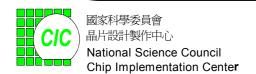
SPICE (07)

國科會晶片系統設計製作中心

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Course Objectives

- Know Basic elements for circuit simulation
- Learn the basic usage of standalone spice simulators
- Know the concept of device models
- Learn the usage of waveform tools
- Advanced features of spice simulator



Further Reading

HSPICE 使用手冊

PDF格式檔:/usr/meta/cur/docs/hspice.pdf

• HSPICE版本新增功能說明

PDF格式檔:/usr/meta/cur/docs/hspice00.4.RN.pdf

PS格式檔:/usr/meta/cur/docs/hspice00.4.RN.ps

HSPICE - awaves使用手冊

PDF格式檔:/usr/meta/cur/docs/avanwaves.pdf

PS格式檔:/usr/meta/cur/docs/ avanwaves.ps

SBTSPICE使用手冊

PDF格式檔:/usr/sbt/man/manu.pdf

PS格式檔:/usr/sbt/man/manu.ps

SBTPLOT 使用手冊

PDF格式檔:/usr/sbt/man/plot.pdf

PS格式檔:/usr/sbt/man/plot.ps

• 問題諮詢

http://www.cic.edu.tw

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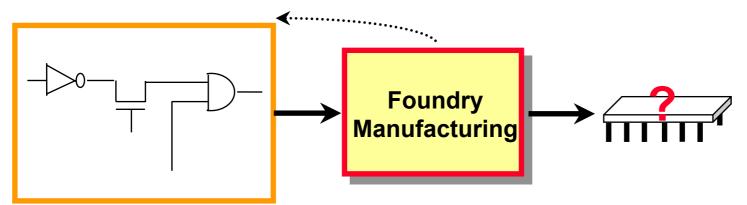
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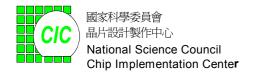
(1). Circuit Design Background

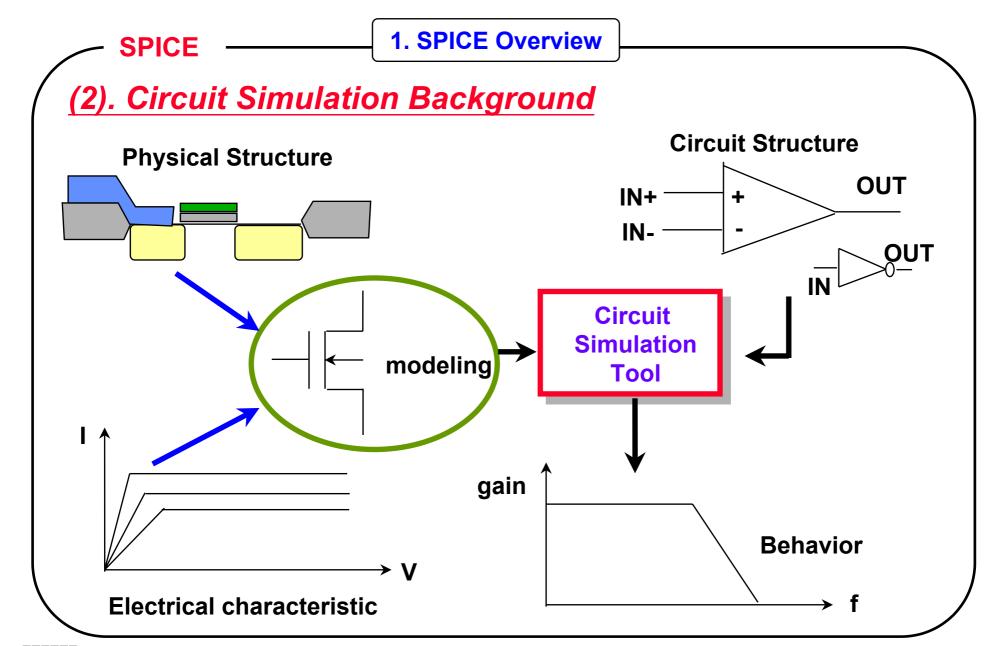
Circuit/System Design:

A procedure to construct a physical structure which is based on a set of basic component, and the constructed structure will provide a desired function at specified time/ time interval under a given working condition.



To predict the Circuit/System Characteristic after manufacture







(3). SPICE Background

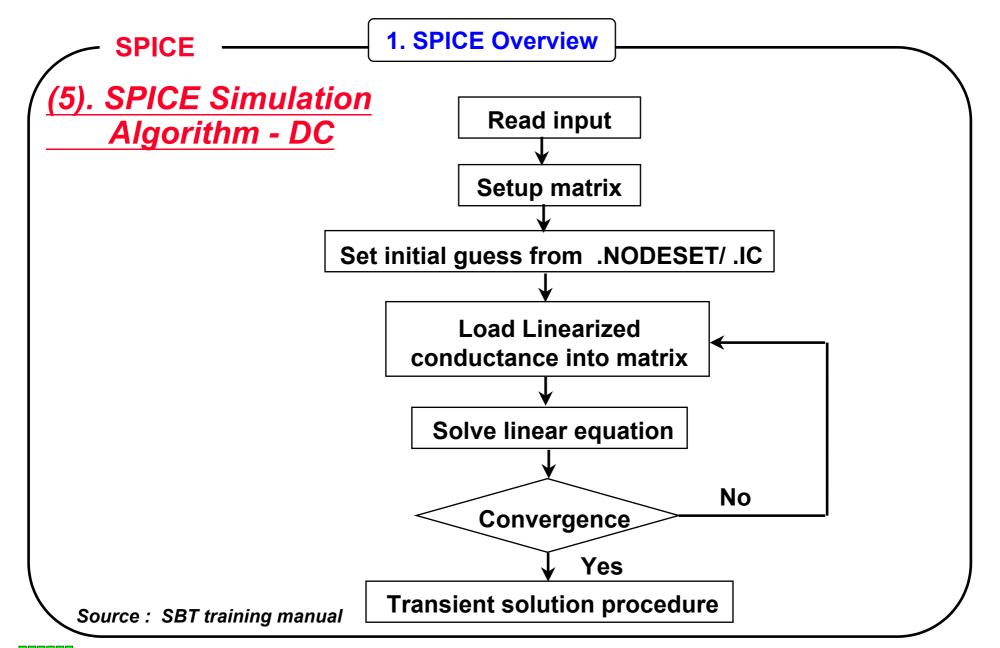
- SPICE : Simulation Program with Integrated Circuit Emphasis
 - Developed by University of California/Berkeley (UCB)
 - Successor to Earlier Effort CANCER
 - Widely Adopted, Become De Facto Standard
- Numerical Approach to Circuit Simulation
 - Circuit Node/Connections Define a Matrix
- Must Rely on Sub-Models for Behavior of Various Circuit Elements
 - Simple (e.g. Resistor)
 - Complex (e.g. MOSFET)

Source: IEEE 1997 CICC Educational Sessions, E3.3

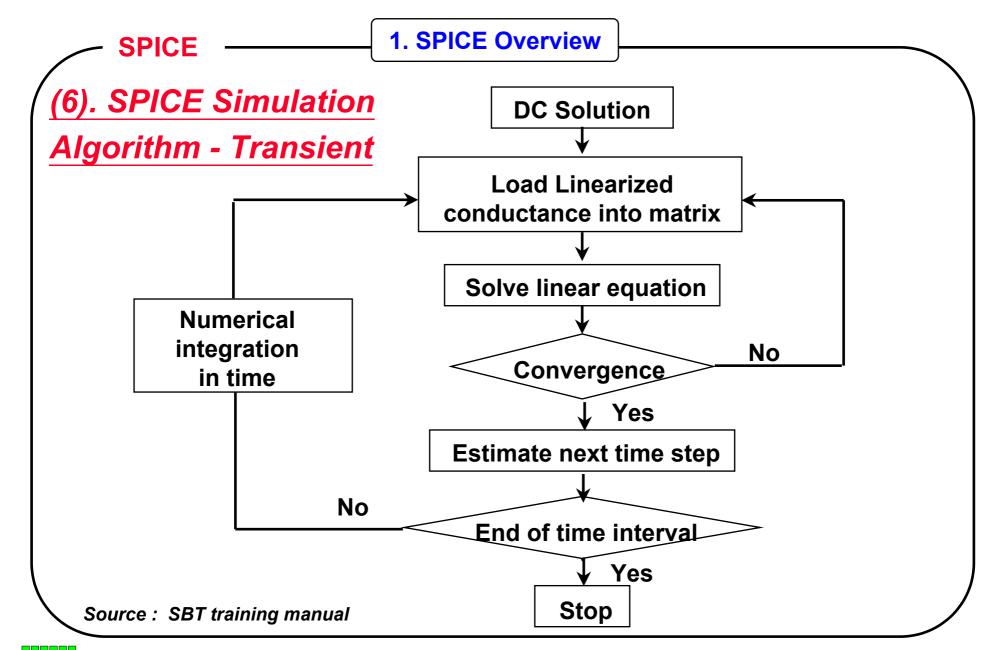


(4). SPICE Introduction

- SPICE generally is a Circuit Analysis tool for Simulation of Electrical Circuits in Steady-State, Transient, and Frequency Domains.
- There are lots of SPICE tools available over the market, SBTSPICE, HSPICE, Spectre, TSPICE, Pspice, Smartspice, ISpice ...
- Most of the SPICE tools are originated from Berkeley's SPICE program, therefore support common original SPICE syntax
- Basic algorithm scheme of SPICE tools are similar, however the control of time step, equation solver and convergence control might be different.







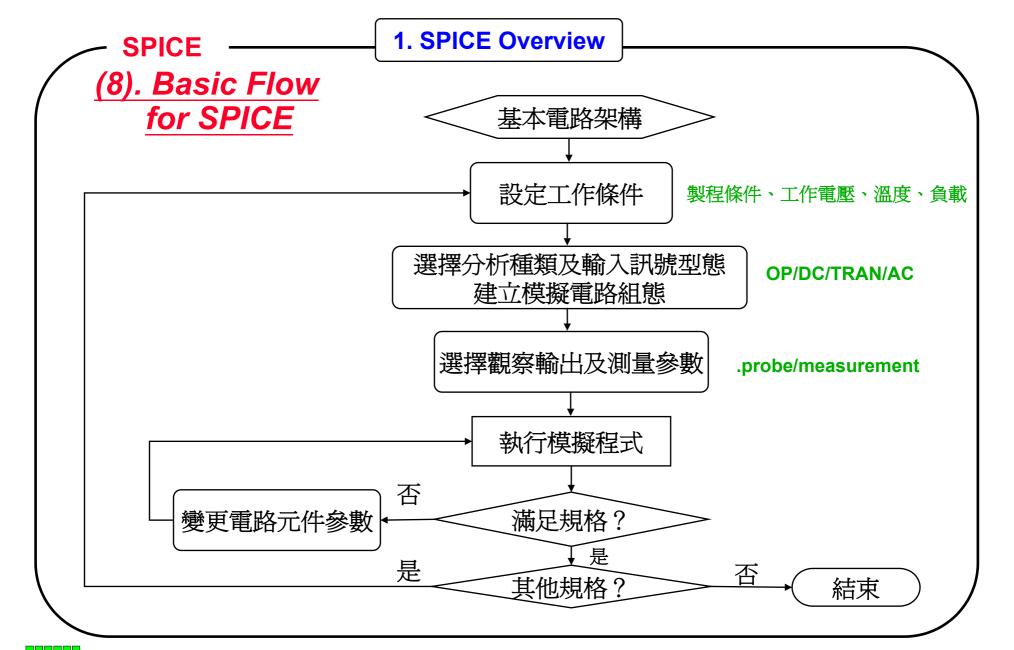


1. SPICE Overview

(7). Basics for Using SPICE Tools

SPICE 之外所需的基本概念

- 了解元件的基本特性
- 熟悉所設計電路的功能
- 了解需要驗證的電路規格及對應的模擬種類及電路組態
- 了解電路的輸入信號特性
- 了解電路各項規格的相依性及優先程度
- 了解電路元件參數與架構對各項電路特性的相關性,以利 模擬結果的改進

