

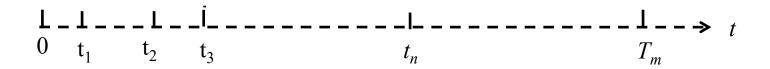
Markov Reliability and Availability Analysis Part II: Continuous-Time Discrete State Markov Processes

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Continuous Time Discrete State Markov Processes

- The **stochastic process** may be **observed** at:
 - Discrete times

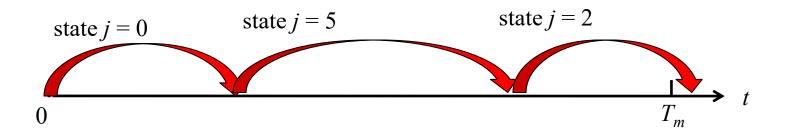
→ DISCRETE-TIME DISCRETE-STATE MARKOV PROCESSES



Continuously



• The stochastic process is **observed continuously** and **transitions** are assumed to **occur continuously in time**



- The random process of system transition between states in time is described by a **stochastic process** $\{X(t); t \ge 0\}$
- X(t) := system state at time t
 - X(3.6) = 5: the system is in state number 5 at time t = 3.6



OBJECTIVE:

Computing the <u>probability</u> that the system is in a <u>given state</u> as a <u>function of time</u>, for <u>all</u> possible states

$$P[X(t)=j], t \in [0,T_m], j=0,1,...,N$$

Objective:

$$P[X(t) = j], t \in [0, T_m], j = 0, 1, ..., N$$



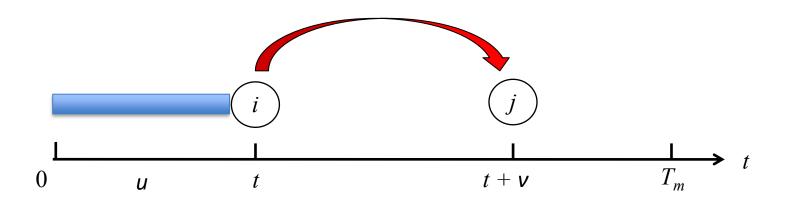
What do we need?

Transition Probabilities!

• Transition probability that the system moves to state j at time $t + \nu$ given that it is in state i at current time t and given the previous system history

$$P[X(t+v)=j \mid X(t)=i, X(u)=x(u), 0 \le u < t]$$

$$(i = 0, 1, ..., N, j = 0, 1, ..., N)$$



• IN GENERAL STOCHASTIC PROCESSES:

the **probability** of a **future** state of the system usually depends on its **entire life history**

$$P[X(t+v)=j \mid X(t)=i, X(u)=x(u), 0 \le u < t]$$

$$(i = 0, 1, ..., N, j = 0, 1, ..., N)$$

IN MARKOV PROCESSES:

the **probability** of a **future** state of the system **only** depends on its **present state**

$$P[X(t+v)=j \mid X(t)=i, X(u)=x(u), 0 \le u < t]$$

$$= P[X(t+v)=j \mid X(t)=i]$$

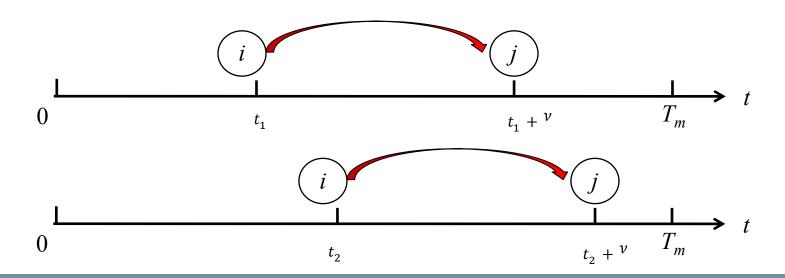
$$(i=0, 1, ..., N, j=0, 1, ..., N)$$

THE PROCESS HAS "NO MEMORY"

If the **transition probability** depends on the **interval** ν and **not** on the **individual times** t and $t + \nu$

