

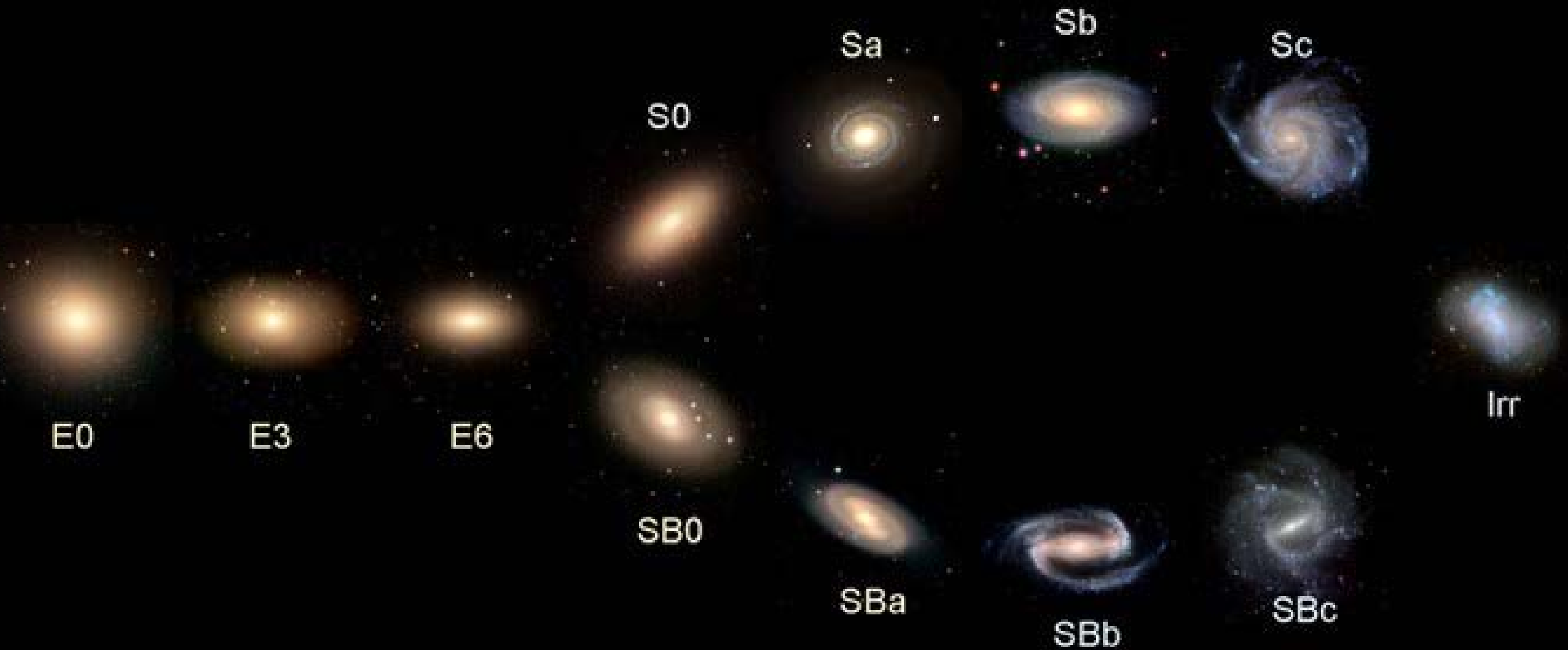
# Astronomical images and OoD behaviour of generative models

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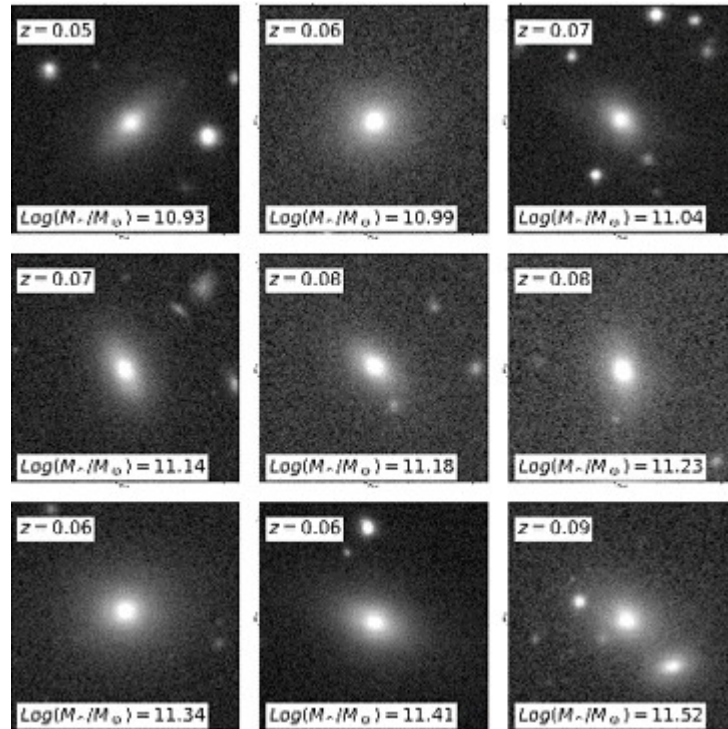
UNIVERSITY OF  
**Southampton**

