Collaborative Filtering

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Outline

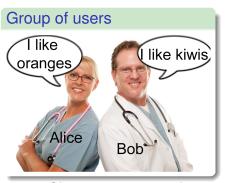
- Problem Formulation
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 - Shrinkage
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- Observe some user-item preferences
- ⊱ Predict new preferences:

Does Bob like strawberries???



Intro

Amazon.com recommends products based on purchase history



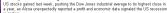




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Bloomberg - Reuters - The Associated Press

- Google News recommends new articles based on click and search history
- Millions of users. millions of articles

Das et al., 2007



Netflix predicts other "Movies You'll ♥" based on past numeric ratings (1-5 stars)



- Recommendations drive 60% of Netflix's DVD rentals.
- Mostly smaller, independent movies (Thompson 2008)





► Netflix Prize: Beat Netflix recommender system, using Netflix data →

Data: 480,000 users 18,000 movies 100 million observed ratings = only 1.1% of ratings observed

"The Netflix Prize seeks to substantially improve the accuracy of predictions about how much someone is going to love a movie based on their movie preferences."



Insight: Personal preferences are correlated

If Jack loves A and B, and Jill loves A, B, and C, then Jack is more likely to love C

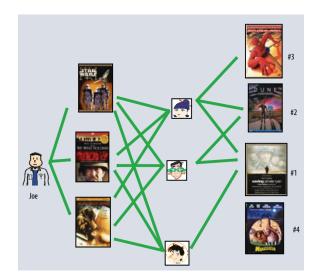
Collaborative Filtering Task

- Discover patterns in observed preference behavior (e.g. purchase history, item ratings, click counts) across community of users
- Predict new preferences based on those patterns

Does not rely on item or user attributes (e.g. demographic info, author, genre)

Content-based filtering: complementary approach







Given:

Intro

- \vdash Users $u \in \{1, ..., U\}$
- \vdash Items $i \in \{1, ..., M\}$
- \succeq Training set \mathcal{T} with observed, real-valued preferences r_{ui} for some user-item pairs (u,i)
 - $r_{ij} = e.g.$ purchase indicator, item rating, click count . . .

Goal: Predict unobserved preferences

 \vdash Test set Q with pairs (u,i) not in \mathcal{T}

View as matrix completion problem

⊱ Fill in unknown entries of sparse preference matrix

$$\mathbf{R} = \left[\begin{array}{cccc} ? & ? & 1 & \dots & 4 \\ 3 & ? & ? & \dots & ? \\ ? & 5 & ? & \dots & 5 \end{array} \right] U \text{ users}$$

$$M \text{ items}$$



Measuring success

- \succeq Interested in error on unseen test set Q, not on training set
- For each (u,i) let r_{ui} = true preference, \hat{r}_{ui} = predicted preference
- Root Mean Square Error

Mean Absolute Error

$$\vdash \mathsf{MAE} = \frac{1}{|Q|} \sum_{(u,i) \in Q} |r_{ui} - \hat{r}_{ui}|$$

- Ranking-based objectives
 - ← e.g. What fraction of true top-10 preferences are in predicted top 10?



Centering Your Data

What?

Intro

Remove bias term from each rating before applying CF methods: $\tilde{r}_{i,i} = r_{i,i} - b_{i,i}$

⊱ Why?

- Some users give systematically higher ratings
- Some items receive systematically higher ratings
- Many interesting patterns are in variation around these systematic biases
- Some methods assume mean-centered data
 - Recall PCA required mean centering to measure variance around the mean



Centering Your Data

- What?
 - ⊱ Remove bias term from each rating before applying CF methods: $\tilde{r}_{t,i} = r_{t,i} b_{t,i}$
- ⊱ How?
 - ⊱ Global mean rating

$$\vdash b_{ui} = \mu := \frac{1}{|\mathcal{T}|} \sum_{(u,i) \in \mathcal{T}} r_{ui}$$

Item's mean rating

$$\vdash b_{ui} = b_i := \frac{1}{|B(i)|} \sum_{u \in R(i)} r_{ui}$$

- \vdash R(i) is the set of users who rated item i
- ⊱ User's mean rating

$$\vdash b_{ui} = b_u := \frac{1}{|B(u)|} \sum_{i \in B(u)} r_{ui}$$

- \vdash R(u) is the set of items rated by user u
- ⊱ Item's mean rating + user's mean deviation from item mean

$$\vdash b_{ui} = b_i + \frac{1}{|R(u)|} \sum_{i \in R(u)} (r_{ui} - b_i)$$



Shrinkage

Intro

What?