- the transition probabilities are **stationary**
- the Markov process is **homogeneous** in time

$$p_{ij}(t,t+v) = P[X(t+v)=j | X(t)=i] = p_{ij}(v)$$



Homogeneus process without memory



Transition time → Exponential distribution

HYPOTHESIS:

• The time interval v = dt is **small** such that **only one** event (i.e., one **stochastic transition**) can occur within it



$$p_{ij}(dt) = P[X(t+dt) = j|X(t) = i] = 1 - e^{-\alpha_{ij} \cdot dt}$$

$$\alpha_{ii} =$$
transition rate from state i to state j

HYPOTHESIS:

• The time interval v = dt is **small** such that **only one** event (i.e., one **stochastic transition**) can occur within it

$$p_{ij}(dt) = P[X(t + dt) = j | X(t) = i] = 1 - e^{-\alpha_{ij} \cdot dt}$$

$$= \text{(Taylor 1}^{st} \text{ order expansion)}$$

$$\alpha_{ij} \cdot dt + \theta(dt), \quad \lim_{dt \to 0} \frac{\theta(dt)}{dt} = 0$$

$$p_{ii}(dt) = 1 - \sum_{j \neq i} p_{ij}(dt) = 1 - dt \cdot \sum_{j \neq i} \alpha_{ij} + \theta(dt)$$

Discrete-time

$$p_{ij} = P[X(n+1) = j | X(n) = i]$$

$$\underline{P}(n+1) = \underline{P}(n) \cdot \underline{\underline{A}}$$

$$\underline{\underline{A}} = \begin{bmatrix} p_{00} & p_{01} & \dots & p_{0N} \\ p_{10} & p_{11} & \dots & p_{1N} \\ \dots & \dots & \dots & \dots \\ p_{N0} & p_{N1} & \dots & p_{NN} \end{bmatrix}$$

Continuous-time

$$\alpha_{ij} = P[X(t+dt) = j|X(t) = i]$$

$$\underline{P}(t+dt) = \underline{P}(t) \cdot \underline{\underline{A}}$$

$$\underline{\underline{A}} = \begin{bmatrix} p_{00} & p_{01} & \dots & p_{0N} \\ p_{10} & p_{11} & \dots & p_{1N} \\ \dots & \dots & \dots & \dots \\ p_{N0} & p_{N1} & \dots & p_{NN} \end{bmatrix}$$

$$\underline{\underline{A}} = \begin{bmatrix} 1 - dt \cdot \sum_{j=1}^{N} \alpha_{0j} & \alpha_{01} \cdot dt & \dots & \alpha_{0N} \cdot dt \\ \alpha_{10} \cdot dt & 1 - dt \cdot \sum_{j=0}^{N} \alpha_{1j} & \dots & \alpha_{1N} \cdot dt \\ \dots & \dots & \dots & \dots \end{bmatrix}$$

The conceptual model: the fundamental matrix equation (1)

$$egin{aligned} igl[P_0igl(t+dtigr) P_1igl(t+dtigr)P_Nigl(t+dtigr) &=& igl[P_0igl(tigr) P_1igl(tigr)P_Nigl(tigr) igr] \cdot egin{aligned} &=& igl[P_0igl(tigr) P_1igl(tigr)P_Nigl(tigr) igr] \cdot igl[&=& igl(1-dt\cdot\sum_{j=1}^Nlpha_{0j} &lpha_{0i}\cdot dt & ... &lpha_{0N}\cdot dt \ &lpha_{10}\cdot dt & 1-dt\cdot\sum_{j=0}^Nlpha_{1j} & ... &lpha_{1N}\cdot dt \ & ... & lpha_{1N}\cdot dt \ & ... & ... & ... & ... & ... \end{aligned}$$

