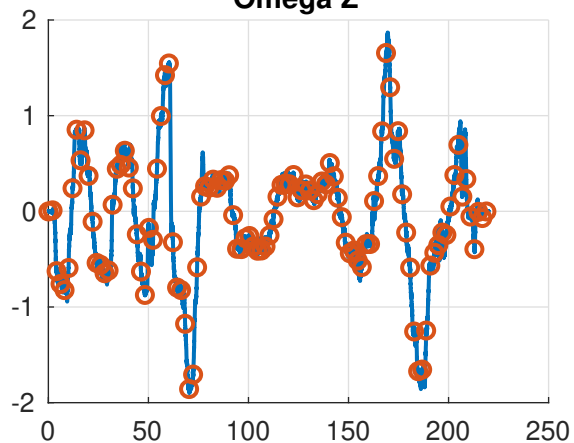


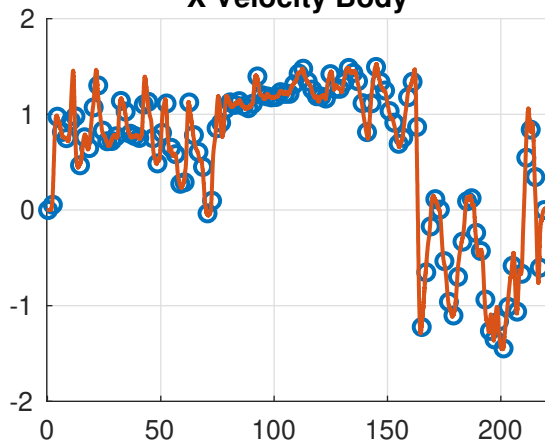
**Control Actions**



**Omega Z**



**X Velocity Body**



**Y Velocity Body**