Interpolating between an estimate computed from data and a fixed, predetermined value

⊱ Why?

- Common task in CF: Compute estimate (e.g. a mean rating) for each user/item
- Not all estimates are equally reliable
- Some users have orders of magnitude more ratings than others
- Estimates based on fewer datapoints tend to be noisier

Hard to trust mean based on one rating



Shrinkage

Intro

- What?
 - Interpolating between an estimate computed from data and a fixed, predetermined value
- ⊱ How?
 - e.g. Shrunk User Mean:

$$\tilde{b}_{u} = \frac{\alpha}{\alpha + |R(u)|} * \mu + \frac{|R(u)|}{\alpha + |R(u)|} * b_{u}$$

- $\succeq \mu$ is the global mean, α controls degree of shrinkage
- \succeq When user has many ratings, $\tilde{b}_{\mu} \approx$ user's mean rating
- \succeq When user has few ratings, $\tilde{b}_u \approx$ global mean rating

Global mean $\mu = 3.58$, $\alpha = 1$



Classification/Regression for CF

Interpretation: CF is a set of *M* classification/regression problems, one for each item

- Consider a fixed item i
- Treat each user as incomplete vector of user's ratings for all items except i: $\vec{r}_{u} = (3, ?, ?, 4, ?, 5, ?, 1, 3)$
- Class of each user w.r.t. item i is the user's rating for item i (e.g. 1,2,3,4, or 5)
- \vdash Predicting rating $r_{ii} \equiv$ Classifying user vector \vec{r}_{ii}



Classification/Regression for CF

Approach:

Intro

- Choose your favorite classifier/regression algorithm
- Train separate predictor for each item
- \succeq To predict r_{ii} for user u and item i, apply item i's predictor to vector of user u's incomplete ratings vector

Pros:

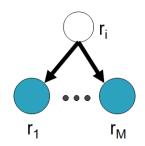
- Reduces CF to a well-known, well-studied problem.
- Many good prediction algorithms available

Cons:

- Predictor must handle missing data (unobserved ratings)
- E Training M independent predictors can be expensive
- Approach may not take advantage of problem structure
 - Item-specific subproblems are often related



Naive Bayes Classifier



- Treat distinct rating values as classes
- Consider classification for item i
- Main assumption
 - \vdash For any items $j \neq k \neq i$, r_i and r_k are conditionally independent given r_i
 - \succeq When we know rating r_{ij} all of a user's other ratings are independent
- Parameters to estimate
 - \vdash Prior class probabilities: $P(r_i = v)$
 - ⊱ Likelihood: $P(r_i = w | r_i = v)$



Naive Bayes Classifier

Train classifier with all users who have rated item i

Use counts to estimate prior and likelihood

$$P(r_{i} = v) = \frac{\sum_{u=1}^{U} \mathbf{1}(r_{ui} = v)}{\sum_{w=1}^{V} \sum_{i=1}^{U} \mathbf{1}(r_{ui} = w)}$$

$$P(r_{j} = w | r_{i} = v) = \frac{\sum_{u=1}^{U} \mathbf{1}(r_{ui} = v, r_{uj} = w)}{\sum_{z=1}^{V} \sum_{u=1}^{U} \mathbf{1}(r_{ui} = v, r_{uj} = z)}$$

Complexity

 $\in O(\sum_{u=1}^{U} |R(u)|^2)$ time and $O(M^2V^2)$ space for all items Predict rating for (u,i) using posterior

$$P(r_{ui} = v | r_{u1}, ..., r_{uM}) = \frac{P(r_{ui} = v) \prod_{j \neq i} P(r_{uj} | r_{ui} = v)}{\sum_{w=1}^{V} P(r_{ui} = w) \prod_{j \neq i} P(r_{uj} | r_{ui} = w)}$$



Naive Bayes Summary

Pros:

Intro

- Easy to implement
- Off-the-shelf implementations readily available

Cons:

- Large space requirements when storing parameters for all M predictors
- Makes strong independence assumptions
- Parameter estimates will be noisy for items with few ratings
 - ⊱ E.g. $P(r_i = w | r_i = v) = 0$ if no user rated both *i* and *j*

Addressing cons:

- Tie together parameter learning in each item's predictor
- Shrinkage/smoothing is an example of this



KNN

K Nearest Neighbor Methods

Most widely used class of CF methods

- Flavors: Item-based and User-based
- ⊱ Represent each item as incomplete vector of user ratings: $\vec{r}_{.i} = (3,?,?,4,?,5,?,1,3)$
- \succeq To predict new rating r_{ui} for query user u and item i:
 - 1 Compute similarity between *i* and every other item
 - 2 Find K items rated by u most similar to i
 - 3 Predict weighted average of similar items' ratings
- Intuition: Users rate similar items similarly.



KNN: Computing Similarities

How to measure similarity between items?

Cosine similarity

$$S(\vec{r}_{.i}, \vec{r}_{.j}) = \frac{\langle \vec{r}_{.i}, \vec{r}_{.j} \rangle}{\left\| \vec{r}_{.i} \right\| \left\| \vec{r}_{.j} \right\|}$$

Pearson correlation coefficient

$$S(\vec{r}_{.i}, \vec{r}_{.j}) = \frac{\langle \vec{r}_{.i} - \text{mean}(\vec{r}_{.i}), \vec{r}_{.j} - \text{mean}(\vec{r}_{.j}) \rangle}{\left\| \vec{r}_{.i} - \text{mean}(\vec{r}_{.i}) \right\| \left\| \vec{r}_{.j} - \text{mean}(\vec{r}_{.j}) \right\|}$$

Inverse Euclidean distance

$$S(\vec{r}_{.i}, \vec{r}_{.j}) = \frac{1}{\|\vec{r}_{.i} - \vec{r}_{.j}\|}$$

Problem: These measures assume complete vectors Solution: Compute over subset of users rated by both items Complexity: $O(\Sigma^U ||B(u)|^2)$ time



KNN: Choosing K neighbors

How to choose *K* nearest neighbors?

Select K items with largest similarity score to guery item i

Problem: Not all items were rated by query user u

Solution: Choose K most similar items rated by u

Complexity: $O(min(KM, M \log M))$

Herlocker et al., 1999



KNN: Forming Weighted Predictions

Predicted rating for query user u and item i

- \vdash N(i; u) is the *neighborhood* of item i for user u
 - ⊱ i.e. the K most similar items rated by u

$$\hat{r}_{ui} = b_{ui} + \sum_{N(i;u)} w_{ij} (r_{uj} - b_{uj})$$

How to choose weights for each neighbor?

- ≥ Equal weights: $w_{ij} = \frac{1}{|N(i;u)|}$
- ϵ Similarity weights: $w_{ij} = \frac{S(i,j)}{\sum_{j \in N(i,u)} S(i,j)}$ (Herlocker et al., 1999)
- Learn optimal global weights (Koren, 2008)

Complexity: O(K)



KNN: User Optimized Weights

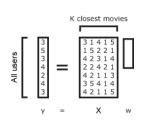
Intuition: For a given query user u and item i, choose weights that best predict other known ratings of item i using only N(i; u):

$$\min_{\mathbf{W}_{i.}} \sum_{s \in R(i), s \neq u} \left(r_{si} - \sum_{j \in N(i;u)} w_{ij} r_{sj} \right)^{2}$$

With no missing ratings, this is a linear regression problem:



KNN: User Optimized Weights



Bell and Koren, 2007

⊱ Optimal solution:
$$w = A^{-1}b$$
 for $A = X^TX \cdot b = X^Tv$

- ⊱ Problem: X contains missing entries
 - \vdash Not all items in N(i; u) were rated by all users
- Solution: Approximate A and b

$$\hat{A}_{jk} = \frac{\sum_{s \in R(j) \cap R(k)} r_{sj} r_{sk}}{|R(j) \cap R(k)|}$$

$$\hat{b}_k = \frac{\sum_{s \in R(i) \cap R(k)} r_{si} r_{sk}}{|R(i) \cap R(k)|}$$

$$\hat{w} = \hat{A}^{-1} \hat{b}$$

Estimates based on users who rated each pair of items



KNN: User Optimized Weights

Benefits

Intro

- Weights optimized for the task of rating prediction
 - ⊱ Not just borrowed from the neighborhood selection phase
- Weights not constrained to sum to 1
 - ⊱ Important if all nearest neighbors are dissimilar
- Weights derived simultaneously
 - Accounts for correlations among neighbors
- Outperforms KNN with similarity or equal weights
- \succeq Can compute entries of \hat{A} and \hat{b} offline in parallel

