How to determine the success of Smart Products?
A Machine Learning Approach

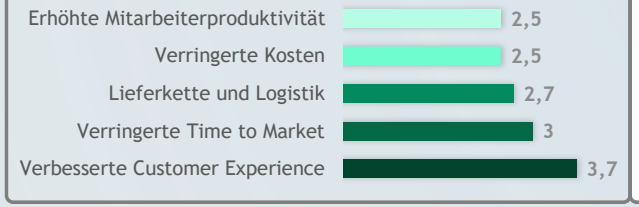
Louis Püschel

WHAT IS A SMART PRODUCT?

"The Internet of Things (IoT) refers to the connectivity of physical objects, equipped with sensors and actuators, to the Internet via data communication technology, enabling interaction with and/or among these objects."

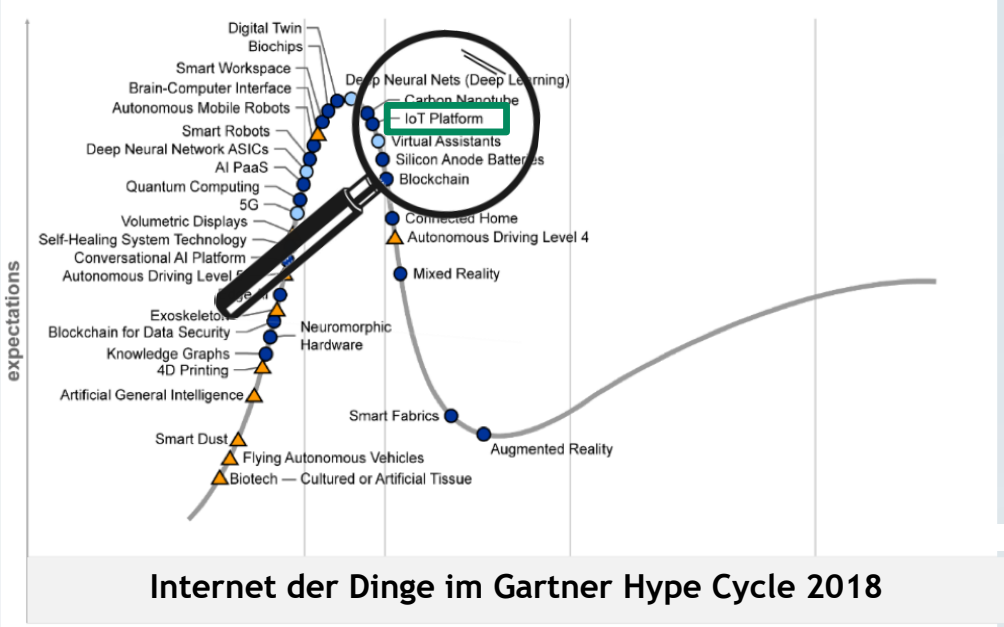
MOTIVATION

Internet der Dinge:
Wertschöpfung bis 2022 $14,4 Billionen



Anzahl verbundener Geräte

2015	2025
ca. 15,4 Milliarden	ca. 75,4 Milliarden



Internet der Dinge im Gartner Hype Cycle 2018

Smart City *Exemplarisch*

Husqvarna, Google, BOSCH, amazon.com

Health, Well-Being *Exemplarisch*

PHILIPS, CliniCloud, fitbit, GARMIN, SIEMENS, Microsoft

Industrial *Exemplarisch*

ROLLS ROYCE, CATERPILLAR, HILTI, BOSCH, AIRBUS

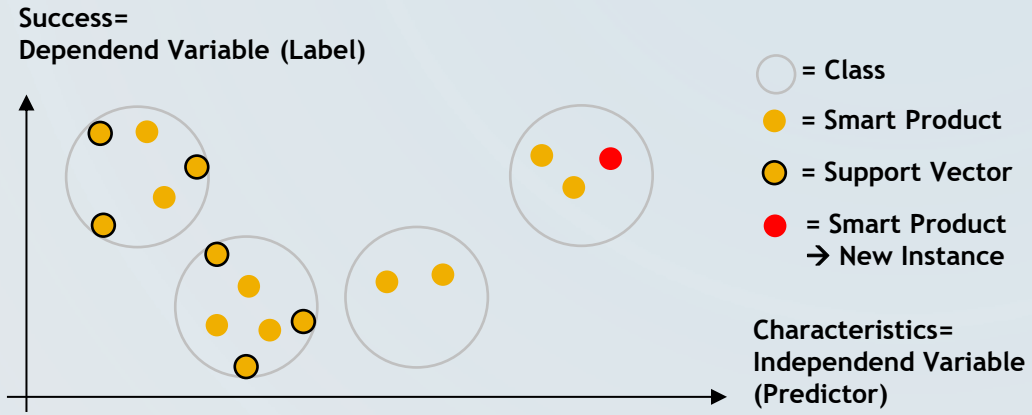
PROJECT QUESTION?

Which Smart Products are especially successfull?

Which kind of Smart Product is my Product?

- ✓ Prediction with a Machine Learning Approach

PREDICTION BASED ON SUPPORT VECTOR MACHINE



Explanation

- **SVM trains** on the basis of **characteristics** and **market success** of the smart products
- **Depending** on the **characteristics** of the smart product, it will have a **certain success**
- **Success** results from **Google search queries**
- **Apply SVM** to an entirely **new object/instance**

WHAT DO WE NEED? THE PREWORK!

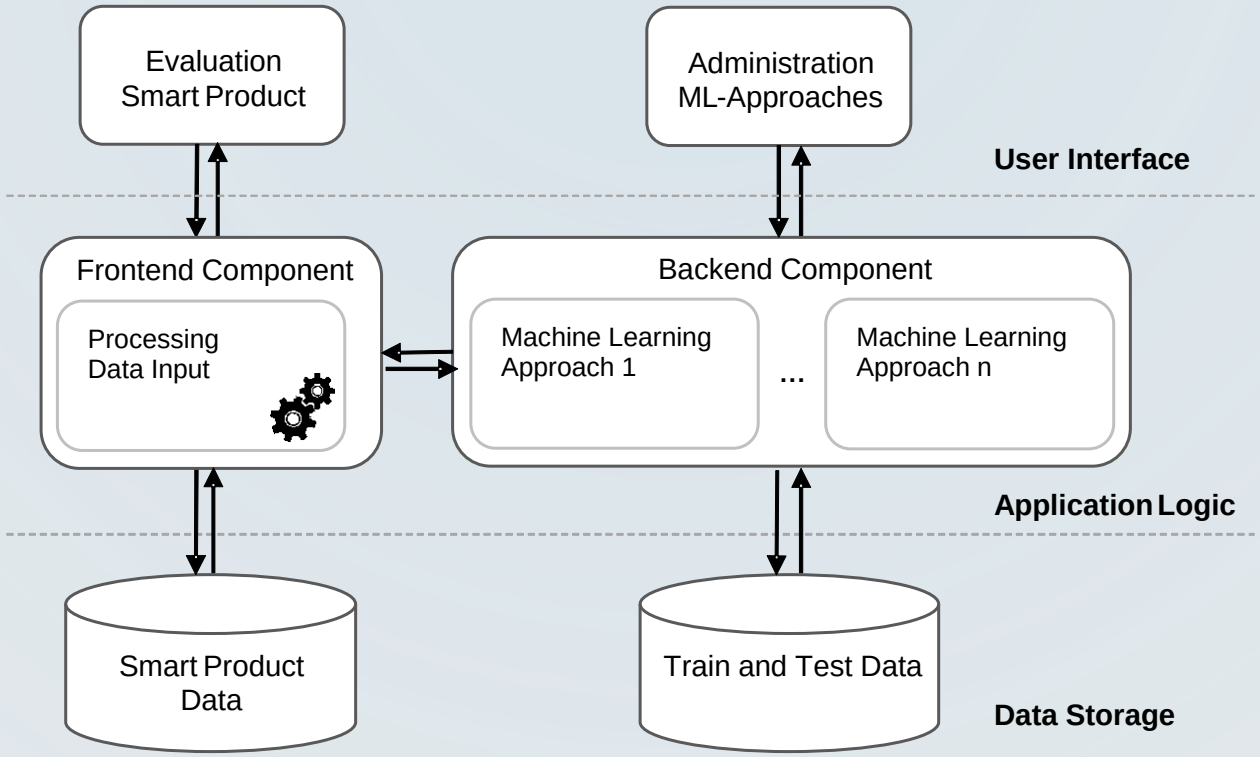
Taxonomy
General description of Smart Products.

Data set
About 200 classified Smart Products, related success and cluster affiliation.

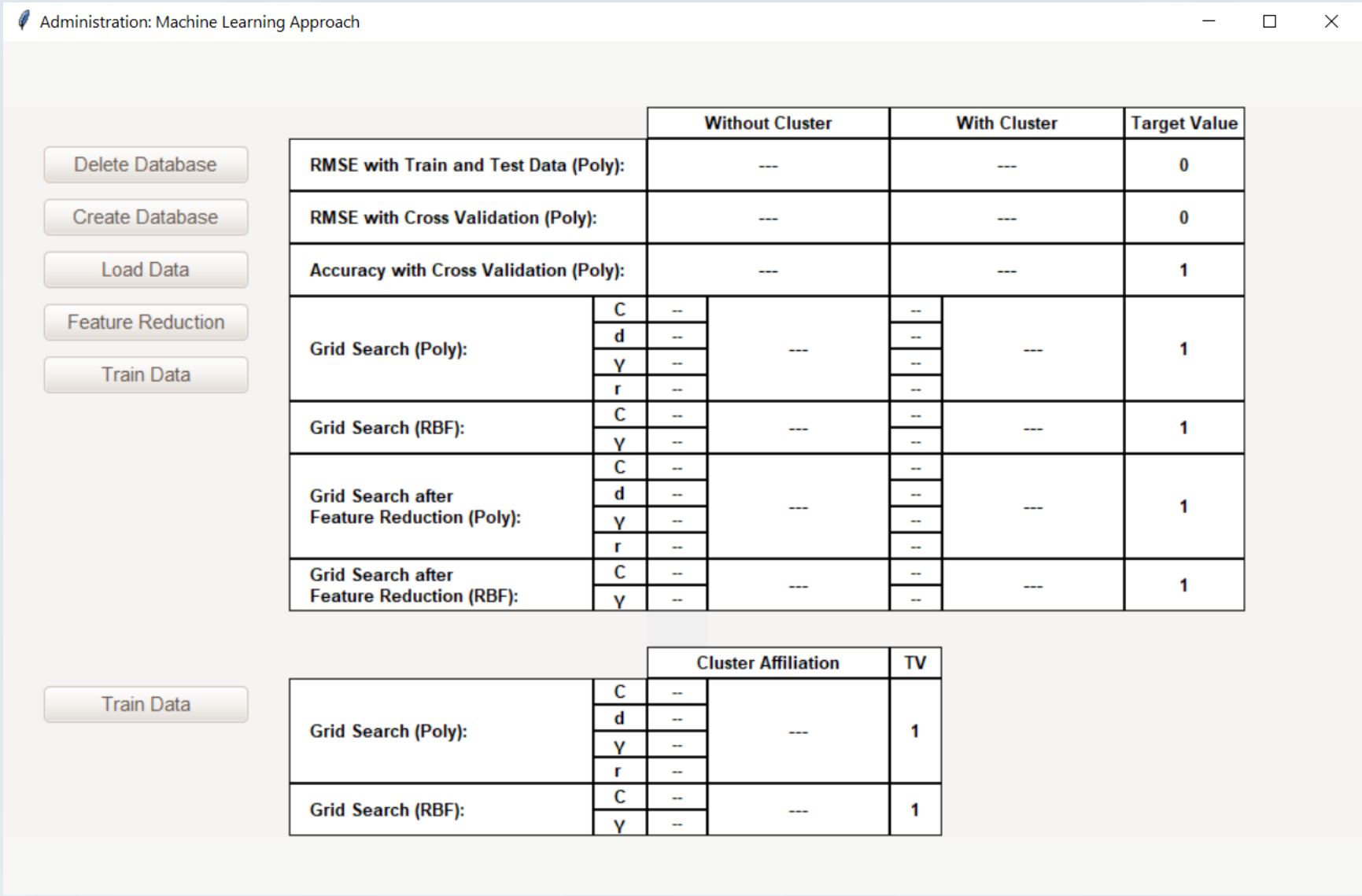
	Dimension	Characteristics			
Service	Ecosystem Integration	None	Proprietary	Open	
	Value Proposition	Thing-centric	Service-centric		
	Offline Functionality	None	Limited		
Data	Data Usage	Transactional	Analytical (basic)	Analytical (extended)	
	Data Source	Thing State	Thing Context	Thing Usage	Cloud
Interaction	Interaction Partner	User(s)	Business(es)	Thing(s)	
	Interaction Multiplicity	One-to-one	One-to-many		
	Interaction Direction	Unidirectional	Bi-directional		
Thing	Autonomy	None	Self-Controlled	Self-Learning	
	Acting Capabilities	Own	Intermediary		
	Sensing Capabilities	Lean	Rich		

	A	B	C	D	E	F	G	H
1	sensing	acting_own	acting_inter	autonomy	direction	multiplicity	partner_use	partner_t
2	0.00	0.50	0.50	0.50	0.00	1.00	0.33	0.00
3	0.00	0.00	0.50	0.00	0.00	0.00	0.33	0.00
4	0.00	0.00	0.50	0.00	0.00	1.00	0.33	0.33
5	0.00	0.50	0.00	0.00	0.00	1.00	0.33	0.00
6	1.00	0.50	0.50	0.50	1.00	0.00	0.33	0.00
7	0.00	0.50	0.50	1.00	1.00	1.00	0.33	0.00
8	0.00	0.50	0.50	0.00	0.00	0.00	0.33	0.00
9	1.00	0.50	0.50	0.00	1.00	0.00	0.33	0.00
10	1.00	0.50	0.50	0.00	1.00	1.00	0.33	0.00
11	0.00	0.00	0.50	0.50	1.00	1.00	0.33	0.00
12	0.00	0.50	0.50	0.50	0.00	1.00	0.33	0.00
13	1.00	0.00	0.50	0.50	0.00	1.00	0.33	0.00
14	1.00	0.50	0.50	0.50	0.00	0.00	0.33	0.00
15	0.00	0.00	0.50	0.00	0.00	0.00	0.33	0.00
16	0.00	0.00	0.50	0.00	0.00	0.00	0.33	0.00
17	0.00	0.50	0.50	0.00	1.00	1.00	0.33	0.00
18	0.00	0.50	0.50	0.50	0.00	1.00	0.33	0.00
19	0.00	0.50	0.50	0.00	1.00	1.00	0.33	0.00
20	0.00	0.00	0.50	1.00	1.00	0.00	0.33	0.00
21	1.00	0.00	0.50	0.00	0.00	1.00	0.33	0.00
22	1.00	0.00	0.50	0.00	0.00	0.00	0.33	0.00

REALIZATION: THREE-LAYER ARCHITECTURE



REALIZATION: BACKEND USER INTERFACE



		Without Cluster		With Cluster		Target Value
RMSE with Train and Test Data (Poly):		---		---		0
RMSE with Cross Validation (Poly):		---		---		0
Accuracy with Cross Validation (Poly):		---		---		1
Grid Search (Poly):	C	--	---	--	---	1
	d	--		--		
	Y	--		--		
	r	--		--		
Grid Search (RBF):	C	--	---	--	---	1
	Y	--		--		
Grid Search after Feature Reduction (Poly):	C	--	---	--	---	1
	d	--		--		
	Y	--		--		
	r	--		--		
Grid Search after Feature Reduction (RBF):	C	--	---	--	---	1
	Y	--		--		

		Cluster Affiliation		TV
Grid Search (Poly):	C	--	---	1
	d	--		
	Y	--		
	r	--		
Grid Search (RBF):	C	--	---	1
	Y	--		

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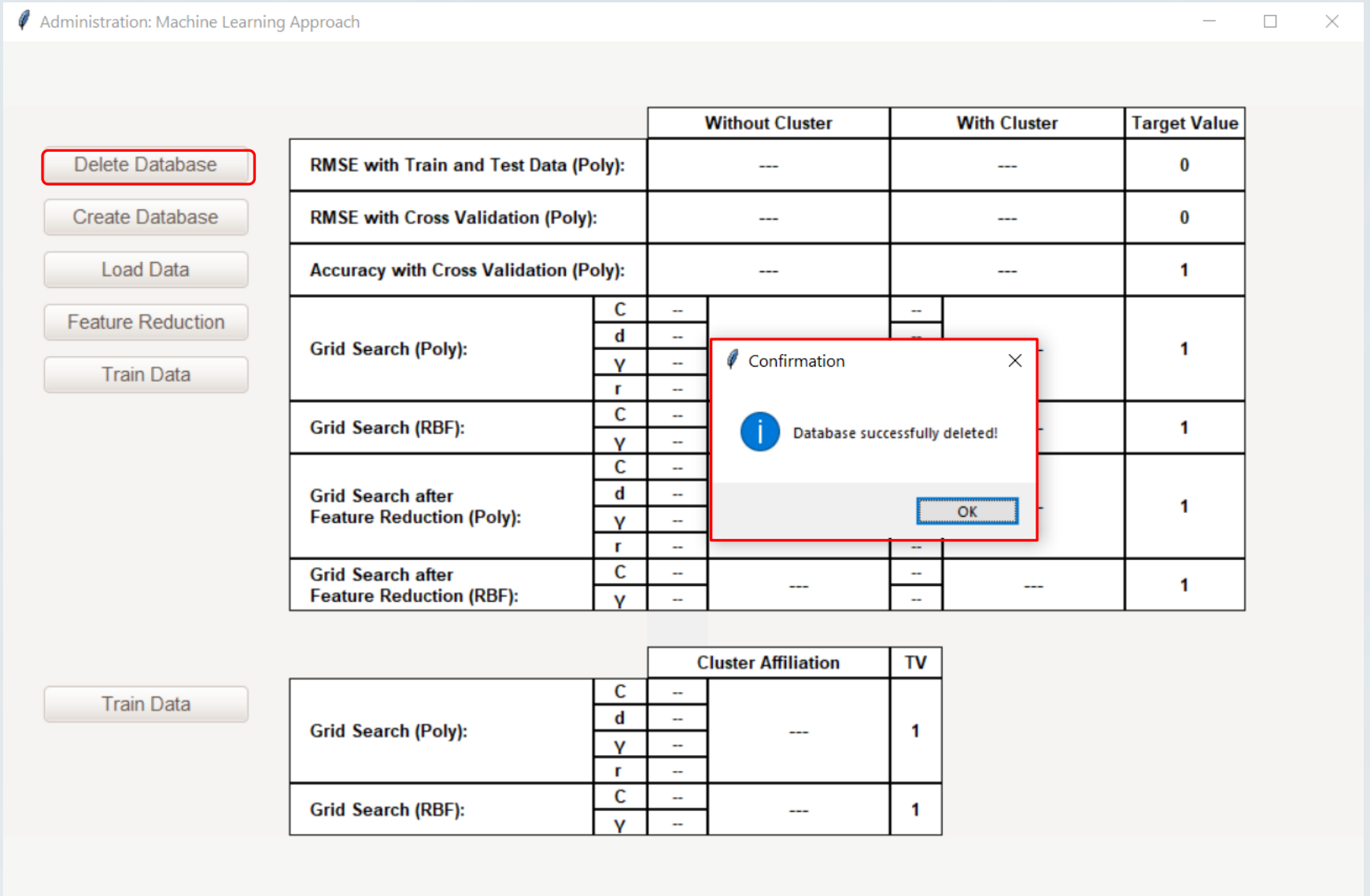