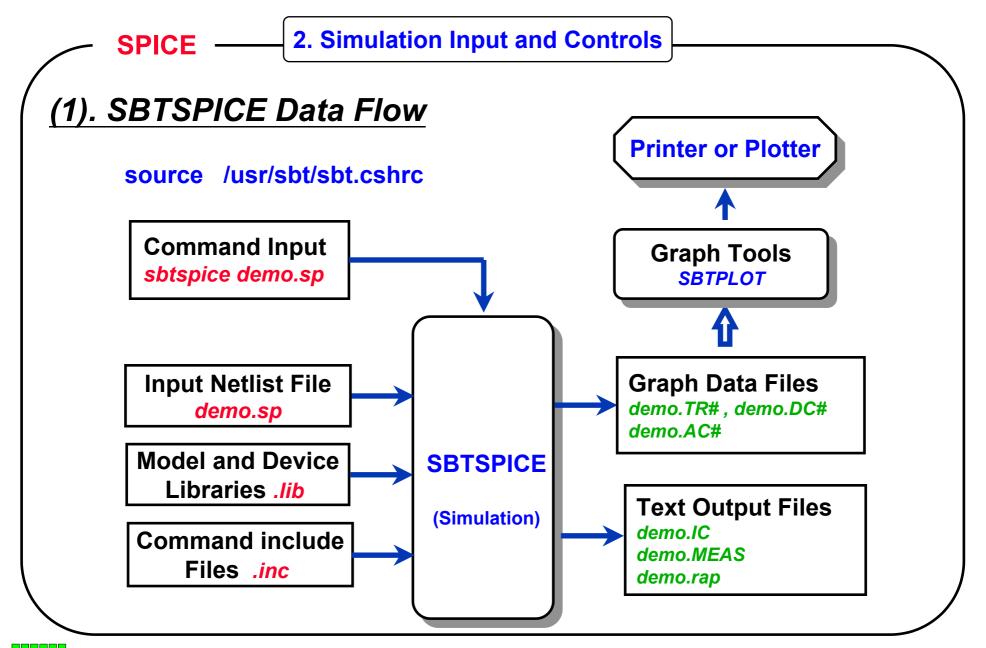




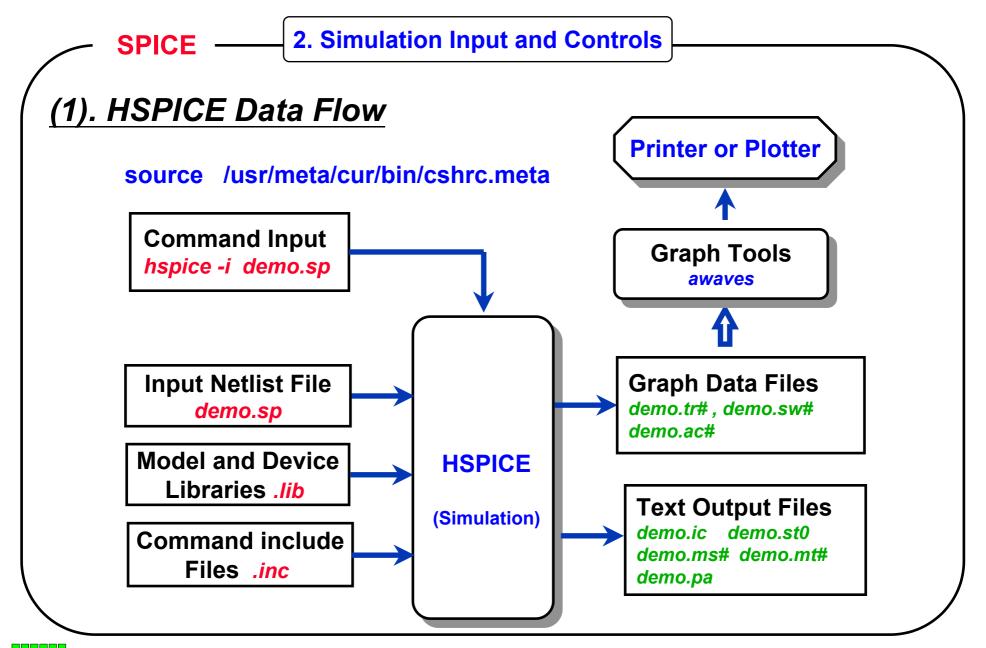
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2. Simulation Input and Controls

(2). Netlist Statements and Elements

First line is Input Netlist File Title TITLE * or \$ Commands to Describe Circuit .OPTIONS Set Conditions for Simulation

Analysis(AC,DC,TRAN..) & .TEMP Statements to Set Sweep Variables .PRINT/.PLOT/.PROBE/.GRAPH Set Print, Plot, and Graph Variables

.IC or .NODESET Sets Initial State

.VEC 'digital vector file' Sets Input Stimuli File

Sources (I or V) Sets Input Stimuli **Schematic Netlist** Circuit Description

In first Column ,+, is Continuation Char. .SUBCKT/.ENDS

Sets/Ends Subcircuit Description

.MEASURE (Optimization Optional) Provides Scope-like Measurement Capability

.LIB or .INCLUDE Call Library or General Include Files

.MODEL Library **Element Model Descriptions**

.DATA or .PARAM Specify parameters or Parametric Variations

Sequence for In-line Case Analysis ALTER .DELETE LIB

Remove Previous Library Selection

Required Statement to Terminate Simulation

.END

(3). Netlist Structure (SPICE Preferred)

```
Title
                            Title Statement - Ignored during simulation
   Controls
                             .option nomod nopage
                             .tran 1 10
                            .print v(5) i(r1)
                            .plot v(3) v(in)
                            * voltage sources
   Sources
                            v3 3 0 dc 0 ac 0 0 pulse 0 1 0 0.1 0.1 4 8
                            vin in 0 sin(0 2 10k 0.5 0)
                            * Components
 Components
                                     2pf
                             m1 1 2 3 4 mod L=10u W=30u
                            x3 2 3 INV
                            *Model & Subcircuit
                            .model... or .LIB or .Subckt
Models & Subckts
     End file - - - - -
```

2. Simulation Input and Controls

(4). Element and Node Naming Conventions

- Node and Element Identification:
 - Either Names or Numbers (e.g. data1, n3, 11,)
 - 0 (zero) is <u>Always</u> Ground
 - *
- Trailing Alphabetic Character are ignored in Node Number, (e.g. 5A=5B=5)
- Ground may be 0, GND, !GND
- All nodes are assumed to be local
- Node Names can be may Across all Subcircuits by a .GLOBAL Statement (e.g. .GLOBAL VDD VSS)



SPICE -

2. Simulation Input and Controls

(4). Element and Node Naming Conventions(Cont.)

Instance and Element Names:

C Capacitor

Diode

E,F,G,H Dependent Current and Voltage Controlled Sources

| Current

J JFET or MESFET

K Mutual Inductor

L Inductor

M MOSFET

O BJT

R Resistor

O,T,U Transmission Line

V Voltage Source

X Subcircuit Call

Path Names of Subcircuits Nodes: e.g. @x1.x2.mn[vth],@x1.x2.mn[id]
V(X1.bit1), I(X1.X4.n3)



(5). Units and Scale Factors

Units:

- R Ohm (e.g. R1 n1 n2 1K)
- **C** Farad (e.g. C2 n3 n4 1e-12)
- L Henry (e.g. L3 n5 n6 1e-9)

Scale Factors :

F 1e-15
P 1e-12
N 1e-19
U 1e-6
M 1e-3

K 1e3
 Meg 1e6
 G 1e9
 T 1e12
 DB 20log₁₀

Examples:

1pF 1nH 10Meg Hz vdb(v3)

Warning: in SBTSPICE 1.e-15F, will be interpreted as 1e-15 fento Farad

Technology Scaling : All Length and Widths are in Meters

Using .options scale=1e-6 → L=2 W=100

- 2. Simulation Input and Controls
- (6). Input Control Statements : .ALTER
 - .ALTER Statement : Description
 - Rerun a Simulation Several Times with Different

Circuit Topology

Models

Elements Statement

Parameter Values

Options

Analysis Variables, etc.

- 1st Run: Reads Input Netlist File up to the first .ALTER
- Subsequent: Input Netlists to next .ALTER, etc.



SPICE -

2. Simulation Input and Controls

(6). Input Control Statements : .ALTER (Cont.)

.ALTER Statement : Example

```
*file2: alter2.sp alter examples $ Title Statement
.lib 'mos.lib' normal
.param wval=50u Vdd=5V
r4 4 3 100
.alter
.del lib 'mos.lib' normal
                                  $ remove normal model lib
. lib 'mos.lib' fast
                                  $ get fast model lib
alter
.temp -50 0 50
                                  $ run with different temperature
r4 4 3 1K
                                  $ change resistor value
c3 3 0 10p
                                  $add the new element
.param wval=100u Vdd=5.5V
                                  $ change parameters
.end
```



SPICE

2. Simulation Input and Controls

- (6). Input Control Statements : .ALTER (Cont.)
 - .ALTER Statement : Limitations
 - CAN Include:
 - **→** Element Statement (Include Source Elements)
 - .DATA, .LIB, .INCLUDE, .MODEL Statements
 - → .IC, .NODESET Statement
 - .OP, .PARAM, .TEMP, .TF, .TRAN, .AC, .DC Statements
 - **CANNOT Include:**
 - .PRINT, .PLOT, .GRAPH, or any I/O Statements



SPICE -

2. Simulation Input and Controls

(7). Input Control Statements: .DATA

DATA Statement: Inline or Multiline .DATA Example

Inline .DATA Example

.TRAN 1n 100n SWEEP DATA=devinf
.AC DEC 10 hhz 100khz SWEEP DATA=devinf
.DC TEMP -55 125 10 SWEEP DATA=devinf

*

.DATA devinf Width Length Vth Cap

+ 10u 100u 2v 5p

+ 50u 600u 10v 10p

+ 100u 200u 5v 20p

.

.ENDDATA

Multiline .DATA Example

.PARAM Vds=0 Vbs=0 L=1.0u

.DC DATA=vdot

.DATA vdot

Vbs Vds L

0 0.1 1.0u

0 0.1 1.5u

-1 0.1 1.0u

0 0.5 1.0u

.....

.ENDDATA

SPICE -

2. Simulation Input and Controls

(8). Input Control Statements: .TEMP

- .TEMP Statement: Description
 - When TNOM is not Specified, it will Default to 25 °C for HSPICE When TNOM is not Specified, it will Default to 27 °C for SBTSPICE
 - Example 1:

```
.TEMP 30 $ Ckt simulated at 30 °C
```

Example 2:

```
.OPTION TEMP = 30 $ Ckt simulated at 30 °C
```

Example 3:

```
.TEMP 100
D1 n1 n2 DMOD DTEMP=30 $ D1 simulated at 130 °C
D2 n3 n4 DMOD $ D2 simulated at 100 °C
R1 n5 n6 1K

HSPICE: DTEMP
SBTSPICE: TEMP
```



- 2. Simulation Input and Controls
- (8). Input Control Statements: .OPTION
 - OPTION Statement : Description
 - Option Controls for

Listing Formats
Simulation Convergence
Simulation Speed
Model Resolution
Algorithm
Accuracy

Option Syntax and Example

.OPTION opt1 <opt2> <opt=x>

.OPTION LVLTIM=2 POST PROBE SCALE=1



SPICE

2. Simulation Input and Controls

- (8). Input Control Statements: .OPTION(Cont.)
 - OPTION Keywords Summary :
 - General Control Options

Input, Output CPU Interfaces Analysis Error Version

DC Operating Point and DC Sweep Analysis

Accuracy
Matrix
Input,Output
Convergence
Pole/Zero

■ Model Analysis

General MOSFETs Inductors BJTs Diodes

Transient and AC Small Signal Analysis

> Accuracy Speed Timestep Algorithm Input, Output

(9). Library Input Statement

.INCLUDE Statement Copy the content of file into netlist

```
.INCLUDE '$installdir/parts/ad'
```

.LIB Definition and Call Statement File reference and Corner selection

```
JIB TT ← Corner name
.MODEL nmos_tt nmos (level=49 Vt0=0.7
+TNOM=27 .....)
.ENDL TT
```

.LIB '~users/model/tsmc/logic06.mod' TT + Corner name

Prevent the listing of included contents ■ .PROTECT ← .LIB "~users/model/tsmc/logic06.mod" TT .UNPROTECT



2. Simulation Input and Controls

(10). Hierarchical Circuits, Parameters, and Models

- .SUBCKT Statement : Description
 - .SUBCKT Syntax

.SUBCKT subname n1 <n2 n3...> <param=val...>

- n1 ... Node Number for External Reference; Cannot be Ground node (0)
 Any Element Nodes Appearing in Subckt but not Included in this
 list are Strictly LOCAL, with these Exceptions:
 - (1) Ground Node (0)
 - (2) Nodes Assigned using .GLOBAL Statement
- (3) Nodes Assigned using BULK=node in MOSFET or BJT Models param Used ONLY in Subcircuit, Overridden by Assignment in Subckt Call or by values set in .PARAM Statement
- Subcircuit Calls (X Element Syntax)

```
.Xyyyy n1 <n2 n3...> subname <param=val...> <M=val>
.XNOR3 1 2 3 4 NOR WN=3u LN=0.5u M=2
```



SPICE -

2. Simulation Input and Controls

(10). Hierarchical Circuits, Parameters, and Models (Cont.)

