# MATH255 - Honours Analysis 2

Summary of Results

Winter, 2024 Notes by Louis Meunier Complete notes

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## 1 Point-Set Topology

Topology is about abstracting openness. It can typically suffice to consider open, closed sets in  $\mathbb{R}$  for intuition, but is obviously not all-general.

**Definition 1** (Metric Space). A space X equipped with a function  $d: X \times X \to [0, \infty)$  is called a metric space and d a metric or distance if

• 
$$d(x,y) = d(y,x) \ge 0$$

• 
$$d(x, y) = 0 \iff x = y$$

• 
$$d(x,y) + d(y,z) \ge d(x,z)$$

for any  $x, y, z \in X$ .

**Definition 2** (Normed Vector Space). A function  $||\cdot||: X \to \mathbb{R}$  defined on a vector space X over  $\mathbb{R}$  is a norm if

- $||x|| \ge 0$
- $||x|| = 0 \iff x = 0$
- $\bullet ||c \cdot x|| = |c| ||x||$
- $||x + y|| \le ||x|| + ||y||$ ,

for any  $x, y \in X$ ,  $c \in \mathbb{R}$ .

*Remark* 1. We can naturally extend this to arbitary fields, but seeing as this is a course in Real Analysis, we won't.

**Proposition 1.** For a normed vector space  $(X, ||\cdot||)$ , d(x, y) := ||x - y|| is a metric on X. We call such a metric the one "induced" by the norm.

**Definition 3** (Topological Set). A set X is a topological set if we have a collection  $\tau$  of subsets of X, called open sets, such that

- $\emptyset \in \tau, X \in \tau$
- For  $A_{\alpha} \in \tau$  for  $\alpha$  in any I (potentially infinite),  $\bigcup_{\alpha \in I} A_{\alpha} \in \tau$
- For  $A_{\alpha} \in \tau$  for  $\alpha \in J$  where J finite, then  $\bigcap_{\alpha \in J} A_{\alpha} \in \tau$

ie, arbitrary unions of open sets are open, and finite intersections of open sets are open.

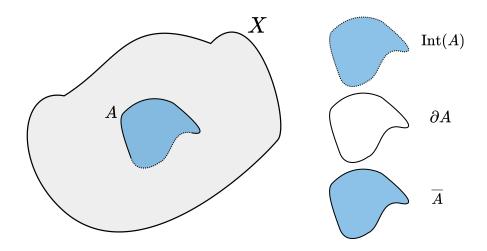
Remark 2. Keep  $\mathbb{R}$  in mind when initially working with these definitions; for instance, the set  $A_n := (0, \frac{1}{n})$  open in  $\mathbb{R}$  for any  $n \in \mathbb{N}$ , but  $\bigcap_{n \in \mathbb{N}} A_n = \{0\}$  which is closed.

*Remark* 3. Complementing each of these requirements gives similar definitions for closed sets of *X*.

**Definition 4** (Topology on a Metric Space). A subset  $A \subseteq X$  open iff  $\forall x \in A, \exists r = r(x) \in \mathbb{R}$ , where r(x) > 0, such that  $B(x, r(x)) := \{y \in x : d(x, y) < r(x)\} \subseteq A$ . We call such a B an open ball, and  $\overline{B}$  a closed ball with the same definition replacing the strict inequality with  $\leq$ .

*Remark* 4. While many of the spaces we look at our metric spaces that induce a topology as such, **not all topological spaces are metric spaces**. Indeed, "metrizability" (ie, equipping a topological space *X* with a metric that respects the open sets) is not a trivial activity.

**Definition 5** (Equivalence of Metrics). We say two metrics on X are equivalent if they admit the same topology; a sufficient condition is that,  $\forall x \neq y \in X$ ,  $\exists 1 < C < \infty$  such that  $\frac{1}{C} < \frac{d_1(x,y)}{d_2(x,y)} < C$ , then  $d_1, d_2$  equivalent, where C independent of x, y.



**Definition 6** (\* Interior, Boundary, Closure). Let *X*-topological space,  $A \subseteq X$ ,  $x \in X$ .

- If  $\exists U$ -open s.t.  $x \in U \subseteq A$ , then we write  $x \in Int(A)$ , the interior of A.
- If  $\exists V$ -open s.t.  $x \in V \subseteq A^C$ , then  $x \in Int(A^C)$ .
- If  $\forall U$ -open s.t.  $x \in U, U \cap A \neq \emptyset$  and  $U \cap A^C \neq \emptyset$ , then  $x \in \partial A$ , the boundary of A.

