

## Custom Input Signal Generation

Folder: ../demos/other possibilities/customInputSignal/

Relevant matlab scripts:

*staliro\_demo\_custom\_input\_signal.m*

*CustomInputSignal\_FixedTime.m*

*CustomInputSignal\_VarTime.m*

In this document, we demonstrate two custom functions for generating input signals for S-TaLiRo. You can run the *staliro\_demo\_custom\_input\_signal.m* script which utilizes *CustomInputSignal\_FixedTime.m* and *CustomInputSignal\_VarTime.m* functions.

### Variable Time

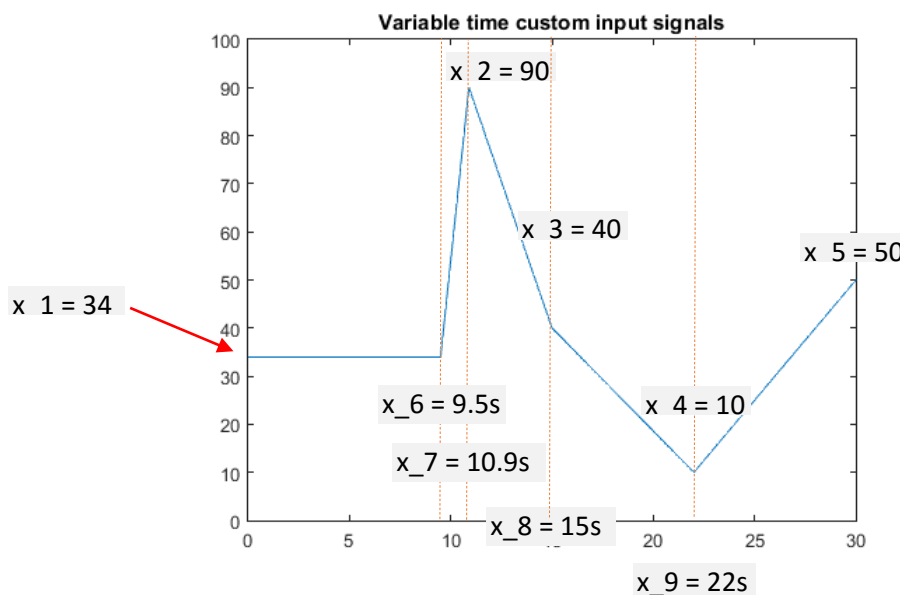
We would like generate input signals that have the following characteristics. The input signal should be within a certain range and remain constant for at least 5 seconds. After, the signal is interpolated at varying time points. As an example, we will utilize 9 control points  $x_1 \dots x_9$ .

- $x_1$ : constant state value for at least 5 seconds between 0 and 100
- $x_2$ - $x_5$ : interpolated state values between 0 and 100
- $x_6$ - $x_9$ : varying time control points between 5 and 30 over which  $x_2$ - $x_5$  are interpolated

Since  $x_6$ - $x_9$  are time control points we have to constrain the search space so that:

1.  $x_6 < x_7 < x_8 < x_9$  and
2. for all  $i$ ,  $5 < x_i \leq 30$  (which is the total simulation time)

An example signal:



### Fixed time

Here, we have similar signal characteristics. The signal should be constant for exactly 5 seconds. After, the signal is interpolated in fixed, equidistant time points over 9 control points  $x_1 \dots x_9$ .

$x_1$ : constant state value for 5 seconds between 0 and 100

$x_2$ - $x_9$ : interpolated state values between 0 and 100

An example signal:

