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Information geometry of quantum systems

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Sommario

In questa tesi viene presentata un'esposizione introduttiva sulla teoria geometrica dell'informazione quantistica. La trattazione inizia dalla teoria geometrica dell'informazione classica, definendo le varietà statistiche e la metrica informativa di Fisher e, infine, dimostrando la disuguaglianza di Cramér-Rao. Successivamente, viene introdotta la formulazione geometrica della meccanica quantistica: partendo dai postulati nella loro formulazione vettoriale, vengono definiti gli operatori di densità e viene mostrato come il prodotto interno dello spazio di Hilbert induca la metrica di Fubini-Study sullo spazio proiettivo di Hilbert. Nell'ultima parte, le due descrizioni geometriche vengono collegate definendo l'informazione quantistica di Fisher come generalizzazione di quella classica e trovando che coincide, a meno di un fattore costante, con la metrica di Fubini-Study. Si conclude utilizzando questa descrizione per dimostrare la versione quantistica della disuguaglianza di Cramér-Rao, risultato centrale della teoria della stima quantistica (QET).

Abstract

This thesis presents an introductory exposition on the information geometry of quantum mechanics. The treatment begins with classical information geometry, defining statistical manifolds and the Fisher information metric, and finally demonstrating the Cramér-Rao inequality. Subsequently, the geometric formulation of quantum mechanics is introduced: starting from the postulates in their vectorial formulation, density operators are defined, and it is shown how the inner product of the Hilbert space induces the Fubini-Study metric on the projective Hilbert space. In the last part, the two geometric descriptions are connected by defining Fisher quantum information as a generalization of the classical one and finding that it coincides, up to a constant factor, with the Fubini-Study metric. The conclusion employs this description to demonstrate the quantum version of the Cramér-Rao inequality, a central result of quantum estimation theory (QET).

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Introduction

Quantum mechanics is a fundamental theory that provides a mathematical framework for modeling the states and evolution of physical systems, as well as predicting the results of observations. Its development began around 1900 to explain physical phenomena that classical mechanics couldn't account for, such as black-body radiation and the photoelectric effect. By the early 1930s, the theory had been rigorously formulated, and many of its predictions had been experimentally confirmed.

One of the distinctive features of quantum mechanics is that the state of a quantum system only determines the probabilities of measurement outcomes, not the outcomes themselves. This suggests the possibility of interpreting quantum states as a generalization of probability distributions and extending the mathematical tools of probability theory to the quantum domain. The two mathematical formalisms can be precisely connected through their geometric descriptions.

The geometrical approach to quantum mechanics emerged in the 1970s and has led to significant theoretical and experimental advancements. In this approach, the state of a quantum system is represented by a point in a set called the state space. This state space is a Hilbert space, i.e., a complex vector space with an inner product. The system's evolutions are then described by trajectories in the state space and from the properties of the Hilbert space a rich geometric structure arises. The study of this structure has provided insights into quantization, the nature of entanglement, and has predicted phenomena such as the Berry phase and the Aharonov-Bohm effect.

Information geometry, developed in the 1940s, studies probability theory from a geometric perspective. Probability distributions are represented as points in a set, and assigning coordinates to a subset is equivalent to considering a family of probability distributions with parameters. A distance between probability distributions can be defined that measures how easy it is to distinguish them based on observed outcomes. This distance endows the set with a geometric structure, which has been used to study statistical models and develop parameter estimation theory. The Cramér-Rao bound, a key result of information geometry, provides a lower bound on the efficiency of parameter estimation from measurement out-

comes.

In the 1990s, it was shown that the intrinsic geometry of quantum systems can be understood as a generalization of an information geometric structure. In this view, estimating the state of a quantum system is a generalization of a parameter estimation problem in probability theory. This approach is known as quantum estimation theory (QET), and the quantum Cramér-Rao bound dictates a limit to the amount of information retrievable from a quantum system. Many other results from information geometry were generalized in this way to quantum mechanics, bringing significant advances to the theory of quantum information (QI) in general.

Quantum information and quantum estimation theory form the theoretical foundation of various rapidly developing quantum technologies such as quantum computing, quantum metrology, quantum sensing, and quantum cryptography. Among them, QET plays a crucial role in quantum metrology, which aims to achieve high-precision measurements by leveraging the quantum properties of the systems involved.

Outline

This thesis provides an introductory exposition of the information geometrical structure of quantum systems, focusing on quantum estimation theory and the quantum Cramér-Rao bound. The treatment is limited to pure states of finite-dimensional quantum systems.

In Chapter 1, we introduce the theory of information geometry and classical parameter estimation. We begin by defining the manifold of probability distributions on finite sample spaces and the relationship between random variables and representations of tangent vectors. Next, we introduce the relative entropy as a squared pseudo-distance and use it to induce a Riemannian structure on the manifold of probability distributions, known as the Fisher information metric. Finally, we utilize this geometric structure to state and prove the Cramér-Rao bound.

In Chapter 2, we discuss the geometric formulation of quantum mechanics. We first state the postulates of quantum mechanics in terms of vectors in the Hilbert space, in the finite-dimensional case. Then, we define quantum states as equivalence classes of physically indistinguishable state vectors and identify them with pure density operators, restating the postulates of quantum mechanics using these terms. Lastly, we demonstrate that the Hilbert space is a fiber bundle with the space of quantum states as the base space. With this description, we use the inner product of the Hilbert space to intrinsically define a Riemannian structure on the space of quantum states: the Fubini-Study metric.

In Chapter 3, we explore the generalization of information geometry to quantum mechanics and introduce quantum estimation theory. We begin by highlighting several analogies between the geometric structure of quantum states and the

one of probability distributions. Then, we define the quantum Fisher information, which generalizes the classic Fisher information through the symmetric logarithmic derivative (SLD), and find that it is equal to the Fubini-Study metric up to a constant factor. Finally, we define quantum estimators and derive the quantum Cramér-Rao bound.

Chapter 1

Geometry of probability distributions

1.1 Manifolds of probability distributions

In this section, we introduce the differential geometrical description of probability distributions and statistical models. The treatment mainly follows the one of [1], where further details can be found.

1.1.1 Space of probability distributions

Consider a *random process* and the set \mathcal{X} of all its possible outcomes. We call this set the *sample space*, and we will only consider random processes for which it is finite. Then, a *probability distribution* on \mathcal{X} is a function $p \in \mathbb{R}^{\mathcal{X}} := \{f \mid f: \mathcal{X} \rightarrow \mathbb{R}\}$ which satisfies

$$p(x) \geq 0 \quad \forall x \in \mathcal{X} \quad \text{and} \quad \sum_{x \in \mathcal{X}} p(x) = 1 \quad (1.1.1)$$

where $p(x)$ represents the probability of the outcome x .

Further, every function $A \in \mathbb{R}^{\mathcal{X}}$ represents a real *random variable*, as it maps every outcome of a random process to a number. Then the *expectation value* of A when the underlying probability distribution is p is expressed by

$$\mathbb{E}_p[A] := \sum_{x \in \mathcal{X}} p(x)A(x) \quad (1.1.2)$$

Also, given two random variables A, B their *covariance* is

$$\text{Cov}_p[A, B] := \mathbb{E}_p[(A - \mathbb{E}_p[A])(B - \mathbb{E}_p[B])] \quad (1.1.3)$$

and so the *variance* of a random variable A is

$$\text{V}_p[A] := \text{Cov}_p[A, A] = \mathbb{E}_p[(A - \mathbb{E}_p[A])^2] \quad (1.1.4)$$

Let now N be the cardinality of \mathcal{X} . To have a picture of $\mathbb{R}^{\mathcal{X}}$ we can index the outcomes and consider the natural isomorphism between $\mathbb{R}^{\mathcal{X}}$ and \mathbb{R}^N

$$f \leftrightarrow (f(x_1), \dots, f(x_N)) \quad (1.1.5)$$

then it's easy to recognize that the *space of probability distributions* is a convex subset of the affine subspace $\mathcal{A}_1 := \{f \in \mathbb{R}^{\mathcal{X}} \mid \sum_{x \in \mathcal{X}} f(x) = 1\}$. In particular, it is the set resulting from the convex mixing of the trivial probability distributions $f_k(x_i) = \delta_{ik}$, represented by the unit vectors of \mathbb{R}^N . Finally, it's also interesting to consider the inner product induced on $\mathbb{R}^{\mathcal{X}}$ by the Euclidean one of \mathbb{R}^N . Let p be a probability distribution and A a random variable, then

$$p \cdot A = \sum_{x \in \mathcal{X}} p(x) A(x) = \mathbb{E}_p[A] \quad (1.1.6)$$

1.1.2 Statistical models and manifolds

We call an n -dimensional *statistical model* on \mathcal{X} a family of probability distributions that are globally parametrized by n real-valued variables. Formally this is a subset \mathcal{S} of the space of probability distributions with an invertible function $\psi: \mathcal{S} \rightarrow \Xi \subseteq \mathbb{R}^n$, so that we may write

$$\mathcal{S} = \left\{ p_{\xi} \mid \exists \xi = (\xi^{(1)}, \dots, \xi^{(n)}) \in \Xi : p_{\xi} = \psi^{-1}(\xi) \right\} \quad (1.1.7)$$

where $p_{\xi}(x)$ may be equivalently written as $p(x; \xi)$ or $p(x; \xi^{(1)}, \dots, \xi^{(n)})$. This definition of a statistical model reflects the act of hypothesizing an underlying model, that may depend on some parameters, for the generation of the random variable's samples. Then only a subset, here represented by \mathcal{S} , of all the possible probability distributions is considered as a candidate of the underlying probability distribution, and every candidate probability distribution is identified uniquely by the corresponding parameters, here represented by ξ .

We now introduce some additional requirements to statistical models so that we may define well-behaved manifolds from them. Firstly we regard \mathcal{S} as a subset of \mathcal{A}_1 equipped with the topology induced by the standard one of \mathbb{R}^N . Then we assume that

$$\begin{aligned} \Xi &\text{ is an open set} \\ \psi &\text{ is a } C^\infty \text{ diffeomorphism from } \mathcal{S} \text{ to } \Xi \end{aligned} \quad (1.1.8)$$

This allows us to differentiate the probability distributions with respect to the parameters so that $\partial_i p(x; \xi)$ is well defined, where we wrote $\partial_i := \frac{\partial}{\partial \xi^{(i)}}$. These conditions also imply that the pair \mathcal{S} and ψ form a chart of \mathcal{S} . Then for any another statistical model on \mathcal{S} with parametrization $\psi': \mathcal{S} \rightarrow \Xi' \subseteq \mathbb{R}^n$ that follows eq. (1.1.8), the composed function $\psi' \circ \psi^{-1}: \Xi \rightarrow \Xi'$ will be a C^∞ diffeomorphism. By

considering all the possible parametrizations of this kind we may treat \mathcal{S} as a C^∞ -differentiable manifold, where statistical models are the charts and the different parametrizations are the coordinate systems; we call manifolds like these *statistical manifolds*.

From our definitions, it is clear that the maximal dimension of a model is $n = N - 1$ and that every statistical manifold is a submanifold of

$$\mathcal{P} := \{p \in \mathbb{R}^{\mathcal{X}} \mid p(x) > 0 \quad \forall x \in \mathcal{X} \quad \text{and} \quad \sum_{x \in \mathcal{X}} p(x) = 1\} \quad (1.1.9)$$

that we call the *manifold of probability distributions*. Notice that \mathcal{P} is the interior of the space of probability distributions, this is because from our definitions follows that every $(N - 1)$ -dimensional statistical manifold must be an open subset of \mathcal{A}_1 .

1.1.3 The tangent space and its representations

We will now study tangent vectors of statistical manifolds looking for useful statistical interpretations of them. To do this we will use the fact that, as explained in section 1.1.1, \mathcal{P} can be embedded in the space of random variables $\mathbb{R}^{\mathcal{X}}$. Then we can try to also embed the tangent spaces in $\mathbb{R}^{\mathcal{X}}$ in some meaningful ways, thus linking tangent vectors and random variables.

The mixture representation

Since \mathcal{P} is an open subset of the affine space \mathcal{A}_1 we can naturally identify the tangent space at every point with the displacement vector space

$$\mathcal{A}_0 := \{A \in \mathbb{R}^{\mathcal{X}} \mid \sum_{x \in \mathcal{X}} A(x) = 0\} \quad (1.1.10)$$

This is the natural embedding of $T_p(\mathcal{P})$ that arises from the trivial embedding of \mathcal{P} in $\mathbb{R}^{\mathcal{X}}$, in fact for any $X \in T_p(\mathcal{P})$ we can define

$$X^{(m)}(x) := X(p(x)) \quad (1.1.11)$$

then by considering a parametrization $\{\xi^{(i)}\}$ of \mathcal{P} and its relative coordinate basis $\{\partial_i\}$ we have that

$$\partial_i^{(m)}(x) = \partial_i p(x; \xi) \in \mathcal{A}_0 \quad (1.1.12)$$

since

$$\sum_{x \in \mathcal{X}} \partial_i p(x; \xi) = \partial_i \sum_{x \in \mathcal{X}} p(x; \xi) = 0 \quad (1.1.13)$$

Finally, from eq. (1.1.8) follows that $\partial_i p(x; \xi)$ are $N - 1$ linearly independent functions and thus

$$X^{(m)} \leftrightarrow X \quad (1.1.14)$$

is an isomorphism and

$$T_p(\mathcal{P}) \sim T_p^{(m)}(\mathcal{P}) \coloneqq \{X^{(m)} \mid X \in T_p(\mathcal{P})\} = \mathcal{A}_0 \quad \forall p \in \mathcal{P} \quad (1.1.15)$$

We call $X^{(m)}$ the *mixture representation* or *m-representation* of X .

The exponential representation

Since $T_p(\mathcal{P})$ is an $(N - 1)$ -dimensional vector space, for every p we may try to identify it to the subspace of $\mathbb{R}^{\mathcal{X}}$ orthogonal to p with respect to the inner product defined in eq. (1.1.6). This is interesting given the statistical meaning of the inner product between a generic element of $\mathbb{R}^{\mathcal{X}}$ and a probability distribution. For every $p \in \mathcal{P}$ the orthogonal space is

$$\mathcal{A}_p^\perp \coloneqq \{A \in \mathbb{R}^{\mathcal{X}} \mid p \cdot A = E_p[A] = 0\} \quad (1.1.16)$$

that is the space of random variables with null expectation value when the underlying probability distribution is p .

Now we wish to find a natural isomorphism between $T_p(\mathcal{P})$ and \mathcal{A}_p^\perp . One way to do this that will prove to be useful is to consider the following alternative embedding of \mathcal{P} in $\mathbb{R}^{\mathcal{X}}$

$$p \mapsto \ln p \in \mathbb{R}^{\mathcal{X}} \quad (1.1.17)$$

then, for any $X \in T_p(\mathcal{P})$ we can define

$$X^{(e)}(x) \coloneqq X(\ln p(x)) = \frac{X(p(x))}{p(x)} \quad (1.1.18)$$

and by considering a parametrization $\{\xi^{(i)}\}$ of \mathcal{P} and its relative coordinate basis $\{\partial_i\}$ we have that

$$\partial_i^{(e)}(x) = \partial_i \ln p(x; \xi) \in \mathcal{A}_p^\perp \quad (1.1.19)$$

since

$$E_p[\partial_i \ln p(x; \xi)] = \sum_{x \in \mathcal{X}} p(x; \xi) \frac{\partial_i p(x; \xi)}{p(x; \xi)} = \sum_{x \in \mathcal{X}} \partial_i p(x; \xi) = 0 \quad (1.1.20)$$

It's easy to prove that the linear independence of $\partial_i \ln p(x; \xi)$ follows from the one of $\partial_i p(x; \xi)$ and thus

$$X^{(e)} \leftrightarrow X \quad (1.1.21)$$

is an isomorphism and

$$T_p(\mathcal{P}) \sim T_p^{(e)}(\mathcal{P}) \coloneqq \{X^{(e)} \mid X \in T_p(\mathcal{P})\} = \mathcal{A}_p^\perp \quad \forall p \in \mathcal{P} \quad (1.1.22)$$

We call $X^{(e)}$ the *exponential representation* or *e-representation* of X .

