Vertical movement behaviour of the starry smooth-hound shark *Mustelus*asterias in the North Sea Master Thesis

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Abstract

This is the abstract. Lorem ipsum dolor sit amet, consectetur adipiscing elit. Vestibulum augue turpis, dictum non malesuada a, volutpat eget velit. Nam placerat turpis purus, eu tristique ex tincidunt et. Mauris sed augue eget turpis ultrices tincidunt. Sed et mi in leo porta egestas. Aliquam non laoreet velit. Nunc quis ex vitae eros aliquet auctor nec ac libero. Duis laoreet sapien eu mi luctus, in bibendum leo molestie. Sed hendrerit diam diam, ac dapibus nisl volutpat vitae. Aliquam bibendum varius libero, eu efficitur justo rutrum at. Sed at tempus elit.

Keywords: acoustic telemetry, geolocation modelling, mustelus asterias

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4 Tables coming from R

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1. Bibliography styles

Let's see how we can cite differently: Nathan (2008) or Dodge et al. (2013).

By default, natbib will be used with the authoryear style, set in classoption variable in YAML. You can sets extra options with natbiboptions variable in YAML header. Example

natbiboptions: longnamesfirst, angle, semicolon

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1.1. Using CSL

If cite-method is set to citeproc in elsevier_article(), then pandoc is used for citations instead of natbib. In this case, the csl option is used to format the references. By default, this template will provide an appropriate style, but alternative csl files are available from https://www.zotero.org/styles?q=elsevier. These can be downloaded and stored locally, or the url can be used as in the example header.

2. Equations

Here is an equation:

$$f_X(x) = \left(\frac{\alpha}{\beta}\right) \left(\frac{x}{\beta}\right)^{\alpha-1} e^{-\left(\frac{x}{\beta}\right)^{\alpha}}; \alpha,\beta,x>0.$$

In line equations work as well: $\sum_{i=2}^{\infty} \{\alpha_i^{\beta}\}$

3. Figures and tables

Figure 1 is generated using an R chunk.

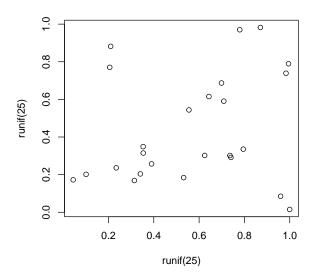


Figure 1: A meaningless scatterplot

4. Tables coming from R

Tables can also be generated using R chunks, as shown in Table 1 example.

knitr::kable(head(mtcars)[,1:4])

Table 1: Caption centered above table

mpg	cyl	disp	hp
21.0	6	160	110
21.0	6	160	110
22.8	4	108	93
21.4	6	258	110
18.7	8	360	175
18.1	6	225	105
	21.0 21.0 22.8 21.4 18.7	21.0 6 21.0 6 22.8 4 21.4 6 18.7 8	21.0 6 160 21.0 6 160 22.8 4 108 21.4 6 258 18.7 8 360

References

Dodge, S., Bohrer, G., Weinzierl, R., Davidson, S.C., Kays, R., Douglas, D., Cruz, S., Han, J., Brandes, D., Wikelski, M., 2013. The environmental-data automated track annotation (env-DATA) system: linking animal tracks with environmental data. Movement Ecology 1, 3. URL: http://dx.doi.org/10.1186/2051-3933-1-3, doi:10.1186/2051-3933-1-3.

Nathan, R., 2008. An emerging movement ecology paradigm. Proceedings of the National Academy of Sciences of the United States of America 105, 19050–19051. URL: http://dx.doi.org/10.1073/pnas.0808918105, doi:10.1073/pnas.0808918105.