

Homework 6



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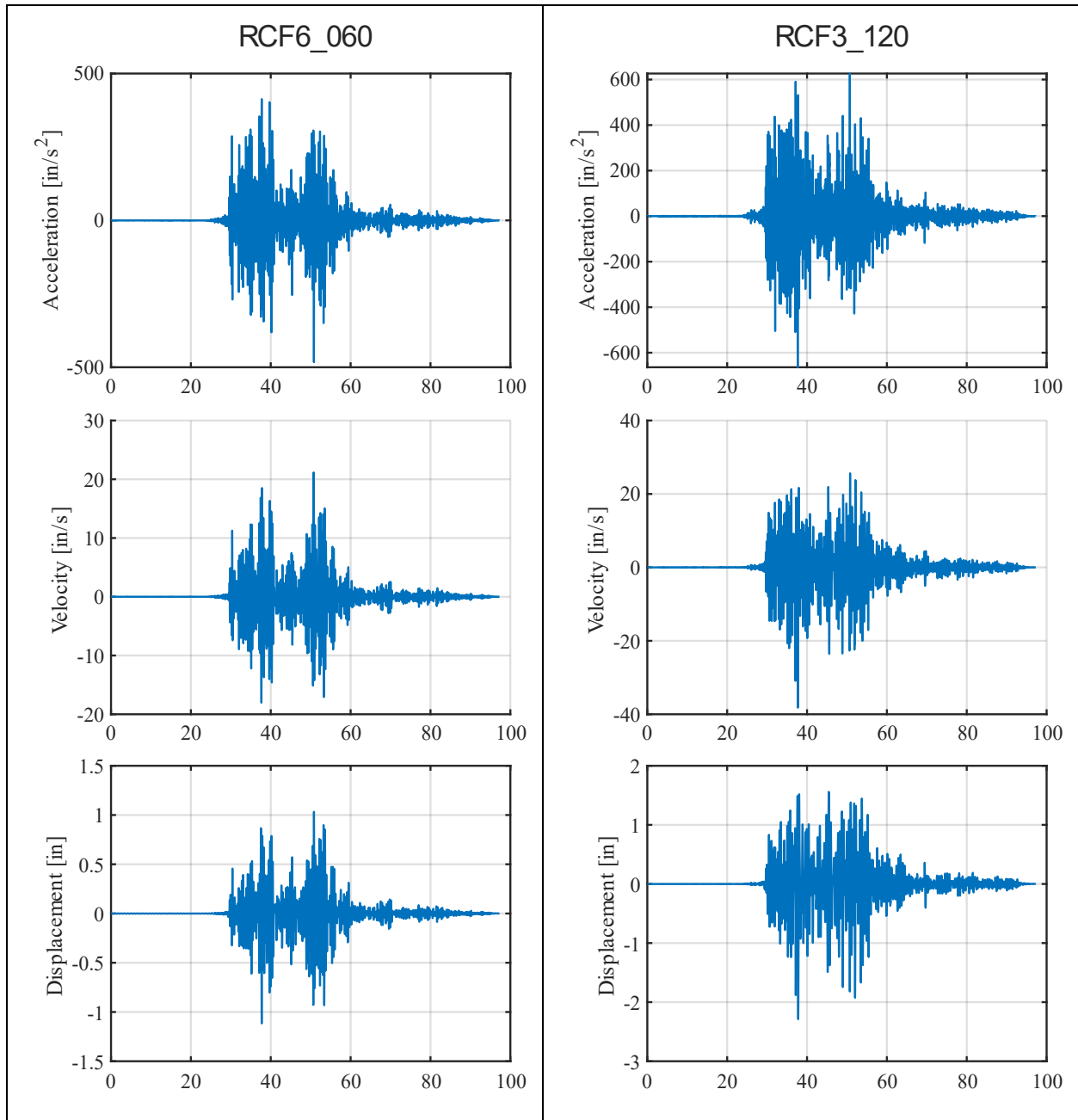
University of California, San Diego

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SE 267A Signal Processing and Spectral Analysis

