



Calcul Scientifique

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## Projet de Calcul Scientifique

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# 1.

## 1.1.

Matrix dimension	Matrix type	Exec. time for <code>eig</code> (s)	Exec. time for <code>power_v11</code> , (s)
$200 \times 200$	Type 1	9.000e-02	1.510e+00
$400 \times 400$	Type 1	4.000e-02	1.831e+01
$600 \times 600$	Type 1	6.000e-02	6.021e+01
$200 \times 200$	Type 2	3.000e-02	3.000e-02
$400 \times 400$	Type 2	4.000e-02	4.000e-02
$600 \times 600$	Type 2	7.000e-02	1.700e-01
$200 \times 200$	Type 3	1.000e-02	5.000e-02
$400 \times 400$	Type 3	3.000e-02	5.200e-01
$600 \times 600$	Type 3	7.000e-02	1.270e+00
$200 \times 200$	Type 4	2.000e-02	1.670e+00
$400 \times 400$	Type 4	3.000e-02	2.094e+01
$600 \times 600$	Type 4	6.000e-02	5.456e+01

Table 1: Execution time for different sizes and types of matrices

We can see that the `power_v11` algorithm is generally slower than the `eigen` function especially for the type 2 and 4 matrices.

## 1.2.

```

1  nb_it = 1;
2  norme = norm(beta*v - z, 2)/norm(beta,2);
3
4  while(norme > eps && nb_it < maxit)
5      beta_old = beta;
6      v = z/norm(z, 2);
7      z = A*v;
8      beta = (v'*z)/(v'*v);
9      norme = abs(beta-beta_old)/abs(beta_old);
10     nb_it = nb_it + 1;
11 end

```

Listing 1: Inner loop of the new algorithm

Matrix dimension	Matrix type	Exec. time for <code>power_v11</code> , (s)	Exec. time for <code>power_v12</code> , (s)
$200 \times 200$	Type 1	1.960e+00	3.200e-01
$400 \times 400$	Type 1	1.888e+01	2.660e+00
$600 \times 600$	Type 1	5.031e+01	7.070e+00
$200 \times 200$	Type 2	1.000e-02	1.000e-02
$400 \times 400$	Type 2	7.000e-02	1.000e-02
$600 \times 600$	Type 2	1.800e-01	4.000e-02
$200 \times 200$	Type 3	3.000e-02	1.000e-02
$400 \times 400$	Type 3	6.100e-01	1.100e-01
$600 \times 600$	Type 3	1.270e+00	2.600e-01

$200 \times 200$	Type 4	1.530e+00	2.900e-01
$400 \times 400$	Type 4	2.113e+01	3.060e+00
$600 \times 600$	Type 4	5.914e+01	6.480e+00

We can see that the `power_v12` algorithm is globally faster than the `power_v11`.

### 1.3.

The main drawback of the deflated power method is the numerous matrix-vector products required to compute the eigenvectors as well as the fact that each iteration compute only one eigenvalue which can be slow if a lot of eigenvalues are desired.

### 1.4.

If we apply Algorithm 1 to  $m$  vectors, there is no reason for the columns of  $V$  to converge to a base. Each vector will converge toward a different projection of the dominant eigenvalue.

### 1.5.

In Algorithm 2, the matrix  $H$  is a smaller matrix, with dimension  $n \times m$ , therefore, even for larger matrices  $A$ , computing the spectral decomposition of  $H$  will not be computationally expensive.

### 1.6.

### 1.7.

```

1: function SUBSPACE ITER V1 (RALEIGH-RITZ PROJECTION)
2:   Input :  $A \in \mathbb{R}^{n \times n}, \epsilon, \text{MaxIter}, \text{PercentTrace}$ 
3:   Output :  $n_{\text{ev}}$  dominant eigenvectors  $V_{\text{out}}$  and the corresponding eigenvalues  $\Lambda_{\text{out}}$ 
4:   Generate an initial set of  $m$  orthonormal vectors  $V \in \mathbb{R}^{n \times m}; k = 0; \text{PercentReached} = 0$ 
5:   repeat until  $\text{PercentReached} > \text{PercentTrace} \vee n_{\text{ev}} = m \vee k > \text{MaxIter}$ 
6:      $k \leftarrow k + 1$ 
7:     Compute  $Y$  such that  $Y = A \cdot V$ 
8:      $V \leftarrow$  orthonormalisation of the columns of  $Y$ 
9:     Rayleigh-Ritz projection applied on matrix  $A$  and orthonormal vectors  $V$ 
10:    Convergence analysis step: save eigenpairs that converged and update PercentReached
```

### 1.8.

### 1.9.

### 1.10.

Matrix dimension	Matrix type	Flops for subspace_iter0	Flops for subspace_iter1	Flops for subspace_iter2	p ( $A^p$ )
$200 \times 200$	Type 1	2309	263	132	2
$200 \times 200$	Type 1	2309	263	88	3
$200 \times 200$	Type 1	2309	263	53	5
$200 \times 200$	Type 1	2309	263	27	10

When increasing the value of  $p$  to compute  $A^p$  in `subspace_iter2`, the number of flops to compute the results is :  $\text{Flops}(\text{iter2}) \simeq \frac{\text{Flops}(\text{iter2})}{p}$ .