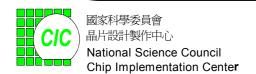
• .SUBCKT Statement : Examples

```
.GLOBAL VDD
VDDA VDD 0 VALUE
.PARAM VALUE=5V
.TRAN 1n 100n
.SUBCKT INV IN OUT WN=2u WP=8u
   OUT IN VDD VDD P L=0.5u W=WP
   OUT IN 0
M2
                   N L=0.5u W=WN
R1
   OUT
          1K
R2
        5
          10K
LENDS INV
          INV
              WN=5u WP=20u
X2 2
         INV
              WN=10u WP=40u
.PRINT TRAN V(2) V(X1.4) I(X2.M1)
```

2. Simulation Input and Controls

(11). Example Circuit

```
Invter gain
              .lib 'ls35_4_1.l' tt
              .option acct post
              .param vref=1.0 Wmask=25u LMask=0.8u vcc=5
              .subckt inv out inp d
              mn1 out inp 0 0 nch w=Wmask I=Lmask
              mp1 out inp d d pch w=Wmask l=Lmask
              .ends inv
subckt call \rightarrowx1 out inp vdd inv
              vdd vdd 0 dc vcc
              vin inp 0 dc 0 pulse(0 vcc 0 1ns 1ns 2ns 5ns)
              .dc vin 0 vcc 0.01 sweep data=d1
                                                              .data d1
              .tran 0.1ns 10ns sweep data=d1
                                                              I mask Wmask
              .meas tran tpd trig v(inp) val=2 rise=1
                                                              0.6u 250u
                             targ v(out) val=3 fall=1
                                                              2.0u 420u
              +
              .probe v(inp) v(out)
                                                              .enddata
                                                              .end
```



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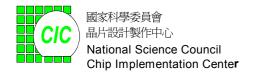
3. Sources and Stimuli

Source / Stimuli: 提供電路驅動來源

Source types

- 固定值獨立電源
 提供固定偏壓或固定驅動電流
- 時變/頻變 獨立電源
 提供變動的電壓或電流輸入,一般供輸入信號用
- 時變/頻變 壓控/源控 相依電源
 提供可控制的電壓或電流源,一般供建立模型用

壓控電壓源(VCVS) 壓控電流源(VCCS) 流控電壓源(CCVS) 流控電流源(CCCS)



SPICE

3. Sources and Stimuli

(1). Independent Source Elements: AC, DC Sources

Source Element Statement :

Syntax :

```
Vxxx n+ n- <<DC=>dcval> <tranfun> <AC=acmag, <acphase>> 
lyyy n+ n- <<DC=>dcval> <tranfun> <AC=acmag, <acphase> <M=val>
```

Examples of DC & AC Sources :

V1 1 0 DC=5V V2 2 0 5V I3 3 0 5mA

V4 4 0 AC=10V, 90 V5 5 0 AC 1.0 180

*AC or Freq. Response Provide Impulse Response

Examples of Mixed Sources :

V6 6 0 5V AC=1V, 90

V7 7 0 0.5V AC 1.0 SIN (0 1 1Meg)

SPICE

3. Sources and Stimuli

(2). Independent Source Functions: Transient Sources

- Transient Sources Statement :
 - Types of Independent Source Functions :
 - **★** Pulse (PULSE Function)
 - **★** Sinusoidal (SIN Function)

 Exponential (EXP Function)
 - ★ Piecewise Linear (PWL Function)
 Single-Frequency FM (SFFM Function)
 Single-Frequency AM (AM Function)

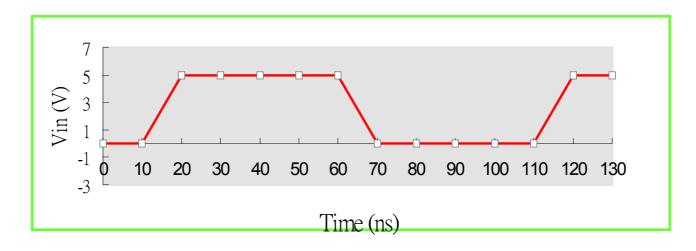


- (2). Indep. Source Functions : Transient Sources(Cont.)
 - Pulse Source Function : PULSE
 - Syntax :

PULSE (V1 V2 < Tdelay Trise Tfall Pwidth Period >)

Example:

Vin 1 0 PULSE (0V 5V 10ns 10ns 10ns 40ns 100ns)





(2). Indep. Source Functions : Transient Sources(Cont.)

- Sinusoidal Source Function : SIN
 - Syntax

SIN (Voffset Vacmag < Freq Tdelay Dfactor >)

Voffset + Vacmag* $e^{-(t-TD)}$ *Dfactor * $sin(2\pi Freq(t-TD))$

Example :

Vin 3 0 SIN (0V 1V 100Meg 2ns 5e7)



3. Sources and Stimuli

(2). Indep. Source Functions : Transient Sources(Cont.)

- Piecewise Linear Source Function : PWL or PL
 - Syntax :

PWL (<t1 v1 t2 v2> <R<=repeat>> <Tdelay=delay>)
\$ R=repeat_from_what_time TD=time_delay_before_PWL_start

Example :

V1 1 0 PWL 60n 0v, 120n 0v, 130n 5v, 170n 5v, 180n 0v, R 0 V2 2 0 PL 0v 60n, 0v 120n, 5v 130n, 5v 170n, 0v 180n, R 60n



3. Sources and Stimuli

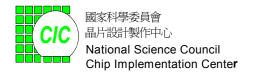
- (2). Indep. Source Functions : Transient Sources(Cont.)
 - Specifying a Digital Vector File : .VEC
 - Syntax :

```
.VEC `digital_vector_file`
```

\$ The digital vector file consists of three parts:

- Vector Pattern Definition
- Waveform Characteristics
- Tabular Data
- Digital Vector File Example :

```
; Vector Pattern
Radix 1 2 3 44
vname v1 va[[1:0]] vb[3:1] vc[8:1]
io i i i oo
tunit ns
```



3. Sources and Stimuli

(2). Indep. Source Functions : Transient Sources(Cont.)

- Specifying a Digital Vector File: .VEC
 - Digital Vector File Example (Cont.):

```
; Waveform Characteristics
slope 1.2
trise 0.2 137FF
tfall 0.5 137FF
tdealy 0.5 1 3 7 FF
vih 3.3 137FF
vil 0.0 00000
; Tabular Data
period 10
10245
137FF
```



3. Sources and Stimuli

(3). Voltage and Current Controlled Elements

- Dependent Sources (Controlled Elements) :
 - **Four Typical Linear Controlled Sources :**

```
Voltage Controlled Voltage Sources (VCVS) --- E Elements
Voltage Controlled Current Sources (VCCS) --- G Elements
Current Controlled Voltage Sources (CCVS) --- H Elements
Current Controlled Current Sources (CCCS) --- F Elements
```

```
      E(name)
      N+
      N-
      NC+
      NC-
      (Voltage Gain Value)

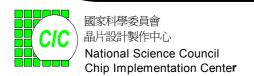
      Eopamp
      3
      4
      1
      2
      1e6

      Ebuf
      2
      0
      1
      0
      1.0
```

- Voltage Controlled Resistor (VCR) and Capacitor (VCCAP)
- Polynomial Controlled Sources POLY(1) ,POLY(2), POLY(3)

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4. Analysis Types

(1). Analysis Types & Orders

- Types & Order of Execution :
 - DC Operating Point : First Calculated for ALL Analysis Types

.OP .IC .NODESET

■ DC Sweep & DC Small Signal Analysis :

.DC .TF .PZ .SENS

■ AC Sweep & Small Signal Analysis :

.AC .NOISE .DISTO .SAMPLE .NET

■ Transient Analysis:

.TRAN .FOUR (UIC)

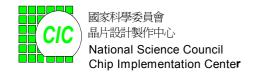
- Other Advanced Modifiers :
 - Temperature Analysis, Optimization



4. Analysis Types

(2). Analysis Types : DC Operating Point Analysis

- Initialization and Analysis:
 - First Thing to Set the DC Operating Point Values for All Nodes and Sources : Set Capacitors OPEN & Inductors SHORT
 - Using .IC or .NODESET to set the Initialized Calculation
 - If UIC Included in .TRAN ==> Transient Analysis Started Directly by Using Node Voltages Specified in .IC Statement
 - .NODESET Often Used to Correct Convergence Problems in .DC Analysis
 - .IC force DC solutions, however .NODESET set the initial guess
- OP Statement :
 - .OP Print out :(1). Node Voltages; (2). Source Currents; (3). Power Dissipation; (4). Semiconductors Device Currents, Conductance, Capacitance



4. Analysis Types

(3). Analysis Types : DC Sweep & DC Small Signal Analysis

- DC Analysis Statements :
 - .DC: Sweep for Power Supply, Temp., Param., & Transfer Curves
 - OP : Specify Time(s) at which Operating Point is to be Calculated
 - .TF: Calculate DC Small-Signal Transfer Function (.OP is not Required)
 - .PZ : Performs Pole/Zero Analysis (.OP is not Required)
- DC Statement Sweep :
 - Any Source Value

Any Parameter Value

■ Temperature Value

DC Model Characterization

■ DC Circuit Optimization

Sweep over model parameter is not allowed Monte Carlo sweep is not supported in SBTSPICE



4. Analysis Types

- (3). Analysis Types : DC Sweep & DC Small Signal Analysis (Cont.)
- .DC Analysis : Syntax

.DC var1 start1 stop1 incr1 < var2 start2 stop2 incr2 >)

.DC var1 start1 stop1 incr1 < SWEEP var2 DEC/OCT/LIN/POI np start2 stop2 >)

Examples :

.DC VIN 0.25 5.0 0.25

.DC VDS 0 10 0.5 VGS 0 5 1

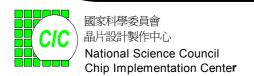
.DC TEMP -55 125 10

.DC TEMP POI 5 0 30 50 100 125

.DC xval 1k 10k 0.5k SWEEP TEMP LIN 5 25 125

.DC DATA=datanm SWEEP par1 DEC 10 1k 100k

.DC par1 DEC 10 1k 100k SWEEP DATA=datanm



4. Analysis Types

(4). Analysis Types : AC Sweep & Small Signal Analysis

AC Analysis Statements :

■ .AC : Calculate Frequency-Domain Response

■ .NOISE : Noise Analysis

.AC Statement Sweep :

Frequency

■ Temperature

Optimization

■ Element

■ .param Parameter



4. Analysis Types

(4). Analysis Types: AC Sweep & Small Signal Analysis (Cont.)

.AC Analysis : Syntax

.AC DEC/OCT/LIN/POI np fstart fstop

.AC DEC/OCT/LIN/POI np fstart fstop < SWEEP var start stop incr >)

Examples :

.AC DEC 10 1K 100MEG

.AC LIN 100 1 100Hz

.AC DEC 10 1 10K SWEEP Cload LIN 20 1pf 10pf

.AC DEC 10 1 10K SWEEP Rx POI 2 5K 15K

.AC DEC 10 1 10K SWEEP DATA=datanm



- (4). Analysis Types: AC Sweep & Small Signal Analysis (Cont.)
- Other AC Analysis Statements:
- .NOISE Statement : Only one noise analysis per simulation

.NOISE v(5) VIN 10

\$ output-variable, noise-input reference, interval

- V(5) <- node output at which the noise output is summed
- VIN <- noise input reference node
- 10 <- interval at which noise analysis summary is to be printed

4. Analysis Types

(5). Analysis Types : Transient Analysis

Transient Analysis Statements :

■ .TRAN : Calculate Time-Domain Response

■ .FOUR : Fourier Analysis

■ .FFT: Fast Fourier Transform

.TRAN Statement Sweep :

- Temperature
- Optimization
- .Param Parameter



4. Analysis Types

(5). Analysis Types: Transient Analysis (Cont.)

.TRAN Analysis : Syntax

```
.TRAN tincr1 tstop1 < tincr2 tstop2 ..... > < START=val>
.TRAN tincr1 tstop1 < tincr2 tstop2 ..... > < START=val> UIC <SWEEP..>
```

Examples:

```
.TRAN 1NS 100NS
```

.TRAN 10NS 1US UIC

.TRAN 10NS 1US UIC SWEEP TEMP -55 75 10 \$ step=10

.TRAN 10NS 1US SWEEP load POI 3 1pf 5pf 10pf

.TRAN DATA=datanm

4. Analysis Types

(5). Analysis Types : Transient Analysis (Cont.)

- Other Transient Analysis Statements:
- .FOUR Statement :

.FOUR 100K V(5) V(7,8) \$ fundamental-freq , output-variable1,2,.....

Note1: As a part of Transient Analysis

Note2: Determines DC and first Nine AC Harmonics & Reports THD (%)

.FFT Statement :

.FFT v(1,2) np=1024 start=0.3m stop=0.5m freq=5K window=Kaiser alfa=2.5

Note1: Window Types: RECT, BLACK, HAMM, GAUSS, KAISER, HINN....

Note2: Determines DC and first Ten AC Harmonics & Reports THD (%)



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5. Simulation Output and Controls

(1). Output Files Summary:

Output File Type	Extension
Output Listing	on screen
DC Analysis Results	.DC#
DC Analysis Measurement Results	.MEAS#
AC Analysis Results	.AC#
AC Analysis Measurement Results	.MEAS#
Transient Analysis Results	.TR#
Transient Analysis Measurement Results	.MEAS#
Subcircuit Cross-Listing	.PA#
Operating Point Node Voltages (Initial Condition)	.IC



5. Simulation Output and Controls

(1). Output Files Summary(HSPICE):

Output File Type	Extensi
Output Lis	.lis
DC Analysis Results	.sw#
DC Analysis Measurement Results	.ms#
AC Analysis Results	.ac#
AC Analysis Measurement Results	.ma#
Transient Analysis Results	.tr#
Transient Analysis Measurement Results	.mt#
Subcircuit Cross-Listing	.pa#
Operating Point Node Voltages (Initial Condition)	.ic



5. Simulation Output and Controls

(2). Output Statements:

Output Commands :

■ .PRINT Statement : Print Numeric Analysis Results

■ .PLOT Statement : Generates Low Resolution Plot in .lis file

■ .PROBE Statement : Allows Save Output Variables Only into the

Graph Date Files

■ .MEASURE Statement: Print Numeric Results of Measured Specifications

Output Variables:

- DC and Transient Analysis : Displays Individual Voltage, Current, & Power
- AC Analysis: Display Real & Imag. Components of Voltage & Current.....
- Element Template Analysis : Display Element-Specific Voltage, Current.....
- .MEASURE : Display User-Defined Variables Defined in .MEAS Statement

5. Simulation Output and Controls

(3). Output Variable Examples: DC, Transient, AC, Template

- DC & Transient Analysis :
 - Nodal Voltage Output : V(1), V(3,4), V(X3.5)
 - Current Output (Voltage Source) : I(VIN), I(X1.VSRC)
 - Current Output (Element Branches) : I2(R1), I1(M1), I4(X1.M3)
- AC Analysis :
 - **AC**: V(2), VI(3), VM(5,7), VDB(OUT), IP(9), IP4(M4)
- Element Template :
 - @x1.mn1[vth]
 - @x1.mn1[gds]
 - @x1.mn1[gm],@x1.mn1[gbs],@x1.mn1[cgd]

R: Real

I: Imaginary

M: Magnitude

P: Phase

DB: Decibels



(4). Regional Analysis of Power for Transient Analysis

.option rap = x <Rap_Tstart=Tstart><Rap_Tstop=Tstop>

0 < x < 1, The nodes with average power consumption greater than $(1-x)^*$ (total power consumption) will be listed

x = 1 will dump all power information of nodes

Tstart is the start time for power report, default is 0

Tstop is the stop time for power report, default is simulation stop time

All RAP output is stored in file .rap

5. Simulation Output and Controls

(5). Output Variable Examples: Parametric Statements

- Algebraic Expressions for Output Statements:
 - .PRINT DC V(IN) V(OUT) PAR('V(OUT)/V(IN)')
 - .PROBE AC Gain=PAR('VDB(5)-VDB(2)') Phase=PAR('VP(5)-VP(2)')
- Other Algebraic Expressions :
 - Parameterization: .PARAM WN=5u LN=10u VDD=5.0V
 - Algebra : .PARAM X='Y+5'
 - Functions : .PARAM Gain(IN, OUT)='V(OUT)/V(IN)'
 - Algebra in Element : R1 1 0 r='ABS(V(1)/I(M1))+10'
- Built-In Functions :

sin(x) cos(x) tan(x) asin(x) acos(x) atan(x) sinh(x) tanh(x) abs(x)<math>sqrt(x) log(x) log10(x) exp(x) db(x) min(x,y) max(x,y) power(x,y)...