From their definitions, we have that the two representations of a tangent vector $X \in T_p(\mathcal{P})$ are related as follows

$$X^{(m)}(x) = X^{(e)}(x)p(x) \quad (1.1.23)$$

and that while $T_p^{(m)}(\mathcal{P})$ is the same for every p , $T_p^{(e)}(\mathcal{P})$ varies since the set of random variables with null expectation value will differ depending on the underlying probability distribution.

1.2 The information metric

In this section, we derive and justify the Fisher information metric. We start by showing that the relative entropy can be thought of as a squared pseudo-distance on the space of probability distributions, following the approach of [2]. Next, we discuss the relationship between the metric tensor of a Riemannian manifold and its squared geodesic distance, and we generalize it to divergences as in [1]. Lastly, we show that the relative entropy is a divergence and from it, we derive the Fisher information metric.

1.2.1 Relative entropy

Given a statistical manifold, we may ask ourselves if a certain metric can be naturally defined on it. Such a metric would give rise to a Riemannian connection and consequently to a geodesic distance between elements of the manifold. For this reason, we should first find a statistical meaning to the notion of distance between probability distributions and only then try to find a metric coherent with it.

One natural way to proceed is to consider how hard it is to distinguish a probability distribution from another one by extracting some samples. More precisely let's assume that a random process has an underlying probability distribution q and that N_s samples are generated. Then we can consider the probability that the resulting frequencies f_i of the samples correspond to the probabilities p_i of another probability distribution p .

For simplicity, let's consider the $N = 2$ case, i.e. the case of binomial distributions. Let $\mathbf{q} = (t, 1-t)$ and $\mathbf{p} = (r, 1-r)$ be two probability distributions. Then if N_s samples are drawn with underlying probability q , the probability $P_{N_s}(\mathbf{p})$ that the obtained frequencies correspond to \mathbf{p} is given by

$$P_{N_s}(\mathbf{p}) = \binom{N_s}{N_s \cdot r} t^{N_s \cdot r} (1-t)^{N_s \cdot (1-r)}$$

then by assuming $r \neq 0, 1$ and using Stirling's formula, we obtain the following asymptotic behavior for $N_s \rightarrow \infty$

$$P_{N_s}(\mathbf{p}) \sim \exp\left\{-N_s\left[r \ln\left(\frac{r}{t}\right) + (1-r) \ln\left(\frac{1-r}{1-t}\right)\right]\right\} \quad (1.2.1)$$

so the probability decreases exponentially with N_s times the factor in the square parenthesis. This factor only depends on the probability distributions p and q , and one may recognize it from statistics as the *relative entropy* of the two distributions. For a generic finite sample space \mathcal{X} , the relative entropy is defined as

$$S(p \parallel q) := \sum_{x \in \mathcal{X}} p(x) \ln\left(\frac{p(x)}{q(x)}\right) \quad (1.2.2)$$

More generally it can be shown that the following theorem holds [2, pg. 42]

Theorem 1 (Sanov's Theorem). *Let $\mathcal{E} \subset \mathcal{P}$ be a closed set of probability distributions without isolated points. Then if N_s samples are drawn with underlying probability distribution $q \in \mathcal{P}$, the probability $P_{N_s}(\mathcal{E})$ that the obtained frequencies correspond to an element in \mathcal{E} has the following asymptotic behavior*

$$P_{N_s}(\mathcal{E}) \sim e^{-N_s S(p_* \parallel q)} \quad \text{for } N_s \rightarrow \infty \quad (1.2.3)$$

where p_* is the element of \mathcal{E} for which $S(p_* \parallel q)$ is smallest.

Roughly speaking, this shows that the greater the relative entropy $S(p \parallel q)$ the faster the probability of obtaining frequencies in a small neighborhood of p decreases with the number of samples drawn with underlying probability q . In this view, relative entropy can serve as a kind of distance between probability distributions, but with some caveats. From the definition in eq. (1.2.2) relative entropy has the following properties

$$S(p \parallel q) \geq 0 \quad \forall p, q \in \mathcal{P} \quad (1.2.4)$$

$$S(p \parallel q) = 0 \iff p = q \quad (1.2.5)$$

but it is not symmetric and it doesn't follow the triangle inequality, so it is not a metric distance. We may ask ourselves if the asymmetry is an accident of our definition of relative entropy or if it is inherent in the distinguishability of probability distributions. The latter turns out to be true, as shown by the following example.

Example. Consider two coins, one fair and one with heads on both sides. We want to pick one and guess which one it is just by tossing it multiple times. Clearly, the game is not symmetric in the choice of the coin; in fact, if we pick the fair coin the first time we will get a tail we will be sure that we picked the fair one, while if we pick the double-head one we will only get heads but this result will always be also compatible with a fair coin that, by chance, is only giving heads.

This game is precisely a problem of distinguishability of probability distributions. In fact, we have the $N = 2$ sample space and two probability distributions: $\mathbf{p} = (0.5, 0.5)$ (the fair coin) and $\mathbf{q} = (1, 0)$ (the double-head coin), so the two relative entropies are $S(p \parallel q) \rightarrow \infty$ and $S(q \parallel p) = \ln 2$. If we pick the fair coin for large N_s , the obtained frequencies will approach \mathbf{p} ; then we consider the probability of obtaining these frequencies if the underlying distribution was q . This probability is identically 0, and it is coherent with Sanov's theorem since $S(p \parallel q) \rightarrow \infty$ and so $P_{N_s}(p) \sim e^{-N_s \cdot \infty} = 0$. Otherwise, if we pick the double-head coin the frequencies will always match exactly \mathbf{q} , and the probability of getting this if the underlying distribution was q is 0.5^{N_s} . This is coherent with Sanov's theorem since $S(q \parallel p) = \ln 2$ and so $P_{N_s}(q) \sim e^{-N_s \cdot \ln 2} = 0.5^{N_s}$.

Even though relative entropy doesn't follow triangle inequality, it can be shown to follow a generalization of the Pythagorean theorem [2, pg. 43]

Theorem 2 (Generalized Pythagorean theorem). *Let $\mathcal{E} \subset \mathcal{P}$ be a convex set and consider $p \in \mathcal{E}$ and $q \in \mathcal{P} \setminus \mathcal{E}$. Then*

$$S(p \parallel q) \geq S(p \parallel p_*) + S(p_* \parallel q) \quad (1.2.6)$$

where p_* is the element of the boundary $\partial\mathcal{E}$ for which $S(p_* \parallel q)$ is smallest.

This is a generalization of the Pythagorean theorem in the sense that if it was stated in terms of the Euclidean distance squared, the angle between $\overline{pp_*}$ and $\overline{p_*q}$ would be obtuse and so eq. (1.2.6) would be the corollary of the Pythagorean theorem for obtuse triangles. This suggests that the relative entropy may be regarded as an asymmetric distance squared and as we will see this is enough to define a metric on the manifold.

1.2.2 Squared Riemannian distances

Now that we have some notion of distance, we explore how to define a coherent metric on the manifold. First, we shall study this for a Riemannian distance. The notation and the definitions will follow the ones of [3].

Let (M, g) be a Riemannian manifold where g is the metric tensor, then consider a point $p \in M$. We define the *exponential map* in p as follows

$$\text{Exp}_p : T_p M \rightarrow M, \quad \text{Exp}_p(\mathbf{v}) := \gamma_{\mathbf{v}}(1) \quad (1.2.7)$$

where $\mathbf{v} \in T_p$ and $\gamma_{\mathbf{v}} : [0, 1] \rightarrow M$ is the unique geodesic tangent to v in p , i.e. satisfying $\gamma_{\mathbf{v}}(0) = p$ and $\gamma'_{\mathbf{v}}(0) = \mathbf{v}$. In general, this map will be well-defined only from a neighborhood of the origin of T_p to a neighborhood of p , since only locally the uniqueness of the geodesic curve is guaranteed. By eventually further

restricting the neighborhood, this map will also be 1-1 since locally the geodesic curves don't cross.

Then in this neighborhood, we have the inverse of the exponential map that maps $q \mapsto \mathbf{v}_q \in T_p M$ so that $\gamma_{\mathbf{v}_q}(1) = q$. Since $\gamma_{\mathbf{v}_q}$ is the only geodesic connecting p and q , the geodesic distance between them will be

$$L(p, q) = \int_0^1 \sqrt{g_{\gamma_{\mathbf{v}_q}(\lambda)}(\gamma'_{\mathbf{v}_q}(\lambda), \gamma'_{\mathbf{v}_q}(\lambda))} d\lambda \quad (1.2.8)$$

Because $\gamma_{\mathbf{v}_q}$ is a geodesic, by definition we have that $\gamma'_{\mathbf{v}_q}(\lambda)$ is parallel transported along the curve and so

$$g_{\gamma_{\mathbf{v}_q}(\lambda)}(\gamma'_{\mathbf{v}_q}(\lambda), \gamma'_{\mathbf{v}_q}(\lambda)) = g_p(\mathbf{v}_q, \mathbf{v}_q) \quad \forall \lambda \in [0, 1] \quad (1.2.9)$$

Finally then, we get

$$L(p, q) = \int_0^1 \sqrt{g_p(\mathbf{v}_q, \mathbf{v}_q)} d\lambda = \sqrt{g_p(\mathbf{v}_q, \mathbf{v}_q)} = \|\mathbf{v}_q\| \quad (1.2.10)$$

and so $\hat{\mathbf{v}}_q = \mathbf{v}_q/L(p, q)$.

Now chose a vector $\mathbf{dp} \in T_p M$ and let $q = \text{Exp}_p(\mathbf{dp})$. Then, let $\Gamma_{\hat{\mathbf{dp}}}$ be the unique geodesic curve such that $\Gamma_{\hat{\mathbf{dp}}}(0) = p$ and $\Gamma'_{\hat{\mathbf{dp}}}(0) = \hat{\mathbf{dp}}$. Clearly, this is the following reparametrization of $\gamma_{\mathbf{dp}}$

$$\Gamma_{\hat{\mathbf{dp}}}(l) = \gamma_{\mathbf{dp}}\left(\frac{l}{\|\mathbf{dp}\|}\right) = \gamma_{\mathbf{dp}}\left(\frac{l}{L(p, q)}\right) \quad (1.2.11)$$

and so $q = \Gamma_{\hat{\mathbf{dp}}}(L(p, q))$.

Now let $\{x^{(i)}\}$ be a coordinate system for the neighborhood; from the Taylor expansion of $\Gamma_{\hat{\mathbf{dp}}}(l)$ in $l = 0$ we get

$$\Gamma_{\hat{\mathbf{dp}}}^{(i)}(l) = \Gamma_{\hat{\mathbf{dp}}}^{(i)}(0) + \left. \frac{d\Gamma_{\hat{\mathbf{dp}}}^{(i)}(l)}{dl} \right|_{l=0} \cdot l + O(l^2) \quad (1.2.12)$$

then, from $\Gamma_{\hat{\mathbf{dp}}}(0) = p$, $\Gamma'_{\hat{\mathbf{dp}}}(0) = \hat{\mathbf{dp}}$ and $q = \Gamma_{\hat{\mathbf{dp}}}(L(p, q))$ we get that

$$q^{(i)} = p^{(i)} + \hat{dp}^i L(p, q) + O(L^2(p, q)) = p^{(i)} + dp^i + O(\|\mathbf{dp}\|^2) \quad (1.2.13)$$

for every q in the image of $\Gamma_{\hat{\mathbf{dp}}}$. Then, combining eq. (1.2.10) and eq. (1.2.13) we get

$$L^2(\{p^{(i)}\}, \{p^{(i)} + dp^i\}) \rightarrow L^2(p, q) = g_{ij} dp^i dp^j \quad \text{for small } dp^i \quad (1.2.14)$$

We define $L_p^2 : M \rightarrow [0, +\infty)$, $L_p^2(q) := L^2(p, q)$ and consider its Taylor expansion in $q = p$

$$L_p^2(\{p^{(i)} + dp^i\}) = \frac{1}{2} \left[\partial_i \partial_j L_p^2(q) \right]_{q=p} dp^i dp^j + O(dp^3) \quad (1.2.15)$$

where the first derivative vanishes because p is a minimum of L_p^2 . Then we get

$$g_{ij}^{(p)} = \frac{1}{2} \left[\partial_i \partial_j L_p^2(q) \right]_{q=p} \quad (1.2.16)$$

so the metric tensor in p is proportional to the Hessian matrix of L_p^2 in p . This is possible because the Hessian matrix of any C^2 function of a differentiable manifold evaluated in a critical point is a $\binom{0}{2}$ tensor.

We have thus found a way to recover the metric tensor from its squared Riemannian distance.

1.2.3 Divergences

As argued in the last paragraph of section 1.2.1, relative entropy has some properties of squared distances and so we may try to find a metric tensor coherent with it as we did in section 1.2.2.

Let M be a differentiable manifold and $D(\cdot \| \cdot) : M \times M \rightarrow [0, +\infty)$ a C^2 function (possibly asymmetric) satisfying

$$D(p \| q) \geq 0 \quad \text{and} \quad D(p \| q) = 0 \iff p = q \quad \forall p, q \in M \quad (1.2.17)$$

Then, given a coordinate system $\{\xi^{(i)}\}$ on M we have that every pair of points $(q, q') \in M \times M$ has coordinates $(\{\xi^{(i)}\}, \{\xi^{(i)'}\})$ and we use the following notation for partial derivatives in one of the two terms on the diagonal (p, p)

$$\begin{aligned} D[\partial_i \| \cdot] &: p \mapsto [\partial_i D(q \| q')]_{(q,q')=(p,p)} \\ D[\cdot \| \partial_i] &: p \mapsto [\partial'_i D(q \| q')]_{(q,q')=(p,p)} \end{aligned}$$

From the fact that the diagonal (p, p) is a constant surface of minima of D follows that

$$D[\partial_i \| \cdot] = D[\cdot \| \partial_i] \equiv 0 \quad (1.2.18)$$

so the diagonal is also a constant surface of the derivatives of D . Then by further deriving parallel to the diagonal, we get

$$\begin{aligned} (\partial_i + \partial'_i) D[\cdot \| \partial_j] &= D[\cdot \| \partial_i \partial_j] + D[\partial_i \| \partial_j] \equiv 0 \\ (\partial_j + \partial'_j) D[\partial_i \| \cdot] &= D[\partial_i \partial_j \| \cdot] + D[\partial_i \| \partial_j] \equiv 0 \end{aligned}$$

where we used the fact that since D is C^2 we can swap second-order derivatives. Finally, we get

$$D[\partial_i \partial_j \parallel \cdot] = D[\cdot \parallel \partial_i \partial_j] = -D[\partial_i \parallel \partial_j] =: g_{ij}^{(D)} \quad (1.2.19)$$

where from the fact that the diagonal is a surface of minima, it follows that the previous expression defines a (symmetric) positive semi-definite tensor. From eq. (1.2.18) and eq. (1.2.19) it follows that denoting

$$D_p^{(R)} : q \mapsto D(p \parallel q) \quad \text{and} \quad D_p^{(L)} : q \mapsto D(q \parallel p)$$

to second order, we get

$$D_p^{(R)}(q) = \frac{1}{2} g_{ij}^{(D)} d\xi^i d\xi^j + O(d\xi^2) \quad \text{and} \quad D_p^{(L)}(q) = \frac{1}{2} g_{ij}^{(D)} d\xi^i d\xi^j + O(d\xi^2)$$

where $d\xi^i := \xi_p^{(i)} - \xi_q^{(i)}$

and so to the lowest order, the asymmetry is not present.