We put  $\overline{A} := \operatorname{Int}(A) \cup \partial A$ , the closure of A. Equivalently,  $x \in \overline{A} \iff$  for every open set  $U : x \in U$ ,  $U \cap A \neq \emptyset$ . We call  $x \in \overline{A}$  the limit points of A.

*Remark* 5. The limit point interpretation of the closure can be more intuitive; the points that we can get "arbitrary close to" are the closure. For instance,  $\overline{(a,b)} = [a,b] \subseteq \mathbb{R}$  with the standard topology.

**Proposition 2.** Let  $A \subseteq X$ -topological space. Then, Int(A) is open, the largest open set contained in A, the union of all open sets contained in A, and Int(Int(A)) = Int(A). Also,  $\overline{A}$  closed, the smallest closed set that contains A,  $\overline{A}$  the intersection of all closed sets that A is contained in, and  $\overline{\overline{A}} = \overline{A}$ .

**Corollary 1.** A open 
$$\iff$$
  $A = Int(A)$  and A closed  $\iff$   $A = \overline{A}$ 

*Remark* 6. Remark that these are not exclusive, nor indeed the only possibilities.

**Definition 7** (Basis). A basis for a topology X with open sets  $\tau$  is a collection  $B \subseteq \tau$  such that every  $U \in \tau$  a union of sets in B.

*Remark* 7. Don't think about bases for vector spaces in this regard - there is no "minimality" requirement.

Keep in mind  $\{(a, b) : -\infty < a < b < \infty\}$ , a basis of topology on  $\mathbb{R}$ .

**Proposition 3.** For a metric space (X, d),  $\{B(x, r) : x \in X, r > 0\}$  a basis of topology.

**Definition 8** (Subspace Topology). For a subset  $Y \subseteq X$ -topological space, we define the subspace topology on Y as  $\tau_Y := \{Y \cap U : U \in \tau\}$ .

**Definition 9** (\* Continuous). For X, Y-topological spaces, a function  $f: X \to Y$  is continuous iff  $\forall V$ -open in Y,  $f^{-1}(V)$ -open in X.

*Remark* 8. One can verify that this is consistent with the  $\varepsilon - \delta$  definition of continuity for functions on  $\mathbb{R}$ .

**Theorem 1** (Continuity of Composition). *If*  $f: X \to Y$ ,  $g: Y \to Z$  *continuous*,  $g \circ f$  *continuous*.

*Remark* 9. Note how much easier this is to prove via toplogical spaces than the  $\varepsilon - \delta$  definition.

**Definition 10** (Product Space). For an index set I and  $X_{\alpha}$ ,  $\alpha \in I$ , we define  $\prod_{\alpha \in I} X_{\alpha}$  as a product space; I may be finite or infinite.

**Proposition 4.** A basis for the product space is given by cyliders of the form  $A = \prod_{\alpha \in J} A_{\alpha} \times \prod_{\alpha \notin J} X_{\alpha}$  for  $A_{\alpha}$ -open in  $X_{\alpha}$ , where  $J \subseteq I$ -finite.

**Definition 11** (Compact). A set  $A \subseteq X$  is compact if every cover has a finite subcover, that is

$$A \subseteq \bigcup_{\alpha \in I} U_{\alpha}$$
-open  $\Longrightarrow \exists \{\alpha_1, \dots, \alpha_n\} \subseteq I \text{ s.t. } A \subseteq \bigcup_{i=1}^n U_{\alpha_i}.$ 

**Proposition 5.** Closed intervals [a,b] compact in  $\mathbb{R}$ .

**Proposition 6.**  $A \subseteq \mathbb{R}^n$  compact  $\iff$  closed and bounded.

**Definition 12** (Connected). X is said to not be connected if  $X = U \cup V$  for U, V open, nonempty, disjoint. If X cannot be written as such, X is said to be connected.

**Theorem 2.** If X connected and  $f: X \to Y$ , then f(X) connected in Y.

**Proposition 7.** *Intervals in*  $\mathbb{R}$  *are connected.* 

**Theorem 3** (\* Intermediate Value Theorem). *If* X *connected,*  $f: X \to \mathbb{R}$  *continuous, then* f *takes intermediate value; if* a = f(x), b = f(y) *for*  $x, y \in X$  *with* a < b, *then for any* a < c < b  $\exists z \in X \text{ s.t. } f(z) = c$ .