5. Simulation Output and Controls

(6). Displaying Simulation Results: .PRINT & .PLOT

Syntax :

.PRINT anatype ov1 <ov2 ov2...>

Note: .PLOT with same Syntax as .PRINT, Except Adding <pol1, phi1> to set plot limit

Examples :

.PRINT TRAN V(4) V(X3.3) P(M1) P(VIN) POWER PAR('V(OUT)/V(IN)')

.PRINT AC VM(4,2) VP(6) VDB(3)

.PRINT AC INOISE ONOISE VM(OUT) HD3

.PRINT DISTO HD3 HD3(R) SIM2

.PLOT DC V(2) I(VSRC) V(37,29) I1(M7) BETA=PAR('I1(Q1)/I2(Q1)')

.PLOT AC ZIN YOUT(P) S11(DB) S12(M) Z11(R)

.PLOT TRAN V(5,3) (2,5) V(8) I(VIN)



5. Simulation Output and Controls

(7). Displaying Simulation Results: .PROBE & .GRAPH

.PROBE Statement :

.PROBE Syntax : .PROBE anatype ov1 <ov2 ov2...>

Note 1 : .PROBE Statement Saves Output Variables into the Interface & Graph Data Files

Note 2 : Set .OPTION PROBE to Save Output Variables Only, Otherwise
HSPICE Usually Save All Voltages & Supply Currents in Addition
to Output Variables



5. Simulation Output and Controls

(8). Output Variable Examples: .MEASURE Statement

- General Descriptions :
 - .MEASURE Statement Prints User-Defined Electrical Specifications of a Circuit and is Used Extensively in Optimization
 - .MEASURE Statement Provides Oscilloscope-Like Measurement Capability for either AC , DC, or Transient Analysis
 - Using .OPTION AUTOSTOP to Save Simulation Time when TRIG-TARG or FIND-WHEN Measure Functions are Calculated
- Fundamental Measurement Modes :
 - Rise, Fall, and Delay (TRIG-TARG)
 - AVG, RMS, MIN, MAX, & Peak-to-Peak (FROM-TO)
 - **FIND-WHEN**



5. Simulation Output and Controls

(9). MEASURE Statement : Rise, Fall, and Delay

Syntax :

.MEASURE DC|AC|TRAN result_var TRIG ... TARG ... < Optimization Option>

- result_var : Name Given the Measured Value in HSPICE Output
- TRIG ... : TRIG trig_var VAL=trig_value <TD=time_delay> <CROSS=n> + <RISE=r_n> <FALL=f_n|LAST>
- TRIG ... : TRIG AT=value
- TARG ... : TARG targ_var VAL=targ_value <TD=time_delay> + <CROSS=n|LAST> <RISE=r_n|LAST> <FALL=f_n|LAST>
- <Optimization Option> : <GOAL=val> <MINVAL=val> <WEIGHT=val>
- Example:

.meas TRAN tprop trig v(in) val=2.5 rise=1 targ v(out) val=2.5 fall=1



5. Simulation Output and Controls

(10). MEASURE Statement : AVG, RMS, MIN, MAX, & P-P

Syntax :

- result_var : Name Given the Measured Value in HSPICE Output
- FUNC : AVG ----- Average MAX ----- Maximun PP ---- Peak-to-Peak MIN ----- Minimum RMS ----- Root Mean Square
- out_var : Name of the Output Variable to be Measured
- <Optimization Option>: <GOAL=val> <MINVAL=val> <WEIGHT=val>
- Example:

```
.meas TRAN minval MIN v(1,2) from=25ns to=50ns .meas TRAN tot_power AVG power from=25ns to=50ns .meas TRAN rms_power RMS power
```



5. Simulation Output and Controls

(11). MEASURE Statement: Find & When Function

Syntax :

```
.measure DC|AC|TRAN result WHEN ... <Optimization Option>
.measure DC|AC|TRAN result FIND out_var1 WHEN ... <Optimization Option>
.measure DC|AC|TRAN result_var FIND out_var1 AT=val <Optimization Option>
```

- result: Name Given the Measured Value in HSPICE Output
- WHEN ... : WHEN out_var2=val|out_var3 <TD=time_delay> + <CROSS=n|LAST> <RISE=r_n|LAST> <FALL=f_n|LAST>
- <Optimization Option> : <GOAL=val> <MINVAL=val> <WEIGHT=val>

Example:

```
.meas TRAN fifth WHEN v(osc_out)=2.5V rise=5
.meas TRAN result FIND v(out) WHEN v(in)=2.5V rise=1
.meas TRAN vmin FIND v(out) AT=30ns
```

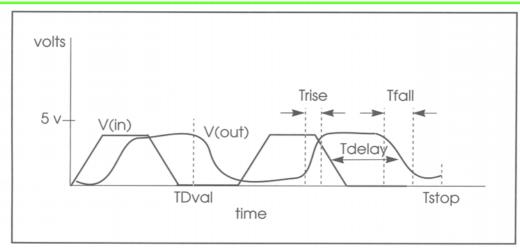


5. Simulation Output and Controls

(12). MEASURE Statement : Application Examples

Rise, Fall, and Delay Calculations :

```
.meas TRAN Vmax MAX v(out) FROM=TDval
                                               TO=Tstop
.meas TRAN Vmin MIN
                    v(out) FROM =TDval
                                                TO =Tstop
.meas TRAN Trise TRIG v(out) VAL='Vmin+0.1*Vmax' TD=Tdval
                                                          RISE=1
               TARG v(out) VAI='0.9*Vmax'
                                                           RISE=1
.meas TRAN Tfall TRIG v(out) VAL='0.9*Vmax'
                                                TD=Tdval
                                                          FALL=2
               TARG v(out) VAI='Vmin+0.1*Vmax'
                                                           FALL=2
+
.meas TRAN Tdelay TRIG v(in) VAL=2.5
                                                TD=Tdval
                                                           FALL=1
                 TARG v(out) VAL=2.5
                                                           FALL=2
+
```



5. Simulation Output and Controls

(12). MEASURE Statement : Application Examples(Cont.)

Ripple Calculation :

```
.meas TRAN Th1 WHEN v(out)='0.5*v(Vdd)' CROSS=1
```

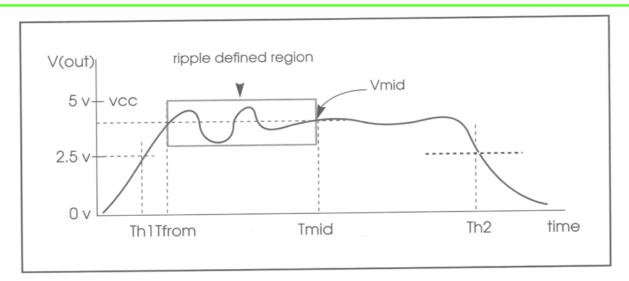
.meas TRAN Th2 WHEN v(out)='0.5*v(Vdd)' CROSS=2

.meas TRAN Tmid PARAM='(Th1+Th2)/2'

.meas TRAN Vmid FIND v(out) AT='tmid'

.meas TRAN Tfrom WHEN v(out)='Vmid' RISE=1

.meas TRAN Ripple PP v(out) FROM='tfrom' TO='tmid'



5. Simulation Output and Controls

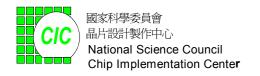
(12). MEASURE Statement : Application Examples(Cont.)

Unity-gain Freq, Phase margin, & DC gain(db/M):

```
.meas AC unitfreqWHEN vdb(out)=0FALL=1.meas AC phaseFIND vp(out)WHEN vdb(out)=0.meas AC 'gain(db)'MAX vdb(out).meas AC 'gain(mag)'MAX vm(out)
```

Bandwidth & Quality Factor (Q):

```
.meas AC gainmax MAX vdb(out)
.meas AC fmax WHEN vdb(out)='gainmax'
.meas AC band TRIG vdb(out) VAL='gainmax-3.0' RISE=1
+ TARG vdb(out) VAL='gainmax-3.0' FALL=1
.meas AC Q_factor PARAM='fmax/band'
```



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(1). Types of Elements:

- Passive Devices :
 - R ---- Resistor
 - C ---- Capacitor
 - L ---- Inductor
 - K ---- Mutual Inductor
- Active Devices :
 - D ---- Diode
 - Q ---- BJT
 - J ---- JFET and MESFET
 - ★ M ---- MOSFET
- Other Devices :
 - Subcircuit (X)
 - Behavioral (E,G,H,F,B)
 - Transmission Lines (T,U,O)



6. Elements & Device Models

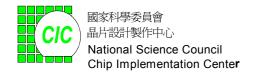
(2). Passive Devices : R, C, L, and K Elements

Passive Devices Parameters :

	Resistor	Capacitor	Inductor	Mutual Inductor
Netlist	Rxxx, n1,n2, mname, rval	Cxxx, n1,n2, mname, cval	Lxxx, n1,n2, mname, lval	Kxxx, Lyyy, Lzzz, kval
Temperature	DTEMP, TC1, TC2	DTEMP, TC1, TC2	DTEMP, TC1, TC2	
Geometric	L, M, W, SCALE	L, M, W, SCALE	M, SCALE	
Parasitics	С		R	
Initialization		IC(v)	IC(i)	

Examples:

R1 12 17 1K TC1=1.3e-3 TC2=-3.1e-7 C2 7 8 0.6pf IC=5V LSHUNT 23 51 10UH 0.01 1 IC=15.7mA K4 Laa Lbb 0.9999



(3). Active Device : BJT Element

BJT Element Parameters :

TYPE	Parameters	
Netlist	Qxxx, nb, nc, ne, ns, mname	
Temperature	DTEMP	
Geometric	AREA, AREAB, AREAC, M	
Initialization	IC(VBE, VCE), OFF	

BJT Syntax Examples :

Q100 NC NB NE QPNP AREA=1.5 AREAB=2.5 AREAC=3.0 IC= 0.6, 5.0

BJT Model Syntax :

.MODEL mname NPN (PNP) <param=val>

BJT Models in SBTSPICE: Gummel-Poon Model

6. Elements & Device Models

(4). Active Device: MOSFET Introduction

MOSFET Model Overview :

■ MOSFET Defined by : (1). MOSFET Model & Element Parameters

(2). Two Submodel: CAPOP & ACM

■ CAPOP: Specifies MOSFET Gate Capacitance

■ ACM : Modeling of MOSFET Bulk_Source & Bulk_Drain Diodes

MOSFET Model Levels :

Available : All the public domain spice model

■ Level = 4 or 13 : **BSIM1**

■ Modified BSIM1

■ Level = 5 or 39 : **BSIM2**

■ Level = 49 : BSIM3.3

Level = 8 : SBT MOS8



6. Elements & Device Models

(5). MOSFET Introduction: Element Statement

MOSFET Element Syntax :

MOSFET Element Statement Examples:

```
M1 24 2 0 20 MODN L=5u W=100u M=4

M2 1 2 3 4 MOD1 5u 100u

M3 4 5 6 8 N L=2u W=10u AS=100P AD=100p PS=40u PD=40u
```

```
.OPTIONS SCALE=1e-6
M1 24 2 0 20 MODN L=5 W=100 M=4
```



(6). MOSFET Introduction: Model Statement

MOSFET Model Syntax :

MOSFET Model Statement Examples:

```
.MODEL MODP PMOS LEVEL=2 VTO=-0.7 GAMMA=1.0.....
.MODEL NCH NMOS LEVEL=39 TOX=2e-2 UO=600.......
```

Corner_LIB of Models:

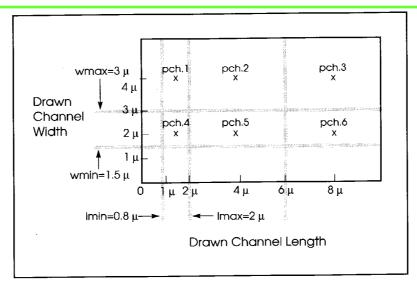
```
.LIB TT or (FF|SS|FS|SF)
.param toxn=0.0141 toxp=0.0148.....
.lib '~/simulation/model/cmos.l' MOS
.ENDL TT or (FF|SS|FS|SF)
```

```
.LIB MOS
.MODEL NMOD NMOS (LEVEL=49
+ TOXM=toxn LD=3.4e-8, .....)
.ENDL MOS
```

(7). MOSFET Introduction : Automatic Model Selection

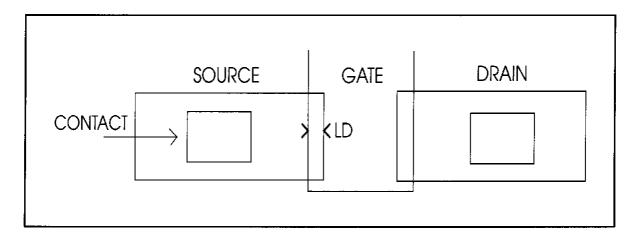
- Automatic Model Selection :
 - HSPICE can Automatically Find the Proper Model for Each Transistor Size by Using Parameters, LMIN,LMAX,WMIN, & WMAX in MOSFET Models

.MODEL pch.4 PMOS WMIN=1.5u WMAX=3u LMIN=0.8u LMAX=2.0u .MODEL pch.5 PMOS WMIN=1.5u WMAX=3u LMIN=2.0u LMAX=6.0u M1 1 2 3 4 pch W=2u L=4u \$ Automatically Select pch.5 Model



(8). MOSFET Introduction: MOSFET Diode Model

- MOSFET Diode Model : ACM
 - Area calculation Method (ACM) Parameter Allows for the Precise Control of Modeling Bulk-Source & Bulk_Drain Diodes within MOSFET Models
- ACM=0 MOSFET Diode: (Conventional MOSFET Structure)



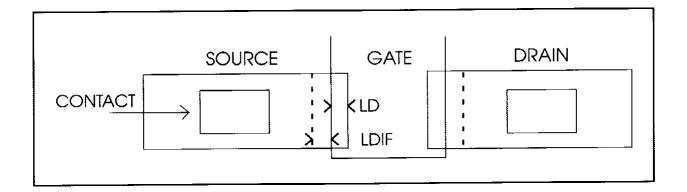
- ACM=0 : PN Bulk Junction of MOSFET are Modeled in the SPICE-style.
- ACM=0 : Not Permit Specifications of HDIF & LDIF.