• First-equation:

$$P_{0}(t+dt) = \left[1 - dt \sum_{j=1}^{N} \alpha_{0j}\right] P_{0}(t) + \alpha_{10} P_{1}(t) \cdot dt + \dots + \alpha_{N0} P_{N}(t) dt$$

$$P_{0}(t+dt) = \left[1 - dt \sum_{j=1}^{N} \alpha_{0j}\right] P_{0}(t) + \alpha_{10} P_{1}(t) \cdot dt + \dots + \alpha_{N0} P_{N}(t) dt$$

subtract $P_0(t)$ on both sides

$$P_0(t+dt) - P_0(t) = P_0(t) - P_0(t) - \sum_{j=1}^{N} \alpha_{0j} P_0(t) dt + \alpha_{10} P_1(t) dt + \dots + \alpha_{N0} P_N(t) dt$$

divide by *dt*

$$\frac{P_0(t+dt)-P_0(t)}{dt} = -\sum_{j=1}^{N} \alpha_{0j} P_0(t) + \alpha_{10} P_1(t) + \dots + \alpha_{N0} P_N(t)$$

$$\int \int dt \, dt \to 0$$

$$\lim_{dt\to 0} \frac{P_0(t+dt) - P_0(t)}{dt} = \frac{dP_0}{dt} = -\sum_{j=1}^{N} \alpha_{0j} \cdot P_0(t) + \alpha_{10} \cdot P_1(t) + \dots + \alpha_{N0} \cdot P_N(t)$$

The conceptual model: The Transition Probability Matrix

$$\frac{dP_0}{dt} = -\sum_{j=1}^{N} \alpha_{0j} P_0(t) + \alpha_{10} P_1(t) + \dots + \alpha_{N0} P_N(t) = [P_0(t), P_1(t), \dots, P_N(t)] \cdot \begin{bmatrix} -\sum_{j=1}^{N} \alpha_{0j} \\ \alpha_{10} \\ \dots \\ \alpha_{N0} \end{bmatrix}$$

Extending to the other equations:

$$\frac{dP}{dt} = \underline{P}(t) \cdot \underline{A}^*, \ \underline{A}^* = \begin{bmatrix} -\sum_{j=1}^{N} \alpha_{0j} & \alpha_{01} & \dots & \alpha_{0N} \\ -\sum_{j=1}^{N} \alpha_{0j} & \alpha_{01} & \dots & \alpha_{1N} \\ \alpha_{10} & -\sum_{j=0}^{N} \alpha_{1j} & \dots & \alpha_{1N} \\ \dots & \dots & \dots & \dots \end{bmatrix}$$
TRANSITION RATE
MATRIX
It will be indicated as A

System of N+1 linear, first-order differential equations in the unknown state probabilities

$$P_{j}(t), j = 0, 1, 2, ..., N, t \ge 0$$

Consider a system made by one component which can be in two states: working or failed. Assume constant failure rate λ and constant repair rate μ . You are required to:

- Draw the Markov diagram
- Find the transition rate matrix, A

Consider a system made by N identical components which can be in two states: working or failed. Assume constant failure rate λ , that N repairman are available and that the single component repair rate is constant and equal to μ . You are required to:

- Draw the Markov diagram
- Find the transition rate matrix, A

Example 3: system with *N* identical components and 1 repairman available

Consider a system made by N identical components which can be in two states: working or failed. Assume constant failure rate λ , that 1 repairman is available and that the component repair rate is constant and equal to μ . You are required to:

- Draw the Markov diagram
- Find the transition rate matrix

Solution to the Fundamental Equation

Solution to the fundamental equation of the Markov process continuous in time

$$\begin{cases}
\frac{d\underline{P}}{dt} = \underline{P}(t) \cdot \underline{A} \\
\underline{P}(0) = \underline{C}
\end{cases}$$
where
$$\underline{\underline{A}} = \begin{pmatrix}
-\sum_{j=1}^{N} \alpha_{0j} & \alpha_{01} & \dots & \alpha_{0N} \\
\alpha_{10} & -\sum_{j=0}^{N} \alpha_{1j} & \dots & \alpha_{1N} \\
\vdots & \vdots & \vdots & \vdots \\
\dots & \dots & \dots & \dots
\end{pmatrix}$$