# Hubble's Galaxy Classification Scheme



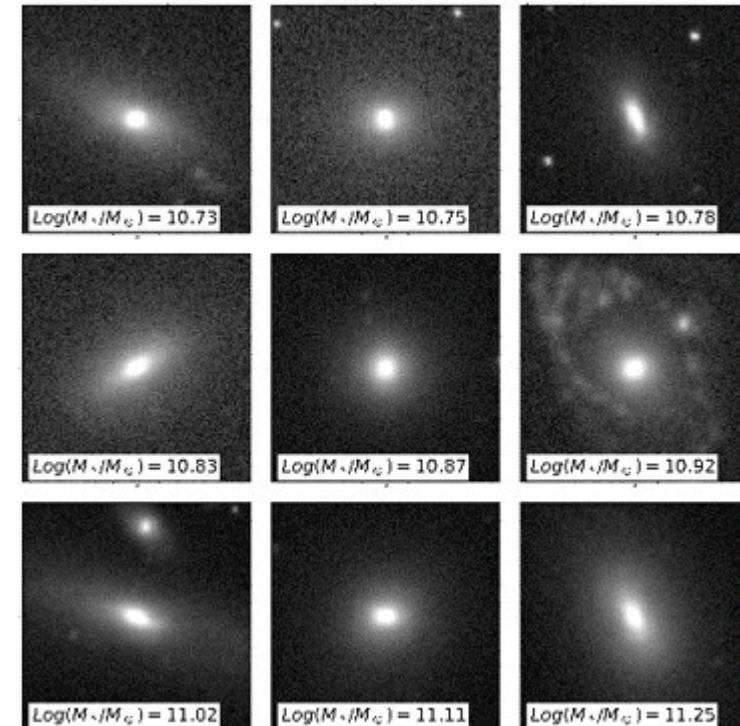
## Real

Sloan Digital Sky Survey, SDSS



## Simulated

Illustris TNG simulation



$$X \sim p(x) \xrightarrow{\text{red arrow}} p \overset{?}{=} q \xleftarrow{\text{blue arrow}} Y \sim q(y)$$

# Generative models for OoD detection

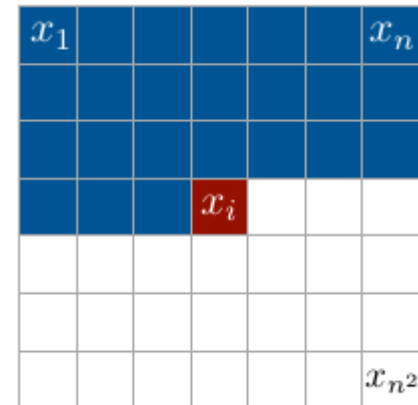
## Why generative models?

- Unsupervised approach
- Distribution of data  $p$  is learned
- Use the likelihood for OoD tasks

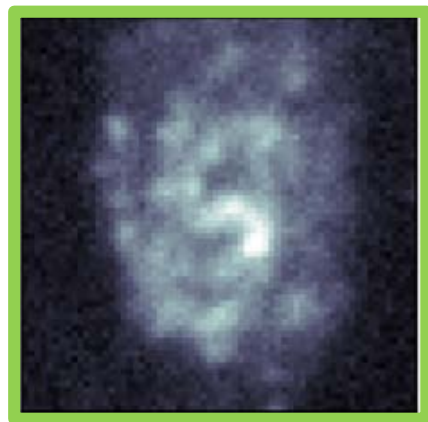
## PixelCNN

- Explicit likelihood
- Autoregressive

$$P(X) = \prod_{i=1}^{N^2} P(X_i | X_{1 \dots i-1})$$



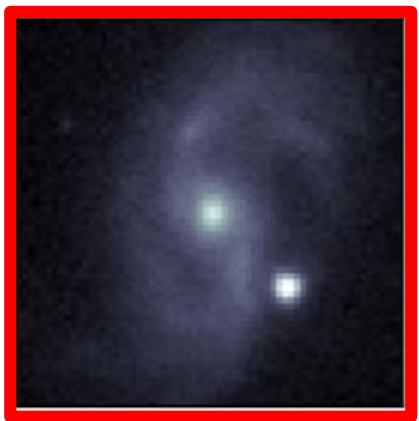
A test image  
(simulated or real)