ADeff = M • AD • WMLT² • SCALE²

6. Elements & Device Models

(8). MOSFET Introduction: MOSFET Diode Model (Cont.)

ACM=1 MOSFET Diode: (Not Popular)



■ ACM=1 : ASPEC-style Diode Model.

■ ACM=1 : Parameter Function of Element Width.

■ ACM=1 : AS, AD, PS, & PD are not Used.

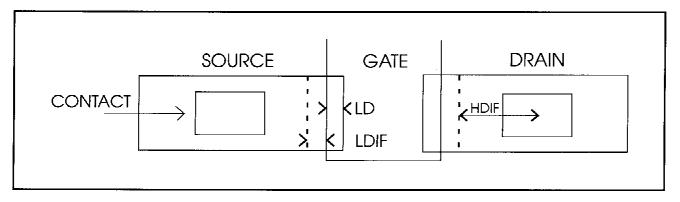
ADeff = Weff • WMLT

Pdeff = Weff

■ ACM=1 : JS and CJ Differ from the SPICE_style Diode (ACM=0)

Ignore AS,AD, PS,PD parameters

- (8). MOSFET Introduction: MOSFET Diode Model (Cont.)
- ACM=2 MOSFET Diode: (MOSFET LDD Structure)

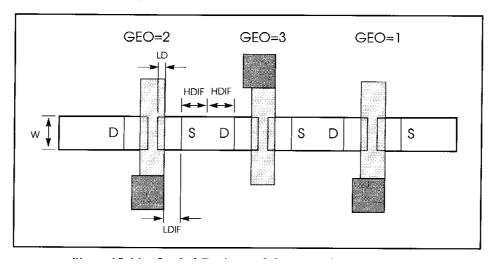


- ACM=2: HSPICE_Style Diode Model, Combination of ACM=0 & 1.
- ACM=2: Supports both Lightly & Heavily Doped Diffusions by Settling LD, LDIF, and HDIF Parameters.
- ACM=2 : Effective Areas and Peripheries can be Calculations by LDIF & HDIF (i.e. AS, AD, PS, & PD can be Omitted in MOS Element Statement)

ADeff = 2•HDIF•Weff

PDeff = 4•HDIF+2•Weff

- 6. Elements & Device Models
- (8). MOSFET Introduction: MOSFET Diode Model (Cont.)
- ACM=3 MOSFET Diode : (Stacked MOSFET Diode Model)

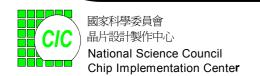


- ACM=3: Extension of ACM=2 Model that Deals with Stacked Devices.
- ACM=3: AS, AD, PS, & PD Calculations Depend on the Layout of the Device, which is Determined by the Value of Element Parameter GEO.
- ACM=3 : GEO=0 (Default) Indicates Drain & source are not Shared by other Devices

6. Elements & Device Models

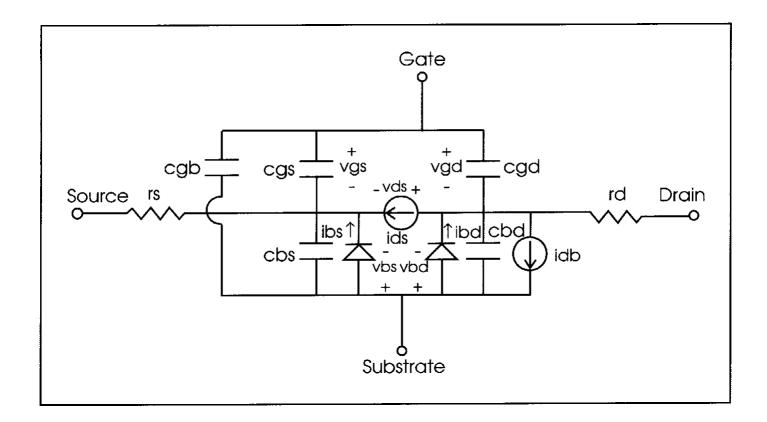
(9). MOSFET Introduction: Gate Capacitance Models

- MOSFET Gate Capacitance Models:
 - Capacitance Model Parameters can be Used with all MOSFET Model Statement.
 - Model Charge Storage Using Fixed and Nonlinear Gate Capacitance and Junction Capacitance.
 - Fixed Gate Capacitance: Gate-to-Drain, Gate-to-Source, and Gate-to-Bulk Overlap Capacitances are Represented by CGSO, CGDO, & CGBO.
 - Nonlinear Gate Capacitance : Voltage-Dependent MOS Gate Capacitance Depends on the Value of Model Parameter CAPOP.
- MOSFET Gate Capacitance Selection :
 - Available CAPOP Values = 0, 1, 2(General Default), 4



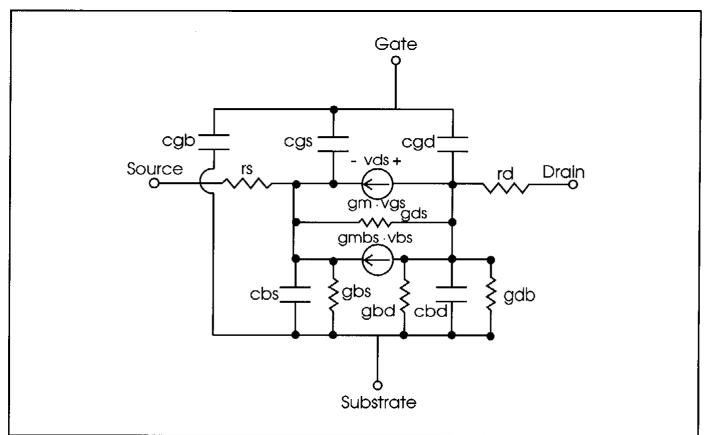
(10). MOSFET Introduction: Equivalent Circuits

MOSFET Equivalent Circuit for Transient Analysis:



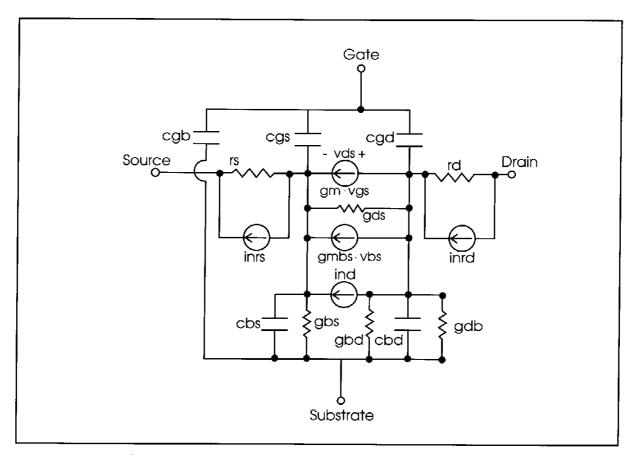
(10). MOSFET Introduction : Equivalent Circuits (Cont.)

MOSFET Equivalent Circuit for AC Analysis:



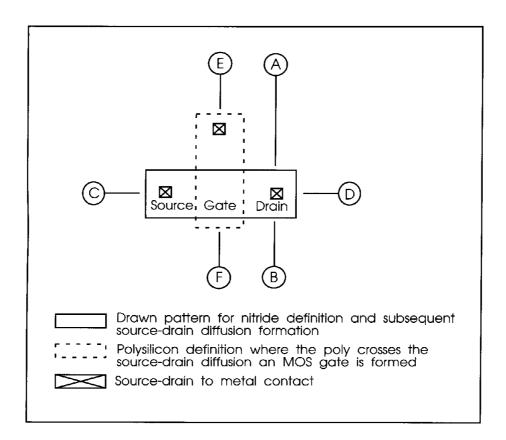
(10). MOSFET Introduction: Equivalent Circuits (Cont.)

MOSFET Equivalent Circuit for AC Noise Analysis:



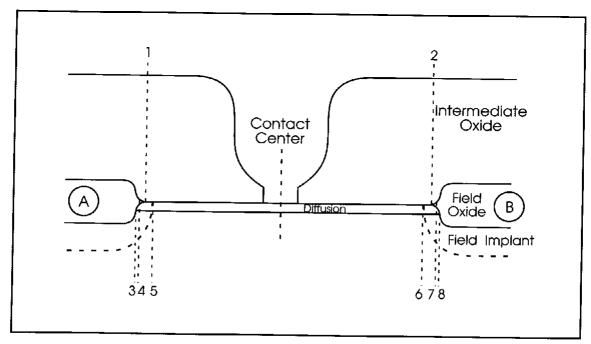
(11). MOSFET Introduction: Construction of MOSFET

Isoplanar Silicon Gate Transistor :



(11). MOSFET Introduction: Construction of MOSFET (Cont.)

Isoplanar MOSFET Construction : (Cut through A-B)

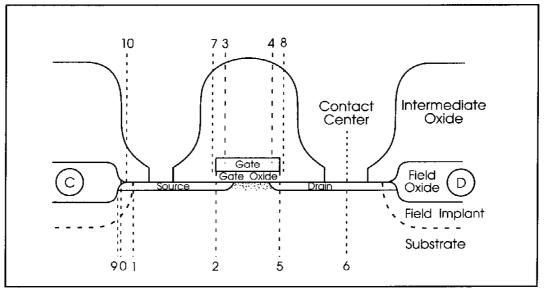


- 1-2 diffusion drawn dimension for nitride
- 4 7 nitride layer width after etch
- 3 1 periphery of the diode



(11). MOSFET Introduction: Construction of MOSFET(Cont.)

Isoplanar MOSFET Construction : (Cut through C-D)

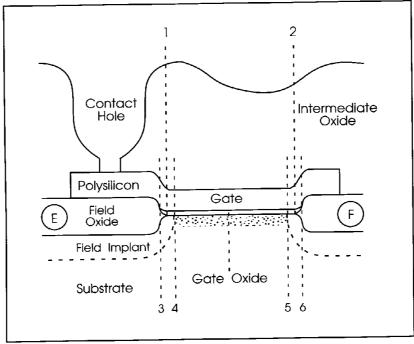


- 7 8 drawn channel length L
- 2-5 actual poly width after etching L + XL where XL<0
- 3 4 effective channel length after diffusion L + XL LD
- 4-5 lateral diffusion LD
- 9 10 diffusion periphery for diode calculations
- 5 6 gate edge to center contact for ACM=1 and ACM=2 calculations



(11). MOSFET Introduction: Construction of MOSFET(Cont.)