System of *N*+1 linear, first-order differential equations in the unknown state probabilities

$$P_{j}(t), j = 0,1,2,...,N, t \ge 0$$



USE LAPLACE TRANSFORM

- Laplace Transform: $\tilde{P}_{j}(s) = L[P_{j}(t)] = \int_{0}^{\infty} e^{-st} P_{j}(t) dt, \ j = 0,1,...,N$
- First derivative: $L\left(\frac{dP_j(t)}{dt}\right) = s \cdot \tilde{P}_j(s) P_j(0), \quad j = 0,1,...,N$ Apply the Laplace operator to $\frac{d\underline{P}}{dt} = \underline{P}(t) \cdot \underline{\underline{A}}$

$$L\left\lceil \frac{d\underline{P}(t)}{dt}\right\rceil = L\left[\underline{P}(t) \cdot \underline{\underline{A}}\right]$$

First derivative
$$\leftarrow s\underline{\tilde{P}}(s) - \underline{C} = \underline{\tilde{P}}(s) \cdot \underline{\underline{A}} \longrightarrow \text{Linearity}$$

$$\underline{\underline{\tilde{P}}}(s) = \underline{\underline{C}} \cdot \left[s \cdot \underline{\underline{I}} - \underline{\underline{A}} \right]^{-1}$$
 \(\begin{aligned}
\underline{P}(t) = \text{inverse transform of } \begin{aligned}
\underline{P}(s)
\end{aligned}

Solution to the Fundamental Equation: Steady State Probabilities

At steady state

$$\frac{\underline{P}(t) = \underline{\Pi}}{\frac{d\underline{P}(t)}{dt} = 0} \implies \frac{d\underline{P}(t)}{dt} = \underline{P}(t) \cdot \underline{\underline{A}} = \underline{\Pi} \cdot \underline{\underline{A}} = 0$$

Solve the (linear) system: $\frac{\underline{\Pi} \cdot \underline{A} = 0}{\sum_{j=0}^{N} \Pi_{j} = 1}$

$$\sum_{j=0}^{N} \Pi_{j} = 1$$

Solution to the Fundamental Equation: Steady State Probabilities

• At steady state: $\underline{P}(t) = \underline{\Pi}$ $\frac{d\underline{P}(t)}{dt} = 0$ $\Rightarrow \frac{d\underline{P}(t)}{dt} = \underline{P}(t) \cdot \underline{\underline{A}} = \underline{\Pi} \cdot \underline{\underline{A}} = 0$

• Solve the (linear) system:

$$\frac{\prod \cdot \underline{A}}{\sum_{j=0}^{N} \prod_{j} = 1}$$

• It can be shown that:

$$\Pi_{j} = \frac{D_{j}}{\sum_{i=0}^{N} D_{i}}$$

$$j = 0,1,2,...,N$$

$$D_{j} = \text{determinant of the so}$$

 $D_j = \text{determinant of the square matrix obtained from } \underline{\underline{A}}$ by **deleting** the *j*-th row and column

Consider a system made by one component which can be in two states: working ('0') or Failed ('1'). Assume constant failure rate λ and constant repair rate μ and that the component is working at t = 0: $\underline{C} = \begin{bmatrix} 1 & 0 \end{bmatrix}$

- You are required to find the component steady state and instantaneous availability

Quantity of Interest

• Unconditional probability of arriving in state j in the next dt departing from state i at time t: P[X(t + dt) = j, X(t) = i]

$$P[X(t+dt) = j, X(t) = i] = P[X(t+dt) = j|X(t) = i] \cdot P[X(t) = i] = p_{ij}(dt)P_i(t)$$

• Frequency of departure from state *i* to state *j*:

$$v_{ij}^{dep}(t) = \lim_{dt \to 0} \frac{P[X(t+dt) = j, X(t) = i]}{dt} = \lim_{dt \to 0} \frac{p_{ij}(dt)P_i(t)}{dt} = \alpha_{ij}P_i(t)$$