Finally, if $g_{ij}^{(D)}$ is positive definite we say that D is a *divergence*, then $\frac{1}{2} g_{ij}^{(D)}$ defines a metric tensor and so a unique Riemannian structure on the manifold. The induced squared Riemannian distance coincides at the lowest order near the diagonal with the divergence.

1.2.4 The Fisher information metric

We now go back to the relative entropy, we report the definition given in section 1.2.1

$$S(p \parallel q) := \sum_{x \in \mathcal{X}} p(x) \ln \left(\frac{p(x)}{q(x)} \right)$$

this is a C^2 function of $\mathcal{P} \times \mathcal{P}$ and it follows eq. (1.2.17). So for any model \mathcal{S} with parameters $\{\xi^{(i)}\}$ we can define

$$g_{ij}^{(\mathcal{S})} = S[\cdot \parallel \partial_i \partial_j] = \partial'_i \partial'_j \sum_{x \in \mathcal{X}} p(x; \xi) \ln \left(\frac{p(x; \xi)}{q(x; \xi')} \right) \Big|_{\xi=\xi'} \quad (1.2.20)$$

And so we have

$$g_{ij}^{(\mathcal{S})} = - \sum_{x \in \mathcal{X}} p(x) \partial_i \partial_j \ln p(x; \xi) = -\mathbb{E}_p[\partial_i \partial_j \ln p(x; \xi)] \quad (1.2.21)$$

and equivalently

$$g_{ij}^{(\mathcal{S})} = \mathbb{E}_p \left[\frac{1}{p^2(x)} \partial_i p(x; \xi) \partial_j p(x; \xi) \right] = \mathbb{E}_p[\partial_i \ln p(x; \xi) \partial_j \ln p(x; \xi)] \quad (1.2.22)$$

$$= \sum_{x \in \mathcal{X}} \frac{\partial_i p(x; \xi) \partial_j p(x; \xi)}{p(x)} \quad (1.2.23)$$

where we used the fact that

$$\sum_{x \in \mathcal{X}} \partial_i \partial_j p(x; \xi) = \partial_i \partial_j \sum_{x \in \mathcal{X}} p(x; \xi) = 0 \quad (1.2.24)$$

Since we know that any $g_{ij}^{(D)}$ is positive semi-definite, $g_{ij}^{(S)}$ will be positive definite if and only if it is invertible. It can be easily shown that if the functions $\partial_i p(x; \xi)$ are linearly independent, then $g_{ij}^{(S)}$ is invertible and thus positive definite. Then, relative entropy is a divergence and in fact, it is also known as *Kullback-Leibler divergence* or *information divergence*.

Finally, then, $G_F := \{g_{ij}^{(S)}\}$ defines a metric tensor at every point and it is known as the *Fisher information metric*. This is, up to a constant factor, the unique metric induced by the relative entropy, and it plays a focal role in the geometrical modeling and interpretation of statistics.

1.2.5 The geometry of \mathcal{P}

The Fisher metric defines the inner product $\langle \cdot, \cdot \rangle_p$ between tangent vectors of a point $p \in \mathcal{P}$. Let us now express this inner product through the representations we defined in section 1.1.3. Given two tangent vectors $X, Y \in T_p \mathcal{P}$ from eq. (1.2.22) we find that

$$\langle X, Y \rangle_p = E_p[X^{(e)} Y^{(e)}] \quad (1.2.25)$$

while from eq. (1.2.23) we get

$$\langle X, Y \rangle_p = \sum_{x \in \mathcal{X}} \frac{X^{(m)}(x) Y^{(m)}(x)}{p(x)} \quad (1.2.26)$$

$$= \sum_{x \in \mathcal{X}} X^{(m)}(x) Y^{(e)}(x) = \sum_{x \in \mathcal{X}} X^{(e)}(x) Y^{(m)}(x) \quad (1.2.27)$$

These expressions will prove to be very useful in section 1.3.

We notice that in neither representation the inner product is the Euclidean one induced by $\mathbb{R}^{\mathcal{X}}$ on the respective embeddings. For such a representation we would have that

$$\langle X, Y \rangle_p = \sum_{x \in \mathcal{X}} X^{(0)}(x) Y^{(0)}(x) \quad (1.2.28)$$

then it's easy to guess that the embedding

$$p \mapsto 2\sqrt{p} =: p_{(0)} \quad (1.2.29)$$

is the one whose representation of the tangent spaces

$$X^{(0)} := X(2\sqrt{p}) = \frac{X(p)}{\sqrt{p}}, \quad X \in T_p(\mathcal{P}) \quad (1.2.30)$$

follows eq. (1.2.28). This means that the information geometry of \mathcal{P} , i.e. the geometry induced on it by the Fisher metric, is that of an N -dimensional round sphere (of radius 2) since

$$\sum_{x \in \mathcal{X}} p(x) = 1 \implies \sum_{x \in \mathcal{X}} p_{(0)}^2(x) = 4 \quad (1.2.31)$$

1.3 Parameter estimation

In this section, we will use the Riemannian structure of the Fisher metric to derive interesting results of probability theory and parameter estimation, following the treatment in [1]. First, we will define parameter estimators and their variance-covariance matrix. Next, we will show that the Fisher metric links the variance of random variables with the differential of their expectation value. Lastly, we will use these results to state and prove the Cramér-Rao bound.

1.3.1 Unbiased estimators

Consider a random process and an n -dim statistical model $\mathcal{S} = \{p_\xi \mid \xi \in \Xi\}$ of it, as defined in section 1.1.2; it is often the case that from a measured sample $x \in \mathcal{X}$ we want to estimate the parameters ξ of the underlying probability distribution, that we assume to be in \mathcal{S} .

The estimation is represented by a function

$$\hat{\xi} = (\hat{\xi}^{(1)}, \dots, \hat{\xi}^{(n)}) : \mathcal{X} \rightarrow \Xi \subseteq \mathbb{R}^n \quad (1.3.1)$$

that we call *estimator*. Each component $\hat{\xi}^{(i)}$ is a random variable, and we say that $\hat{\xi}$ is an *unbiased estimator* if

$$E_{p_\xi} [\hat{\xi}] = (E_{p_\xi} [\hat{\xi}^{(1)}], \dots, E_{p_\xi} [\hat{\xi}^{(n)}]) = \xi \quad \forall \xi \in \Xi \quad (1.3.2)$$

i.e. if for each $p_\xi \in \mathcal{S}$ the expectation value of the estimator is the correct parameter ξ .

Then for an unbiased estimator, we may represent the deviation from the true parameters with the variance-covariance matrix of the estimator $V_\xi [\hat{\xi}] := \{v_\xi^{ij}\}$ where

$$v_\xi^{ij} := \text{Cov}_{p_\xi} [\hat{\xi}^{(i)}, \hat{\xi}^{(j)}] = E_{p_\xi} [(\hat{\xi}^{(i)}(x) - \xi^i)(\hat{\xi}^{(j)}(x) - \xi^j)] \quad (1.3.3)$$

In particular, the elements on the diagonal are the variances of the components of the estimator.

1.3.2 Variance and expectation value

For a generic random variable $A \in \mathbb{R}^{\mathcal{X}}$ we may define a real function $E[A]$ on \mathcal{P} that maps every probability distribution p to the expectation value of A when the sample is generated with p as underlying probability distribution

$$E[A]: \mathcal{P} \rightarrow \mathbb{R} \quad p \mapsto E_p[A] \quad (1.3.4)$$

Since this is a function of the manifold \mathcal{P} , at every point p we may consider its differential $(dE[A])_p$. This is the element of the cotangent space $T_p^*(\mathcal{P})$ such that for any tangent vector $X \in T_p(\mathcal{P})$ we have

$$(dE[A])_p(X) = X(E[A]) \quad (1.3.5)$$

Also, because a metric is defined on \mathcal{P} we have a natural isomorphism between tangent and cotangent vectors, thus the gradient of $E[A]$ is the tangent vector defined by

$$\langle (gradE[A])_p, X \rangle_p = (dE[A])_p(X) = X(E[A]) \quad \forall X \in T_p(\mathcal{P}) \quad (1.3.6)$$

We now state and prove the following theorem that relates the deviation of a random variable to the gradient of its expectation value

Theorem 3. *For any random variable $A \in \mathbb{R}^{\mathcal{X}}$ we have that*

$$(gradE[A])_p^{(e)} = A - E_p[A] \quad \forall p \in \mathcal{P} \quad (1.3.7)$$

where the gradient is the dual tangent vector of the differential with respect to the Fisher metric.

Proof. For every $X \in T_p$ we have

$$\begin{aligned} X(E[A]) &= \sum_{x \in \mathcal{X}} X(p(x))A(x) = \sum_{x \in \mathcal{X}} X^{(m)}(x)A(x) \\ &= E_p[X^{(e)}A] = E_p[X^{(e)}(A - E_p[A])] \end{aligned}$$

where in the last equation we used the fact that $E_p[X^{(e)}] = 0$. We notice that

$$E_p[A - E_p[A]] = 0 \implies (A - E_p[A]) \in T_p^{(e)}(\mathcal{P})$$

and so there must exist a tangent vector $Y \in T_p(\mathcal{P})$ such that $Y^{(e)} = (A - E_p[A])$. Then

$$X(E[A]) = E_p[X^{(e)}Y^{(e)}] = \langle X, Y \rangle_p$$

and so from eq. (1.3.6) we have that $Y = (gradE[A])_p$ and so

$$(gradE[A])_p^{(e)} = A - E_p[A]$$

□

We also get the following

Corollary 3.1. *For any random variable A*

$$V_p[A] = \|(dE[A])_p\|_p^2 \quad (1.3.8)$$

Proof. Follows from theorem 3 noticing that

$$\begin{aligned} \|(dE[A])_p\|_p^2 &= \langle (gradE[A])_p, (gradE[A])_p \rangle_p \\ &= E_p[(A - E_p[A])^2] \end{aligned}$$

□

Let now \mathcal{S} be an n -dim statistical manifold, since it is a submanifold of \mathcal{P} we have that $T_p(\mathcal{S})$ is a linear subspace of $T_p(\mathcal{P})$ for every $p \in \mathcal{S}$. Then the gradient of the restriction on \mathcal{S} of a function of \mathcal{P} is its orthogonal projection on $T_p(\mathcal{S})$. In particular, we have that

$$T_p(\mathcal{P}) = T_p(\mathcal{S}) \oplus T_p(\mathcal{S})^\perp \quad (1.3.9)$$

and so we may uniquely decompose

$$(gradE[A])_p = v_{\parallel} + v_{\perp} \quad v_{\parallel} \in T_p(\mathcal{S}), v_{\perp} \in T_p(\mathcal{S})^\perp \quad (1.3.10)$$

then we find that $\forall X \in T_p(\mathcal{S})$

$$\langle (gradE[A]|_{\mathcal{S}})_p, X \rangle_p = X(E[A]) = \langle v_{\parallel} + v_{\perp}, X \rangle_p = \langle v_{\parallel}, X \rangle_p \quad (1.3.11)$$

and so $(gradE[A]|_{\mathcal{S}})_p = v_{\parallel}$.

Finally, we have the following theorem relating the variance of a random variable and the sensitivity of its expectation value to the changes in the model parameters

Theorem 4. *Given a statistical manifold S , for any random variable A we have that*

$$V_p[A] \geq \|(dE[A]|_{\mathcal{S}})_p\|_p^2 \quad (1.3.12)$$

where the equality holds if and only if

$$A - E_p[A] \in T_p^{(e)}(\mathcal{S}) \quad (1.3.13)$$

Proof. Follows immediately from Corollary 3.1 and eq. (1.3.11) □

1.3.3 The Cramér-Rao bound

We are now in the position to state and prove an important result of parameter estimation theory

Theorem 5 (Cramér-Rao bound). *Let $\mathcal{S} = \{p_\xi \mid \xi \in \Xi\}$ be an n -dim statistical model of \mathcal{P} . Then, for any unbiased estimator $\hat{\xi}$ the variance-covariance matrix $V_\xi[\hat{\xi}]$ satisfies*

$$V_\xi[\hat{\xi}] \geq G_F^{-1}(p_\xi) \quad (1.3.14)$$

in the sense that $V_\xi[\hat{\xi}] - G_F^{-1}(p_\xi)$ is positive semi-definite.

Proof. Let $A = c_i \hat{\xi}^{(i)}$ where c is an arbitrary element of \mathbb{R}^n . Then A is a random variable with $E_{p_\xi}[A] = c_i \xi^i$ and

$$\begin{aligned} V_{p_\xi}[A] &= E_{p_\xi}[(c_i \hat{\xi}^{(i)}(x) - c_i \xi^i)(c_j \hat{\xi}^{(j)}(x) - c_j \xi^j)] \\ &= E_{p_\xi}[c_i(\hat{\xi}^{(i)}(x) - \xi^i)(\hat{\xi}^{(j)}(x) - \xi^j)c_j] \\ &= c_i v_\xi^{ij} c_j \end{aligned}$$

Then letting $p = p_\xi$ from theorem 4 we get

$$c_i v_\xi^{ij} c_j \geq \| (dE[A]|_{\mathcal{S}})_p \|^2_p$$

where, in the coordinate basis of $\{\xi^{(i)}\}$

$$\begin{aligned} \| (dE[A]|_{\mathcal{S}})_p \|^2_p &= (\partial_i E[A])_p g^{ij}(p) (\partial_j E[A])_p \\ &= c_i g^{ij}(p) c_j \end{aligned}$$

and so, finally

$$c_i (v_\xi^{ij} - g^{ij}(p_\xi)) c_j \geq 0$$

□

An unbiased estimator that saturates eq. (1.3.14) is called an *efficient estimator* and is the best unbiased estimator in the sense that its variance is minimum between all unbiased estimators. It's important to notice that an efficient estimator doesn't always exist. This result shows that the efficiency with which we can infer the underlying probability distribution of a process is deeply linked with the information geometry of the model.

Chapter 2

Geometry of quantum states

2.1 Quantum mechanics

In this section the foundations of quantum mechanics are described, following the approach of [4]. We first state the postulates in terms of state vectors of the Hilbert space. Then, we define quantum states as equivalence classes of physically indistinguishable state vectors and show that their space is the complex projective space. Lastly, we identify quantum states with pure density operators and we restate the postulates of quantum mechanics using these terms.

2.1.1 The postulates of quantum mechanics

Quantum mechanics is a fundamental theory that provides a mathematical framework for modeling the states and evolution of physical systems, as well as predicting the results of observations. In what follows will state the postulates of quantum mechanics, roughly following the treatment in [4].

Postulate 0 (The Hilbert space). *Any isolated physical system is associated with a complex Hilbert space i.e. a, possibly infinite-dimensional, complex vector space \mathcal{H} with an inner product $\langle \cdot, \cdot \rangle$ that is also complete with respect to the metric induced by the inner product.*

If the Hilbert space is finite-dimensional with dimension N , then it is isomorphic to \mathbb{C}^N with a hermitian form as the inner product. In what follows we will only study systems that are associated with a finite-dimensional Hilbert space.