1.11.

1.12.

By freezing the converged columns, the algorithm will not have to recalculate them everytime. Which means that the accuracy for the eigenpairs will be more equal. The first and last will have the same approximate size.

2.

2.1.

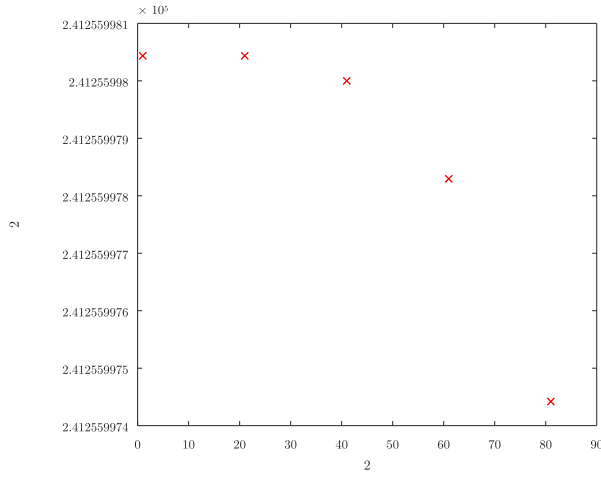


Figure 1: eig method

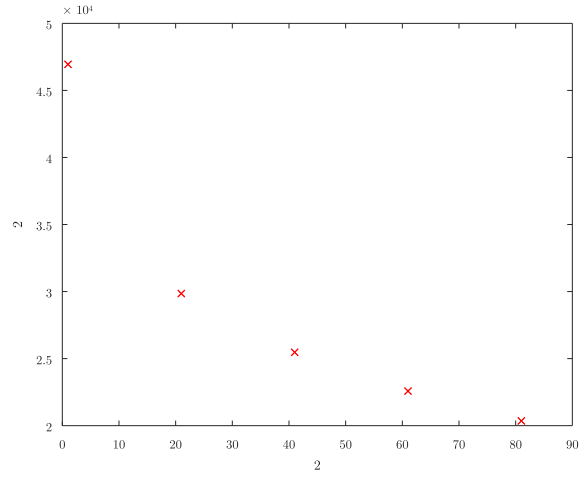


Figure 2: power method

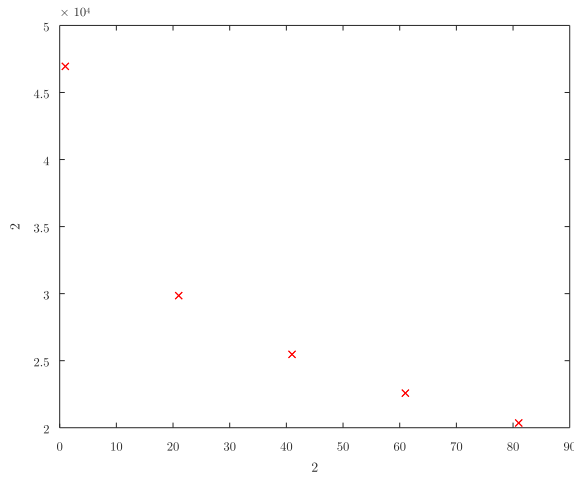


Figure 3: subspace\_iter0 method

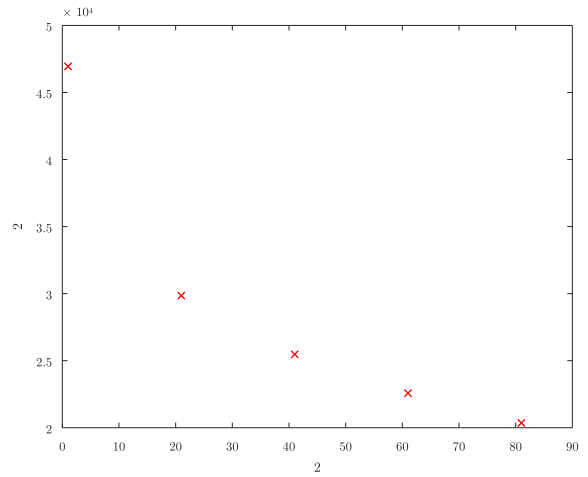


Figure 4: subspace\_iter1 method

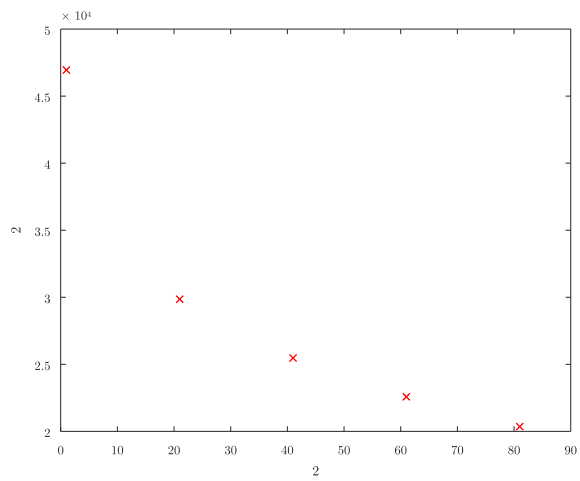


Figure 5: subspace\_iter2 method