• Total frequency of <u>departure</u> from state *i* to any other state *j*:

$$v_{i}^{dep}(t) = \sum_{\substack{j=0 \ j \neq i}}^{N} v_{ij}^{dep}(t) = \sum_{\substack{j=0 \ j \neq i}}^{N} \alpha_{ij} \cdot P_{i}(t) = P_{i}(t) \sum_{\substack{j=0 \ j \neq i}}^{N} \alpha_{ij} = -\alpha_{ii} \cdot P_{i}(t)$$

• Unconditional probability of arriving in state j in the next dt departing from state i at time t: P[X(t + dt) = j, X(t) = i]

$$P[X(t+dt) = j, X(t) = i] = P[X(t+dt) = j|X(t) = i] \cdot P[X(t) = i] = p_{ij}(dt)P_i(t)$$

• Frequency of departure from state *i* to state *j*:

$$v_{ij}^{dep}(t) = \lim_{dt \to 0} \frac{P[X(t+dt) = j, X(t) = i]}{dt} = \lim_{dt \to 0} \frac{p_{ij}(dt)P_i(t)}{dt} = \alpha_{ij}P_i(t)$$
 (at steady state)
$$= v_{ij}^{dep} = \alpha_{ij} \cdot \prod_{i=1}^{dep} \frac{p_{ij}(dt)P_i(t)}{dt} = \alpha_{ij}P_i(t)$$

• Total frequency of <u>departure</u> from state *i* to any other state *j*:

$$v_i^{dep}(t) = \sum_{j=0}^{N} v_{ij}^{dep}(t) = \sum_{j=0}^{N} \alpha_{ij} \cdot P_i(t) = P_i(t) \sum_{j=0}^{N} \alpha_{ij} = -\alpha_{ii} \cdot P_i(t) \quad \text{(at steady state)} \quad v_i^{dep} = -\alpha_{ii} \cdot \Pi_i$$

• In analogy, considering the arrivals to state i from any state k:

$$v_{i}^{arr}(t) = \sum_{\substack{k=0 \ k \neq i}}^{N} \alpha_{ki} \cdot P_{k}(t)$$

$$v_{i}^{arr} = \sum_{\substack{k=0 \ k \neq i}}^{N} \alpha_{ki} \cdot \Pi_{k} \quad \text{(at steady state)}$$

$$\underline{\Pi} \cdot \underline{A} = 0 \quad \Rightarrow \quad \sum_{k=0}^{N} \alpha_{ki} \cdot \Pi_{k} = 0 \quad (i = 0, 1, 2, ..., N)$$

$$\underline{\alpha_{ii}} \cdot \Pi_{i} = \sum_{\substack{k=0 \ k \neq i}}^{N} \alpha_{ki} \cdot \Pi_{k} \quad (i = 0, 1, 2, ..., N)$$

AT STEADY STATE:

frequency of departures from state i = frequency of arrivals to state i

- SYSTEM FAILURE INTENSITY W_f :
 - Rate at which system failures occur
 - Expected number of system failures per unit of time
 - Rate of exiting a success state to go into one of fault

• SYSTEM FAILURE INTENSITY W_f :

- Rate at which system failures occur
- Expected number of system failures per unit of time
- Rate of exiting a success state to go into one of fault

$$W_f(t) = \sum_{i \in S} P_i(t) \cdot \lambda_{i \to F}$$

S =set of success states of the system

F = set of failure states of the system

 $P_i(t)$ = probability of the system being in the functioning state i at time t

 $\lambda_{i \to F}$ = conditional (transition) probability of leaving success state *i* towards failure states

• SYSTEM REPAIR INTENSIT W_r :

- Rate at which system repairs occur
- Expected number of system repairs per unit of time
- Rate of exiting a failed state to go into one of success

$$W_r(t) = \sum_{j \in F} P_j(t) \cdot \mu_{j \to S}$$

S = set of success states of the system

F = set of failure states of the system

 $P_j(t)$ = probability of the system being in the failure state j at time t

 $\mu_{j \to S}$ = conditional (transition) probability of leaving failure state *j* towards success states