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Grid Search (Poly):	C	--	--	1
	d	--	--	
	Y	--	--	
	r	--	--	
Grid Search (RBF):	C	--	--	1
	Y	--	--	
Grid Search after Feature Reduction (Poly):	C	--	--	1
	d	--	--	
	Y	--	--	
	r	--	--	
Grid Search after Feature Reduction (RBF):	C	--	--	1
	Y	--	--	

		Cluster Affiliation	TV
Grid Search (Poly):	C	--	1
	d	--	
	Y	--	
	r	--	
Grid Search (RBF):	C	--	1
	Y	--	

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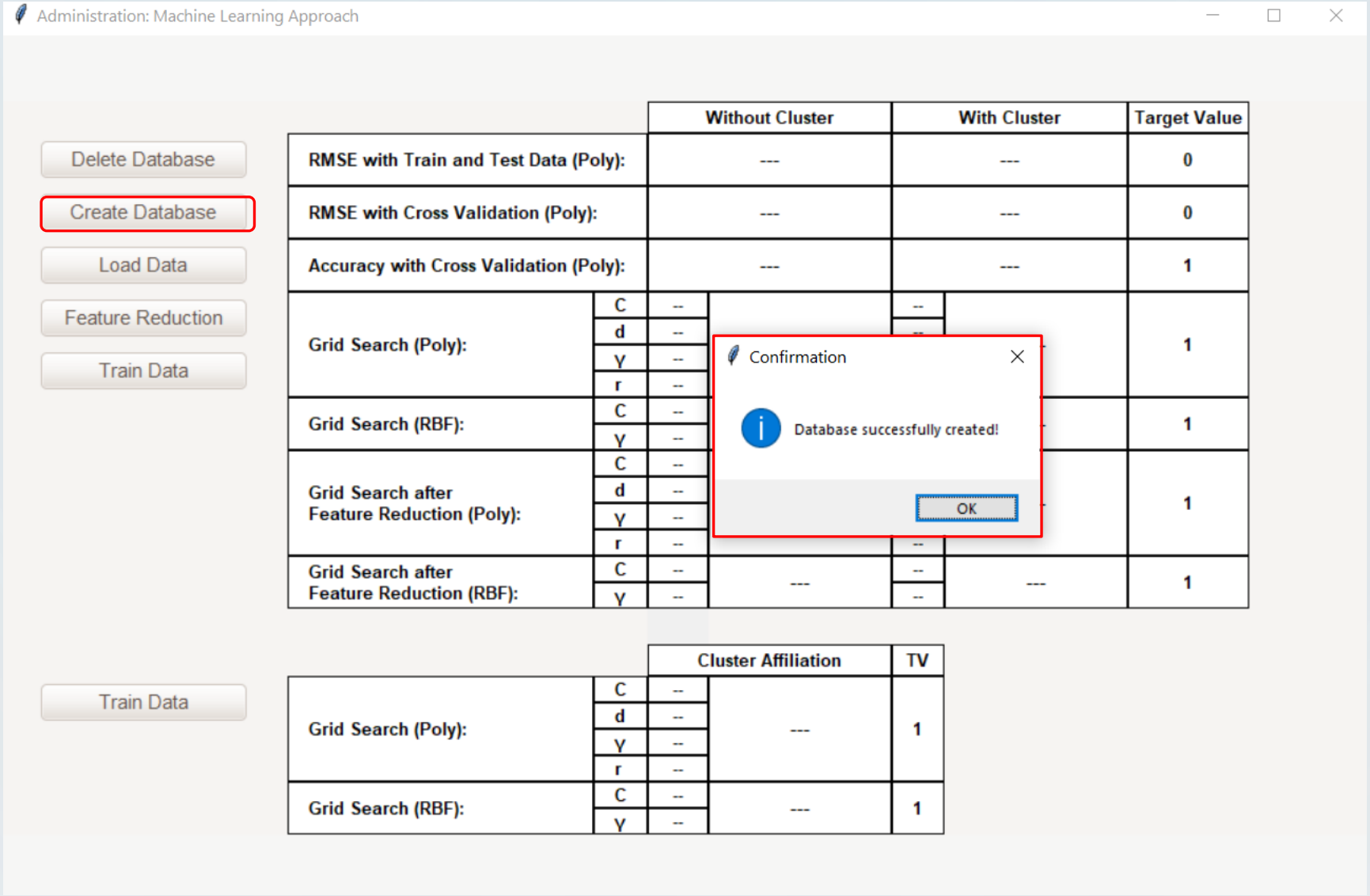

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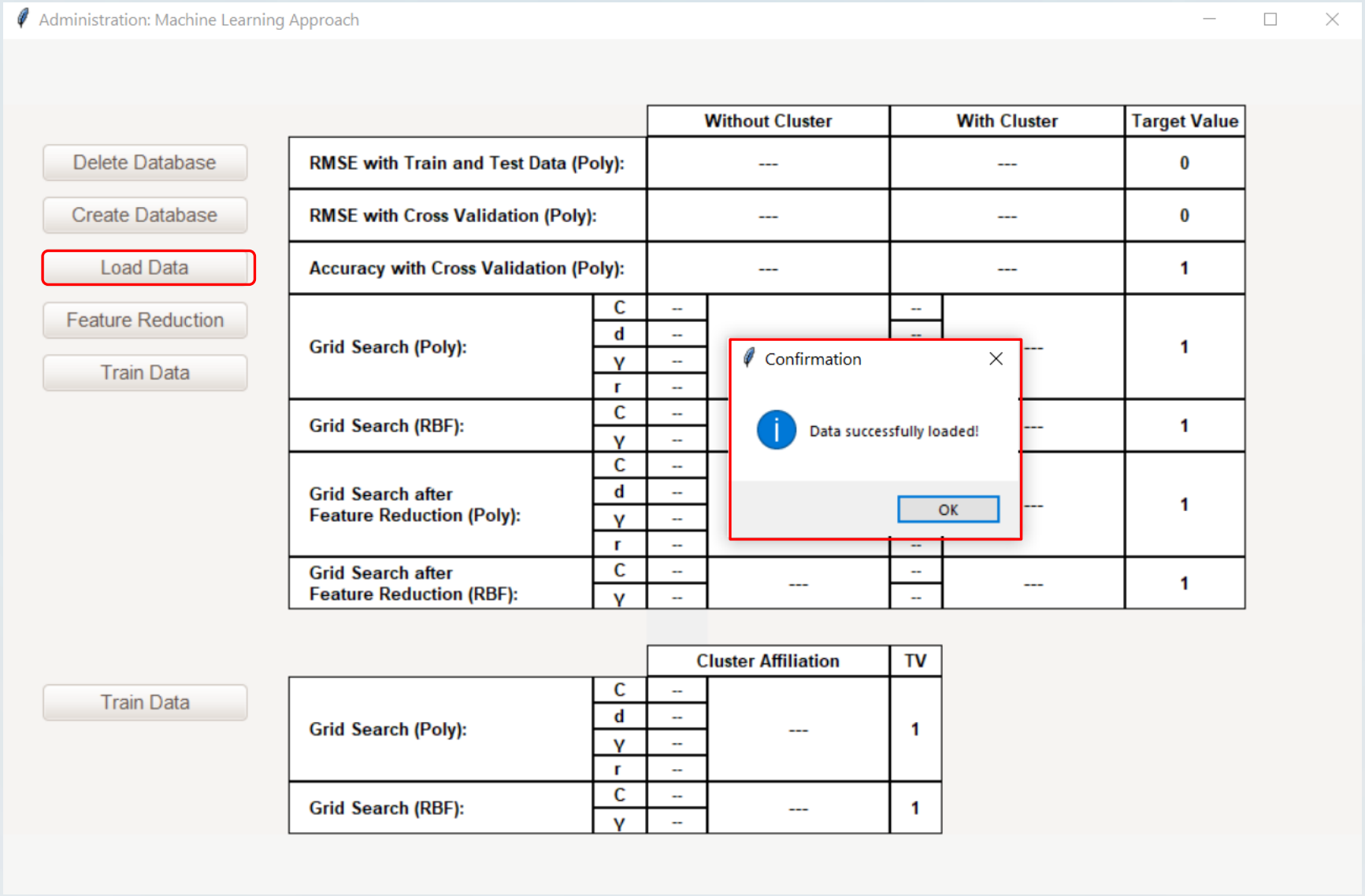
RMSE with Cross Validation (Poly):		---	---	0
Accuracy with Cross Validation (Poly):		---	---	1
Grid Search (Poly):	C	--	--	1
	d	--	--	
	γ	--	--	
	r	--	--	
Grid Search (RBF):	C	--	--	1
	γ	--	--	
Grid Search after Feature Reduction (Poly):	C	--	--	1
	d	--	--	
	γ	--	--	
	r	--	--	
Grid Search after Feature Reduction (RBF):	C	--	--	1
	γ	--	--	