The chosen inner product allows us to define a canonical isomorphism between \mathcal{H} and its dual vector space \mathcal{H}^* , where for every $\mathbf{Z} \in \mathcal{H}$ its dual functional is defined as

$$\mathbf{Z}^* \equiv f_{\mathbf{Z}} : \mathcal{H} \rightarrow \mathbb{C} \quad f_{\mathbf{Z}}(\mathbf{X}) = \langle \mathbf{Z}, \mathbf{X} \rangle \quad \forall \mathbf{X} \in \mathcal{H} \quad (2.1.1)$$

We also define tensors T of type $\binom{p}{q}$ as multilinear maps

$$T : \mathcal{H}^{*p} \times \mathcal{H}^q \rightarrow \mathbb{C} \quad (2.1.2)$$

where vectors can be identified with tensors of type $\binom{1}{0}$ and dual vectors with tensors of type $\binom{0}{1}$. Operators, which are linear maps from \mathcal{H} to itself, can be identified with $\binom{1}{1}$ tensors. For any operator A , the corresponding tensor T_A is defined as

$$T_A(\mathbf{X}^*, \mathbf{Y}) = \mathbf{X}^*(A\mathbf{Y}) = \langle \mathbf{X}, A\mathbf{Y} \rangle \quad (2.1.3)$$

The tensor product \otimes between two tensors T and T' of type $\binom{p}{q}$ and $\binom{p'}{q'}$ is a tensor of type $\binom{p+p'}{q+q'}$ defined as

$$\begin{aligned} (T \otimes T')(\mathbf{X}_1^*, \dots, \mathbf{X}_{p+p'}^*, \mathbf{Y}_1, \dots, \mathbf{Y}_{q+q'}) \\ = T(\mathbf{X}_1^*, \dots, \mathbf{X}_p^*, \mathbf{Y}_1, \dots, \mathbf{Y}_q) \cdot T'(\mathbf{X}_{p+1}^*, \dots, \mathbf{X}_{p+p'}^*, \mathbf{Y}_{q+1}, \dots, \mathbf{Y}_{q+q'}) \end{aligned}$$

In particular, given a vector \mathbf{Y} and a dual vector \mathbf{X}^* , their tensor product is the operator

$$A(\mathbf{Z}) = \mathbf{X}^*(\mathbf{Z}) \cdot \mathbf{Y} = \langle \mathbf{X}, \mathbf{Z} \rangle \cdot \mathbf{Y} \quad (2.1.4)$$

The adjoint of any operator A is the operator A^\dagger such that

$$\langle A^\dagger \mathbf{X}, \mathbf{Y} \rangle = \langle \mathbf{X}, A \mathbf{Y} \rangle \quad \forall \mathbf{X}, \mathbf{Y} \in \mathcal{H} \quad (2.1.5)$$

It can be shown that this is always well-defined for finite-dimensional Hilbert spaces and that $(A^\dagger)^\dagger = A$. There are two families of operators that will be instrumental to the formulation of the remaining postulates: unitary operators and self-adjoint operators. Unitary operators are defined as operators U that preserve the inner product, i.e.

$$\langle U\mathbf{X}, U\mathbf{Y} \rangle = \langle \mathbf{X}, \mathbf{Y} \rangle \quad \forall \mathbf{X}, \mathbf{Y} \in \mathcal{H} \quad (2.1.6)$$

From eq. (2.1.5), it's easy to show that

$$U \text{ is unitary} \iff UU^\dagger = \mathbb{I} \text{ i.e. } U^{-1} = U^\dagger \quad (2.1.7)$$

from which also follows $UU^\dagger = U^\dagger U$. Self-adjoint operators are defined as operators A that are equal to their adjoint, i.e.

$$\langle A\mathbf{X}, \mathbf{Y} \rangle = \langle \mathbf{X}, A\mathbf{Y} \rangle \quad \forall \mathbf{X}, \mathbf{Y} \in \mathcal{H} \quad (2.1.8)$$

or, equivalently, $A = A^\dagger$. From their definition follows immediately that

$$\langle A\mathbf{X}, \mathbf{X} \rangle = \overline{\langle \mathbf{X}, A\mathbf{X} \rangle} = \overline{\langle A\mathbf{X}, \mathbf{X} \rangle} \in \mathbb{R} \quad \forall \mathbf{X} \in \mathcal{H} \quad (2.1.9)$$

We can now state the remaining postulates of quantum mechanics for the finite-dimensional case.

Postulate 1 (The state vectors). *Every non-zero vector of the Hilbert space completely characterizes a possible state of the system, we call such vectors state vectors. We thus have that the elements of*

$$\mathcal{H}_0 := \mathcal{H} \setminus \{0\} \quad (2.1.10)$$

describe all the possible states of the system.

For state vectors, we will also use the Dirac notation writing vectors as $|\psi\rangle$ and their dual as $\langle\psi|$. An exhaustive treatment of this notation may be found in [5].

Postulate 2 (Unitary evolution). *The state vectors of a closed system evolve only through unitary transformations of the Hilbert space. That is, the time evolution of any state vector $|\psi(t)\rangle$ is given by*

$$|\psi(t_2)\rangle = U(t_1, t_2) |\psi(t_1)\rangle \quad (2.1.11)$$

where $U(t_1, t_2)$ is a unitary operator that only depends on t_1 and t_2 .

We may interpret this as requiring that the evolution of a closed system preserves the structure we defined on the set \mathcal{H} , that is the vector space structure and the inner product space structure. Thus we expect the transformations to be invertible, and linear and to preserve the inner product; in this sense, unitary operators are the automorphisms of the Hilbert space.

Postulate 3 (Quantum measurements). *Quantum measurements are described by a collection of pairs $M = \{(M_x, x)\}_{x \in \mathcal{X}}$ of measurement operators M_x and outcomes $x \in \mathcal{X}$ such that the following completeness equation is satisfied*

$$\sum_{x \in \mathcal{X}} M_x^\dagger M_x = \mathbb{I} \quad (2.1.12)$$

where \mathbb{I} is the identity operator. Then, given a system in a state described by a state vector $|\psi\rangle$, the probability distribution of the outcomes is

$$p(x) = \frac{\langle\psi|M_x^\dagger M_x|\psi\rangle}{\langle\psi|\psi\rangle} \quad (2.1.13)$$

Finally, any interaction with the system that leads to the measurement of a specific outcome x transforms any state vector $|\psi\rangle$ before the measurement to a new state vector $|\psi'\rangle$ after the measurement according to

$$|\psi'\rangle = M_x |\psi\rangle \quad (2.1.14)$$

that depends on the outcome measured.

The probabilities of eq. (2.1.13) are well defined since

$$p(x) = \frac{\|M_x|\psi\rangle\|^2}{\|\psi\rangle\|^2} \geq 0 \quad \forall x \quad (2.1.15)$$

$$\sum_{x \in \mathcal{X}} p(x) = \frac{\langle\psi|\sum_x M_x^\dagger M_x|\psi\rangle}{\langle\psi|\psi\rangle} = 1 \quad (2.1.16)$$

We thus have that for any fixed measurement every state vector defines a probability distribution on the outcomes. In this sense, quantum states can be thought of as a generalization of probability distributions.

Quantum measurements define both the probability distributions and the state obtained after the measurement. If we are only interested in the measurement per se we can equate quantum measurements that share the same probability distributions, so that

$$M \sim M' \iff M_x^\dagger M_x = M'^\dagger M'_x \quad \forall x \in \mathcal{X} \quad (2.1.17)$$

and the equivalence classes that follow are known as *positive operator-valued measures* (POVMs). Then the following holds

Theorem 6 (POVMs). *Positive operator-valued measurements are uniquely determined by a collection of pairs $E = \{(E_x, x)\}_{x \in \mathcal{X}}$ of positive self-adjoint operators and outcomes $x \in \mathcal{X}$ such that*

$$\sum_{x \in \mathcal{X}} E_x = \mathbb{I} \quad (2.1.18)$$

Given a system in a state described by a state vector $|\psi\rangle$, the probability distribution of the outcomes is

$$p(x) = \frac{\langle\psi|E_x|\psi\rangle}{\langle\psi|\psi\rangle} \quad (2.1.19)$$

Then the POVM of a quantum measurement M is

$$E^{(M)} = \{(E_x^{(M)} = M_x^\dagger M_x, x)\}_{x \in \mathcal{X}} \quad (2.1.20)$$

Example: the qubit

The simplest non-trivial kind of quantum system is the one modeled by the 2-dimensional Hilbert space $\mathcal{H} = \mathbb{C}^2$: the *qubit*. The name refers to the fact that it can be regarded as a quantum version of the classical two-state system, the bit.

To perform explicit calculations we can express \mathbb{C}^2 vectors, dual vectors and operators with column vectors, raw vectors and square matrices respectively. Thus, for a fixed orthonormal basis $\{|0\rangle, |1\rangle\}$ we can write

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad (2.1.21)$$

so that any state vector $|\psi\rangle = c_0|0\rangle + c_1|1\rangle$ is expressed as

$$|\psi\rangle = \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} \quad \text{with } c_i \in \mathbb{C} \quad (2.1.22)$$

Then any operator O is represented by a 2×2 complex matrix

$$O = \begin{pmatrix} c_{1,1} & c_{1,2} \\ c_{2,1} & c_{2,2} \end{pmatrix} \quad \text{with } c_{i,j} \in \mathbb{C} \quad (2.1.23)$$

Self-adjoint operators are the Hermitian matrices, i.e., matrices equal to their conjugate transpose. A well-known real basis for 2×2 Hermitian matrices is the following

$$\mathbb{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (2.1.24)$$

where $\mathbb{1}$ is the identity matrix and σ_i are the Pauli matrices. Any self-adjoint operator A can thus be expressed as

$$A = a_0\mathbb{1} + a_1\sigma_1 + a_2\sigma_2 + a_3\sigma_3 = a_0\mathbb{1} + \vec{a} \cdot \vec{\sigma}, \quad \vec{a} = (a_1, a_2, a_3) \quad (2.1.25)$$

where $a_0 \in \mathbb{R}$ and $\vec{a} \in \mathbb{R}^3$.

Unitary operators are the 2×2 unitary matrices, i.e., invertible matrices whose inverse is equal to their conjugate transpose. Then they form a group under matrix multiplication so that any unitary matrix U can be expressed as

$$U = e^{iA} \quad \text{with } A = A^\dagger \quad (2.1.26)$$

and thus the general unitary evolution of a qubit is given by

$$U = \exp[i(a_0\mathbb{1} + \vec{a} \cdot \vec{\sigma})] = \exp[i\alpha\mathbb{1}] \cdot \exp\left[i\frac{\theta}{2}\hat{n} \cdot \vec{\sigma}\right] \quad (2.1.27)$$

$$= e^{i\alpha} \left(\cos \frac{\theta}{2} \mathbb{1} + i \sin \frac{\theta}{2} \hat{n} \cdot \vec{\sigma} \right) \quad (2.1.28)$$

where we used the notation $\alpha = a_0$, $\frac{\theta}{2} = \|\vec{a}\|$ and $\hat{n} = \frac{\vec{a}}{\|\vec{a}\|}$ that will be useful later on.

Finally, the positive operators of POVMs are the positive semidefinite matrices, i.e., Hermitian matrices whose eigenvalues are all non-negative. For 2×2 matrices, this means that the determinant and the trace are non-negative.

2.1.2 PVM and observables

There is a special class of quantum measurements we will be interested in: projection-valued measurements (PVM). PVMs are quantum measurements where the measurement operators $\{P_x\}$ are required to be orthogonal projectors, i.e.

$$P_x^\dagger = P_x \quad \forall x \quad (2.1.29)$$

$$P_x^2 = P_x \quad \forall x \quad (2.1.30)$$

and to form a complete set of orthogonal projectors

$$P_x P_y = \delta_{xy} P_x \quad \forall x, y \quad (2.1.31)$$

$$\sum_x P_x = \mathbb{I} \quad (2.1.32)$$

To understand these definitions we first state an important theorem from linear algebra about self-adjoint operators, a complete treatment and proof can be found in [6].

Theorem 7 (Spectral theorem). *Let \mathcal{H} be a finite-dimensional complex Hilbert space and A a self-adjoint operator on \mathcal{H} . Then there exists an orthonormal basis of eigenvectors of A with real eigenvalues.*

This means that for any self-adjoint operator, we may decompose the Hilbert space in orthogonal linear subspaces of eigenvectors with the same eigenvalue, the *eigenspaces*.

For any orthogonal projector P , we can show that

$$\begin{aligned} P|\psi\rangle = \lambda|\psi\rangle &\implies P^2|\psi\rangle = \lambda^2|\psi\rangle = P|\psi\rangle = \lambda|\psi\rangle \\ &\implies \lambda^2 = \lambda \\ &\implies \lambda = 0, 1 \end{aligned} \quad (2.1.33)$$

and, given an orthonormal base of eigenvectors $\{|e_i\rangle\}$ we may partition it into the two subsets $\{|e_j^{(0)}\rangle\}$ and $\{|e_k^{(1)}\rangle\}$ respectively of eigenvectors with eigenvalue 0 and 1. Then by expressing a generic vector as a linear combination of this base, we have that

$$|\psi\rangle = \sum_i \langle e_i | \psi \rangle |e_i\rangle \implies P|\psi\rangle = \sum_k \langle e_k^{(1)} | \psi \rangle |e_k^{(1)}\rangle \quad (2.1.34)$$

so that any orthogonal projector "orthogonally projects" vectors to its eigenspace with eigenvalue 1, which is thus also its image.

We can now recognize that a set of orthonormal projectors is complete when the spaces on which they project are orthogonal (eq. (2.1.31)) and add up to all the Hilbert space (eq. (2.1.32)). With this setting, it can be easily shown that the following corollary holds

Corollary 7.1. Any self-adjoint operator A with eigenvalues $\{\lambda_i\}$ may be expressed in terms of the projectors P_i of its eigenspaces as

$$A = \sum_i \lambda_i P_i \quad (2.1.35)$$

We thus have that, intuitively, PVMs are defined by decomposing the Hilbert space into orthogonal subspaces and then assigning a certain outcome to each one. In fact, if $|\psi_x\rangle$ is in the projected space of P_x the probability distribution of the outcomes will be

$$p(y) = \frac{\langle \psi_x | P_y^\dagger P_y | \psi_x \rangle}{\langle \psi_x | \psi_x \rangle} = \delta_{xy} \quad (2.1.36)$$

and also, after the measurement, any state vector is projected onto the subspace of the outcome

$$|\psi'\rangle = P_x |\psi\rangle \quad (2.1.37)$$

With this interpretation, it's easy to recognize an interesting property of PVMs: repeating the same PVM multiple times while the Hilbert space is evolving with the identity operator (i.e. is not changing) always leads to identical results. In fact, after the first measurement, if the measured outcome was x , we will have that

$$|\psi'_{(0)}\rangle = P_x |\psi\rangle \quad (2.1.38)$$

for any initial vector state $|\psi\rangle$. Then, repeating the same measurement, we will have the probability distribution

$$p(y) = \frac{\langle \psi | P_x^\dagger P_y^\dagger P_y P_x | \psi \rangle}{\langle \psi | P_x^\dagger P_x | \psi \rangle} = \delta_{xy} \quad (2.1.39)$$

and so we will get with certainty the same result. After the measurement, we will have the state vector

$$|\psi'_{(1)}\rangle = P_x P_x |\psi\rangle = P_x |\psi\rangle \quad (2.1.40)$$

and we can reiterate the same argument for the following measurements.

When considering well-defined measurable properties of a system, we may require repeated measurements to always give the same outcome if the system remains unchanged in between. From this intuitive concept follows the definition of an *observable* as a PVM with real-valued outcomes. Then, from Corollary 7.1, there is a 1-1 relationship between observables and self-adjoint operators through eq. (2.1.35), allowing us to identify any observable with its self-adjoint operator

$$\{P_i, \lambda_i\} \leftrightarrow A = \sum_i \lambda_i P_i \quad (2.1.41)$$

The expectation value of the observable when the system is in a state described by a state vector $|\psi\rangle$ is then given by

$$E[A] = \sum_i \lambda_i p_i = \sum_i \lambda_i \frac{\langle \psi | P_i^\dagger P_i | \psi \rangle}{\langle \psi | \psi \rangle} = \frac{\langle \psi | A | \psi \rangle}{\langle \psi | \psi \rangle} \quad (2.1.42)$$

Example: the qubit

We have already seen that any self-adjoint operator A can be expressed as

$$A = a_0 \mathbb{1} + \vec{a} \cdot \vec{\sigma} \quad \text{with} \quad a_0 \in \mathbb{R}, \vec{a} \in \mathbb{R}^3 \quad (2.1.43)$$

and so these also represent the observables of the qubit.