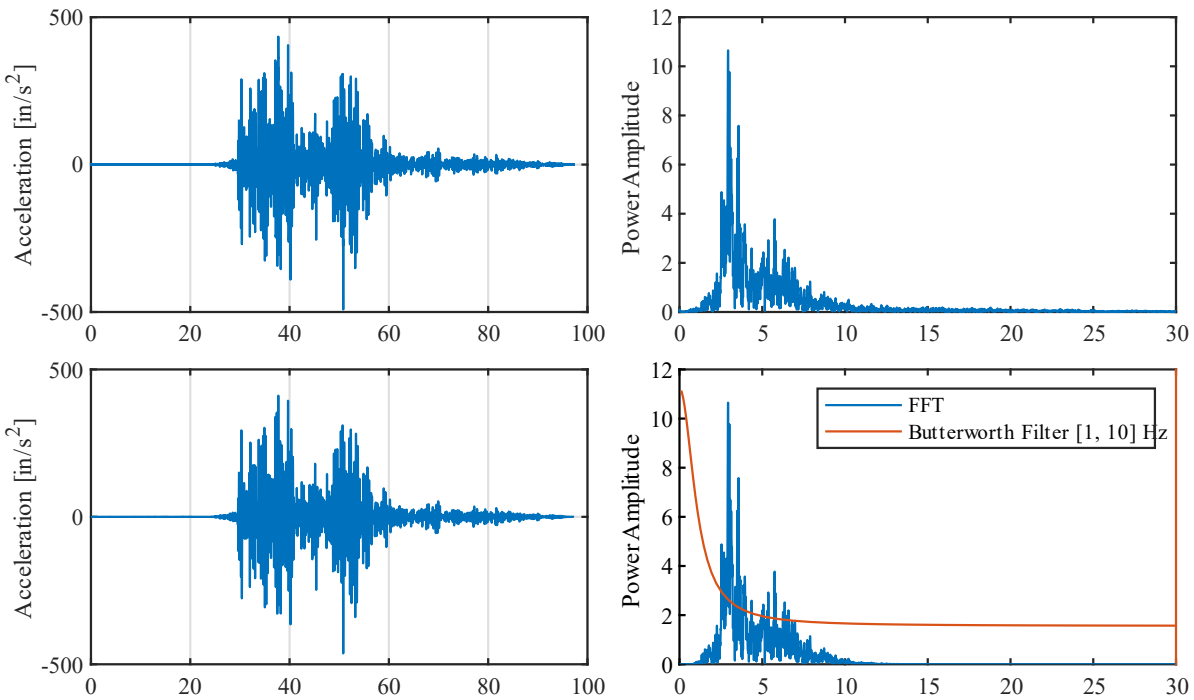
Problem 6

The objective of this homework was to examine getting the displacement of a civil structure from an acceleration time history data set. Two sensors were chosen for this assignment: RCF6_060 and RCF3_120.