		Cluster Affiliation	TV
Grid Search (Poly):	C	--	1
	d	--	
	γ	--	
	r	--	
Grid Search (RBF):	C	--	1
	γ	--	

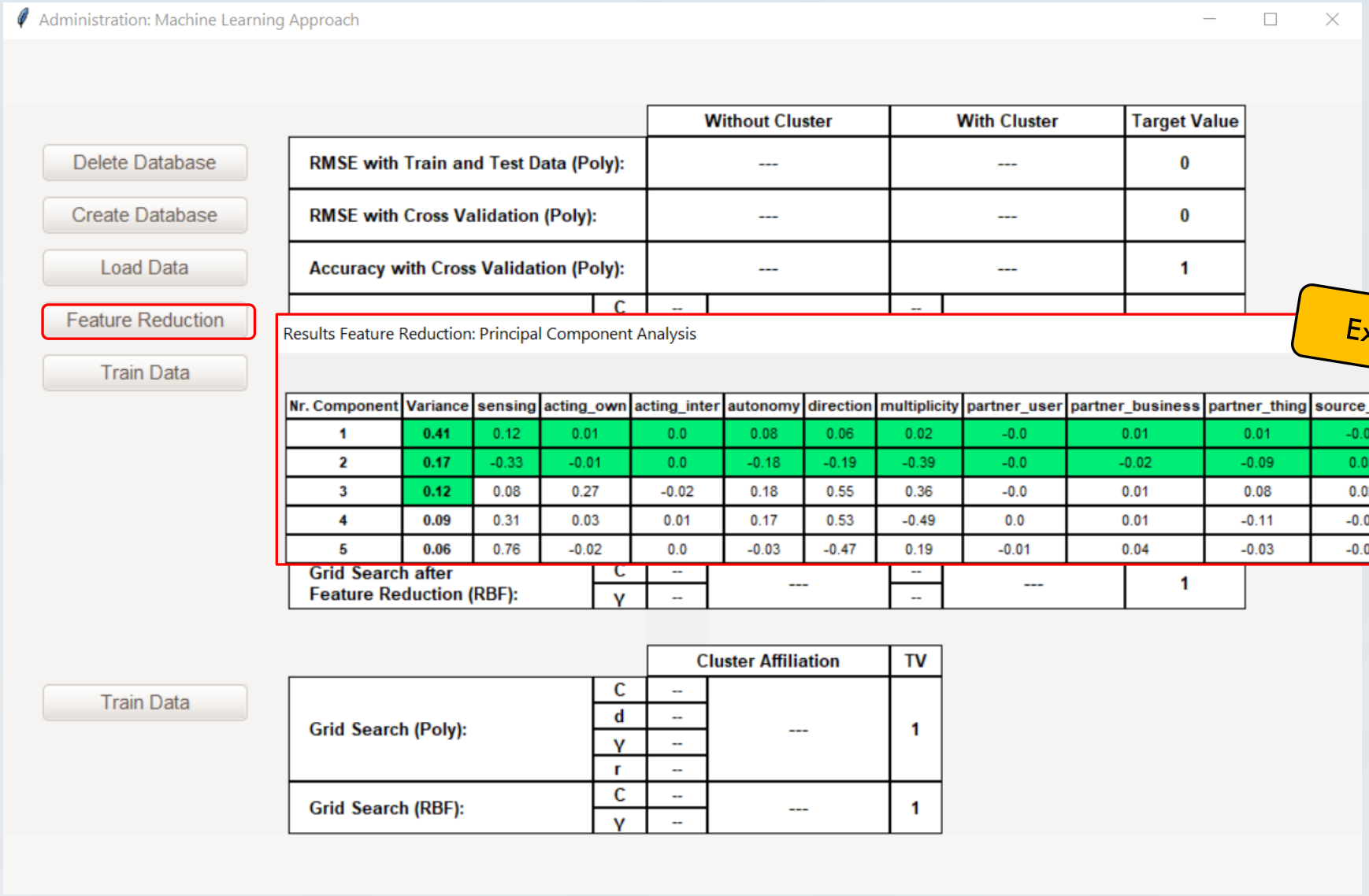
REALIZATION: BACKEND USER INTERFACE



		Without Cluster	With Cluster	Target Value
RMSE with Train and Test Data (Poly):		---	---	0
RMSE with Cross Validation (Poly):		---	---	0
Accuracy with Cross Validation (Poly):		---	---	1
Grid Search (Poly):	C	--	--	1
	d	--	--	
	γ	--	--	
	r	--	--	
Grid Search (RBF):	C	--	--	1
	γ	--	--	
Grid Search after Feature Reduction (Poly):	C	--	--	1
	d	--	--	
	γ	--	--	
	r	--	--	
Grid Search after Feature Reduction (RBF):	C	--	--	1
	γ	--	--	