TEST

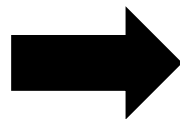


TRAIN



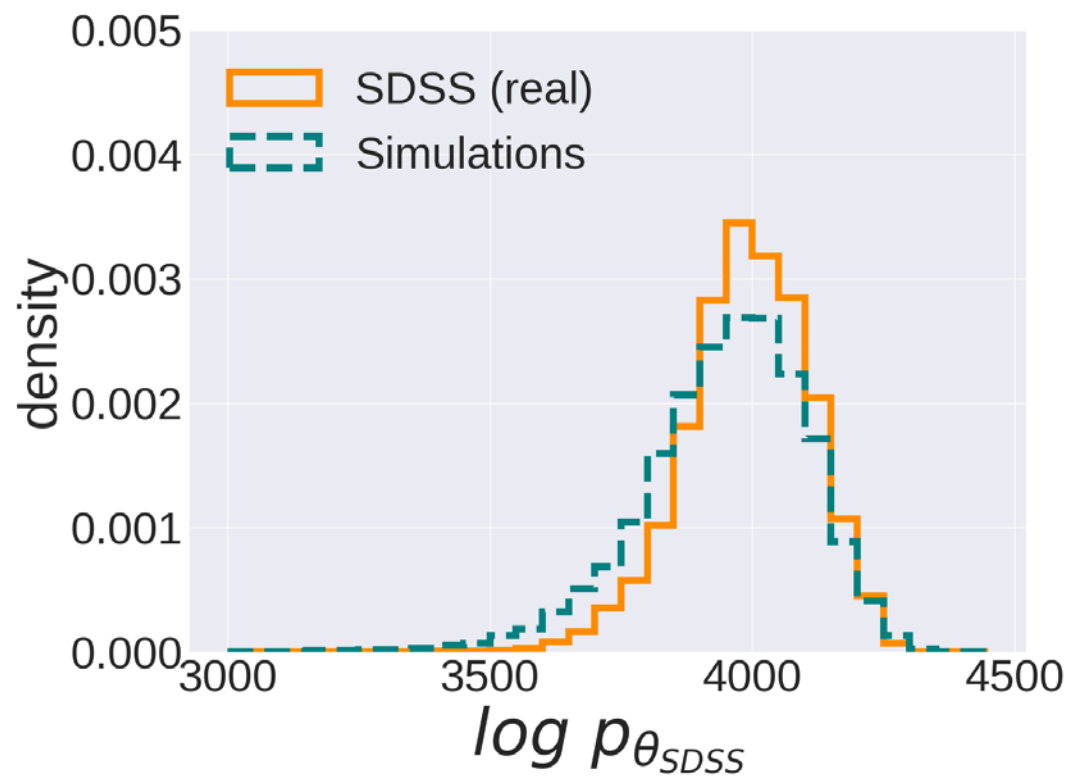
Real

PixelCNN



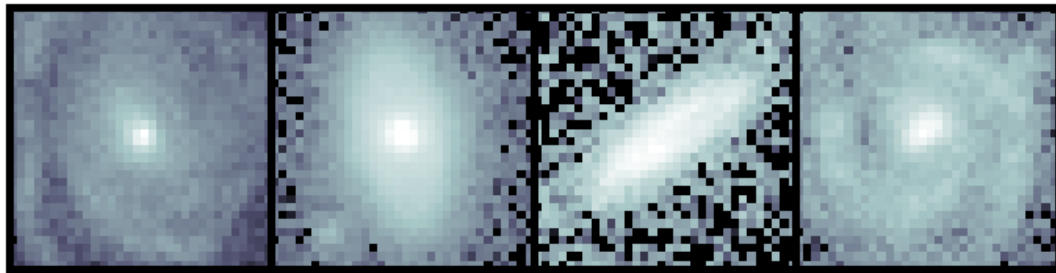
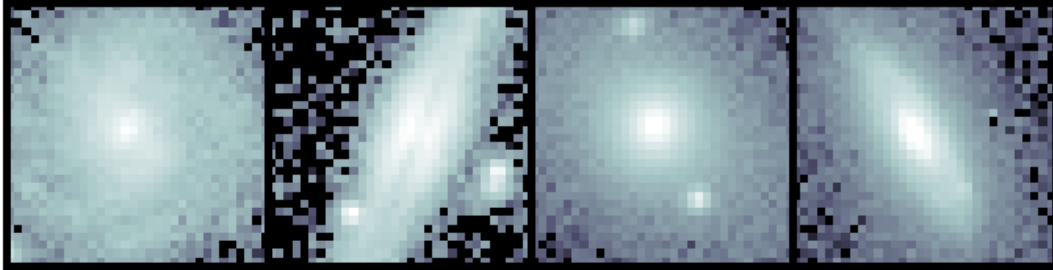
## Likelihood-based OoD

Bishop 1994



## Low likelihood

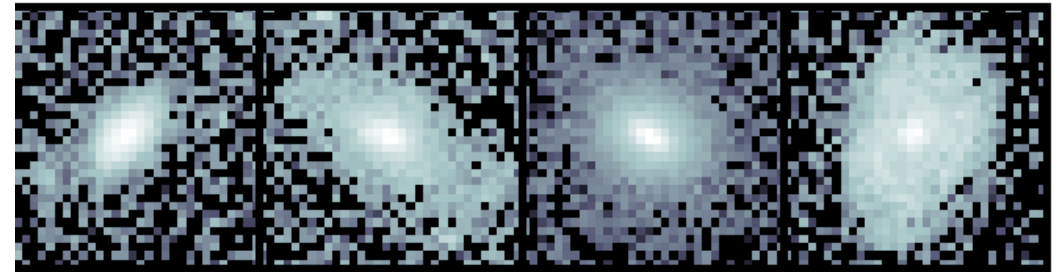
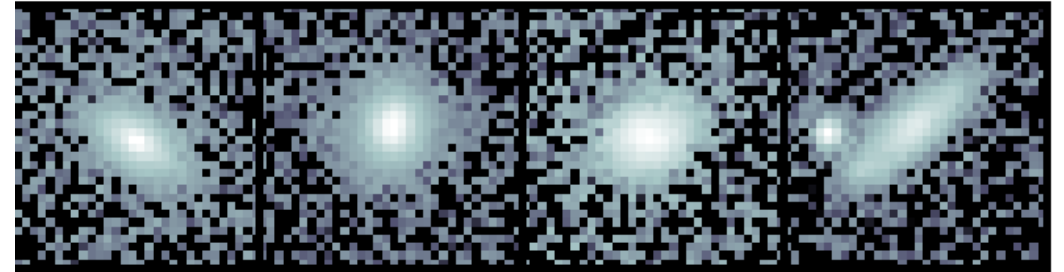
3675.0