**Theorem 4.** For X compact,  $f: X \to Y$  continuous, f(X) compact in Y.

**Proposition 8.** For X compact and  $f: X \to \mathbb{R}$ , f attains both max and min on X.

**Definition 13** (Path Connected). A set  $A \subseteq X$  is path connected if for any  $x, y \in A, \exists f : [a,b] \to X$  continuous such that  $f(a) = x, f(b) = y, f([a,b]) \subseteq A$ .

**Theorem 5.** Path connected  $\implies$  connected.

For open sets in  $\mathbb{R}^n$ , the converse holds too.

**Definition 14** (Connected Component, Path Component). For  $x \in X$ , the connected component of x is the largest connected subset of X containing x and the path component of x is the largest path connected subset of X containing x.

#### 2 METRIC SPACES

We discuss mostly the metric on  $\ell_p$  space and notions of completeness, as well as some topological results specific to metric spaces, namely compactness.

**Definition 15**  $(\ell_p)$ . For  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$  and  $1 \le p \le +\infty$ , we define

$$||x||_p := \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}, \quad ||x||_{\infty} := \max_{i=1}^n |x_i|,$$

and similarly, for sequences  $x = (x_1, ..., x_n, ...)$ ,

$$||x||_p := \left(\sum_{i=1}^{\infty} |x_i|^p\right)^{\frac{1}{p}}, \quad ||x||_{\infty} := \sup_{i=1}^{\infty} |x_i|,$$

and define  $\ell_p := \{x : ||x||_p < +\infty\}$ . It can be shown that these are well-defined norms on their respective spaces.

**Theorem 6** (Holder, Minkowski's Inequalities). For  $x = (x_1, ..., x_n)$ ,  $y = (y_1, ..., y_n)$  and p, q such that  $\frac{1}{p} + \frac{1}{q} = 1$ , then

Holder's: 
$$\langle x, y \rangle = \left| \sum_{i=1}^{n} x_i y_i \right| \le ||x||_p ||y||_q$$

and

*Minkowski's*: 
$$||x + y||_p \le ||x||_p + ||y||_p$$
.

The identical inequalities hold for infinite sequences.

**Definition 16** (Completeness). We say a metric space is complete if every Cauchy sequence converges to a limit point in the space.

**Proposition 9.** For  $\{x_n\}_{n\in\mathbb{N}}$ ,  $\ell_p$  complete for any  $1 \le p \le +\infty$ .

**Proposition 10.** *If* p < q,  $\ell_p \subseteq \ell_q$ .

**Definition 17** (Contraction Mapping). For a metric space (X, d), a function  $f: X \to X$  is a contraction mapping if there exists 0 < c < 1 such that

$$d(f(x), f(y)) \le c \cdot d(x, y)$$

for any  $x, y \in X$ .

**Theorem 7.** Let (X, d) be a complete metric space,  $f: X \to X$  a contraction. Then, there exist a unique fixed point z of f such that f(z) = z; ie  $\lim_{n \to \infty} f^n(x) = \lim_{n \to \infty} f \circ f \circ \cdots \circ f(x) = z$  for any  $x \in X$ .

**Theorem 8.**  $\ell_p$  *complete.* 

*Remark* 10. It can be kind of funky to work with sequences in  $\ell_p$ , since the elements of  $\ell_p$  themselves sequences so we have "sequences of sequences".

**Definition 18** (Totally bounded). A metric space X is said to be totally bounded if  $\forall \varepsilon > 0 \exists x_1, \dots, x_n \in X$ ,  $n = n(\varepsilon)$  such that  $\bigcup_{i=1}^n B(x_i, \varepsilon) = X$ .

**Definition 19** (Sequentially compact). A metric space *X* is said to be sequentially compact if every sequence has a convergent subsequence.

**Theorem 9** ( $\star$  Equivalent Notions of Compactness in Metric Spaces). *Let* (X, d) a metric space. TFAE:

- *X compact*
- *X complete and totally bounded*
- *X* sequentially compact

*Remark* 11. This is for a metric space, not a general topological space! Hopefully this is clear because some of the requirements necessitate a distance.

#### 3 DIFFERENTIATION

**Definition 20** (Differentiable). f(x) differentiable at c if  $\lim_{x\to c} \frac{f(x)-f(c)}{x-c}$  exists, and if so we denote the limit f'(c).