Isoplanar Silicon Gate Transistor : (Cut through E-F)



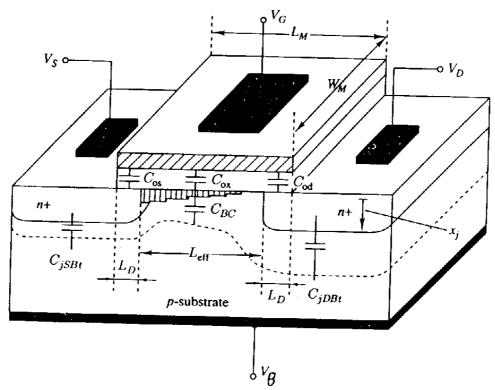
- 1 2 drawn width of the gate W
- 3-4 depleted or accumulated channel (parameter WD)
- 4 5 effective channel width W+ XW -2 WD
- 3-6 physical channel width W + XW



6. Elements & Device Models

(12). MOSFET Transistor Basics : Structure & Bias

MOSFET Structure: A Four Terminal Device (V_G, V_D, V_S, V_B)

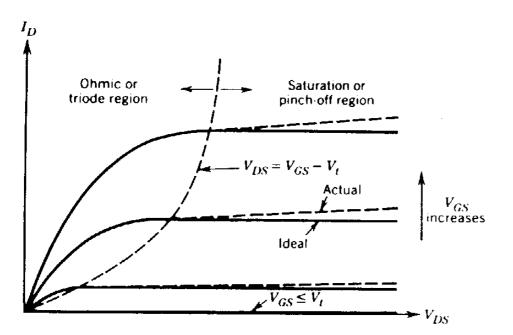


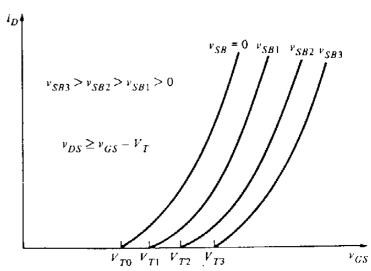
Basic Parameters: Channel Length (L_M), Channel Width(W_M), Oxide Thickness(tox), Junction depth(x_i) & Substrate Doping(Na)



(13). MOSFET Transistor Basics : Transfer Characteristics

Transfer Characteristics of NMOS :





- **Basic Operations: Saturation, Linear, & Subthreshold Regions**
- **Basic Characteristics: Channel Length Modulation & Body Effects**

$$I_{D} = \frac{\mu_{n}C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{T})^{2} (1 + \lambda V_{DS})$$

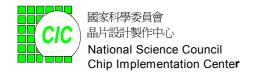
$$I_{D} = \frac{\mu_{n}C_{ox}}{2} \frac{W}{L} (V_{GS} - V_{T})^{2} (1 + \lambda V_{DS}) V_{TN} = V_{TN0} + \gamma \left(\sqrt{|2\Phi_{F}| + V_{SB}} - \sqrt{|2\Phi_{F}|} \right)$$

6. Elements & Device Models

(14). MOSFET Transistor Basics : SPICE Parameters

Normal SPICE Model Parameters :

TOX PHI NSUB		RS RD	RSH	5	SS S	Č	0 B	WSLM	CJSW	š	5	CGB0	CGD0	CGS0		LAMBDA	GAMMA	중	VT0		Туре
5.2E-8 0.60 4.6E15 5E10		5 5	20	3.2E-7	1E-3	0.5	0.6	0.33	6E-10	0.5	4.5E-4		5.2E-10	5.2E-10		0.022	0.92	4.0E-5	0.6		MOS
5.2E-8 0.60 2.5E14 5E10	Pr	20 20	50	3.2E-7	1E-3	0.5	0.6	0.33	6E-10	0.5	3.6E-4		4.0E-10	4.0E-10		0.047	0.54	1.5E-5	-0.77		pMOS
m V cm ⁻³ cm ⁻²	Process parameters	Ω Ω	Ω/□	3	A/m ²	1	<		F/m	1	F/m²	F/m	F/m	F/m		V-1	V1/2	A/V^2	<	Level 1	Dimension
Oxide thickness Surface potential $(2\phi_F)$ Substrate doping Effect of surface charge (Q_{ox})	TS .	Ohmic source resistance Ohmic drain resistance	Sheet resistance diffusion of <i>D</i> and <i>S</i>	Lateral diffusion	Bulk junction saturation current	Coefficient forward bias depletion capacitance	Bulk junction potential	Grading coefficient	Zero bias junction	Grading coefficient	Zero bias junction capacitance	GB overlap capacitance	per meter channel width GD overlap capacitance	GS overlap capacitance	parameter	Channel length modulation	Bulk threshold parameter	Transconductance parameter	Zero bias threshold voltage	demonstrate desired to the second sec	Name



6. Elements & Device Models

(14). MOSFET Transistor Basics : SPICE Parameters(Cont.)

Normal SPICE Model Parameters(Cont.) :

Туре	ype nMOS pMOS		Dimension	Name						
NEFF	0.01	0.01	_	Total channel charge coefficien						
ΧJ	4.0E-7	4.0E-7	m	Metallurgical junction depth						
DELTA	1.6	1.9		Channel width factor (W)						
		<i>P</i>	Added for Level	3						
ETA 0.04 0.06 —		_	Static feedback effective							
-				parameter (L)						
THETA	0.05	0.12	V ⁻¹	Empirical mobility						
•				modulation factor						
KAPPA	1	5	_	Field correlation factor						
DL	0	0	μ m	Change in L due to						
			•	photolithography						
DW	-0.4	-0.4	μ m	Change in W due						
			•	to photolithography						
KF	2E-15	5E-17	Α	Flicker noise coefficient						
AF	1	1		Flicker noise exponent						
		-	Added for Leve	el 2						
NFS	5E10	9E10	cm ⁻²	Effect of fast surface states						
U0	500	200	cm ² /V	Surface mobility						
UCRIT	1E6	5.2 E4	V/cm	Critical field for mobility						
				degradation						
ŲEXP	0.01	0.17	_	Critical field exponent						
UTRA	0.5	0.5	_	Transverse field coefficient						
VMAX	1.0E5	1.0E5	cm/s	Maximum drift velocity						

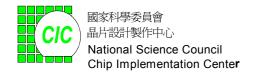


6. Elements & Device Models

(15). MOSFET Transistor Basics : Higher-Order Effects

- Geometry and Doping Effects on Vth :
 - Short Channel Effect (Small L)
 - Narrow Channel Effect (Small W)
 - Non-Uniform Doping Effect
- Physical Effects on Output Resistance :
 - Channel Length Modulation (CLM)
 - Drain Induced Barrier Lowering (DIBL)
 - Substrate Current Induced Body Effects (SCBE)
- Other Physical Effects :
 - Channel Mobility Degradation
 - Carrier Drift Velocity
 Parasitic Resistance
 - Bulk Charge Effect Subthreshold Current

Source: HP Eesof Device Modeling Seminar, March 1996



6. Elements & Device Models

(16). MOSFET Models: Historical Evolution

- Can Define Three Clear Model "Generations"
- First Generation :
 - "Physical" Analytical Models
 - Geometry Coded into the Model Equations
 - Level 1, Level 2, & Level 3
- Second Generation :
 - Shift in Emphasis to Circuit Simulation
 - **Extensive Mathematical Conditioning**
 - Individual Device Parameters & Separate Geometry Parameter
 - Shift "Action" to Parameter Extraction (Quality of Final Model is Heavily Dependent on Parameter Extraction)
 - BSIM1, Modified BSIM1, BSIM2

Source: IEEE 1997 CICC Educational Sessions E3.3

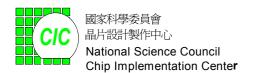


6. Elements & Device Models

(16). MOSFET Models: Historical Evolution (Cont.)

- Third Generation :
 - "Original Intent" was a Return to Simplicity
 - Scalable MOSFET model
 - 1-st derivative is continuous
 - Attempt to Re-Introduce a Physical Basis While Maintaining "Mathematical Fitness"
 - **■** BSIM3, MOS-8, Other ???

Source: IEEE 1997 CICC Educational Sessions E3.3



6. Elements & Device Models

(17). Overview of Most Popular MOSFET Models :

- UCB Level 1 : (Level = 1)
 - Shichman-Hodges Model (1968)
 - Simple Physical Model, Applicable to L> 10um with Uniform Doping
 - Not Precise Enough for Accurate Simulation
 - Use only for Quick, Approximate Analysis of Circuit Performance
- UCB Level 2 : (Level = 2)
 - Physical/Semi-Empirical Model
 - Applicable to Long Channel Device (~ 10 um)
 - Advanced Version of Level 1 which Includes Additional Physical Effects
 - Can Use either Electrical or Process Related Parameters

SPICE: Simulation Program with Integrated Circuit Emphasis

UCB : University of California at Berkeley

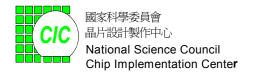


6. Elements & Device Models

(17). Overview of Most Popular MOSFET Models(Cont.) :

- UCB Level 3 : (Level = 3)
 - Semi-Empirical Model Model (1979)
 - Applicable to Long Channel Device (~ 2um)
 - Includes Some New Physical Effects (DIBL, Mobility Degradation by Lateral Field)
 - Very successful Model for Digital Design (Simple & Relatively Efficient)
- BSIM : (Level = 13)
 - First of the "Second Generation" Model (1985)
 - Applicable to Short Channel Device with L~ 1.0um
 - Emphasis on Mathematical Conditioning of Circuit Simulation
 - **Empirical Approach to Small Geometry Effects**

BSIM: Berkeley Short-Channel IGFET Model



(17). Overview of Most Popular MOSFET Models (Cont.) :

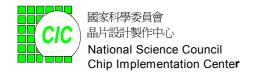
- Modified BSIM1 LEVEL 28 :
 - Enhanced Version of BSIM 1, But Addressed most of the Noted Shortcomings
 - Empirical Model Structure --> Heavy Reliance on Parameter Extraction for Final Model Quality
 - Applicable to Deep Submicron Devices (~ 0.3 0.5um)
 - Suitable for Analog Circuit Design
- BSIM 2 : (HSPICE Level = 39)
 - "Upgraded" Version of BISM 1 (1990)
 - Applicable to Devices with (L~ 0.2um)
 - Drain Current Model has Better Accuracy and Better Convergence Behavior
 - Covers the Device Physics of BSIM 1 and Adds Further Effects on Short Channel Devices

(17). Overview of Most Popular MOSFET Models (Cont.) :

- BSIM 3v3 : (Level = 49)
 - Newly Advanced Submicron MOSFET Model (Third Generation)
 - Latest Physics-Based, Deep-Submicron Model (BSIM3v3.1)
 - Use a Single Equation for a Device Property for All Regions of Device Operation, But Slow & Inefficient Behavior During Circuit Simulation
 - Use of Smoothing Functions Greatly Improves Final Results
 - Attempt to Impose "Global" Capability Creates a Number of Problems

```
In HSPICE, level=53 is BSIM 3V3 Berkeley compliance , level=49 is Avanti implemented BSIM3V3
```

- MOS8 Model: (SBTSPICE Level = 8)
 - Developed by SBT
 - 4-Terminals NQS charge-conservation model
 - Physical-oriented scalable model



(17). Overview of Most Popular MOSFET Models (Cont.) :

EKV Model :

- Developed at Swiss Federal Institute of Technology in Lausanne (EPFL)
- A Newly "Candidate" Model for Future Use
- Description of Small Geometry Effects is Currently Being Improved
- Developed for Low Power Analog Circuit Design
- Fresh Approach to FET Modeling
 - Use Substrate (not Source) as Reference
 - Simpler to Model FET as a Bi-Directional Element
 - Can Treat Pinch-Off and Weak Inversion as the same Physical Phenomenon
- First "Re-Thinking" of Analytical FET Modeling Since Early 1960s.

Source: IEEE 1997 CICC Educational Sessions E3.3



(18). MOSFET Model Comparison:

- Model Equation Evaluation Criteria: (Ref: HSPICE User Manual 1996, Vol._II)
 - Potential for Good Fit to Data
 - Ease of Fitting to Data
 - Robustness and Convergence Properties
 - Behavior Follows Actual Devices in All Circuit Conditions
 - Ability to Simulate Process Variation
 - Gate Capacitance Modeling
- General Comments :
 - Level 3 for Large Digital Design
 - HSPICE Level 28 for Detailed Analog/Low Power Digital
 - BSIM 3v3 & MOS Model 9 for Deep Submicron Devices
 - All While Keeping up with New Models

Source: IEEE 1997 CICC Educational Sessions E3.3



7. Optimization

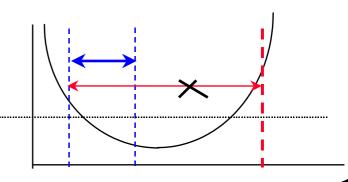
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(1). SPICE Optimization

- Circuit Level Goal Optimization:
 - A procedure for automatic searching instance parameters to meet design goal
 - Can be applied for both .DC , .AC and .TRAN analysis
 - Optimization implemented in SBTSPICE can optimize one goal
 - Optimization implemented in HSPICE can optimize multi-goal circuit parameter/device model parameter
 - The parameter searching range must differentiate the optimization goal





(2). Optimization Preliminaries

- Circuit Topology Including Elements and Models
- List of Element to be Optimized
 - **Initial Guess**, Minimum, Maximum
- .Measure Statements for Evaluating Results
 - Circuit Performance Goals
 - Selection of Independent or Dependent Variables Measurement Region
- Specify Optimizer Model

(3). Optimization Syntax : General Form

Variable Parameters and Components :

```
.PARAM parameter = OPTxxx (init, min, max)
```

Optimizer Model Statement :

```
.MODEL mod_namd OPT <Parameter = val .....>
```

Analysis Statement Syntax :

```
.DC|AC|TRAN ......<DATA=filement > SWEEP OPTIMIZE = OPTxxx
+ Results = meas_name METHOD = method_name
```

Measure Statement Syntax :

```
.MEASURE meas_name ......<GOAL=val> <MINVAL=val>
```

(4). Optimization Example

```
.lib "ls35 4 1.l" tt
                                                  Specify parameter range
option post probe
.param Cload =10p
.param Tpw=opt1(0, 0, 15n)
.model optmod opt method=passfail
                                                  Analysis type and
.tran 0.1n 20n sweep optimize=opt1
                                                   optimization algorithm
                    result = Tprop
                    model = optmod
                                                   Optimization goal by
.measure Tran Tprop Trig V(in) Val=2.5 Rise = 1 —
                                                   measure command
                     Targ v(out) Val=2.5 Fall = 1
vcc 1 0 5
vin in 0 pulse(0 5 1n 1n 1n Tpw 20n)
.end
```

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8. Control Options & Convergence