- Larger
- More structure
- More messy background

## High likelihood

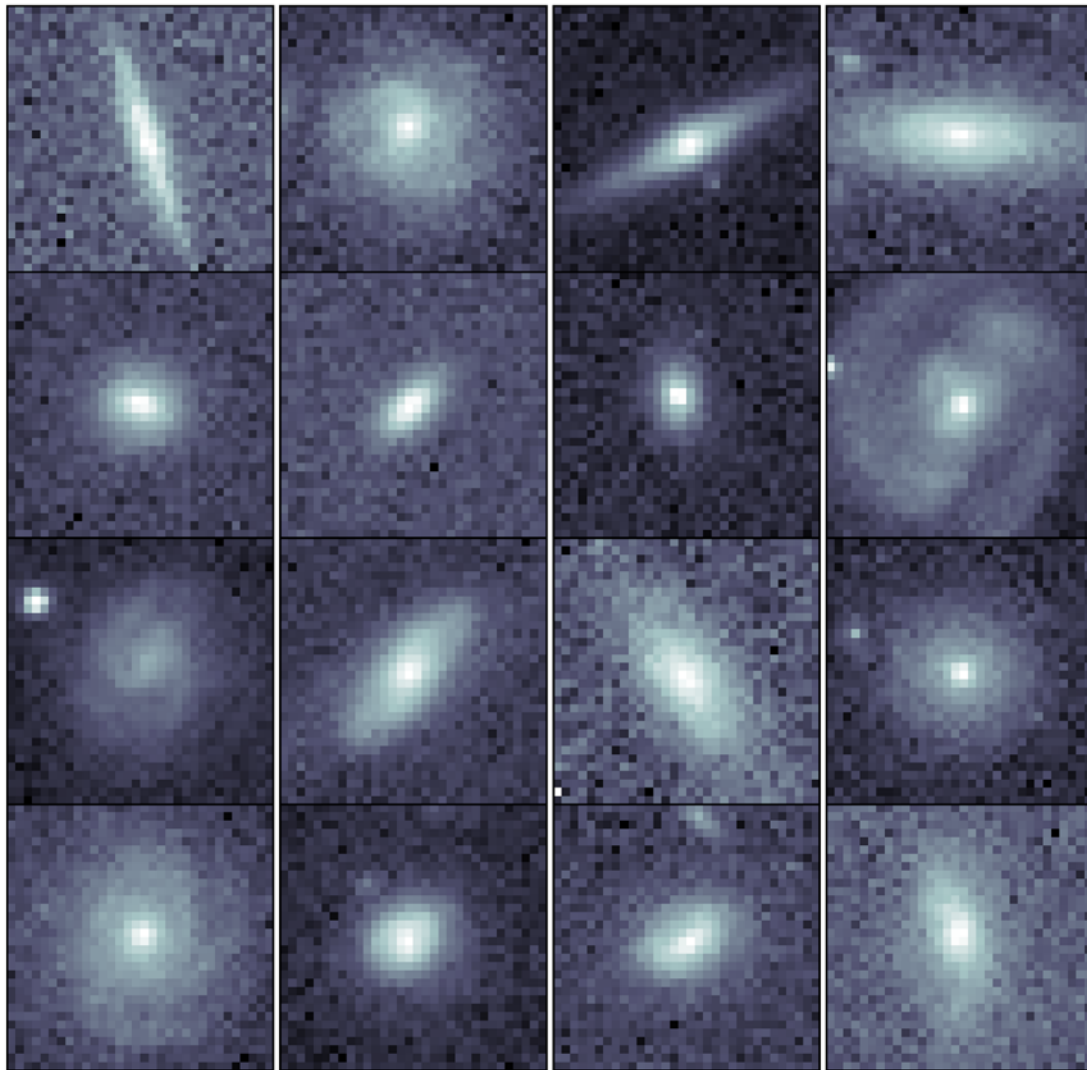
4172.0



- Smaller
- Less structure
- Less messy background

**Size, background, brightness, complexity**

See also:  
Serrà et al. 2019  
Ren et al. 2019



## Complexity

- Less variance than ImageNet
- Appreciable range of shapes

## Background

- Noise and interlopers
- More variance than MNIST
- Less variance than ImageNet

## Our aims

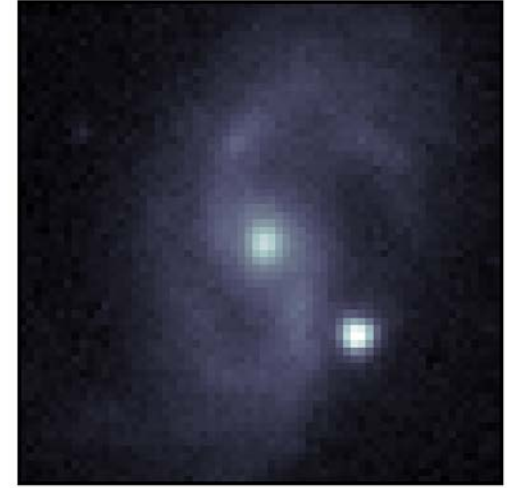
- Get rid of background
- Isolate fine shape details

# Galaxy archetypes

The Sèrsic Function models the light profile of a galaxy

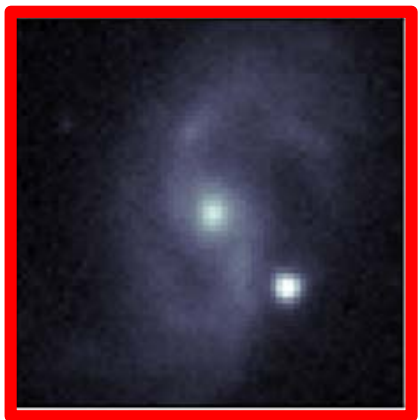
$$I(R; n, R_e) = I_e \exp \left\{ -b_n \left[ \left( \frac{R}{R_e} \right)^{-1/n} - 1 \right] \right\}$$

Smooth, **featureless** “blob” with ***the same global properties*** (size, luminosity, ellipticity..)

