

Lorenzo Feruglio

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Education

2006–2009 **Aerospace Engineering**, *Politecnico di Torino*, Torino, *Bachelor's Degree*.

2009–2012 **Aerospace Engineering**, *Politecnico di Torino*, Torino, *Master of Science*.
Graduated with Honors

2014–now **Aerospace Engineering**, *Politecnico di Torino*, Torino, *PhD Candidate*.

2014 Exchange student at **Massachusetts Institute of Technology** for the project
'CubeSat for Space Exploration: a new paradigm for Planetary Science Missions'

2015 Visiting Student Researcher (JVS RP) at **Jet Propulsion Laboratory** (JPL) for
Mission Autonomy Research

Summary

- research* Autonomous Space Systems, Artificial Intelligence
- experience* Five years and counting of *hands-on* experience with CubeSats
Polito CubeSat Team Leader for C&DH, AOCS and GCS design
- knowledge* Detailed subsystem knowledge (AOCS, C&DH)
STK, Matlab, Python, C
- hands-on projects* e-st@r CubeSat project followed from design to LEOP
e-st@rII CubeSat currently performing Environmental Test Campaign at ESTEC
among Fly Your Satellite! Competition
3-STAR CubeSat for GNSS Remote Sensing

Experience

PhD Student - Space Engineering

- 2014–now **Mission Autonomy Engineer**, *Politecnico di Torino*, Torino.
Methodologies and Technologies to Improve Small Satellites Space Mission Autonomy
Current field of research:
- Neural networks for image quality assessment and event detection
 - Fuzzy logics for failure detection of actuators
 - Definition of case studies (Interplanetary CubeSats) in order to investigate on mission autonomy-enhancing technologies
 - Genetic Algorithms to optimize Multi-Attribute Tradespace Exploration problems
 - Hardware-In-The-Loop testing of training algorithms for neural networks for asteroid recognition

Space System Engineer

2013–2014 **Assistant Researcher**, *Politecnico di Torino*, Torino.

Capture and De-Orbiting Technologies.

Field of Research:

- Development of a Simulator Technology to perform mission analyses and In-The-Loop simulations
- Research on GNC strategies for the latest phases of a rendez-vous and mating manoeuvre
- Attitude Determination and Control Algorithms testing on specific hardware (ARM architecture)
- Code development and upgrading for ADCS and OBC subsystems (e-st@rII CubeSat)
- e-st@r-II CubeSat Subsystem and System Functional Testing

2012–2013 **Operation Architecture Engineer**, *SES (contractor)*, Luxembourg.

Efficient Automation of Satellite Operations (EASO Project).

Detailed achievements:

- Development, verification and validation of automated procedures for Satellite Operations
- Payload and Bus operation procedures for the SES Orbital fleet:
 - Dynamic Satellite Simulators (Orbital)
 - AOCS, TCR, TCS, EPS, CDH procedures development and subsystem analysis by means of DSS
 - Ground Control Station Software (SCORPIO)
- SPELL, Python, Eclipse

2009–2012 **Polito CubeSat Team - Team member**, *Politecnico di Torino*, Italy.

Member of the University CubeSat Team, developing and launching 1U+ CubeSats.

Detailed achievements:

- Satellite (1U and 3U CubeSat) experience:
 - System Engineering methodologies
 - ADCS, C&DH Subsystem development and testing
 - CubeSat functional testing (test definition and execution)
 - ECSS standards for software development and testing
 - Real-time OS (Salvo, RTLinux)

Computer skills

Analysis	STK, Dynamic Satellite Simulation (AOCS, Failure Detection Systems), Space Debris Mitigation
Programming	C, C++, Python, Matlab/Simulink
System Eng	Multi-Attribute Tradespace Exploration, Satellite System Budgets, SysML, UML, Requirements and Functional Analysis
Embedded	MPS430, ARM9, Satellite Hardware-In-The-Loop Testing
Miscellaneous	MS Office, Visio, LaTeX
OS	UNIX (Ubuntu), RTLinux, Windows

Languages

Italian	Mother language
English	Proficient
French	Basic Knowledge
German	Basic Knowledge