		Cluster Affiliation	TV
Grid Search (Poly):	C	--	1
	d	--	
	γ	--	
	r	--	
Grid Search (RBF):	C	--	1
	γ	--	

REALIZATION: BACKEND USER INTERFACE



		Without Cluster	With Cluster	Target Value
RMSE with Train and Test Data (Poly):		---	---	0
RMSE with Cross Validation (Poly):		---	---	0
Accuracy with Cross Validation (Poly):		---	---	1
	C	--	--	

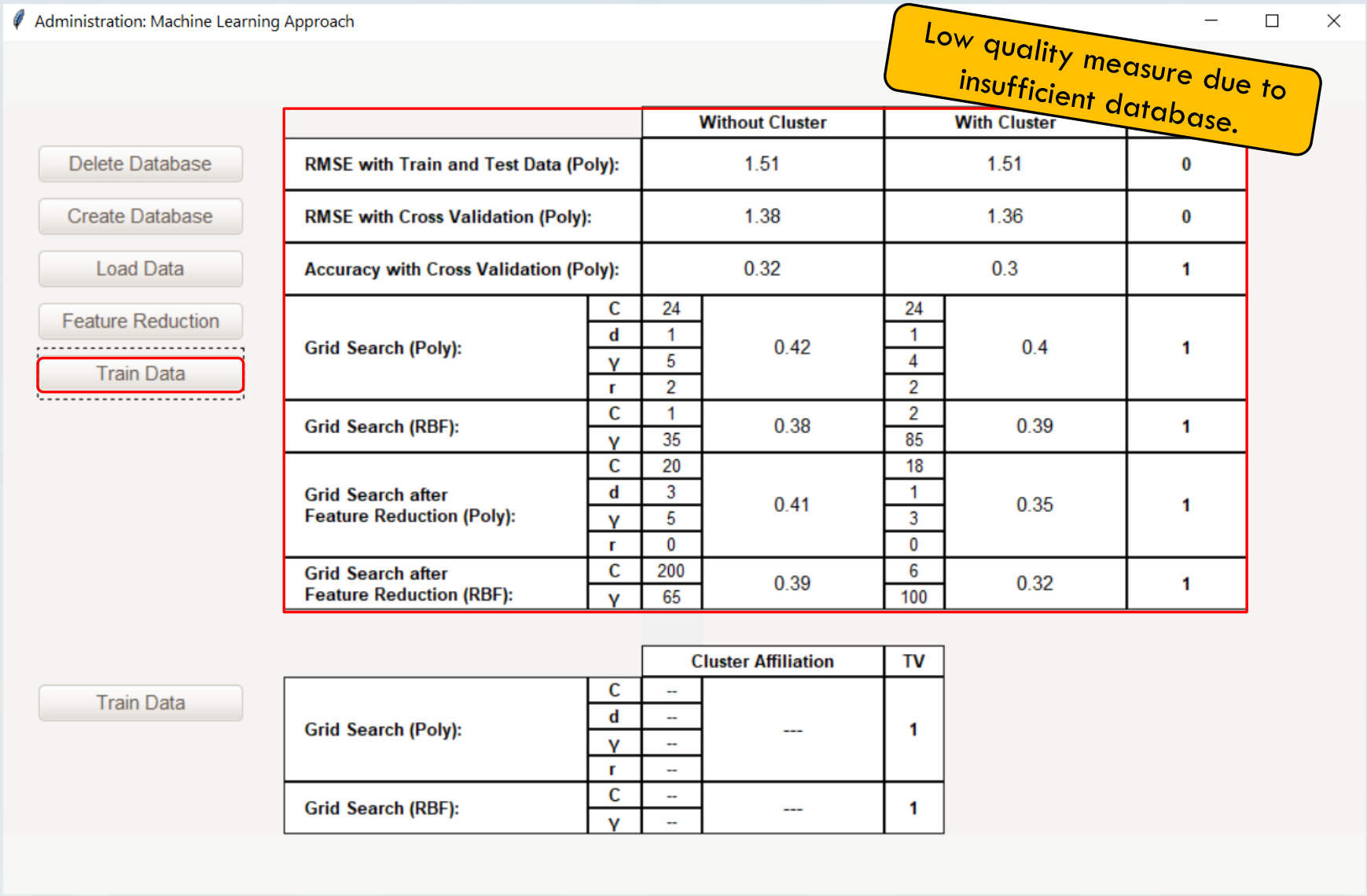
Results Feature Reduction: Principal Component Analysis

Nr. Component	Variance	sensing	acting_own	acting_inter	autonomy	direction	multiplicity	partner_user	partner_business	partner_thing	source_state	so
1	0.41	0.12	0.01	0.0	0.08	0.06	0.02	-0.0	0.01	0.01	-0.01	
2	0.17	-0.33	-0.01	0.0	-0.18	-0.19	-0.39	-0.0	-0.02	-0.09	0.03	
3	0.12	0.08	0.27	-0.02	0.18	0.55	0.36	-0.0	0.01	0.08	0.02	
4	0.09	0.31	0.03	0.01	0.17	0.53	-0.49	0.0	0.01	-0.11	-0.04	
5	0.06	0.76	-0.02	0.0	-0.03	-0.47	0.19	-0.01	0.04	-0.03	-0.01	

Grid Search after Feature Reduction (RBF):	C	--	---	--	---	1
	Y	--		--	

		Cluster Affiliation	TV
Grid Search (Poly):	C	--	---	1
	d	--		
	Y	--		
	r	--		
Grid Search (RBF):	C	--	---	1
	Y	--		