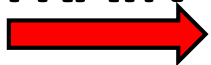




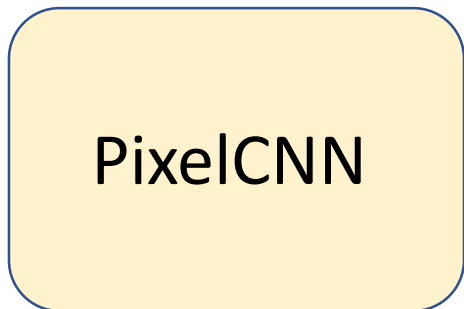
Real



**TRAIN**



PixelCNN



Global properties  
&  
Details  
&  
Background

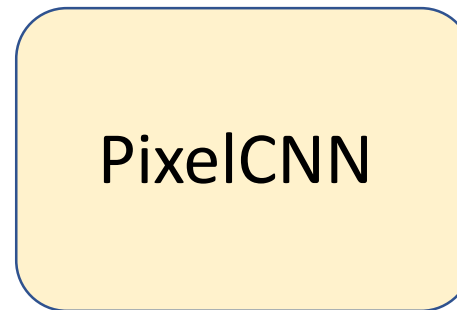
Archetype



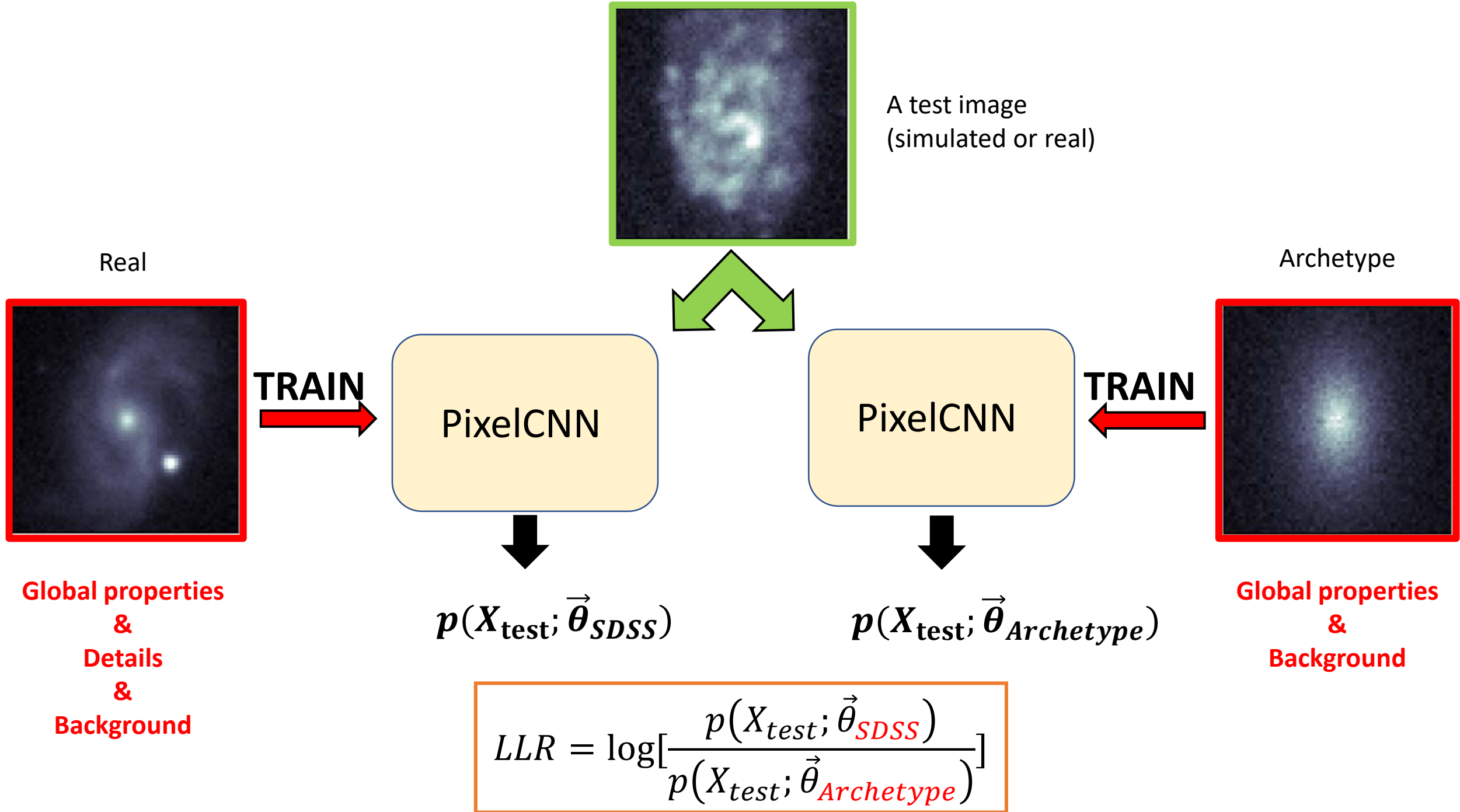
**TRAIN**



PixelCNN



Global properties  
&  
Background



$$p(X_{test}; \vec{\theta}) = p(X_{subject}; \vec{\theta})p(X_{bg}; \vec{\theta})$$

$$LLR = \log \left\{ \left[ \frac{p(X_{subject}; \vec{\theta}_1)}{p(X_{subject}; \vec{\theta}_2)} \right] \left[ \frac{p(X_{bg}; \vec{\theta}_1)}{p(X_{bg}; \vec{\theta}_2)} \right] \right\}$$