Drawbacks

Must solve additional KxK system of linear equations per query



KNN: Globally Optimized Weights

Consider the following KNN prediction rule for query (u,i):

$$\hat{r}_{ui} = b_{ui} + |N(i; u)|^{-\frac{1}{2}} \sum_{i \in N(i; u)} w_{ij} (r_{uj} - b_{uj})$$

Could learn a single set of KNN weights w_{ii} , shared by all users, that minimize regularized MSE:

$$E = \frac{1}{|\mathcal{T}|} \sum_{(u,i) \in \mathcal{T}} \frac{1}{2} (\hat{r}_{ui} - r_{ui})^2 + \lambda \sum_{i=1}^{M} \sum_{j=1}^{M} \frac{1}{2} w_{ij}^2 = \frac{1}{|\mathcal{T}|} \sum_{(u,i) \in \mathcal{T}} E_{ui}$$

Optimize objective using stochastic gradient descent:

⊱ For each example $(u,i) \in \mathcal{T}$, update $w_{ii} \forall j \in N(i;u)$

$$w_{ij}^{t+1} = w_{ij}^t - \gamma \frac{\partial}{\partial w_{ij}} E_{ui}$$

= $w_{ij}^t - \gamma (|N(i; u)|^{-\frac{1}{2}} (\hat{r}_{ui} - r_{ui}) (r_{uj} - b_{uj}) + \lambda w_{ij}^t)$



KNN: Globally Optimized Weights

Benefits

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- Weights optimized for the task of rating prediction
 - ⊱ Not just borrowed from the neighborhood selection phase
- Weights not constrained to sum to 1
 - Emportant if all nearest neighbors are dissimilar
- Weights derived simultaneously
 - Accounts for correlations among neighbors
- Outperforms KNN with similarity or equal weights

Drawbacks

- Must solve global optimization problem at training time
- ⊱ Must store $O(M^2)$ weights in memory



KNN: Summary

Pros

- ⊱ Intuitive interpretation
- ⊱ When weights not learned...
 - Easy to implement
 - Zero training time
- Learning prediction weights can greatly improve accuracy for little overhead in space and time

Cons

- When weights not learned...
 - ⊱ Need to store all item (or user) vectors in memory
 - ⊱ May redundantly recompute similarity scores at test time
 - ⊱ Similarity/equal weights not always suitable for prediction
- When weights learned...
 - ► Need to store $O(M^2)$ or $O(U^2)$ parameters
 - ⊱ Must update stored parameters when new ratings occur



Low Dimensional Matrix Factorization

Matrix Completion

 \succeq Filling in the unknown ratings in a sparse $U \times M$ matrix R

$$\mathbf{R} = \begin{bmatrix} ? & ? & 1 & \dots & 4 \\ 3 & ? & ? & \dots & ? \\ ? & 5 & ? & \dots & 5 \end{bmatrix}$$

Low dimensional matrix factorization

Model R as a product of two lower dimensional matrices



- \succeq A is $U \times K$ "user factor" matrix, $K \ll U, M$
- \succeq B is $M \times K$, "item factor" matrix
- Learning A and B allows us to reconstruct all of R



Low Dimensional Matrix Factorization



Interpretation: Rows of A and B are low dimensional feature vectors a_u and b_i for each user u and item i

Motivation: Dimensionality reduction

- Compact representation: only need to learn and store UK + MK parameters
- Matrices can often be adequately represented by low rank factorizations



Low Dimensional Matrix Factorization



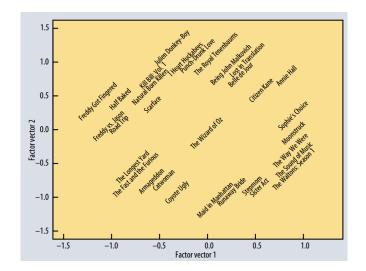
Very general framework that encapsulates many ML methods

