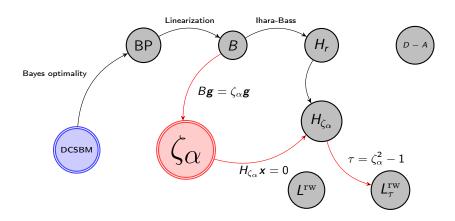
✓ Explains why  $\tau = c$  is a good choice, in practice

$$L_{\zeta_{\alpha}^2-1}^{\mathrm{rw}}$$

- ✓ Explains why  $\tau = c$  is a good choice, in practice
- $\checkmark \tau = \zeta_{\alpha}^2 1$ : minimal regularization for detection down to the threshold

Dall'Amico, Spectral clustering - ICASSP 2020

### A unified framework





Dall'Amico, Spectral clustering - ICASSP 2020

### A unified framework

The non-backtracking matrix

The classical Laplacians



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# The classical Laplacians

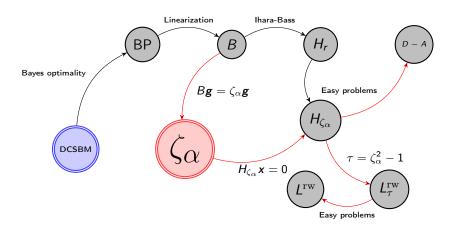
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# The classical Laplacians

For easy detection problems:  $\zeta_{lpha} 
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$$[(\zeta_{\alpha}^{2}-1)I_{n}+D-\zeta_{\alpha}A] \rightarrow D-A$$
$$[D+(\zeta_{\alpha}^{2}-1)I_{n}]^{-1}A \rightarrow D^{-1}A$$

### A unified framework



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## Performance on real networks

Dataset	n	С	Ф	k	Alg	$H_{\sqrt{c\Phi}}$	В	L <sup>rw</sup>	$\mathcal{L}_{ au}^{ ext{sym}}$
Karate	34	4.6	1.7	2	0.37	0.37	0.37	0.37	0.37
Dolphins	62	5	1.3	2	0.38	0.34	0.22	0.38	0.38
Polbooks	105	8.4	1.4	<u>3</u>	0.50	0.50	0.45	0.50	0.50
Football	115	10.7	1	<u>12</u>	0.60	0.60	0.60	0.60	0.60
Mail	1133	9.6	1.9	21	0.50	0.40	0.37	0.48	0.50
Polblogs	1222	27,4	3	2	0.43	0.27	0.23	0.00	0.43
Tv	3892	8.9	3	41	0.85	0.56	0.55	0.55	0.78
Facebook	4039	43.7	2.4	55	0.79	0.49	0.48	0.70	0.58
GrQc	4158	6.5	2.8	29	0.80	0.51	0.51	0.33	0.79
Power grid	4941	2.7	1.5	25	0.92	0.33	0.31	0.92	0.85
Politicians	5908	14.1	3	62	0.85	0.54	0.51	0.74	0.74
GNutella P2P	6299	6.6	2.7	4	0.40	0.14	0.14	0.00	0.35
Wikipedia	7066	28.3	5.1	22	0.27	0.18	0.16	0.34	0.27
HepPh	11204	21.0	6.2	60	0.57	0.42	0.42	0.27	0.52
Vip	11565	11.6	4.4	53	0.65	0.32	0.32	0.16	0.54



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The non-backtracking matrix

### Conclusion





### Contributions

 $\checkmark$  A unified framework for spectral clustering in sparse graphs

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### Future perspectives

✓ More structured graphs (time-evolving, multi-modal...)

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### Future perspectives

- ✓ More structured graphs (time-evolving, multi-modal...)
- ✓ Is hardness-dependent regularization more general? (SSL kernel methods, weighted graphs...)







### Main references (Dall'Amico, Couillet, Tremblay)

- Optimal Laplacian regularization for sparse spectral community detection. ICASSP 2020
- A unified framework for spectral clustering in sparse graphs, arXiv:2003.09198
- Revisiting the Bethe-Hessian: improved community detection in sparse heterogeneous graphs, NeurIPS 2019.

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