

Group theory, Topology and Spin-1/2 Particles

From Dirac's belt to fermions

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Dirac's belt trick and rotations

Dirac's belt trick

You need:

- a belt (not necessarily Dirac's)
- a heavy book

Rules:

1. you can only move the end of the belt
2. you cannot twist or rotate it

Goal: untwist a 2π -twist.

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\Rightarrow it turns out to be impossible ! One turn negates the twist:

$$2\pi \rightarrow -2\pi.$$

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Therefore, possible for a 4π twist ...

Why is that ?

Space of rotations: $\text{SO}(3)$ as a group

Rotations in 3-dimensional space: matrices that acts on \mathbb{R}^3 s.t.

1. preserve the **scalar product**: $O^T O = \mathbb{1}$ ($\Leftrightarrow O$ is orthogonal)
2. preserve the **orientation**: $\det O = 1$

Special orthogonal group

$\text{SO}(3)$ is the set of 3×3 real matrices such that $O^T O = \mathbb{1}$ and $\det O = 1$.

Three “fundamental” rotations:

$$x : \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix} \quad y : \begin{bmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{bmatrix} \quad z : \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

\Rightarrow It forms a **group**.

Space of rotations: $\text{SO}(3)$ as a topological space

Fundamental data that describes a rotation:

- an **axis** of rotation, i.e. a unit vector \vec{n} $\rightarrow 2$ parameters
- an **angle** of rotation $\theta \in [-\pi, \pi]$ (with $-\pi \sim \pi$) $\rightarrow 1$ parameter

The space of rotations can then alternately be defined as a **3-sphere of radius π and its antipodal points identified**:

$$\boxed{\text{SO}(3) \cong B^3(\pi) / \sim}$$

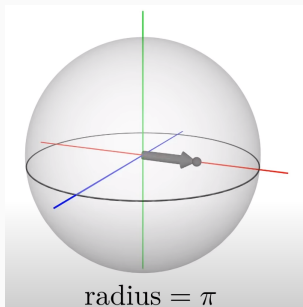
and for each point:

direction \leftrightarrow axis

norm \leftrightarrow angle

\Rightarrow It forms a **topological space**.

(group + topological space = Lie group)



Back to the belt

Lets “mathematicalize” the belt:

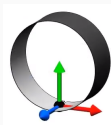
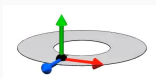
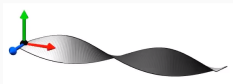
A belt (strip) is just a **path** + an **orientation**.

There is a bijection:

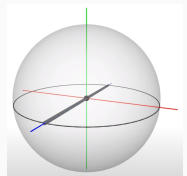
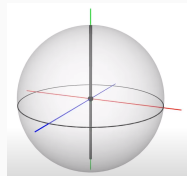
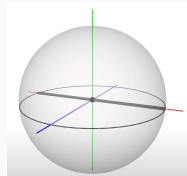
$$\boxed{\text{belt configuration} \Leftrightarrow \text{path in } \text{SO}(3)}$$

This gives us a new language to analyze the problem !

Belt

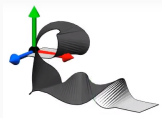


Path

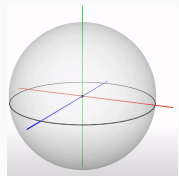
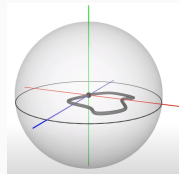


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Belt



Path

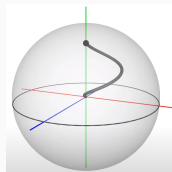
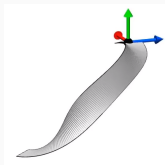
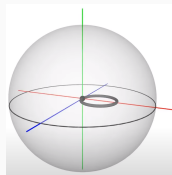
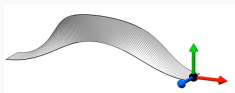


(The color code is consistent.)

Back to Dirac's belt trick

Recall the rules of the game:

1. translating the end of the belt
2. not turning the end of the belt



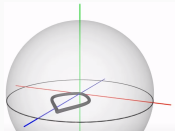
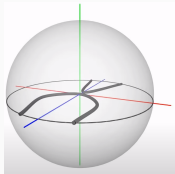
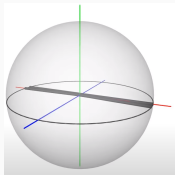
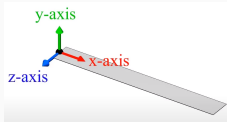
Back to Dirac's belt trick

Back to Dirac's belt trick

Paths in topological spaces (homotopy theory)

The belt trick is a way of physically demonstrating the the fundamental group of $\mathrm{SO}(3)$ is \mathbb{Z}_2 .

In quantum mechanics



Section 2

Section 3

Section 4

Section 5

Three different block environments are pre-defined and may be styled with an optional background color.

Some text.

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Default

Block content.

Alert

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Example

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Backup slides

Sometimes, it is useful to add slides at the end of your presentation to refer to during audience questions.

The best way to do this is to include the `appendixnumberbeamer` package in your preamble and call `\appendix` before your backup slides.

metropolis will automatically turn off slide numbering and progress bars for slides in the appendix. [1]



R. Graham, D. Knuth, and O. Patashnik.

Concrete mathematics.

Addison-Wesley, Reading, MA, 1989.