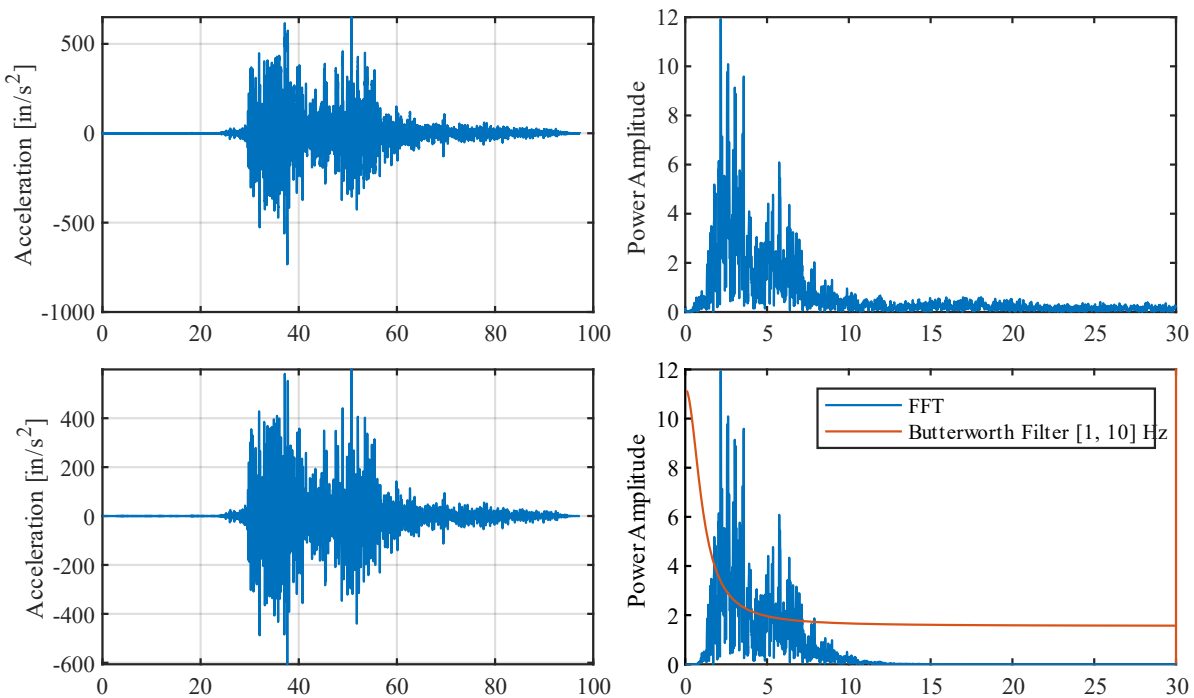


Here the Butterworth filter is demonstrated. Although there is no noticeable difference in the time history, the butterworth filter is shown to decrease high frequency signals within the signal.