Let us now consider some examples of quantum measurements. In particular, we will consider the problem of discerning between two states of a qubit. This is an example of a quantum estimation problem.

We start by considering a qubit that we know to be in one of two possible orthonormal states, $|0\rangle$ or $|1\rangle$. Then we can consider a PVM

$$\{(P_0, \lambda_0), (P_1, \lambda_1)\} : P_0 = |0\rangle\langle 0| = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, P_1 = |1\rangle\langle 1| = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \quad (2.1.44)$$

that corresponds to the observable

$$A = \begin{pmatrix} \lambda_0 & 0 \\ 0 & \lambda_1 \end{pmatrix} \quad (2.1.45)$$

when λ_0 and λ_1 are real numbers. Then the probability distributions of the outcomes are

$$\begin{aligned} p_{|0\rangle}(\lambda_0) &= (1 \ 0) \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 & p_{|0\rangle}(\lambda_1) &= (1 \ 0) \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \\ p_{|1\rangle}(\lambda_0) &= (0 \ 1) \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0 & p_{|1\rangle}(\lambda_1) &= (0 \ 1) \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1 \end{aligned}$$

so that we can distinguish with certainty between the two states.

Consider now the same problem but where the two states are not orthogonal, for example, $|0\rangle$ and $|+\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$. Then the previous PVM will lead to the following probability distributions

$$\begin{aligned} p_{|0\rangle}(\lambda_0) &= 1 & p_{|0\rangle}(\lambda_1) &= 0 \\ p_{|+\rangle}(\lambda_0) &= \frac{1}{\sqrt{2}}(1 \ 1) \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{2} \\ p_{|+\rangle}(\lambda_1) &= \frac{1}{\sqrt{2}}(1 \ 1) \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}}\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{2} \end{aligned}$$

so that if the measured outcome is λ_1 we are certain that the state was $|+\rangle$, but if the measured outcome is λ_0 we cannot distinguish them. Thus if the two initial

states are equally likely, three times out of four we will not be able to distinguish them and it can be shown that this is the best we can do with a PVM for two non-orthogonal states.

We can improve our results by considering a POVM. In particular, we can consider the following POVM

$$E = \{(E_1, \lambda_1), (E_2, \lambda_2), (E_3, \lambda_3)\} \quad (2.1.46)$$

$$E_1 = |1\rangle\langle 1| = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, E_2 = |- \rangle\langle -| = \frac{1}{2} \begin{pmatrix} +1 & -1 \\ -1 & +1 \end{pmatrix}, E_3 = \frac{1}{2} \begin{pmatrix} +1 & +1 \\ +1 & -1 \end{pmatrix} \quad (2.1.47)$$

where $|- \rangle = \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)$, orthogonal to $|+\rangle$. Then one can verify that the probability distributions of the outcomes are

$$\begin{aligned} p_{|0\rangle}(\lambda_1) &= 0 & p_{|0\rangle}(\lambda_2) &= \frac{1}{2} & p_{|0\rangle}(\lambda_3) &= \frac{1}{2} \\ p_{|+\rangle}(\lambda_1) &= \frac{1}{2} & p_{|+\rangle}(\lambda_2) &= 0 & p_{|+\rangle}(\lambda_3) &= \frac{1}{2} \end{aligned}$$

so that half of the time we can distinguish them. It can be shown that this is the best we can do for two non-orthogonal states so that in this sense there is a degree of indistinguishability between non-orthogonal states, similar to the indistinguishability of probability distributions we discussed in section 1.2.1.

2.1.3 Quantum states

Following postulates 1 to 3, if we are given a state vector for the system, we can determine how it will evolve under unitary evolutions, the probability distributions of the outcomes of quantum measurements, and the vector state we will obtain after those measurements, depending on the outcomes. We may then ask if there are multiple state vectors that yield the same probabilities for any measurement and continue to do so after any unitary evolution or measurement. Such two vectors would be completely equivalent in their predictions, and we can regard them as describing the same quantum state. This leads to an equivalence relation between state vectors, so that quantum states are the equivalence classes.

We start by requiring that two equivalent state vectors have the same probability distributions for any measurement. This means that

$$|\psi\rangle \sim |\psi'\rangle \iff \frac{\langle\psi|M_x^\dagger M_x|\psi\rangle}{\langle\psi|\psi\rangle} = \frac{\langle\psi'|M_x^\dagger M_x|\psi'\rangle}{\langle\psi'|\psi'\rangle} \quad \forall x \quad (2.1.48)$$

for any quantum measurement $\{(M_x, x)\}$. It's easy to see that a sufficient condition is

$$\exists c \neq 0 \in \mathbb{C} : |\psi'\rangle = c|\psi\rangle \quad (2.1.49)$$

since for any operator M_x

$$\frac{\langle \psi' | M_x^\dagger M_x | \psi' \rangle}{\langle \psi' | \psi' \rangle} = \frac{\|c\|^2}{\|c\|^2} \cdot \frac{\langle \psi | M_x^\dagger M_x | \psi \rangle}{\langle \psi | \psi \rangle} \quad (2.1.50)$$

Then by choosing $M_x = |\psi\rangle\langle\psi|$, it's easy to show that eq. (2.1.49) is also a necessary condition.

We also note that for any operator A

$$A(c|\psi\rangle) = cA|\psi\rangle \quad \forall c \in \mathbb{C} \quad (2.1.51)$$

so that any operator has a well-defined action on equivalence classes. In particular, this holds for unitary operators and measurement operators, and so two state vectors in the same equivalence class will remain in the equivalence class after any unitary evolution or measurement.

We have thus proved that quantum states are the equivalence classes of

$$|\psi\rangle \sim |\psi'\rangle \iff \exists c \neq 0 \in \mathbb{C}: |\psi'\rangle = c|\psi\rangle \quad (2.1.52)$$

Then for any state vector $|\psi\rangle$, its quantum state is

$$[|\psi\rangle]_\sim = \{c|\psi\rangle \mid c \neq 0 \in \mathbb{C}\} \quad (2.1.53)$$

and so the space of quantum states is isomorphic to the set of 1-dim linear subspaces of \mathcal{H} , also called *complex lines*. This set is known as the *projective Hilbert space* and is denoted as \mathbf{PH} . When $\mathcal{H} = \mathbb{C}^N$, the projective space is known as the n -dimensional complex projective space \mathbb{CP}^n , where $n = N - 1$. Equation (2.1.53) leads to the intrinsic definition of a surjective *projection map*

$$\pi: \mathcal{H}_0 \rightarrow \mathbf{PH} \quad \pi(|\psi\rangle) = [|\psi\rangle]_\sim \quad (2.1.54)$$

that maps every state vector to its quantum state.

Example: the qubit

For the qubit, the projective space is the 1-dimensional complex projective space \mathbb{CP}^1 . We can get a sense of the structure of this space considering the expression of a general state vector as a linear combination of an orthonormal basis $\{|0\rangle, |1\rangle\}$

$$|\psi\rangle = c_0|0\rangle + c_1|1\rangle \quad \text{with} \quad c_0 = \|c_0\|e^{i\alpha}, c_1 = \|c_1\|e^{i\beta} \in \mathbb{C} \quad (2.1.55)$$

so that $\|\psi\|^2 = \|c_0\|^2 + \|c_1\|^2$. Every state vector with the same quantum state is given by

$$|\psi'\rangle = c|\psi\rangle \quad \text{with} \quad c = \|c\|e^{i\gamma} \in \mathbb{C} \setminus \{0\} \quad (2.1.56)$$

so that the quantum state doesn't depend on the norm and the global phase of the state vector. We can then choose a representative for each quantum state by fixing the norm of the state vector to 1 and the phase of the first coefficient to 0, that is

$$|\psi\rangle = c_0|0\rangle + c_1|1\rangle \mapsto \frac{\|c_0\|}{\sqrt{\|c_0\|^2 + \|c_1\|^2}}|0\rangle + \frac{\|c_1\|}{\sqrt{\|c_0\|^2 + \|c_1\|^2}}e^{i(\beta-\alpha)}|1\rangle \quad (2.1.57)$$

so that any quantum state can be represented by a state vector of the form

$$|\psi\rangle = \cos\frac{\theta}{2}|0\rangle + e^{i\phi}\sin\frac{\theta}{2}|1\rangle \quad \text{with } \theta \in [0, \pi], \phi \in [0, 2\pi[\quad (2.1.58)$$

where we have that when $\theta = 0$ or $\theta = \pi$ the expression is independent of ϕ . Then θ and ϕ can be regarded as the polar coordinates of a 2-sphere of quantum states with the north pole corresponding to $|0\rangle$ and the south pole to $|1\rangle$. This is known as the *Bloch sphere* and is a representation of the projective space \mathbb{CP}^1 for a fixed orthonormal basis.

2.1.4 Density operators

We have seen that quantum states are the 1-dimensional linear subspaces of \mathcal{H} , so we can identify them with some orthogonal projectors. The only additional requirement is that the projected spaces must be 1-dim, i.e., they must be rank-1 orthogonal projectors. From eq. (2.1.34), we know that for any rank-1 projector, there must exist a normalized vector $|\tilde{e}\rangle$ such that

$$P_{\tilde{e}}|\psi\rangle = \langle \tilde{e}|\psi\rangle |\tilde{e}\rangle \quad \forall |\psi\rangle \in \mathcal{H}_0 \quad (2.1.59)$$

and so from eq. (2.1.4), we have

$$P_{\tilde{e}} = |\tilde{e}\rangle \langle \tilde{e}| \quad (2.1.60)$$

In the context of quantum mechanics, the set of rank-1 orthogonal projectors is known as the set of *pure density operators* and is denoted as \mathfrak{D} .

We now define a candidate for the *projection map* to pure density operators

$$\Pi : \mathcal{H}_0 \rightarrow \mathfrak{D} \quad \Pi(|\psi\rangle) = \frac{|\psi\rangle \langle \psi|}{\langle \psi|\psi\rangle} := \rho_\psi \quad (2.1.61)$$

This map is well-defined since for every $|\psi\rangle$ we have that ρ_ψ is self-adjoint, idempotent and

$$\rho_\psi = \frac{|\psi\rangle \langle \psi|}{\langle \psi|\psi\rangle} = \left(\frac{1}{\|\psi\|} |\psi\rangle \right) \left(\langle \psi| \frac{1}{\|\psi\|} \right) \quad (2.1.62)$$

so that it is of rank 1. This map also has a well-defined action on quantum states since

$$\frac{(c|\psi\rangle)(\langle\psi|c^*)}{(\langle\psi|c^*)(c|\psi\rangle)} = \frac{|\psi\rangle\langle\psi|}{\langle\psi|\psi\rangle} \quad \forall c \neq 0 \in \mathbb{C} \quad (2.1.63)$$

so that it defines the map

$$f : \mathbf{PH} \rightarrow \mathfrak{D} \quad f([\lvert\psi\rangle]_{\sim}) = \Pi(\lvert\psi\rangle) = \rho_{\psi} \quad (2.1.64)$$

Finally, we can prove that f is invertible, allowing us to identify quantum states with density matrices. The map is 1-1 since given any two state-vectors $\lvert\psi\rangle$ and $\lvert\phi\rangle$, we have that

$$\begin{aligned} \rho_{\psi} = \rho_{\phi} &\implies \rho_{\psi}\rho_{\phi} = \rho_{\phi} \\ &\implies \frac{|\psi\rangle\langle\psi|\phi\rangle\langle\phi|}{\langle\psi|\psi\rangle\langle\phi|\phi\rangle} = \frac{|\phi\rangle\langle\phi|}{\langle\phi|\phi\rangle} \\ &\implies \frac{\langle\psi|\phi\rangle}{\langle\psi|\psi\rangle} |\psi\rangle = |\phi\rangle \\ &\implies |\psi\rangle \sim |\phi\rangle \end{aligned}$$

Then, since any rank-1 orthogonal projector can be expressed as in eq. (2.1.60), we also have that f is surjective. We have thus proved that

$$\mathbf{PH} \sim \mathfrak{D} \quad (2.1.65)$$

through the intrinsic map f , so we may identify quantum states with pure density operators, and the two projection maps π and Π are the same under this identification.

We now want to restate postulates 1 to 3 in terms of pure density matrices. To do so, we will need the concept of the trace of an operator. For a finite-dimensional Hilbert space, we may define the trace of an operator A as the linear functional

$$\text{tr}(A) = \sum_i \langle e_i | A | e_i \rangle, \quad \{|e_i\rangle\} \text{ o.n.basis} \quad (2.1.66)$$

where it can be shown that the expression on the right is independent of the choice of the orthonormal basis. The trace also has the following cyclic property

$$\text{tr}(AB) = \text{tr}(BA) \quad (2.1.67)$$

so that for any number of operators A_1, \dots, A_n , we have

$$\text{tr}(A_1 \dots A_n) = \text{tr}(A_n A_1 \dots A_{n-1}) \quad (2.1.68)$$

We also have the following result from linear algebra

Theorem 8. Let \mathcal{H} be a finite-dimensional complex Hilbert space and A any self-adjoint operator on \mathcal{H} . Then

$$\text{tr}(A) = \sum_i \lambda_i \quad (2.1.69)$$

where $\{\lambda_i\}$ are the eigenvalues of A repeated according to their algebraic multiplicity.

One immediate consequence of this theorem is that an orthogonal projector is of rank 1 if and only if it has a unitary trace. Then we may equivalently define pure density operators in the following, more common, way

$$\mathfrak{D} := \{\rho \in \mathfrak{L} \mid \rho^\dagger = \rho, \rho^2 = \rho, \text{tr}(\rho) = 1\} \quad (2.1.70)$$

We can now reformulate postulate 1 as

Postulate 1 (Quantum states). *The set of all the possible quantum states of a system is the projective space of the system's Hilbert space. Then every quantum state is uniquely determined by a pure density operator $\rho \in \mathfrak{D}$*

Given a unitary evolution of the system, we can compute the evolution of any density operator as follows. Any initial quantum state can be expressed as

$$\rho(t_1) = |\psi(t_1)\rangle\langle\psi(t_1)| \quad (2.1.71)$$

where $|\psi(t_1)\rangle$ is a normalized state vector, then for any unitary evolution $U(t_1, t_2)$ we have that $|\psi(t_2)\rangle$ remains normalized and

$$\begin{aligned} \rho(t_2) &= |\psi(t_2)\rangle\langle\psi(t_2)| \\ &= U(t_1, t_2) |\psi(t_1)\rangle\langle\psi(t_1)| U^\dagger(t_1, t_2) \\ &= U(t_1, t_2) \rho(t_1) U^\dagger(t_1, t_2) \end{aligned}$$

so that we can reformulate postulate 2 as

Postulate 2 (Unitary evolution). *The Hilbert space of a closed system evolves only through unitary transformations. Coherently, the time evolution of any pure density operator $\rho(t)$ describing the quantum state of the system is given by*

$$\rho(t_2) = U(t_1, t_2) \rho(t_1) U^\dagger(t_1, t_2) \quad (2.1.72)$$

where $U(t_1, t_2)$ is a unitary operator that only depends on t_1 and t_2 .