Example 5: one component/one repairman

Consider a system made by one component which can be in two states: working ('0') or Failed ('1'). Assume constant failure rate λ and constant repair rate μ and that the component is working at t = 0: $\underline{C} = \begin{bmatrix} 1 & 0 \end{bmatrix}$

- You are required to find the failure and repair intensities

- Time of occupance of state i (sojourn time), T_i = time spent in a state i
- Is the time (t) that the system has already been in state i influencing the time (s) the system will remain in state i?

$$P(T_i > t + s | T_i > t) = P(X(t + u) = i, 0 \le u \le s | X(\tau) = i, 0 \le \tau \le t) =$$

$$= P(X(t + u) = i, 0 \le u \le s | X(t) = i) \text{ (by Markov property)}$$

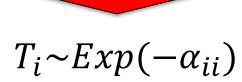
$$= P(X(u) = i, 0 \le u \le s | X(0) = i) \text{ (by homogeneity)}$$

$$= P(T_i > s) \quad \text{Memoryless Property}$$

• The only distribution satisfying the memoryless property is the **Exponential distribution**

$$T_i \sim Exp$$

• System departure **rate from state** i (at steady state): $-\alpha_{ii}$



• Expected sojourn time l_i : average time of occupancy of state i

$$l_i = \mathbb{E}\{T_i\} = \frac{1}{-\alpha_{ii}}$$

- Total frequency of departure at steady state: $v_i^{\text{dep}} = -\alpha_{ii} \cdot \Pi_i$
- Average time of occupancy of state: $l_i = \frac{1}{-\alpha_{ii}}$

$$v_{i}^{dep} = -\alpha_{ii} \cdot \Pi_{i} = \frac{\Pi_{i}}{l_{i}}$$

$$v_{i}^{dep} = v_{i}^{arr}$$

The **mean** proportion of time Π_i that the system spends in state i is equal to the total frequency of arrivals to state i multiplied by the mean duration of one visit in state i

 $\Pi_i = v_i^{arr} \cdot l_i$

- System instantaneous availability at time t
 - = sum of the probabilities of being in a success state at time t

$$p(t) = \sum_{i \in S} P_i(t) = 1 - q(t) = 1 - \sum_{j \in F} P_j(t)$$



In the Laplace domain

$$\tilde{p}(s) = \sum_{i \in S} \tilde{P}_i(s) = \frac{1}{s} - \sum_{j \in F} \tilde{P}_j(s)$$

S = set of success states of the system

F = set of failure states of the system

• TWO CASES:

1) Non-Reparaible Systems→ No repairs allowed

2) Reparaible Systems

→ Repairs allowed

- No repairs allowed \Rightarrow Reliability = Availability $R(t) \equiv p(t) = 1 q(t)$
- In the Laplace Domain: $\tilde{R}(s) = \sum_{i \in S} \tilde{P}_i(s) = \frac{1}{s} \sum_{i \in F} \tilde{P}_i(s)$
- Mean Time to Failure (MTTF):

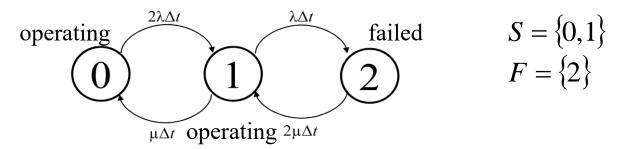
$$MTTF = \int_{0}^{\infty} R(t)dt = \left[\int_{0}^{\infty} R(t)e^{-st}dt\right]_{s=0} = \widetilde{R}(0) = \sum_{i \in S} \widetilde{P}_{i}(0) = \left[\frac{1}{S} - \sum_{j \in F} \widetilde{P}_{j}(s)\right]_{s=0}$$