- Singular value decomposition
- Clustering
 - ⊱ A can represent cluster centers
 - ⊱ B probabilities of belonging to each cluster
- ⊱ Factor Analysis/Probabilistic PCA



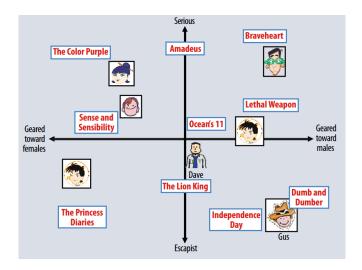
IProjecting movies

Intro





Projecting users and movies





Singular Value Decomposition

Squared error objective for MF

$$\underset{A,B}{\operatorname{argmin}} \|R - AB^{T}\|_{2}^{2} = \underset{A,B}{\operatorname{argmin}} \sum_{u=1}^{U} \sum_{i=1}^{M} (r_{ui} - \langle a_{u}, b_{i} \rangle)^{2}$$

Reasonable objective since RMSE is our error metric

When all of R is observed, this problem is solved by singular value decomposition (SVD)

- \succ SVD: $R = H\Sigma V^T$
 - \vdash H is $U \times U$ with $H^T H = I_{U \times U}$
 - \vdash V is $M \times M$ with $V^T V = I_{M \times M}$
 - $\succeq \Sigma$ is $U \times M$ and diagonal
- Solution: Take first K pairs of singular vectors
 - ⊱ Let $A = H_{IJ \times K} \Sigma_{K \times K}$ and $B = V_{M \times K}$



SVD with Missing Values

Weighted SE objective

$$\underset{A,B}{\operatorname{argmin}} \sum_{u=1}^{U} \sum_{i=1}^{M} W_{ui} (r_{ui} - \langle a_u, b_i \rangle)^2$$

Binary weights

- $W_{ui} = 1$ if r_{ui} observed, $W_{ui} = 0$ otherwise
- Only penalize errors on known ratings

How to optimize?

- Straightforward singular value decomposition no longer applies
- ⊱ Local minima exist ⇒ algorithm initialization is important



SVD with Missing Values

Insight: Chicken and egg problem

- ⊱ If we knew the missing values in R, could apply SVD
- ⊱ If we could apply SVD, we could find the missing values in R
- Idea: Fill in unknown entries with best guess; apply SVD; repeat

Expectation-Maximization (EM) algorithm

- Alternate until convergence:
 - 1 E step: $X = W * R + (1 W) * \hat{R}$ (* represents entrywise product)
 - 2 M step: $[H, \Sigma, V] = SVD(X)$, $\hat{R} = H_{U \times K} \Sigma_{K \times K} V_{M \times K}^T$

Complexity: O(UM) space and O(UMK) time per EM iteration

- ⊱ What if *UM* or *UMK* is very large?
 - ⊱ UM = 8.5 billion for Netflix Prize dataset
- Complete ratings matrix may not even fit into memory!



SVD with Missing Values

Regularized weighted SE objective

$$\underset{A,B}{\operatorname{argmin}} \sum_{u=1}^{U} \sum_{i=1}^{M} W_{ui} (r_{ui} - \langle a_u, b_i \rangle)^2 + \lambda (\sum_{u=1}^{U} ||a_u||^2 + \sum_{i=1}^{M} ||b_i||^2)$$

Equivalent form

$$\underset{A,B}{\operatorname{argmin}} \sum_{(u,i) \in \mathcal{T}} (r_{ui} - \langle a_u, b_i \rangle)^2 + \lambda (\sum_{u=1}^{U} ||a_u||^2 + \sum_{i=1}^{M} ||b_i||^2)$$

Motivation

- Counters overfitting by implicitly restricting optimization space
 - ⊱ Shrinks entries of A and B toward 0
- E Can improve *generalization error*, performance on unseen test data



Low Dimensional MF: Summary

Pros

- Data reduction: only need to store UK + MK parameters at test time
 - \vdash $MK + M^2$ needed for Factor Analysis
- Gradient descent and ALS procedures are easy to implement and scale well to large datasets
- Empirically yields high accuracy in CF tasks
- Matrix factors could be used as inputs into other learning algorithms (e.g. classifiers)

Cons

- Missing data MF objectives plagued by many local minima
- ⊱ Initialization is important
- EM approaches tend to be slow for large datasets



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