## Background removal

Ren et al. 2019  
(monochromatic bg)



$$p(X_{test}; \vec{\theta}) = p(X_{subject}; \vec{\theta})p(X_{bg}; \vec{\theta})$$

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$$p(X_{subject}; \vec{\theta}) = p(X_{details}|X_{global}; \vec{\theta})p(X_{global}; \vec{\theta})$$

$$LLR = \log \left\{ \frac{p(X_{details}|X_{global}; \vec{\theta}_1)p(X_{global}; \vec{\theta}_1)}{p(X_{global}; \vec{\theta}_2)} \right\}$$

## Background removal

Ren et al. 2019  
(monochromatic bg)



## Details enhancement

$$p(X_{test}; \vec{\theta}) = p(X_{subject}; \vec{\theta})p(X_{bg}; \vec{\theta})$$

$$LLR = \log \left\{ \frac{p(X_{subject}; \vec{\theta}_1)}{p(X_{subject}; \vec{\theta}_2)} \left[ \frac{p(X_{bg}; \vec{\theta}_1)}{p(X_{bg}; \vec{\theta}_2)} \right] \right\}$$

## Background removal

Ren et al. 2019  
(monochromatic bg)

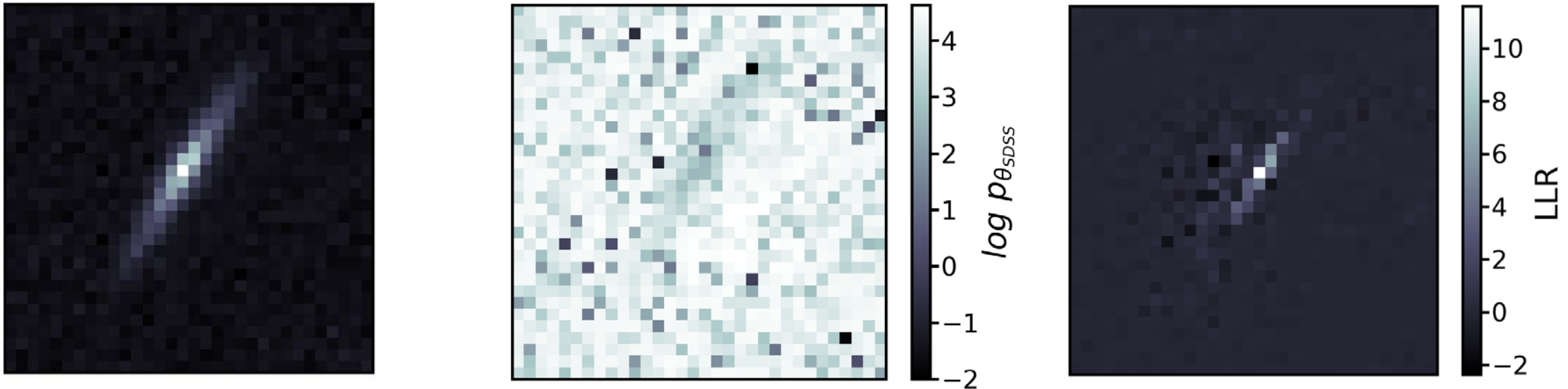


$$p(X_{subject}; \vec{\theta}) = p(X_{details}|X_{global}; \vec{\theta})p(X_{global}; \vec{\theta})$$

$$LLR = \log \left\{ \frac{p(X_{details}|X_{global}; \vec{\theta}_1)p(X_{global}; \vec{\theta}_1)}{p(X_{global}; \vec{\theta}_2)} \right\}$$