- TWO CASES:
 - 1) Non-reparable systems→ No repairs allowed

2) Reparaible systems

→ Repairs allowed

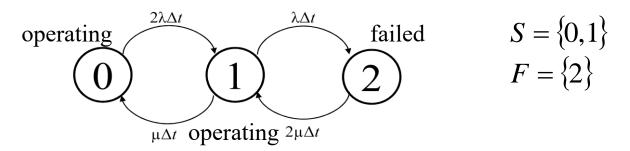
Parallel System of two identical components



$$R(t) = P(T > t) = P\{X(\tau) = 0 \text{ or } X(\tau) = 1, \forall \tau \in [0, t)\} = P_0^*(t) + P_1^*(t)$$

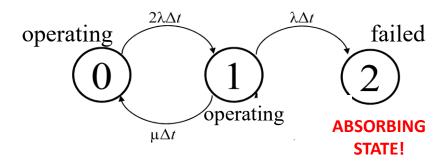
Can I trasnsform the Markov Diagram in such a way that $R(t) = P_0^*(t) + P_1^*(t)$?

Parallel System of two identical components

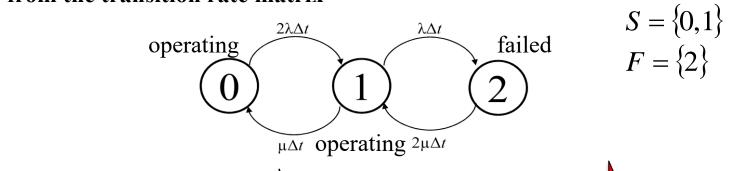


$$R(t) = P(T > t) = P\{X(\tau) = 0 \text{ or } X(\tau) = 1, \forall \tau \in [0, t)\} = P_0^*(t) + P_1^*(t)$$

Can I trasnsform the Markov Diagram in such a way that $R(t) = P_0^*(t) + P_1^*(t)$?



1. Transform the failed states $j \in F$ into absorbing states (the system cannot be repaired \rightarrow it is not possible to escape from a failed state). i.e., exclude all the failed states $j \in F$ from the transition rate matrix



$$\underline{A} = \begin{bmatrix} -2\lambda & 2\lambda & 0 \\ \mu & -(\mu + \lambda) & \lambda \\ \hline 0 & 2\mu & -2\mu \end{bmatrix}$$

$$\underline{A}^* = \begin{bmatrix} -2\lambda & 2\lambda & 0 \\ \mu & -(\mu + \lambda) & \lambda \\ 0 & 0 & 0 \end{bmatrix}$$

$$\underline{A}^* = \begin{bmatrix} -2\lambda & 2\lambda & 0 \\ \mu & -(\mu + \lambda) & \lambda \\ 0 & 0 & 0 \end{bmatrix}$$

The new matrix $\underline{\underline{A}}^*$ contains the transition rates for transitions **only** among the success states $i \in S$

(the "reduced" system is virtually functioning continuously with no interruptions)

2. Solve the **reduced problem** of $\underline{\underline{A}}^*$ for the probabilities $P_i^*(t)$, $i \in S$ of being in these (**transient**) safe states

$$\frac{d\underline{P}^{*}(t)}{dt} = \underline{P}^{*}(t) \cdot \underline{\underline{A}}^{*}$$

Reliability

$$R(t) = \sum_{i \in S} P_i^*(t)$$

Mean Time To Failure (MTTF)

$$MTTF = \int_{0}^{\infty} R(t)dt = \sum_{i \in S} \tilde{P}_{i}^{*}(0) = \tilde{R}(0)$$

NOTICE: in the reduced problem we have only transient states $\Rightarrow \prod_{i=1}^{\infty} P_{i}^{*}(\infty) = 0$

Consider a system made by 2 identical components in parallel. Each component can be in two states: working or failed. Assume constant failure rate λ , that 2 repairmen are available and that the single component repair rate is constant and equal to μ . You are required to:

- find the system reliability
- find the system MTTF

Consider a system made by 2 identical components in series. Each component can be in two states: working or failed. Assume constant failure rate λ , that 2 repairmen are available and that the single component repair rate is constant and equal to μ . You are required to:

- find the system reliability
- find the system MTTF