Given any quantum measurement $\{(M_x, x)\}$ and a quantum state ρ we have that

$$\rho = |\psi\rangle\langle\psi| \implies p(x) = \langle\psi|M_x^\dagger M_x|\psi\rangle = \|M_x|\psi\rangle\|^2 \quad (2.1.73)$$

for some normalized state vector $|\psi\rangle$. Then by choosing

$$\frac{M_x |\psi\rangle}{\|M_x |\psi\rangle\|} \quad (2.1.74)$$

as the first element of an orthonormal basis, we have that

$$\text{tr}(M_x \rho M_x^\dagger) = \frac{\langle \psi | M_x^\dagger M_x | \psi \rangle \langle \psi | M_x M_x^\dagger | \psi \rangle}{\|M_x |\psi\rangle\|^2} = \|M_x |\psi\rangle\|^2 \quad (2.1.75)$$

so that we can reformulate postulate 3 as

Postulate 3 (Quantum measurements). *Quantum measurements are described by a collection of pairs $\{(M_x, x)\}$ of measurement operators M_x and outcomes x such that the following completeness equation is satisfied*

$$\sum_x M_x^\dagger M_x = \mathbb{I} \quad (2.1.76)$$

where \mathbb{I} is the identity operator. Then, given a system in a quantum state described by a pure density operator ρ , the probability distribution of the outcomes is

$$p(x) = \text{tr}(M_x \rho M_x^\dagger) \quad (2.1.77)$$

Finally, any interaction with the system that leads to the measurement of a specific outcome x transforms the quantum state ρ before the measurement to a new quantum state ρ' after the measurement according to

$$\rho' = \frac{M_x \rho M_x^\dagger}{\text{tr}(M_x \rho M_x^\dagger)} \quad (2.1.78)$$

that depends on the outcome measured.

At last, we have that the expectation value of an observable A when the system is in a quantum state described by a pure density operator ρ is

$$\text{E}[A] = \sum_i \lambda_i \text{tr}(P_i \rho P_i^\dagger) = \text{tr}(\rho A) \quad (2.1.79)$$

Example: the qubit

Pure density operators for the qubit are the self-adjoint operators with one eigenvalue equal to 1 and the other equal to 0. Then pure density operators are represented by 2×2 Hermitian matrices with trace 1 and determinant 0. Expressing a generic Hermitian matrix A as in eq. (2.1.25) it can be shown that

$$\text{tr}(A) = 2a_0 \quad \det(A) = a_0^2 - \|\vec{a}\|^2 \quad (2.1.80)$$

so that for any pure density operator, we have that $a_0 = \frac{1}{2}$ and $\|\vec{a}\| = \frac{1}{2}$. Then we can represent any pure density operator as

$$\rho = \frac{\mathbb{1} + \vec{n} \cdot \vec{\sigma}}{2} \quad \text{with} \quad \vec{n} \in \mathbb{R}^3 : \|\vec{n}\| = 1 \quad (2.1.81)$$

where we recognize the Bloch sphere representation of the quantum states of the qubit.

2.2 The manifold of quantum states

In this section, we discuss the differential geometrical structure of the complex projective space. We start by showing that both the Hilbert space and its complex projective space are complex manifolds, and we recognize that the inner product of the Hilbert space induces an intrinsic metric on itself. We show that the Hilbert space is a fiber bundle with the complex projective space as base space. Finally, through this structure, we induce an intrinsic metric to the complex projective space, the Fubini-Study metric. The treatment is based on [7], [8] and [2] in general, and on [3] for the theory of fiber bundles and Lie groups; more details and different prospectives can be found in these references.

2.2.1 Geometry of the Hilbert space

Complex manifolds are defined in analogy with real ones with the requirement of being locally isomorphic to \mathbb{C}^N for some N and with holomorphic transition functions between charts [9]; the tangent space at each point is thus also isomorphic to \mathbb{C}^N . Every N -dimensional complex manifold is also a $2N$ -dimensional real manifold where every complex coordinate basis $\{e_1, \dots, e_N\}$ corresponds to a real coordinate basis $\{e_1, \dots, e_N, ie_1, \dots, ie_N\}$, this manifold is called the *realification* of the original complex one.

Finite-dimensional Hilbert spaces are isomorphic to \mathbb{C}^N for some N and so they are also trivial complex manifolds. Moreover, there is a canonical isomorphism between the tangent space at each point and the Hilbert space itself

$$T_{|\psi\rangle}\mathcal{H} \sim \mathcal{H} \quad \text{with} \quad \frac{\partial}{\partial\theta} \leftrightarrow \left. \frac{d|\psi(\theta)\rangle}{d\theta} \right|_{\theta=0} := |d\psi_\theta\rangle \quad (2.2.1)$$

so that the inner product on the Hilbert space defines an inner product on the complex tangent space of every point, i.e., it defines a complex $\binom{0}{2}$ tensor field on the manifold. Hilbert spaces also are metric spaces with respect to the distance induced by the inner product

$$d(\mathbf{X}, \mathbf{Y}) = \|\mathbf{X} - \mathbf{Y}\| = \sqrt{\langle \mathbf{X} - \mathbf{Y}, \mathbf{X} - \mathbf{Y} \rangle} \quad \forall \mathbf{X}, \mathbf{Y} \in \mathcal{H} \quad (2.2.2)$$

For finite-dimensional Hilbert spaces, the inner product is a hermitian form that may be expressed as

$$\langle \mathbf{X}, \mathbf{Y} \rangle = h(\mathbf{X}, \mathbf{Y}) = g(\mathbf{X}, \mathbf{Y}) + iw(\mathbf{X}, \mathbf{Y}) \quad (2.2.3)$$

where g is a real-valued symmetric bilinear form and w is a real-valued antisymmetric bilinear form. Then, the distance may be expressed as

$$d(\mathbf{X}, \mathbf{Y}) = \sqrt{g(\mathbf{X} - \mathbf{Y}, \mathbf{X} - \mathbf{Y})} \quad (2.2.4)$$

so that the real part of the inner product also defines a metric tensor on the Hilbert space as explained in section 1.2.2, endowing it with a Riemannian structure.

We thus have that the space of state vectors \mathcal{H}_0 is also a complex manifold with the Riemannian structure

$$g_{|\psi\rangle}(|d\psi_1\rangle, |d\psi_2\rangle) = \text{Re} [\langle d\psi_1 | d\psi_2 \rangle] \quad (2.2.5)$$

This metric tensor is intrinsically derived from the structure of the Hilbert space and so it is invariant under unitary transformations. The set $U(N)$ of unitary transformations of \mathbb{C}^N is a Lie group and so the Lie algebra of its left-invariant vector fields are the killing vector fields of the Hilbert space. The integral curves of these vector fields also preserve the norm of the points in the Hilbert space, and it can be shown that in each point their tangent vectors form a real $(2N - 1)$ -dimensional linear subspace of the tangent space. From this follows that the integral curves of the killing vector fields mesh to form a foliation of the realified Hilbert space where each leaf is the set of state vectors with a fixed norm and is thus isomorphic to S^{2N-1} . Then each leaf is a $(2N - 1)$ -dimensional submanifold of the realified Hilbert space and inherits a Riemannian structure.

2.2.2 Fiber bundle structure of the Hilbert space

We are now interested in the geometry of the space of quantum states. For start we have that, with a sound choice of coordinates, one can easily verify that \mathbb{CP}^n is also a complex manifold [2, pg. 108]. Then tangent vectors of $\mathbf{P}\mathcal{H}$ can be intrinsically mapped to operators of \mathcal{H} as follows

$$\frac{\partial}{\partial \theta} \in T_\rho \mathfrak{D} \mapsto d\rho_\theta \quad \text{with} \quad d\rho_\theta(\mathbf{X}) = \left. \frac{d}{d\theta} [\rho(\theta)(\mathbf{X})] \right|_{\theta=0} \quad \forall \mathbf{X} \in \mathcal{H} \quad (2.2.6)$$

where from the linearity of differentiation follows that $d\rho_\theta$ is a well-defined linear operator on \mathcal{H} .

Now we may ask ourselves if there is a natural way to induce a metric on $\mathbf{P}\mathcal{H}$ from the one of \mathcal{H} . Such an intrinsic metric would lead to a natural notion of

distance between quantum states. To do this we will start by investigating the relationship between \mathcal{H} and $\mathbf{P}\mathcal{H}$ as complex manifolds.

Firstly let us now recall the intrinsic projection map of eq. (2.1.54)

$$\pi : \mathcal{H}_0 \rightarrow \mathbf{P}\mathcal{H} \quad |\psi\rangle \mapsto [|\psi\rangle]_{\sim} = \{c|\psi\rangle \mid c \neq 0 \in \mathbb{C}\}$$

it can be shown that it is a smooth surjective map between the two manifolds so that we may regard \mathcal{H}_0 as a fiber bundle with base space $\mathbf{P}\mathcal{H}$. The fibers of the fiber bundle are the orbits of the action on \mathcal{H}_0 of the abelian Lie group

$$\mathbf{C}_0 = \{c \cdot \mathbb{I} \mid c \neq 0 \in \mathbb{C}\} \tag{2.2.7}$$

Since this group acts smoothly and transitively on the fibers, we have that the fibers are isomorphic to \mathbf{C}_0 , and the fiber bundle is a principal fiber bundle.

One way to induce a metric on $\mathbf{P}\mathcal{H}$ would be to find a natural embedding of it into \mathcal{H}_0 . It is a known result from the theory of principal fiber bundles that if such an embedding existed, then the fiber bundle would be the trivial $\mathcal{H}_0 = \mathbf{P}\mathcal{H} \times \mathbf{C}_0$. Since this is not the case, there is no natural embedding, i.e., there is no way to choose a representative state vector for every quantum state in terms of the structure of the Hilbert space only.

2.2.3 The Fubini-Study metric

Now that we have described the fiber bundle structure that links \mathcal{H}_0 and $\mathbf{P}\mathcal{H}$, we introduce two concepts that will be instrumental in our aim of inducing a metric on the space of quantum states: the push-forward of vectors and the pull-back of 1-forms.

Given a fiber bundle X with base space B , the projection map $\pi : X \rightarrow B$ allows us to locally project any smooth curve on the fiber bundle to a smooth curve on the base space. From this follows that we have a natural map

$$d\pi_x : T_x X \rightarrow T_{\pi(x)} B \quad \forall x \in X \tag{2.2.8}$$

such that given any smooth curve $\gamma(t)$ with $\gamma(0) = x$, then

$$d\pi_x(\gamma'(0)) = \left. \frac{d}{dt} [\pi(\gamma(t))] \right|_{t=0} \tag{2.2.9}$$

where we have used the identification of tangent vectors with equivalence classes of curves. From the linearity of the differentiation follows that $d\pi$ is also linear. Then the push-forward is the map between the tangent bundles of the fiber bundle and the base space such that

$$d\pi : TX \rightarrow TB \quad \text{with} \quad d\pi(x, v) = (\pi(x), d\pi_x(v)) \tag{2.2.10}$$

The pull-back of 1-forms is the dual map of the push-forward. Given any 1-form $\alpha \in T_{\pi(x)}^*B$, we define its pull-back on T_x^*X as the 1-form $\alpha' \in T_x^*X$ such that

$$\alpha'(v) = \alpha(d\pi_x(v)) \quad \forall v \in T_x X \quad (2.2.11)$$

Then we have that given a 1-form in the cotangent space of some point of the base space, we can pull it back to the cotangent spaces of the entire corresponding fiber of the fiber bundle. From this follows that the pull-back is defined as a map from entire fields of 1-forms in the base space to entire fields of 1-forms in the fiber bundle. This is in contrast with the push forward since for vector fields to be pushed forward, it would be necessary that every vector on the same fiber was pushed to the same vector on the corresponding element of the base space. Finally, using the tensor product, we can similarly define the push-forward of $\binom{p}{0}$ tensors and the pull-back of $\binom{0}{q}$ tensor fields.

The structure we want to project onto \mathbf{PH} is the $\binom{0}{2}$ metric tensor field, and so we cannot simply push it forward. The fiber bundle we are interested in, \mathcal{H}_0 , is also a Riemannian principal fiber bundle. As we will see, this allows us to uniquely *lift* vector fields from the base space to the fiber bundle.

Given a fiber bundle X as before, we have that at every point $x \in X$, the curves through x that remain on the same fiber are projected to single points on the base manifold so that the push-forward of their tangent vectors must be the null vector. We define the vertical subspace of $T_x X$ as the kernel of the push-forward

$$V_x := \ker d\pi_x \subseteq T_x X \quad (2.2.12)$$

Then a vector field is vertical if its value at every point is in the vertical subspace. For a general fiber bundle, there may not be any vertical vector fields since the vertical subspaces may not be a smooth subset of its tangent bundle. If X is also a principal fiber bundle with structure group G , we have that the fibers are given by the mesh of left-invariant vector fields of G . Then the vertical vector fields are precisely the left-invariant vector fields of G , and the vertical subspace is isomorphic to the Lie algebra of G at every point

$$V_x \sim \mathfrak{g}_G \quad (2.2.13)$$

We may also choose at every point $x \in X$ a horizontal subspace O_x , i.e., a complementary subspace to the vertical one so that

$$T_x X = V_x \oplus O_x \quad (2.2.14)$$

In general, there is no intrinsic way to choose a horizontal subspace at every point, but if X is also a Riemannian manifold, then we can define the horizontal subspaces as the orthogonal complements of the vertical ones

$$O_x := V_x^\perp \quad (2.2.15)$$

and horizontal vector fields are defined in analogy with the vertical ones. We thus have a well-defined notion of vertical motion, tangent to the fibers, and of horizontal motion, orthogonal to the fibers.

Intuitively, we can now lift any curve in the base space to the fiber bundle by starting from a point on the fiber and then moving orthogonally to it. To precisely define this concept, let us consider the restriction to O_x of the push-forward at every point

$$d\pi'_x \equiv d\pi_x|_{O_x} : O_x \subseteq T_x X \rightarrow T_{\pi(x)} B \quad (2.2.16)$$

It can be shown that from the smoothness of the metric tensor field follows that $d\pi'_x$ defines a smooth map between the tangent bundles of the fiber bundle and the base space. Then from our previous considerations follows that

$$\ker d\pi'_x = \{\mathbf{0}\} \quad \forall x \in X \quad (2.2.17)$$

and thus $d\pi'_x$ defines an isomorphism between O_x and $T_{\pi(x)} B$ at every point. We can then uniquely define the *horizontal lift* $v_l(x) \in T_x X$ to the fiber bundle of any vector field $v(y) \in T_y B$ on the base space as

$$v_l(x) = d\pi_y'^{-1}(v(y)), \quad y = \pi(x) \quad \forall x \in X \quad (2.2.18)$$

that is the unique horizontal vector field on the fiber bundle that projects to $v(y)$.

We can now try to induce a metric tensor field on the base space by identifying its action on vector fields with the action of the metric tensor of the fiber bundle on the horizontal lift of the vector fields of the base space, i.e., given $dy_1, dy_2 \in T_y B$

$$g'_y(dy_1, dy_2) = g_x(d\pi_y'^{-1}(dy_1), d\pi_y'^{-1}(dy_2)) \quad (2.2.19)$$

where $y = \pi(x)$. This is possible only if the scalar field resulting from the inner product of the horizontal lifts is constant on the fibers; only in this case, we can then push forward the scalar field to the base space and thus define the action of the induced metric tensor field on the original vector fields. Requiring the inner product of the horizontal lifts to be constant on the fibers is equivalent to requiring it to be constant under the action of the structure group G . By definition, horizontal lifts are invariant under the action of G , so the only requirement is that the metric tensor field must be invariant, i.e., the left-invariant vector fields must also be killing vector fields.