RCF6_060

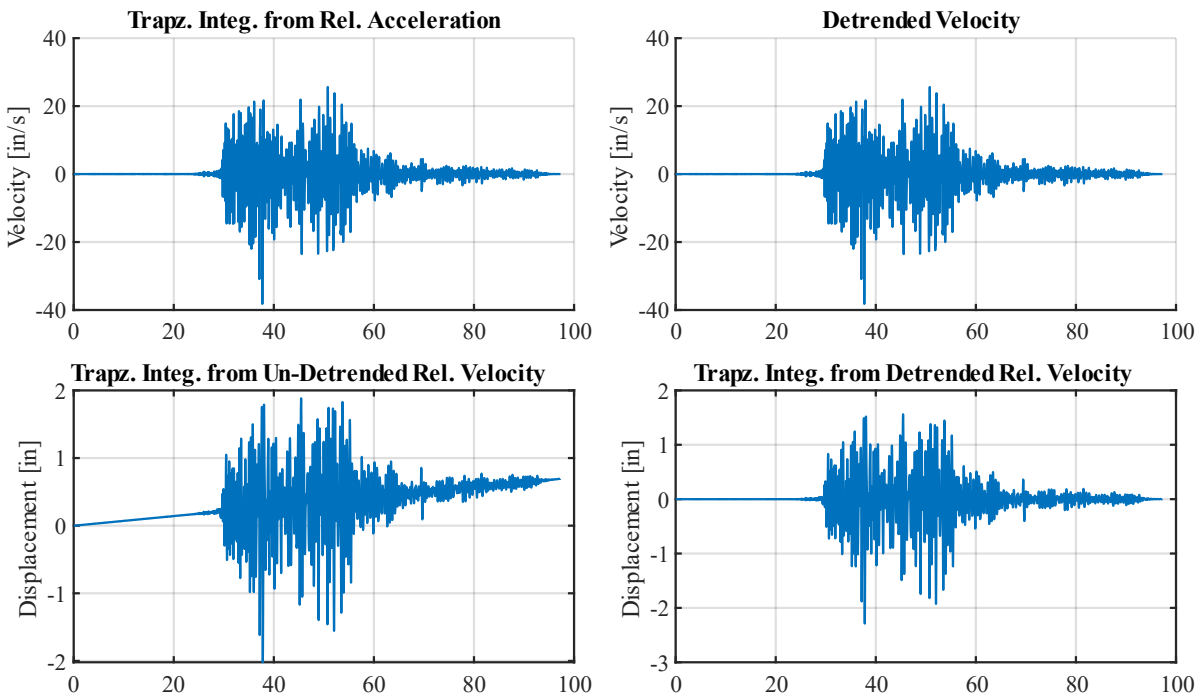


RCF3_120

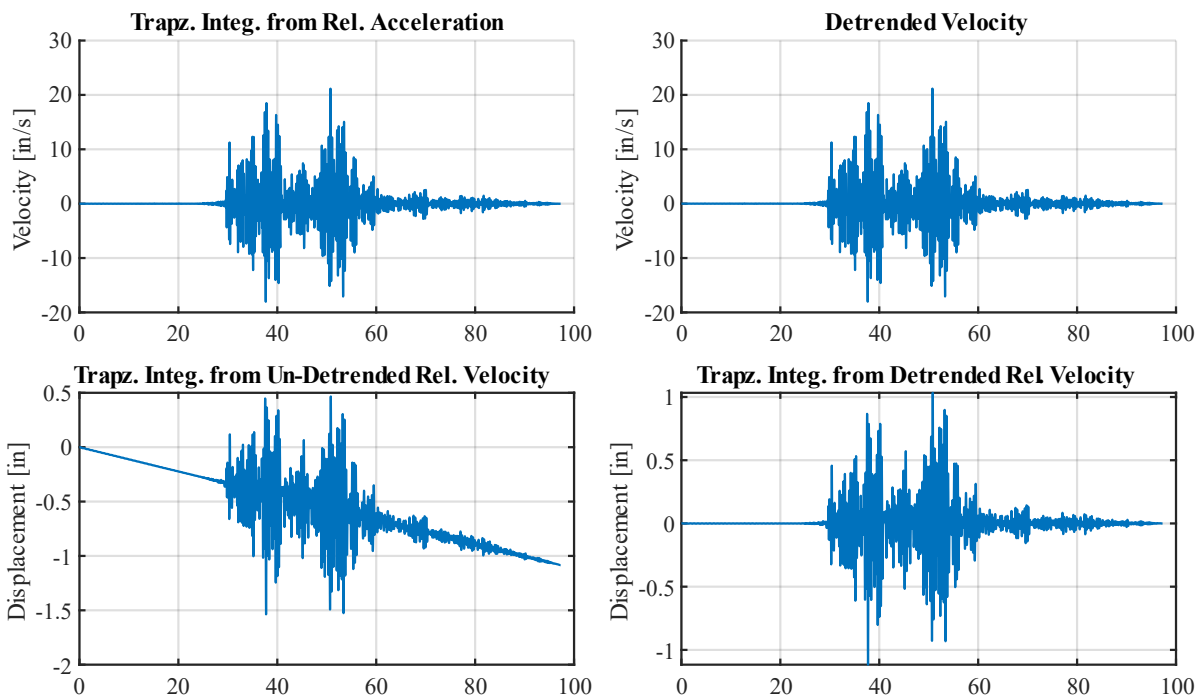


The importance of detrending the velocity is shown below. Although the trend is barely noticeable, the constant will lead to spurious growth of the displacement.

RCF3_120



RCF6_060



```

%% Import Data
clc; clear; clf;
data = readtable("Homework-2 data set-RCF-Four Specimen Test Data.xlsx");
%%
fs = 200; % Sampling rate
dt = 1/fs;
ii = 0;
for RC = ["6_060", "3_120"]
    ii = ii + 1;
    figure(ii); clf; clc
    tiledlayout(3,1,"TileSpacing","compact","Padding","compact")
    udd_g = data("RCF" + RC + "_A10"); % Base acceleration
    udd_a = data("RCF" + RC + "_A04"); % Building level acceleration

    % Remove DC Gain if any
    preTriggerTime = 10; % seconds; Pretrigger time based on visual observations
    udd_g = udd_g - mean(udd_g(1:fs*preTriggerTime));
    udd_a = udd_a - mean(udd_a(1:fs*preTriggerTime));

    udd_r = udd_a - udd_g; % Relative acceleration
    npt = length(udd_r);
    t = (1:npt) * dt;
    g = 386.4;
    udd_r = udd_r * g;

    % Pass Through low pass filter
    n = 4; % order of butterworth filter
    Wn = [1, 20] ./ (fs/2); % Cutoff Frequencies
    ftType = 'bandpass'; % Option
    [b,a] = butter(n, Wn, ftType);
    udd_r = filtfilt(b,a,udd_r);
    nexttile;
    plot(t, udd_r);
    grid on;
    ylabel("Acceleration [in/s^2]")

    % Integration to velocity
    ud_r = cumtrapz(t, udd_r);
    ud_r = detrend(ud_r, 1);
    nexttile(); hold on;
    plot(t, ud_r);
    grid on;
    ylabel("Velocity [in/s]")

    % Integration to displacement
    u_r = cumtrapz(t, ud_r);
    nexttile()
    plot(t, u_r);
    grid on;
    ylabel("Displacement [in]")

    sgtitle("RCF" + RC, interpreter = 'none')
end

```