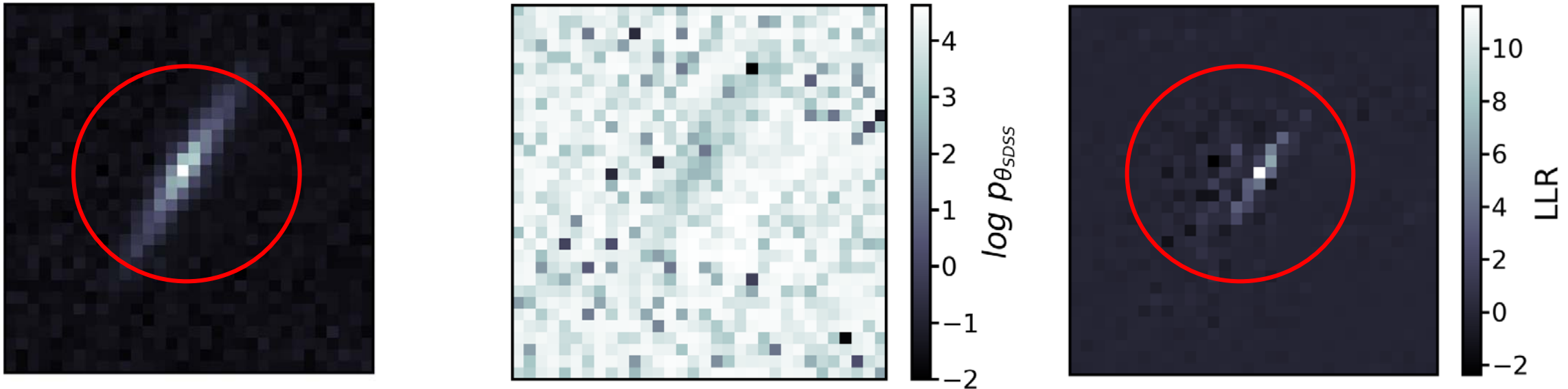
## Details enhancement

# Pixel-wise contributions



**Contribution of the background is null in the LLR**

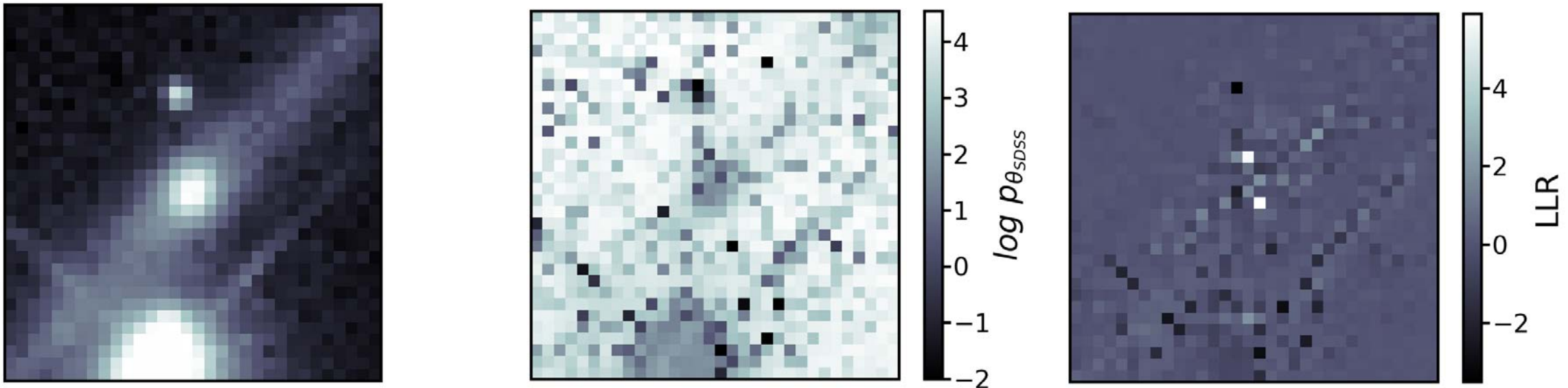
# Pixel-wise contributions



**Central regions are enhanced in LLR**

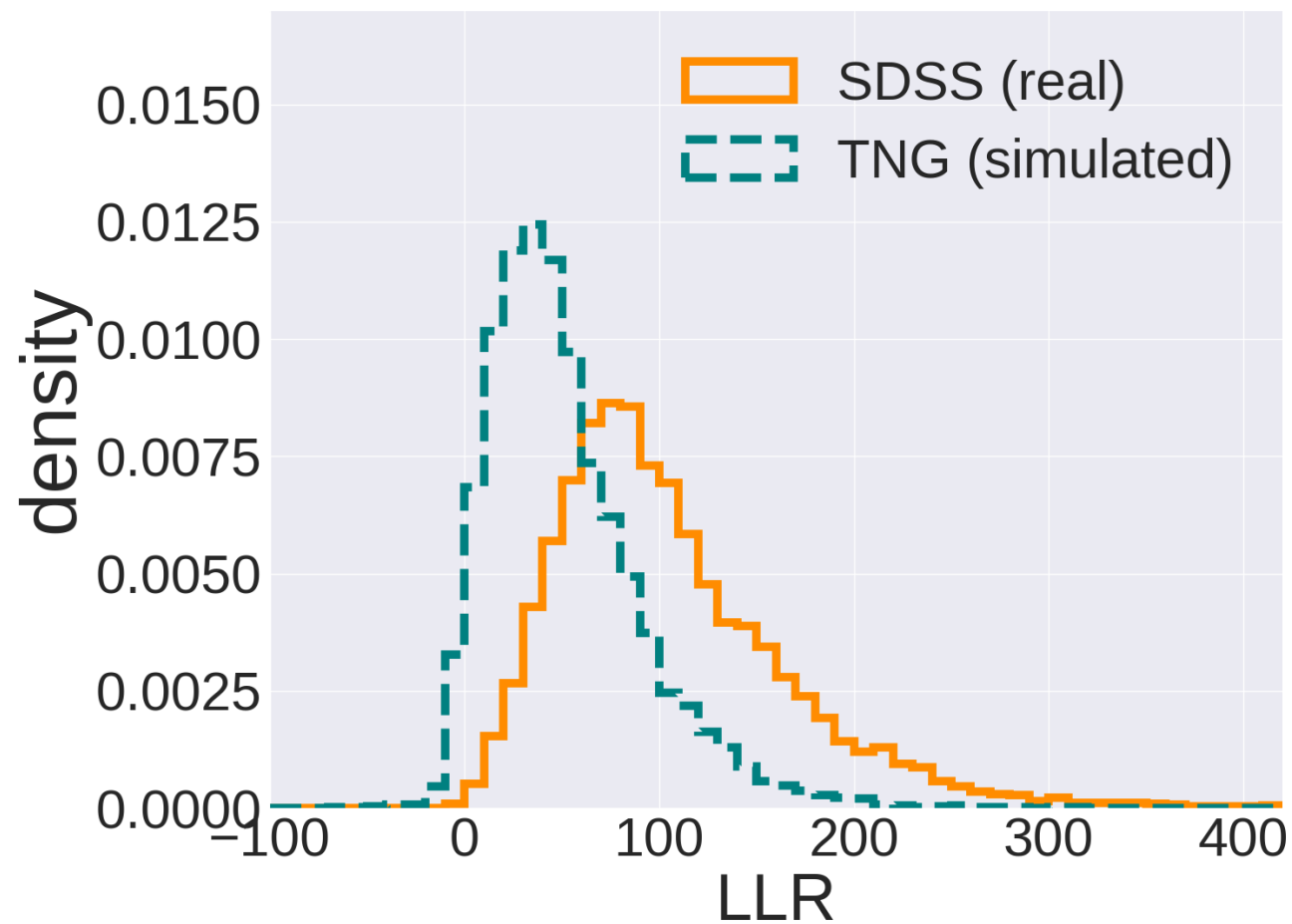


# Pixel-wise contributions

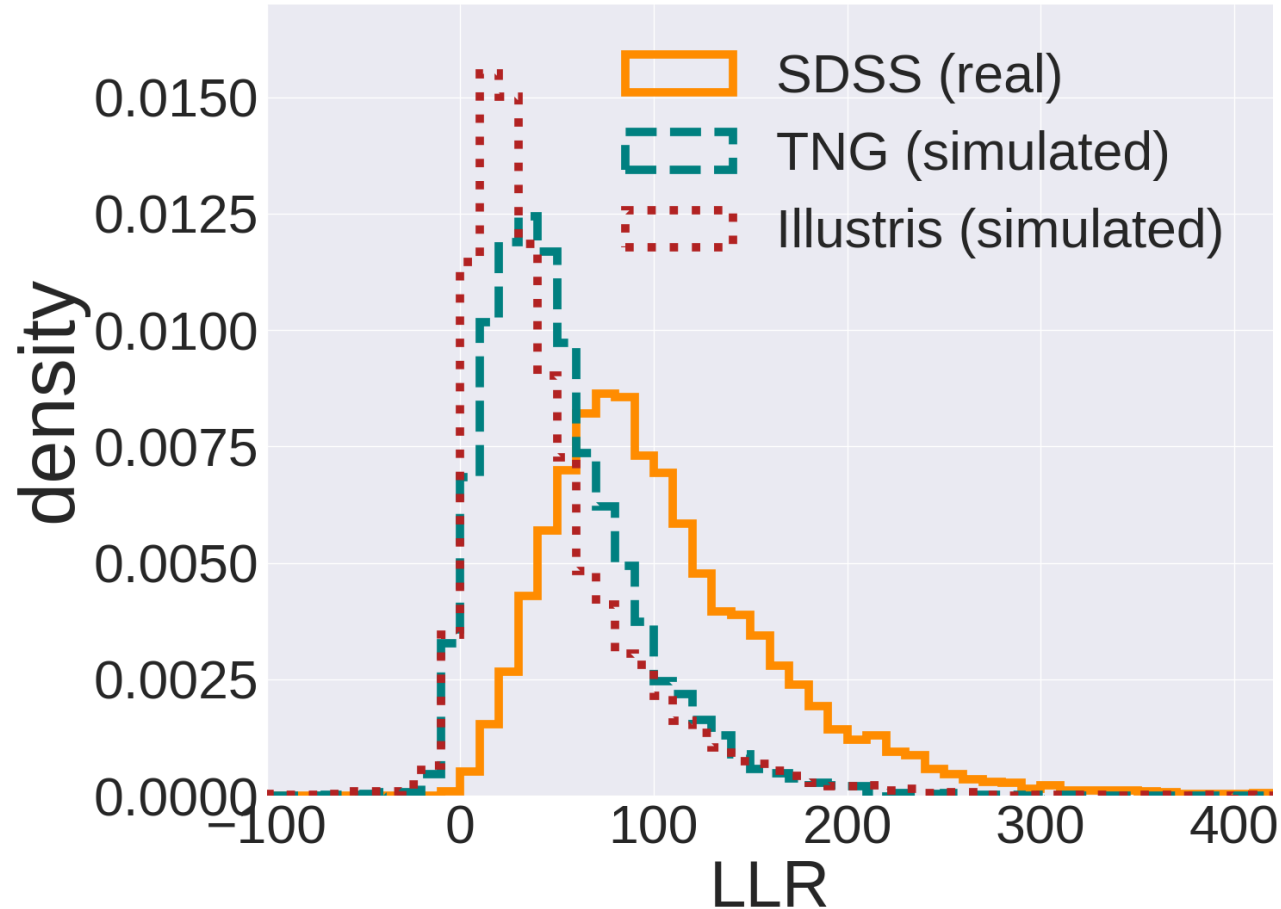


Contribution of ~~the background~~ a simple background is null in the LLR

## LLR-based OoD



$$LLR \approx \log[p(X_{details}|X_{global}; \vec{\theta}_{SDSS})]$$



## LLR-based OoD

$$LLR \approx \log[p(X_{details}|X_{global}; \vec{\theta}_{SDSS})]$$

**LLR-based feature enhancement and  
background removal:**

**a framework to compare datasets**

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