We have thus shown that we can induce a metric tensor field on the base space of a Riemannian principal fiber bundle if the elements of the structure group are isometries of the fiber bundle. As we have seen in section 2.2.1, the set of isometries of $\mathcal{H}_0 = \mathbb{C}_0^N$ is the unitary group $U(N)$, while its structure group is the abelian group \mathbf{C}_0 . Then not every element of the structure group is an isometry since

$$\mathbf{C}_0 = \mathbb{R}^+ \times U(1) \quad c = \|c\| \cdot e^{i\theta} \leftrightarrow (\|c\|, e^{i\theta}) \quad (2.2.20)$$

To proceed, we must first fibrate with \mathbb{R}^+ and induce a metric on the base of this fibration. This is easily done since we can intrinsically define the embedding of the projection as the normalized state vectors

$$|\psi\rangle \mapsto \frac{|\psi\rangle}{\| |\psi\rangle \|} = \frac{|\psi\rangle}{\sqrt{\langle \psi | \psi \rangle}} \in \mathcal{H}_0 \quad \forall |\psi\rangle \in \mathcal{H}_0 \quad (2.2.21)$$

so that the base space is one of the leaves of the foliation induced by $U(N)$ on \mathcal{H}_0

$$S^{2N-1} = \mathbb{C}_0^N / \mathbb{R}^+ \quad (2.2.22)$$

as described in section 2.2.2, then it also inherits the Riemannian structure such that

$$g_{|\psi\rangle}(|d\psi_1\rangle, |d\psi_2\rangle) = \text{Re} [\langle d\psi_1 | d\psi_2 \rangle] \quad (2.2.23)$$

for any normalized state vector $|\psi\rangle$. Considering the restriction of the projection map of eq. (2.1.54) on the set of normalized state vectors, we can repeat the same arguments of section 2.2.2 and show that S^{2N-1} is a Riemannian principal fiber bundle with structure group $U(1)$ and base space

$$\mathbb{CP}^n = S^{2N-1} / U(1) \quad (2.2.24)$$

where $n = N - 1$. The structure group is then a one-parameter subgroup of the isometry group, so we can induce a metric tensor field on \mathbb{CP}^n as described in this section. This metric for \mathbb{CP}^n is known as the Fubini-Study metric g_{FS} and is thus intrinsically defined in terms of the structure of the Hilbert space only.

The pullback of the FS metric on state vectors

We first derive an explicit expression for the pullback of the Fubini-Study metric on \mathcal{H}_0 . From our definitions, we have that for any normalized state vector $|\psi\rangle$

$$g_{FS}(|d\psi_1\rangle, |d\psi_2\rangle) = g(d\pi_\rho'^{-1}(d\rho_1), d\pi_\rho'^{-1}(d\rho_2)) \quad (2.2.25)$$

where $\rho = \pi(|\psi\rangle)$ and $d\rho_i = d\pi_{|\psi\rangle}(|d\psi_i\rangle)$. We first notice that the linear map

$$d\pi_\rho'^{-1} \circ d\pi_{|\psi\rangle} : T_{|\psi\rangle} \mathcal{H} \rightarrow O_{|\psi\rangle} \quad (2.2.26)$$

must act as the identity on $O_{|\psi\rangle}$ and must have kernel $V_{|\psi\rangle}$, the same as $d\pi_{|\psi\rangle}$, so that we can recognize it as the orthogonal projector on $O_{|\psi\rangle}$. Since for every $|\psi\rangle$, the motion along its fiber is given by $c|\psi\rangle$ for some complex number c , then

$$V_{|\psi\rangle} = \{c|\psi\rangle \quad \forall c \in \mathbb{C}\} \quad (2.2.27)$$

and so the projector to the vertical space is ρ . The projector to the horizontal space is then $(\mathbb{I} - \rho)$ so that

$$d\pi_\rho'^{-1} \circ d\pi_{|\psi\rangle}(|d\psi\rangle) = (\mathbb{I} - \rho)|d\psi\rangle = |d\psi\rangle - \langle\psi|d\psi\rangle|\psi\rangle \quad (2.2.28)$$

and for normalized state vectors we have

$$\begin{aligned} g_{FS}(|d\psi_1\rangle, |d\psi_2\rangle) &= \text{Re}[(\langle d\psi_2| - \langle\psi| \langle d\psi_2|\psi\rangle)(|d\psi_1\rangle - \langle\psi|d\psi_1\rangle|\psi\rangle)] \\ &= \text{Re}[\langle d\psi_2|d\psi_1\rangle - \langle d\psi_2|\psi\rangle\langle\psi|d\psi_1\rangle] \end{aligned} \quad (2.2.29)$$

Finally, it can be similarly shown that for any state vector $|\psi\rangle \in \mathcal{H}_0$ and two tangent vectors $|d\psi_1\rangle, |d\psi_2\rangle \in T_{|\psi\rangle}\mathcal{H}$ we have

$$g_{FS}(|d\psi_1\rangle, |d\psi_2\rangle) = \text{Re}\left[\frac{\langle d\psi_2|d\psi_1\rangle}{\langle\psi|\psi\rangle} - \frac{\langle d\psi_2|\psi\rangle\langle\psi|d\psi_1\rangle}{\langle\psi|\psi\rangle^2}\right] \quad (2.2.30)$$

The FS metric on pure density operators

We now want to derive an explicit expression for the Fubini-Study metric on \mathbb{CP}^n . As we have seen, the first fibration projects the state vectors to the normalized state vectors, which constitute a leaf of the foliation of submanifolds of \mathcal{H}_0 that are meshed by the integral curves of the left-invariant vector fields of $U(N)$. Then, at any point of S^{2N-1} , the tangent space is isomorphic to the Lie algebra of $U(N)$. This is the space of anti-hermitian operators since the action of any 1-parameter subgroup of $U(N)$ on a normalized state vector $|\psi\rangle$ can always be locally expressed as

$$U(\theta)|\psi\rangle = e^{iA\theta}|\psi\rangle \quad (2.2.31)$$

for some hermitian operator A . Then, for any tangent vector $|d\psi\rangle \in T_{|\psi\rangle}S^{2N-1}$, there must exist a unique hermitian operator A such that

$$|d\psi\rangle = \frac{d}{d\theta}(e^{iA\theta}|\psi\rangle)\Big|_{\theta=0} = iA|\psi\rangle \quad (2.2.32)$$

The push forward of this vector is then given by

$$\begin{aligned} d\rho &= \frac{d}{d\theta}(e^{iA\theta}\rho e^{-iA\theta})\Big|_{\theta=0} = (iA\rho - \rho iA) \\ &= i[A, \rho] \end{aligned} \quad (2.2.33)$$

We can then express the pullback of the Fubini-Study metric on S^{2N-1} in terms of the push forward of the tangent vectors

$$\begin{aligned}
g_{FS}(|d\psi_1\rangle, |d\psi_2\rangle) &= \text{Re} [\langle d\psi_2|d\psi_1\rangle - \langle d\psi_2|\psi\rangle \langle \psi|d\psi_1\rangle] \\
&= \text{Re} [\langle \psi|A_2 A_1|\psi\rangle - \langle \psi|A_2|\psi\rangle \langle \psi|A_1|\psi\rangle] \\
&= \text{Re} [\text{tr}(\rho(A_2 A_1 - A_2 \rho A_1))] \\
&= \frac{1}{2} \text{tr} (\rho A_2 A_1 + \rho A_1 A_2 - \rho A_2 \rho A_1 - \rho A_1 \rho A_2) \\
&= \frac{1}{2} \text{tr} ([A_1, \rho][\rho, A_2]) = \frac{1}{2} \text{tr} (d\rho_1 d\rho_2)
\end{aligned} \tag{2.2.34}$$

and so we find that the Fubini-Study metric on \mathbb{CP}^n is given by

$$g_{FS}(d\rho_1, d\rho_2) = \frac{1}{2} \text{tr} (d\rho_1 d\rho_2) \tag{2.2.35}$$

Chapter 3

Quantum information

3.1 Quantum information geometry

In this section, we draw the connection between the geometry of probability distributions and the one of quantum states. We begin by defining the mixture and exponential representations of tangent vectors to quantum states, using the symmetric logarithmic derivative (SLD). Then we define by analogy the quantum Fisher information and we find it to be equal to the Fubini-Study metric, up to a constant factor. Lastly, we discuss in more depth the analogy between random variables and observables through the definition of a symmetric generalized covariance. The treatment is based on [1], [8] for the general theory and on [10], [11] and [12] for the details of the pure state case.

3.1.1 Observables and the tangent space

As we have seen in section 2.1.1, quantum states can be interpreted as a generalization of probability distributions. We now want to further investigate the parallelisms between the geometry of quantum states and the one of probability distributions.

We start by recalling the representation of tangent vectors as linear operators, from eq. (2.2.6) we have

$$\tilde{X}_\theta \equiv \frac{\partial}{\partial \theta} \in T_\rho \mathbf{PH} \mapsto d\rho_\theta \in T_\rho \mathfrak{D} \quad \text{where} \quad d\rho_\theta = \left. \frac{d}{d\theta} [\rho(\theta)] \right|_{\theta=0} \quad (3.1.1)$$

which is analogous to the mixture representation of tangent vectors to probability distributions we defined in eq. (1.1.11), so that

$$\tilde{X}_\theta^{(m)} \equiv d\rho_\theta \quad \forall \tilde{X}_\theta \in T_\rho \mathbf{PH} \quad (3.1.2)$$

$$\text{and} \quad T_\rho^{(m)} \mathbf{PH} \equiv T_\rho \mathfrak{D} \quad (3.1.3)$$

In the last paragraph of section 2.2.3 it was shown that any tangent vector $d\rho \in T_\rho \mathfrak{D}$ can be expressed as

$$d\rho = i[A, \rho] \quad (3.1.4)$$

for some Hermitian operator A , thus $d\rho$ is also Hermitian and we may interpret it as an observable. Further, we have

$$\text{tr}(d\rho_\theta) = \frac{d}{d\theta} [\text{tr}(\rho(\theta))] = 0 \quad (3.1.5)$$

that is analogous to eq. (1.1.13).

To define the exponential representation of tangent vectors, we would have to divide the mixture representation by the probability distribution itself. This is not possible since we are dealing with operators, instead, we can use the implicit expression of eq. (1.1.23) and symmetrize it to obtain

$$d\rho_\theta = \frac{1}{2} \left[\rho L_\theta^{(\rho)} + L_\theta^{(\rho)} \rho \right] \quad (3.1.6)$$

To precisely define this operator we express any $d\rho \in T_\rho \mathfrak{D}$ as in eq. (3.1.4), so that we obtain the following expression

$$i[A, \rho] = \frac{1}{2} \{ \rho, L^{(\rho)}(A) \} \quad (3.1.7)$$

It can be proven that when ρ is Hermitian and positive semi-definite $L^{(\rho)}(A)$ is determined for every operator A , up to a term that anticommutes with ρ . Then $L^{(\rho)}(A)$ is known as the *symmetric logarithmic derivative (SLD)* and one can also show that if A is Hermitian $L^{(\rho)}(A)$ is also Hermitian. Analogously with probability distributions, the expectation value of the SLD is zero

$$\text{E}[L^{(\rho)}] = \text{tr}(\rho L^{(\rho)}) = \frac{1}{2} \text{tr}(\rho L^{(\rho)} + L^{(\rho)} \rho) = \text{tr}(d\rho) = 0 \quad (3.1.8)$$

regardless of the anticommutating term.

For pure density operators, we can find an explicit expression for the SLD as follows

$$d\rho_\theta = \frac{d}{d\theta} [\rho(\theta)] \Big|_{\theta=0} = \frac{d}{d\theta} [\rho^2(\theta)] \Big|_{\theta=0} = \rho d\rho_\theta + d\rho_\theta \rho \quad (3.1.9)$$

so that we can set

$$L_\theta^{(\rho)} = 2d\rho_\theta \quad \forall d\rho_\theta \in T_\rho \mathfrak{D} \quad (3.1.10)$$

by implicitly fixing the anticommutating term. It will become clear in the next sections that this choice has no effect on the geometry we will develop.

We thus have that $L_\theta^{(\rho)}$ is analogous to the exponential representation of $d\rho_\theta$

$$\tilde{X}_\theta^{(e)} \equiv L_\theta^{(\rho)} \quad \forall \tilde{X}_\theta \in T_\rho \mathbf{PH} \quad (3.1.11)$$

and we can identify the space of exponential representations with the space of mixture representations

$$T_\rho^{(e)} \mathbf{PH} \equiv T_\rho^{(m)} \mathbf{PH} \equiv T_\rho \mathfrak{D} \quad (3.1.12)$$

3.1.2 Quantum Fisher information

In light of the analogies between the space of quantum states and the space of probability distributions, we can now try to define the Fisher information metric for quantum states. We start from the formulation of the Fisher information metric in terms of the exponential representation of tangent vectors, recalling eq. (1.2.25)

$$G_F(X, Y) = \text{E}_p[X^{(e)} Y^{(e)}] \quad \forall X, Y \in T_p \mathcal{P} \quad (3.1.13)$$

Then we can define the quantum Fisher information metric by analogy, symmetrizing the arguments

$$\begin{aligned} G_{QF}(\tilde{X}_1, \tilde{X}_2) &= \text{E}_\rho \left[\frac{1}{2} \left(L_1^{(\rho)} L_2^{(\rho)} + L_2^{(\rho)} L_1^{(\rho)} \right) \right] \quad \forall \tilde{X}_1, \tilde{X}_2 \in T_\rho \mathbf{PH} \\ &= \text{tr} \left(\rho \frac{L_1^{(\rho)} L_2^{(\rho)} + L_2^{(\rho)} L_1^{(\rho)}}{2} \right) \end{aligned} \quad (3.1.14)$$

$$\begin{aligned} &= \text{tr} \left(\frac{1}{2} \{ \rho, L_1^{(\rho)} \} L_2^{(\rho)} \right) = \text{tr} \left(L_1^{(\rho)} \frac{1}{2} \{ \rho, L_2^{(\rho)} \} \right) \\ &= \text{tr} \left(d\rho_1 L_2^{(\rho)} \right) = \text{tr} \left(L_1^{(\rho)} d\rho_2 \right) \end{aligned} \quad (3.1.15)$$

The symmetrization of the arguments is necessary to ensure that the metric is symmetric, and it is also the reason why the choice of the anticommutating term in the SLD has no effect on the geometry. Then, from eq. (3.1.10), we have that for pure quantum states

$$G_{QF}(\tilde{X}_1, \tilde{X}_2) = 2 \text{tr}(d\rho_1 d\rho_2) \quad (3.1.16)$$

$$= 4 G_{FS}(\tilde{X}_1, \tilde{X}_2) \quad (3.1.17)$$

This shows that the Fubini-Study metric we defined intrinsically for pure quantum states can be precisely interpreted as a quantum information metric.

3.1.3 Symmetric covariance

Our analogy between the geometry of quantum states and the one of probability distributions is now almost complete, but there are still some details to be clarified. Firstly, we would want to treat observables as we treated random variables, but while every tangent vector can be associated with an observable with zero expectation value, the converse is not directly true. Let \mathfrak{A} be the set of observables of \mathcal{H} and ρ a pure density operator, then

$$T_\rho \mathfrak{D} \subset \mathfrak{A}_\rho^\perp := \{A \in \mathfrak{A} \mid E_\rho[A] = 0\} \quad (3.1.18)$$

as can be easily checked by comparing the real dimensions of the two vector spaces. Secondly, since operators don't commute in general, we must define a sound generalization of the covariance, and as we will show, these two problems are related.