(1). Control Options: Output Format

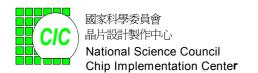
- Output Format : General (LIST, NODE, ACCT, OPTS, NOMOD)
 - .OPTION LIST: Produces an Element Summary Listing of the Data to be Printed. (Useful in Diagnosing Topology Related NonConvergence Problems)
 - OPTION NODE: Prints a Node Connection Table. (Useful in Diagnosing Topology Related NonConvergence Problems)
 - OPTION ACCT: Reports Job Accounting and Run-Time Statistics at the End of Output Listing. (Useful in Observing Simulation Efficient)
 - .OPTION OPTS : Prints the Current Settings of All Control Options.
 - OPTION NOMOD : Suppress the printout of Model Parameters (Useful in Decreasing Size of Simulation Listing Files)



8. Control Options & Convergence

(2). Simulation Controls & Convergence

- Definition of "Convergence":
 - The Ability to Obtain a Solution to a Set of Circuit Equations Within a Given Tolerance Criteria & Specified Iteration Loop Limitations.
 - The Designer Specifies a Relative & Absolute Accuracy for the Circuits Solution and the Simulator Iteration Algorithm Attempts to Converge onto a Solution that is within these Set Tolerance
- Error Messages for "NonConvergence" :
 - " No Convergence in Operating Point (or DC Sweep)"
 - "Iteration TimeStep is Too Small in Transient Analysis"
- Possible Causes of "NonConvergence" :
 - Circuit Reasons: (1). Incomplete Netlist; (2). Feedback; (3). Parasitics
 - Model Problems: (1). Negative Conductance (2). Model Discontinuity
 - Simulation Options: (1). Tolerances; (2). Iteration Algorithm



8. Control Options & Convergence

(3). AutoConvergence for DC Operating Point Analysis

- AutoConvergence Process:
 - If Convergence is not Achieved in the Number of Iteration set by ITL1, HSPICE Initiates an AutoConvergence Process, in which it Manipulates DCON, GRAMP, and GMINDC, as well as CONVERGENCE in some Cases.
 - ITL1= x : Set the Maximum DC Iteration Limit, Default=100. Increasing Values as High as 400 Have Resulted in Convergence for Certain Large Circuits with Feedback, such as OP Amp & Sense Amplifiers.

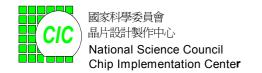
GMINDC= x: A Conductance that is Placed in Parallel with All PN Junction and All MOSFET Nodes for DC Analysis. It is Important in Stabilizing the Circuit During DC Operating Point Analysis.



8. Control Options & Convergence

(4). Steps for Solving DC Operating Point NonConvergence

- (1). Check Topology:
 - Set .OPTIONS NODE to Get a Nodes Cross Reference Listing if You are in Doubt
 - Check if All PMOS Substrates Connected to VDD or Positive Supplies ?
 - Check if All NMOS Substrates Connected to GND or Negative Supplies ?
 - Check if All Vertical NPN Substrates Connected to GND or Negative Supplies ?
 - Check if All Lateral PNP Substrates Connected to Negative Supplies?
 - Check if All Latches Have Either an OFF Transistor or a .NODESET or an .IC on one side ?
 - Check if All Series Capacitors Have a Parallel Resistance, or is .OPTION DCSTEP Set ?



8. Control Options & Convergence

(4).Steps for Solving DC Operating Point NonConvergence (Cont.)

- (2). Check Your .MODEL Statements :
 - Be Sure to Check your Model Parameter Units.
 - Check if Your MOS Models had Subshreshold Parameter Set ? (NFS= 1e11 for HSPICE Level 1,2 &3 and N0=1 for HSPICE BSIM1,2,3 Models & Level 28)
 - Use MOS ACM=1, ACM=2, or ACM=3 Source and Drain Diode Calculation to Automatically Generate Parasitics.
- (3). General Remarks :
 - Circuits that Converge Individually and Fail when Combined are Almost Guaranteed to have a Modeling Problem.
 - Schmitt Triggers are Unpredictable for DC Sweep and Sometimes for Operating Point for the same Reasons Oscillators and Flip-Flops are. Use Slow Transient.



8. Control Options & Convergence

(4).Steps for Solving DC Operating Point NonConvergence (Cont.)

- (3). General Remarks (Cont.):
 - Open Loop OP Amp have High Gain, which can Lead to Difficulties in Converging. ==> Start OP Amp in Unity-Gain Configuration and Open them Up in Transient Analysis with a Voltage-Variable Resistor or a Resistor with a Large AC Value for AC Analysis.
- (4). Check Your Options :
 - Remove All Convergence-Related Options and Try First with No Special Options Setting.
 - Check NonConvergence Diagnostic Table for NonConvergence Nodes. Look up NonConvergence Nodes in the Circuit Schematic. They are Generally Latches, Schmitt Triggers or Oscillating Nodes.
 - SCALE and SCALM Scaling Options Have a Significant Effect on the Element and Model Parameters Values. Be Careful with Units.



8. Control Options & Convergence

(5). Solutions for Some Typical NonConvergence Circuits

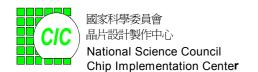
- Poor Initial Conditions :
 - Multistable Circuits Need State Information to Guide the DC Solution. For Example, You must Initialize Ring Oscillator or Flip-Flops Circuits Using the .IC Statement.
- Inappropriate Model Parameters :
 - It is Possible to Create a <u>Discontinuous</u> Ids or Capacitance Model by Imposing Nonphysical Model Parameters
 - Discontinuities Most Exits at the Intersection of the Linear & Saturation Regions
- PN Junctions (Diodes, MOSFETs, BJTs) :
 - PN Junctions Found in Diodes, BJTs, and MOSFET Models can Exhibit NonConvergence Behavior in Both DC and Transient Analysis.==> Options GMINDC and GMIN Automatically Parallel Every PN Junction with a Conductance.



8. Control Options & Convergence

(5).Solutions for Some Typical NonConvergence Circuits (Cont.)

- Rapid Transitions in DC Sweep :
 - Increase the ITL2, which is the Number for Iteration Allowed at Each Steps in DC Sweep Analysis, Value to 100, 200 or more. Default=50. (ITL1 is for the Initial Operating Point)
- DC Options for High Power Circuits :
 - For High Power Bipolar Transistors, Set Options ABSI up from Default 1 nA to Perhaps 10 mA. Also, Minimum Voltage Tolerance Should be Raised from 50 uV to 10mV.
 - If the Accuracy Given by Tight Tolerance is Necessary, Be Sure to Increase Option ILT1 to 300~~400.
- DC Options for Op Amp and Comparator :
 - High Gain Op Amp and Comparator can Cause Convergence Problems, as well as Possible Violations of KCL Law. It is Sometimes Necessary to Tighten the Options RELI to 0.005 and ABSI to 1 pA



8. Control Options & Convergence

(6).Numerical Integration Algorithm Controls

- Types of Numerical Integration Methods :
 - Trapezoidal Algorithm (Default in HSPICE)

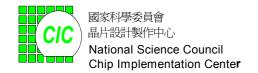
.OPTION METHOD = TRAP

GEAR Algorithm

.OPTION METHOD = GEAR

- Trapezoidal Algorithm :
 - Highest Accuracy
 - Lowest Simulation Time
 - Best for CMOS Digital Circuits

- GEAR Algorithm :
 - Most Stable
 - Highly Analog, Fast Moving Edges
- One Limitation of Trapezoidal Algorithm :
 - It can Results in Unexpected Computational Oscillation. (Also Produces an Usually Long Simulation Time)
 - For Circuits are Inductive in Nature, such as Switching Regulator, Use GEAR Algorithm. (Circuit NonConvergent with TRAP will often Converge with GEAR)



8. Control Options & Convergence

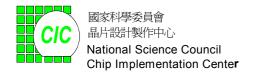
(7). Timestep Control Algorithms

- Types of Dynamic Timestep Control Algorithm :
 - Iteration Count (Simplest):
 - If Iterations Required to Converge > MAX, Decrease the Timestep
 - If Iterations Required to Converge < MIN, Increase the Timestep</p>
 - Local Truncation Error (LTE) :
 - Use a Taylor Series Approximation to Calculate Next Timestep
 - Timestep is Reduced if Actual Error is > Predicted Error
- Timestep Control Algorithm vs. Numerical Integration Algorithm :
 - For GEAR is Selected => Defaults to Truncation Timestep Algorithm; For TRAP is Selected => Defaults to ITERATION Algorithm



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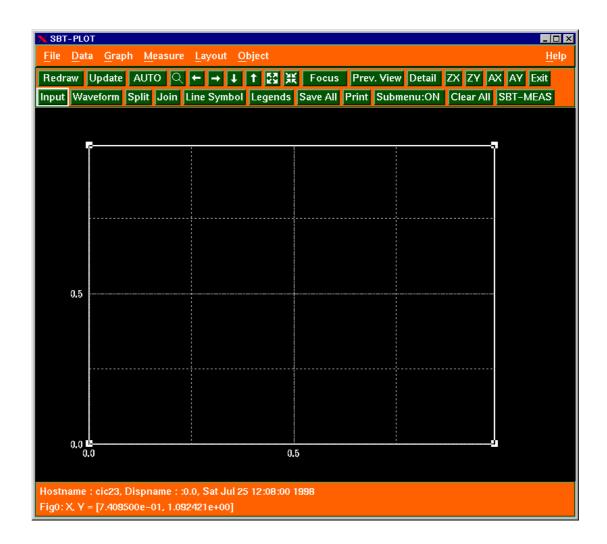
(1). Window environment for Graphic tools

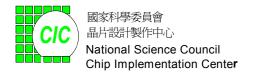
- All the Graphic tools are X-window Based, Must be used within X-window environment
- Use SETENV DISPLAY your_xhost_server:0 to redirect the graphic window from a remote host to your working host.
- Use xhost + remote_host to allow remote host display window on your machine
- The waveform tool define its own color table, the color table may conflict with other programs, so some colors in waveform window might not be visible, quit other application

9. Graphic Tools

(2).SBTPLOT

Environment setup
source /usr/sbt/sbt.cshrc
sbtplot



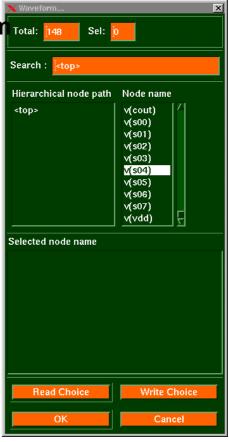


(3)Select waveform file

Select waveform file

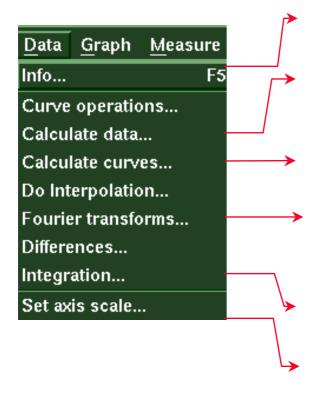


Select waveform Total: 148
to display





(4). Data calculation



Hide/kill displayed curves

Evaluates a formula defined by user

Evaluates equation on curve data

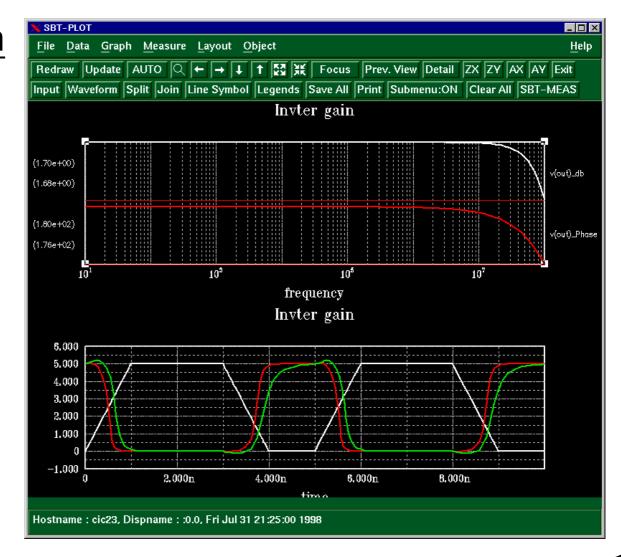
Discrete Fourier Transform < 1000 data point Fast Fourier Transform - 2 × data points

Numerical integration/Differentiation on curve

Set the current figure type to linear-linear, log-linear, linear-log, log-log

9. Graphic Tools

(5).Waveform





HSPICE 模擬波形觀測介面-awaves 簡介

- HSPICE 係模擬程式,模擬結果依選項揩示存於檔案中。
- 原波形界面 gsi 及 hsplot 已由 awaves(avanwaves)取代,98.4版中不提供此兩者之執行檔。
- Gsi 仍可使用awaves 之license
- awaves係視窗程式,需在Xwindow環境下使用。
- 在輸入netlist檔中需指定graphic輸出,hspice才會儲存waveform 資料,即加入.option post 的指令項
- 99.4版的輸出資料, gsi無法接受, 需於netlist 檔中加入.option post_version-9007的指令項
- 執行awaves 之指令 /usr/meta/cur/bin/awaves