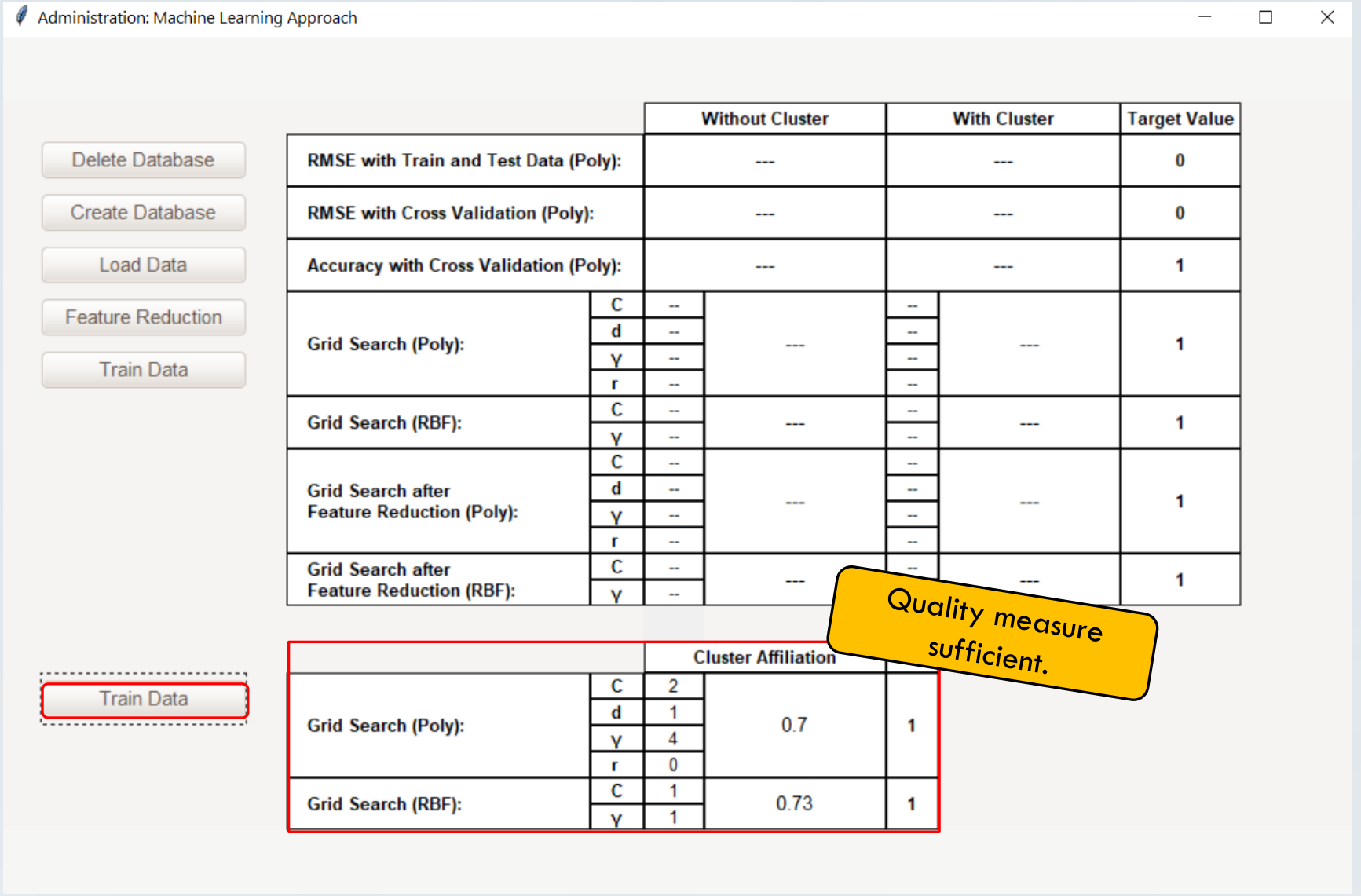
REALIZATION: BACKEND USER INTERFACE



		Without Cluster		With Cluster		
RMSE with Train and Test Data (Poly):		1.51		1.51		0
RMSE with Cross Validation (Poly):		1.38		1.36		0
Accuracy with Cross Validation (Poly):		0.32		0.3		1
Grid Search (Poly):	C	24	0.42	24	0.4	1
	d	1		1		
	γ	5		4		
	r	2		2		
Grid Search (RBF):	C	1	0.38	2	0.39	1
	γ	35		85		
Grid Search after Feature Reduction (Poly):	C	20	0.41	18	0.35	1
	d	3		1		
	γ	5		3		
	r	0		0		
Grid Search after Feature Reduction (RBF):	C	200	0.39	6	0.32	1
	γ	65		100		

		Cluster Affiliation		TV
Grid Search (Poly):	C	--	---	1
	d	--		
	γ	--		
	r	--		
Grid Search (RBF):	C	--	---	1
	γ	--		

REALIZATION: BACKEND USER INTERFACE



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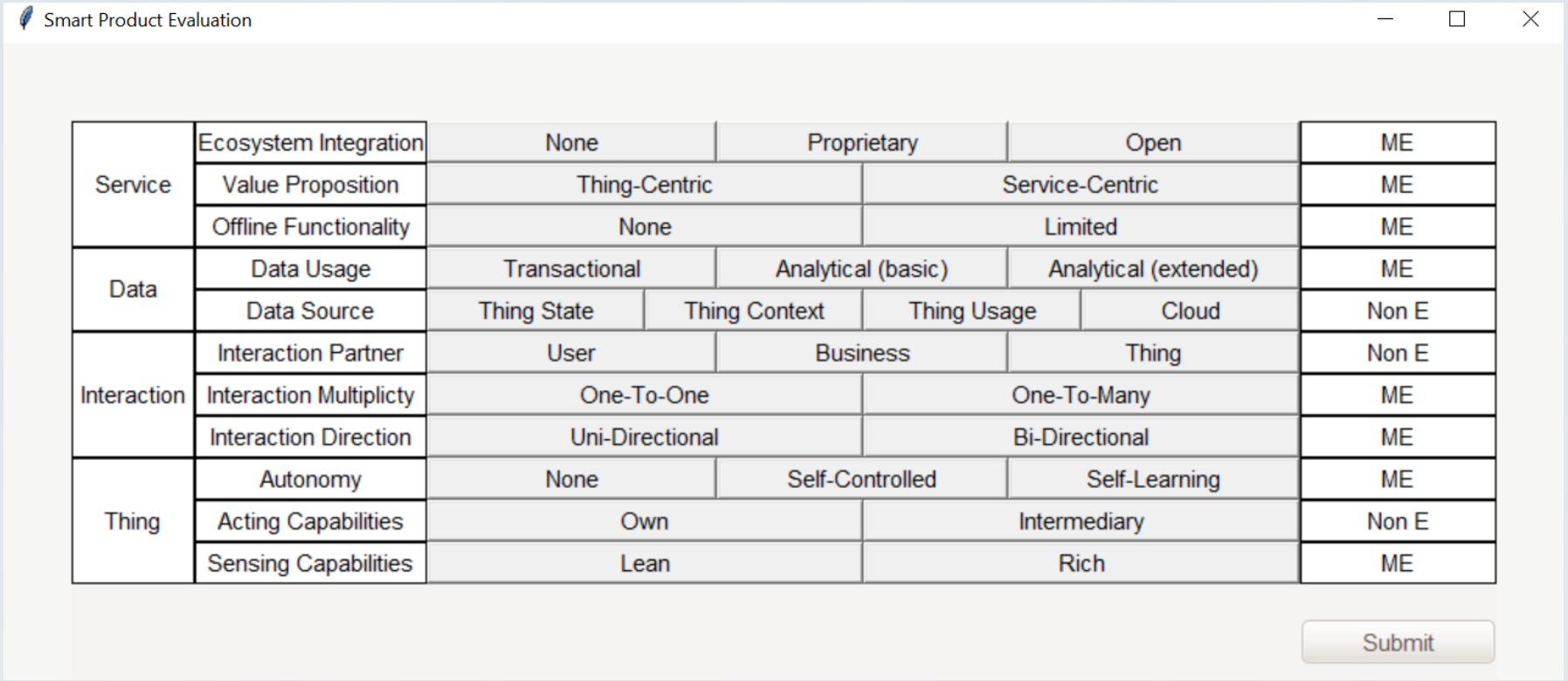
RMSE with Train and Test Data (Poly):		---		---		0
RMSE with Cross Validation (Poly):		---		---		0
Accuracy with Cross Validation (Poly):		---		---		1
Grid Search (Poly):	C	--	---	--	---	1
	d	--		--		
	γ	--		--		
	r	--		--		
Grid Search (RBF):	C	--	---	--	---	1
	γ	--		--		
Grid Search after Feature Reduction (Poly):	C	--	---	--	---	1
	d	--		--		
	γ	--		--		
	r	--		--		
Grid Search after Feature Reduction (RBF):	C	--	---	--	---	1
	γ	--				

		Cluster Affiliation		
Grid Search (Poly):	C	2	0.7	1
	d	1		
	γ	4		
	r	0		
Grid Search (RBF):	C	1	0.73	1
	γ	1		

REALIZATION: FRONTEND USER INTERFACE

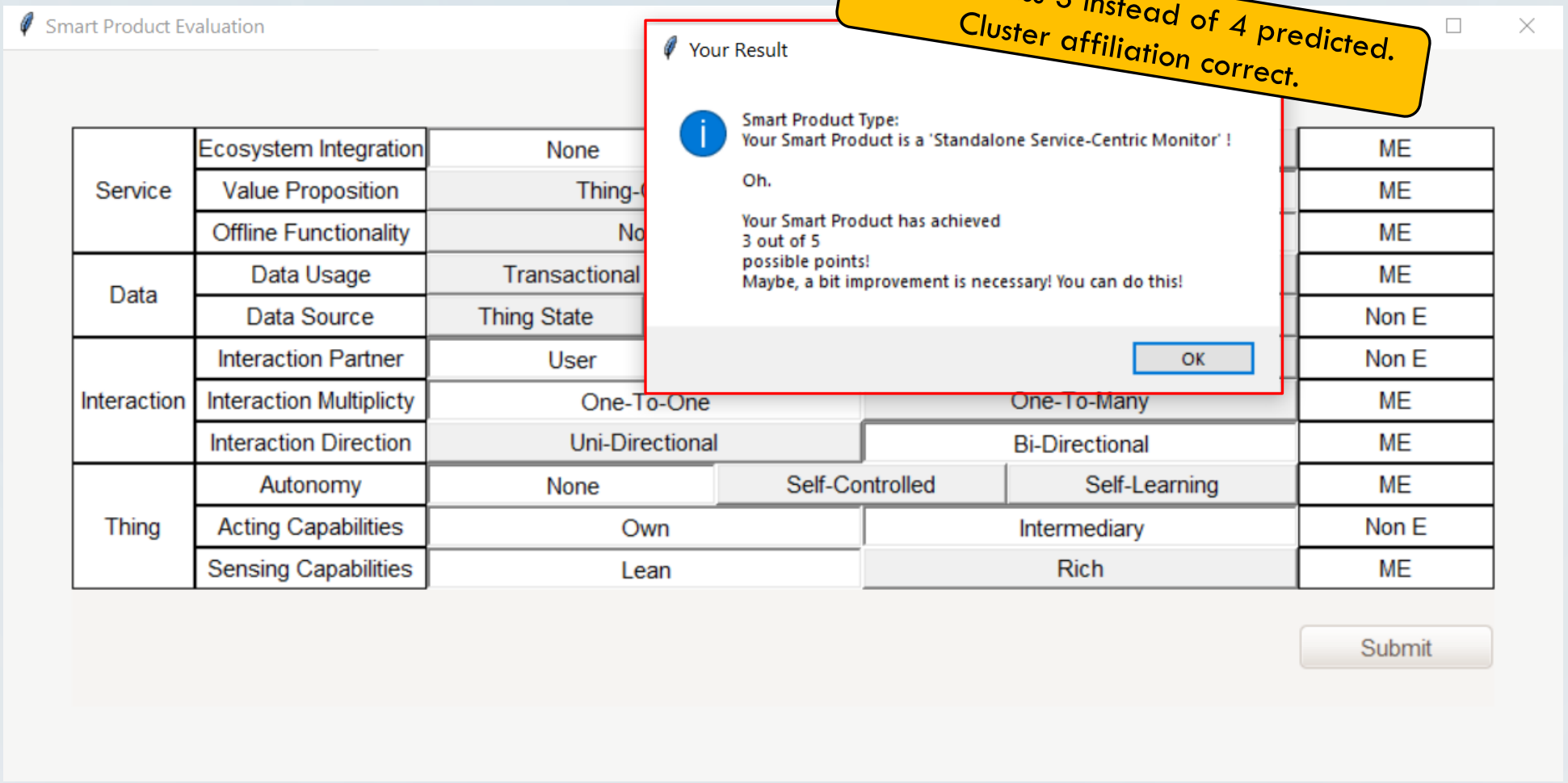


SHOW CASE USING THE EXAMPLE „FITBIT“

	Dimension	Characteristics			
Service	Ecosystem Integration	None	Proprietary	Open	
	Value Proposition	Thing-centric		Service-centric	
	Offline Functionality	None		Limited	
Data	Data Usage	Transactional	Analytical (basic)	Analytical (extended)	
	Data Source	Thing State	Thing Context	Thing Usage	Cloud
Interaction	Interaction Partner	User(s)	Business(es)	Thing(s)	
	Interaction Multiplicity	One-to-one		One-to-many	
	Interaction Direction	Unidirectional		Bi-directional	
Thing	Autonomy	None	Self-Controlled	Self-Learning	
	Acting Capabilities	Own		Intermediary	
	Sensing Capabilities	Lean		Rich	

Success: Classes 1 to 5. Devices in class **5 most successful**.
Fitbit in **class 4**, was **not part of** the **training data set**.

REALIZATION: FRONTEND USER INTERFACE



CONCLUSION

Learnings

- **Improvement of quality measures necessary** for the success of Smart Things
- Possible **reasons** for **insufficient results**:
  - **Too many features** (i.e. characteristics)
  - **Extension** of the **data set** by further Smart Things to achieve a representative sample
  - **Devices** with **similar characteristics** have **different degrees of success**

- Quality measures for **cluster allocation achieve good results**. Thus, assignment based on user input is possible

- **Evaluation** in comparison **with other methods** (e.g. neural networks)

OVERVIEW FILES CREATED DURING THE PROJECT