For starters, we require our generalized covariance to reduce to the variance of the observable when evaluated on the diagonal

$$\text{Cov}_\rho[A, A] = V_\rho[A] = \text{tr}(\rho(A - E_\rho[A])^2) \quad \forall A \in \mathfrak{A} \quad (3.1.19)$$

Then by requiring it to be symmetric in its arguments, we are naturally led to the definition

$$\text{Cov}_\rho[A, B] := \frac{1}{2} \text{tr}(\rho \{A - E_\rho[A], B - E_\rho[B]\}) \quad \forall A, B \in \mathfrak{A} \quad (3.1.20)$$

Since $(A - E_\rho[A])$ always has zero expectation value, we can recognize that this expression also defines for every quantum state an inner product in the space of observables with zero expectation value

$$\langle\langle A, B \rangle\rangle_\rho := \frac{1}{2} E[\{A, B\}] \quad \forall A, B \in \mathfrak{A}^\perp \quad (3.1.21)$$

Then this inner product coincides with the quantum Fisher metric when the arguments are the exponential representations of tangent vectors

$$\langle\langle L_1^{(\rho)}, L_2^{(\rho)} \rangle\rangle_\rho = G_{QF}(\tilde{X}_1, \tilde{X}_2) \quad \forall \tilde{X}_1, \tilde{X}_2 \in T_\rho \mathbf{PH} \quad (3.1.22)$$

This is no coincidence, and it can be shown that the definitions of the exponential representation and the generalized covariance are deeply linked [1].

Let us now go back to the problem of associating every observable with zero expectation value to the exponential representation of a tangent vector. We notice that every observable $A \in \mathfrak{A}$ can be thought of as an element of the Lie algebra of $U(N)$, and thus we can associate it with a tangent vector through the linear map

$$\mathfrak{M}_\rho : \mathfrak{A} \rightarrow T_\rho \mathfrak{D} \quad | \quad A \mapsto \left. \frac{d}{d\theta} (e^{iA\theta} \rho e^{-iA\theta}) \right|_{\theta=0} = i[A, \rho] =: d\rho_A \quad (3.1.23)$$

The kernel of this map is the linear subspace of the Lie algebra of $U(N)$ that corresponds to the 1-parameter subgroups that leave the quantum state unchanged. We notice that $\ker \mathfrak{M}_\rho$ is the set of observables that commute with the pure density operator of the quantum state, i.e, the set of observables for which the state vectors of ρ are eigenvectors; let $\rho = |\psi\rangle\langle\psi|$ for some normalized state vector $|\psi\rangle$, then

$$[\rho, A] = 0 \implies \rho A = A \rho \quad (3.1.24)$$

$$\implies A|\psi\rangle = A\rho|\psi\rangle = \rho A|\psi\rangle = \langle\psi|A|\psi\rangle|\psi\rangle \quad (3.1.25)$$

$$\implies A\rho = E_\rho[A]\rho$$

Then any element of $\ker \mathfrak{M}_\rho$ can be expressed as

$$K = \lambda^{(k)}\rho + K' \quad \text{with} \quad K' = K'^\dagger, \quad K'\rho = \rho K' = 0 \quad (3.1.26)$$

notice that the two components decompose the kernel in two linear subspaces closed under commutation, thus they define two subgroups of $U(N)$

$$e^{i\theta\lambda^{(k)}\rho}|\psi\rangle = e^{i\theta\lambda^{(k)}}|\psi\rangle \quad e^{i\theta K'}|\psi\rangle = e^{i\theta \cdot 0}|\psi\rangle = |\psi\rangle \quad (3.1.27)$$

The first is isomorphic to $U(1)$ and is the subgroup that moves the state vectors of ρ along the fiber. The second one is isomorphic to $U(N-1)$ and leaves the state vectors of ρ unchanged. Through the matrix representation of operators, we can easily compute the real dimension of the lie algebra of $U(N)$ to be N^2 for any N . Then the dimension of $\ker \mathfrak{M}_\rho$ is $1 + (N-1)^2$ while the dimension of the domain is N^2 , so that $T_\rho \mathfrak{D}$ has dimension $2N-2$ as we expected.¹

We consider now the restriction of \mathfrak{M}_ρ to the observables with zero expectation value in ρ

$$\mathfrak{M}_\rho^{(0)} \Big|_{\mathfrak{A}_\rho^\perp} : \mathfrak{A}_\rho^\perp \rightarrow T_\rho \mathfrak{D} \quad (3.1.28)$$

From eq. (3.1.26) we can easily compute the real dimensions of the domain and of the kernel of $\mathfrak{M}_\rho^{(0)}$ to be respectively $N^2 - 1$ and $(N-1)^2$. Then the image of $\mathfrak{M}_\rho^{(0)}$ must have a real dimension of $2N-2$, equal to the one of the tangent space, thus proving that $\mathfrak{M}_\rho^{(0)}$ is surjective. Then we also have that $\mathfrak{M}_\rho^{(0)}$ maps $T_\rho \mathfrak{D}$ to itself

¹This shows that we can define $\mathbb{CP}^n = \frac{U(N)}{U(1) \times U(N-1)}$. Through the same arguments, this expression can be easily generalized to mixed states, so that the space of rank-m density matrices is given by $\frac{U(N)}{U(m) \times U(N-m)}$. This is treated in detail in [8].

since

$$\begin{aligned}
[L^{(\rho)}, \rho] = 0 &\implies d\rho = L^{(\rho)}\rho = \rho L^{(\rho)} \\
&\implies (d\rho - L^{(\rho)})\rho = \rho(d\rho - L^{(\rho)}) \\
&\implies iA\rho - i\rho A\rho - L^{(\rho)}\rho = i\rho A - i\rho A\rho - \rho L^{(\rho)} \\
&\implies i[A, \rho] = [L^{(\rho)}, \rho] \\
&\implies d\rho = 0, L^{(\rho)} = 0
\end{aligned}$$

where we considered $d\rho = i[A, \rho]$. It follows that we can decompose the vector space of observables with zero expectation value in ρ as

$$\mathfrak{A}_\rho^\perp = \mathfrak{A}_{C(\rho)}^\perp \oplus T_\rho \mathfrak{D} \quad \forall \rho \in \mathfrak{D} \quad (3.1.29)$$

where $\mathfrak{A}_{C(\rho)}^\perp$ is the set of zero expectation value observables that commute with ρ , then we write

$$\begin{aligned}
A = A_C^{(\rho)} + A^{(\rho)} &\quad \forall A \in \mathfrak{A}_\rho^\perp \\
\text{with } A_C^{(\rho)} \in \mathfrak{A}_{C(\rho)}^\perp &\quad \text{and } A^{(\rho)} \in T_\rho \mathfrak{D}
\end{aligned} \quad (3.1.30)$$

Finally, we can show that the inner product we defined on $A \in \mathfrak{A}$ depends only on the non-commuting part of the decomposition

$$\begin{aligned}
\langle\langle A, B \rangle\rangle_\rho &= \frac{1}{2} \text{tr}(\rho \{A, B\}) \\
&= \frac{1}{2} \text{tr}\left(\rho \left\{A_C^{(\rho)} + A^{(\rho)}, B_C^{(\rho)} + B^{(\rho)}\right\}\right) \\
&= \frac{1}{2} \text{tr}\left(\rho \{A^{(\rho)}, B^{(\rho)}\}\right) + \frac{1}{2} \text{tr}\left(\rho \{A^{(\rho)}, B_C^{(\rho)}\}\right) + \\
&\quad + \frac{1}{2} \text{tr}\left(\rho \{A_C^{(\rho)}, B^{(\rho)}\}\right) + \frac{1}{2} \text{tr}\left(\rho \{A_C^{(\rho)}, B_C^{(\rho)}\}\right) \\
&= \frac{1}{2} \text{tr}\left(\rho \{A^{(\rho)}, B^{(\rho)}\}\right) = \langle\langle A^{(\rho)}, B^{(\rho)} \rangle\rangle_\rho
\end{aligned} \quad (3.1.31)$$

so that we can map every observable with zero expectation value in ρ to a tangent vector of ρ through

$$A \in \mathfrak{A}_\rho^\perp \mapsto \tilde{A} \in T_\rho \mathbf{PH} : \quad \tilde{A}^{(e)} = A^{(\rho)} \in T_\rho \mathfrak{D} \quad (3.1.32)$$

Then we have proved that

$$\langle\langle A, B \rangle\rangle_\rho = G_{QF}(\tilde{A}, \tilde{B}) \quad (3.1.33)$$

completing our analogy.

3.2 Quantum estimation

In this section, we will use the framework of quantum information geometry to state and prove the quantum version of the results of probability theory and parameter estimation that we presented in section 1.3. Quantum estimators will be defined in the general case of POVMs, and we will prove the quantum Cramér-Rao bound. The treatment is based on [1] and [13].

3.2.1 Variance and expectation value

The analogy between quantum states and statistical models we developed allows us to prove the following results that connect vector fields on \mathbf{PH} and observables. We start with the quantum version of theorem 3.

Theorem 9. *For any observable $A \in \mathfrak{A}$, we have*

$$(\text{grad } E[A])_{\rho}^{(e)} = (A - E_{\rho}[A])^{(\rho)} \quad \forall \rho \in \mathbf{PH} \quad (3.2.1)$$

where the gradient is the dual tangent vector of the differential with respect to the quantum Fisher metric.

Proof. For every $\tilde{X}_{\theta} \in T_{\rho}\mathbf{PH}$, we have

$$\begin{aligned} \tilde{X}_{\theta}(E[A]) &= \text{tr}(\tilde{X}_{\theta}(\rho) A) = \text{tr}(d\rho_{\theta} A) \\ &= \text{tr}(d\rho_{\theta}(A - E_{\rho}[A])) \\ &= \text{tr}\left(\frac{1}{2}\{\rho, L_{\theta}^{(\rho)}\}(A - E_{\rho}[A])\right) \\ &= \frac{1}{2}\text{tr}\left(\rho L_{\theta}^{(\rho)}(A - E_{\rho}[A]) + L_{\theta}^{(\rho)}\rho(A - E_{\rho}[A])\right) \\ &= \langle\langle L_{\theta}^{(\rho)}, (A - E_{\rho}[A])\rangle\rangle_{\rho} = \langle\langle L_{\theta}^{(\rho)}, (A - E_{\rho}[A])^{(\rho)}\rangle\rangle_{\rho} \end{aligned}$$

□

Then it also follows that

Corollary 9.1. *For any observable $A \in \mathfrak{A}$,*

$$V_{\rho}[A] = \| (dE[A])_{\rho} \|_{\rho}^2 \quad (3.2.2)$$

We can now consider pure state models, i.e., submanifolds \mathcal{S} of \mathbf{PH} , and, using the same arguments as in the classical case, we have

Theorem 10. *Given a pure state model \mathcal{S} , for any observable A , we have*

$$V_{\rho}[A] \geq \| (dE[A]|_{\mathcal{S}})_{\rho} \|_{\rho}^2 \quad (3.2.3)$$

where the equality holds if and only if

$$(A - E_{\rho}[A])^{(\rho)} \in T_{\rho}\mathcal{S} \quad (3.2.4)$$

3.2.2 Quantum Cramér-Rao bound

We can now develop the quantum version of the Cramér-Rao bound for statistical models. We will proceed similarly to the classical version, but we need to be careful when treating multivariate models.

Let us consider an m -dimensional pure state model

$$\mathcal{S} = \{\rho_\xi \mid \xi = [\xi^{(1)}, \dots, \xi^{(m)}] \in \Xi \subseteq \mathbb{R}^n\} \quad (3.2.5)$$

where Ξ is the parameters set. We can define the unbiased estimators for the single parameters as the observables

$$F^{(i)} \in \mathfrak{A} : \quad \mathbf{E}_\rho[F^{(i)}] = \xi^{(i)} \quad \forall \rho \in \mathcal{S} \quad (3.2.6)$$

Then, if we consider an m -tuple of single-parameter estimators

$$\vec{F} = [F^{(1)}, \dots, F^{(m)}] \quad (3.2.7)$$

we can define the matrix $W_\xi[\vec{F}] = \{w_\xi^{ij}\}$ where

$$w_\xi^{ij} := \text{Cov}_{\rho_\xi}[F^{(i)}, F^{(j)}] = \langle\langle F^{(i)} - \xi^{(i)}, F^{(j)} - \xi^{(j)} \rangle\rangle_{\rho_\xi} \quad (3.2.8)$$

so that on the diagonal we have the variances of the estimators of the individual parameters

$$w_\xi^{ii} = V_{\rho_\xi}[F^{(i)}] \quad (3.2.9)$$

We can then repeat the same arguments as for theorem 5 to prove the following theorem.

Theorem 11. *Let $\mathcal{S} = \{\rho_\xi \mid \xi \in \Xi\}$ be an m -dimensional pure state model of \mathbf{PH} . Then, for any m -tuple \vec{F} of single-parameter estimators, the matrix $W_\xi[\vec{F}]$ satisfies*

$$W_\xi[\vec{F}] \geq G_F^{-1}(\rho_\xi) \quad (3.2.10)$$

in the sense that $W_\xi[\vec{F}] - G_F^{-1}(\rho_\xi)$ is positive semi-definite.

Unlike the classical case, the m -tuple of single-parameter estimators we defined cannot be used as a multivariate estimator. Intuitively, this is because every single-parameter estimator is a PVM and, unless the corresponding observables commute, the order of the measurements changes the distributions of the outcomes.

A general quantum estimator is composed of a POVM \hat{M} with outcomes in a set \mathcal{X} and a classical estimator $\hat{\xi}$ such that

$$\hat{M} = \{(M_x, x)\}_{x \in \mathcal{X}} \quad \text{and} \quad \hat{\xi} : \mathcal{X} \rightarrow \Xi \quad (3.2.11)$$

This definition can be interpreted as performing a quantum measurement on a system and then classically processing the results to estimate the parameters of the original quantum state. By denoting

$$E_\rho[\hat{\xi}] := \sum_{x \in \mathcal{X}} \hat{\xi}(x) p_\rho(x) = \sum_{x \in \mathcal{X}} \hat{\xi}(x) \text{tr}(\rho M_x) \quad (3.2.12)$$

we say that a quantum estimator $(\hat{M}, \hat{\xi})$ is unbiased when

$$E_{\rho_\xi}[\hat{\xi}] = \xi \quad \forall \rho_\xi \in \mathcal{S} \quad (3.2.13)$$

The variance-covariance matrix of the estimator is then $V_\xi[(\hat{M}, \hat{\xi})] = \{v_\xi^{ij}\}$ where

$$v^{ij} = \sum_{x \in \mathcal{X}} (\hat{\xi}^{(i)}(x) - \xi^{(i)}) (\hat{\xi}^{(j)}(x) - \xi^{(j)}) \text{tr}(\rho M_x) \quad (3.2.14)$$

and the following lemma holds.

Lemma 1. *Let $(\hat{M}, \hat{\xi})$ be an unbiased estimator for a pure state model. Then*

$$F^{(i)} = \sum_{x \in \mathcal{X}} \xi^{(i)}(x) M_x \quad (3.2.15)$$

defines an m -tuple \vec{F} of unbiased single-parameter estimators. Moreover, the following inequality holds

$$V_\xi[(\hat{M}, \hat{\xi})] \geq W_\xi[\vec{F}] \quad (3.2.16)$$

where the equality is satisfied if and only if \hat{M} is a PVM.

Proof. A complete proof can be found in [1, pg. 162]. \square

We can thus finally state the quantum version of the Cramér-Rao bound, also known as the *Holevo-Helstrom theorem*.

Theorem 12 (Quantum Cramér-Rao bound). *Let $(\hat{M}, \hat{\xi})$ be an unbiased estimator for a pure state model $\mathcal{S} = \{\rho_\xi \mid \xi \in \Xi\}$ of \mathbf{PH} . Then its variance-covariance matrix satisfies*

$$V_\xi[(\hat{M}, \hat{\xi})] \geq G_{QF}^{-1}(\rho_\xi) = \frac{1}{4} G_{FS}^{-1}(\rho_\xi) \quad (3.2.17)$$

where G_{QF} and G_{FS} are the matrix representations, respectively, of the quantum Fisher metric and the Fubini-Study metric of \mathbf{PH} .

This important result sets an intrinsic limit to the amount of information retrievable from the state of a quantum system.

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