Awaves - Awaves Window

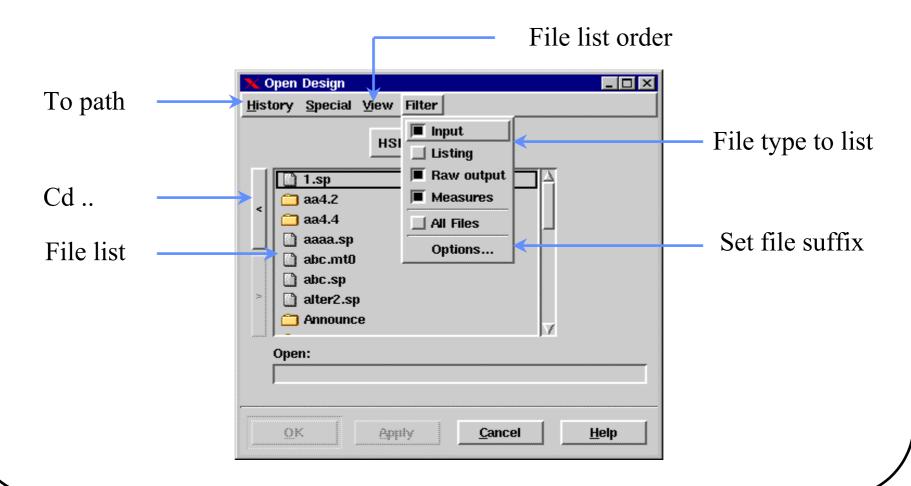
Tool button waveform menu AvanWaves 98.2.1 (980912) _ | _ | × | Design Panels Window Measure Configuration Tools g N/A y N/A *file: mos2bit.sp – adder – 2 bit all–nand–gate binary adder Wave List D0:A0:v(12) D0:A0:v(14) D0:A0:v(24) -2n 0 2n 4n 6n 8n 10n 12n 14n 16n 18n 20n 22n 24n 26n 28n 30n 32n 34n 36n 38n 40n 42n 44n 46n 48n 50n 52n 54n 56n 58n 60n 62n Time (lin) (TIME)

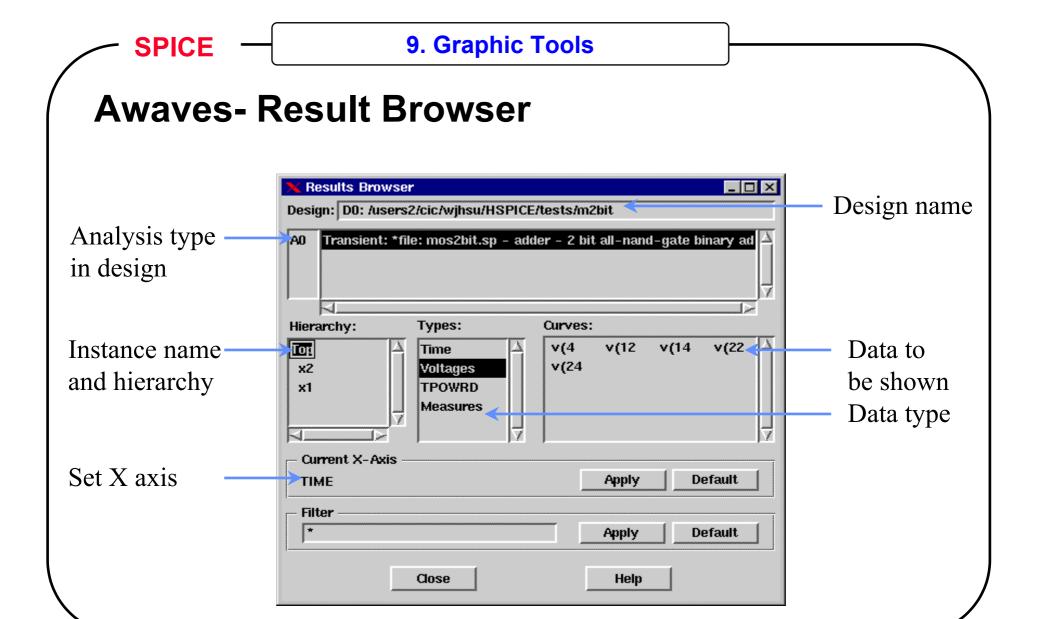
Data names





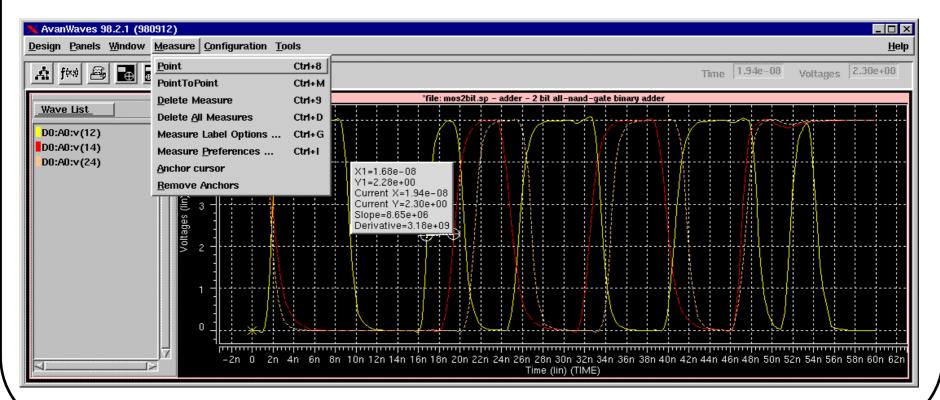
Awaves-Open Design

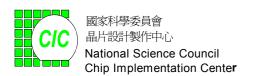




Awaves - Measurement

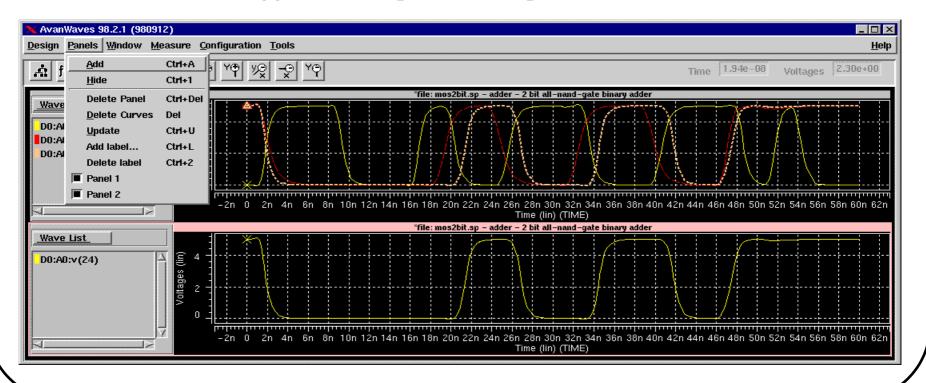
On window measurement function





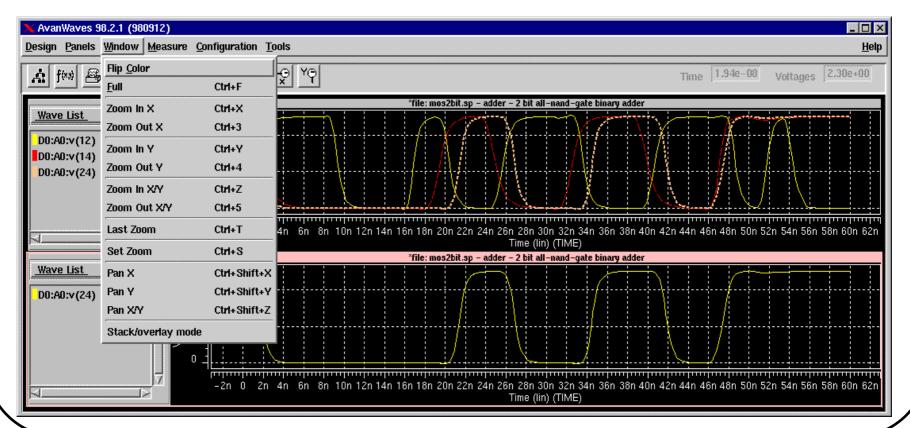
Awaves - Multiple Panels

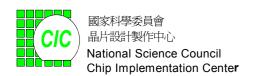
Multiple panels can be displayed on window
Maximum number of panels displayed depends on window size
Waveforms can be dragged and drop into other panels



Awaves - View Port Management

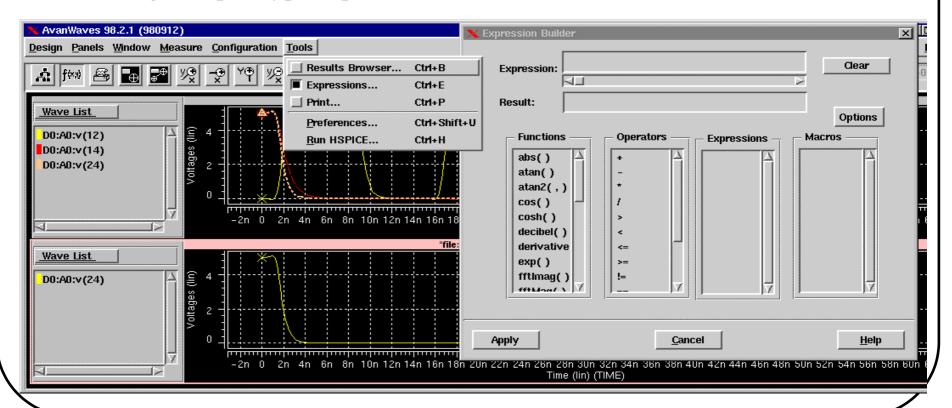
Zoom size is independent between panels

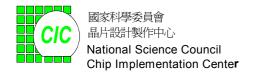




Awaves - Expressions

Expressions provide capability for data calculation Can use drag&drop to type expression





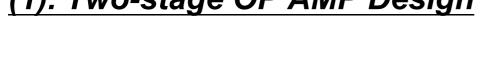
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- 10. Applications Demonstration



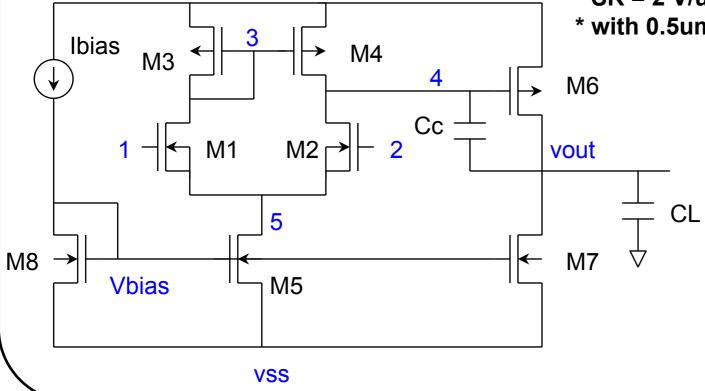
10. Application Demo

(1). Two-stage OP AMP Design



vdd

- * Target specification:
- * CL = 4pF, Av > 4000,
- * GB=2MHz
- * 1 < CMR < 4 , 0.8 < Vout < 4.2
- * SR = 2 V/us , Pdiss < 10mW ,
- * with 0.5um UMC process





10. Application Demo

<u>(2). Netlist</u>

```
*Two stage OP design
```

.lib "9905spice.model" mos_tt

.option post nomod

.TEMP 27

* Netlist information

M1 3 1 5 0 nmos L=2u W=8u AS=18p AD=18p

+ PS=18u PD=18u

M2 4 2 5 0 nmos L=2u W=8u AS=18p AD=18p

+ PS=18u PD=18u

M3 3 3 vdd vdd pmos L=10u W=10u AS=12p AD=12p PS=16u PD=16u

M4 4 3 vdd vdd pmos L=10u W=10u AS=12p AD=12p PS=16u PD=16u

M5 5 vbias vss vss nmos L=2u W=7u AS=49p AD=49p PS=26u PD=26u

M6 vout 4 vdd vdd pmos L=2u W=70u AS=490p AD=490p PS=150u PD=150u

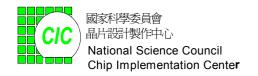
M7 vout vbias vss vss nmos L=2u W=130u AS=930p AD=930p

+ PS=260u PD=260u

M8 vbias vbias vss vss nmos L=2u W=7u AS=49p AD=49p PS=26u PD=26u

* Feedback CAP Cc vout 4 0.44pF Cl vout 0 4pF Ibias vdd vbias 8.8u

* Voltage sourses vdd vdd 0 5v vss vss 0 0v

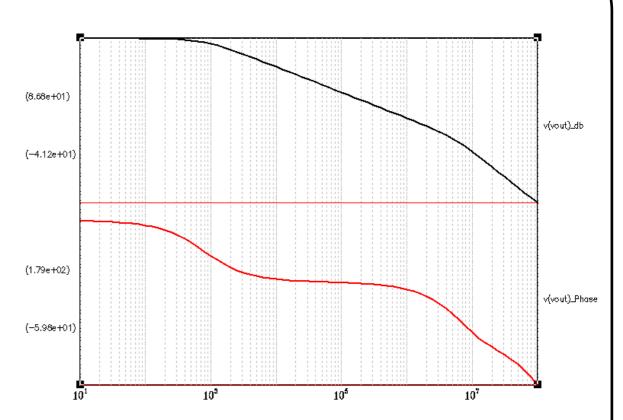


(3). AC Frequency Analysis

vin2 2 0 2.5v vin1 1 0 DC 2.5v AC 1

*.OP

- * AC Analysis function
- .ac dec 10 10 100MEG
- .probe ac vdb(vout)
- + vp(vout) vdb(4) vp(4)
- .meas ac Unit_gain
- + when vdb(vout)=0
- .meas ac phase_mar
- + FIND vp(vout) when vdb(vout)=0



10. Application Demo

(4). Transient Analysis Slew Rate analysis

* Transient analysis section

M1 3 vout 5 0 nmos L=2u W=8u AS=18p AD=18p PS=18u PD=18u vin2 2 0 pulse(0v 5v 1n 1p 1p 600n 1200n)

.tran 5n 2u

.probe tran

.save all