Alternatively, one can view differentiation as a linear map between spaces of differentiable functions.

**Theorem 10.** Differentiable  $\implies$  continuous.

*Proof.* Short enough to write the full proof;  $\lim_{x\to c} (f(x) - f(c)) = \lim_{x\to c} (x-c) \frac{f(x)-f(c)}{x-c} = 0 \cdot f'(c) = 0.$ 

**Theorem 11** (Caratheodory's). For  $f: I \to \mathbb{R}$ ,  $c \in I$ , f differentiable at c iff  $\exists \varphi: I \to \mathbb{R}: \varphi$  continuous at c,  $f(x) - f(c) = \varphi(x)(x - c)$ .

*Sketch.* Its worth recalling the definition of  $\varphi$  for the forward implication,

$$\varphi(x) := \begin{cases} \frac{f(x) - f(c)}{x - c} & x \neq c \\ f'(c) & x = c \end{cases}.$$

The converse follows by taking limits.

*Remark* 12. While not a particularly enlightening result, it is helpful in proofs of the chain rule, etc.

**Theorem 12** (\* Chain Rule). Let  $f: J \to \mathbb{R}$ ,  $g: I \to R$  s.t.  $f(J) \subseteq I$ . If f(x) differentiable at c and g(y) at f(c),  $g \circ f$  differentiable at c with  $(g \circ f)'(c) = g'(f(c)) \cdot f'(c)$ .

Sketch. Apply Caratheodory's to f at c and g at f(c), and compose.

**Theorem 13** ( $\star$  Rolle's). Let  $f:[a,b] \to \mathbb{R}$  continuous. If f'(x) exists on (a,b) and f(a) = f(b) = 0,  $\exists c \in (a,b) : f'(c) = 0$ .

*Sketch.* If constant function, done. Else, assuming function positive, it obtains a maximum, and thus its derivative 0 at this point.

**Theorem 14** (\* Mean Value). Let f continuous on [a,b] and differentiable on (a,b). Then,  $\exists c \in (a,b)$  such that f(b) - f(a) = f'(c)(b-a).

Sketch. Let  $\phi(x) := f(x) - f(a) - \frac{f(b) - f(a)}{(b - a)}(x - a)$ . Then  $\phi(a) = \phi(b) = 0$  so applying Rolle's  $\exists c \in (a, b) : \phi'(c) = 0 = f'(x) - \frac{f(b) - f(a)}{b - a}$ . The proof is done after rearranging.

**Proposition 11** (L'Hopital's). If f, g:  $[a,b] \to \mathbb{R}$  with f(a) = g(a) = 0,  $g(x) \neq 0$  on a < x < b, f, g differentiable at x = 0 with  $g'(a) \neq 0$ , then  $\lim_{x \to a^+} \frac{f(x)}{g(x)}$  exists and is equal to  $\frac{f'(a)}{g'(a)}$ .

*Remark* 13. Other versions exist, but this is certainly one of them.

**Theorem 15** ( $\star$  Taylor's). Let  $f \in C^n([a,b])$  such that  $f^{(n+1)}(x)$  exists on (a,b). Let  $x_0 \in [a,b]$ , then, for any  $x \in [a,b]$ ,  $\exists c$  between x,  $x_0$  such that

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 + \dots + \frac{f^{(n)}(x_0)}{n!}(x - x_0)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(x - x_0)^{n+1}.$$

**Corollary 2.** Let  $x_0 \in [a,b]$ . With the same assumptions as Taylor's (but in a neighborhood of  $x_0$ ), with  $f'(x_0) = f''(x_0) = \cdots = f^{(n-1)}(x_0) = 0$  and  $f^{(n)}(x_0) \neq 0$ , then

- *n even; then f has a local minimum at*  $x_0$  *if*  $f^{(n)}(x_0) > 0$  *and a local max if*  $f^{(n)}(x_0) < 0$ .
- *n odd; neither.*

Sketch. Apply Taylor's and gaze.

### 4 Integration

## Its all just rectangles.

**Definition 21** (Riemann Integration). Consider an interval (a, b). We call a subdivision  $\mathcal{P} := \{a = x_0, x_1, \dots, x_{n-1}, x_n = b\}$  a partition, and  $\dot{\mathcal{P}}$  a marked partition if in addition we are given a point  $t_i \in (x_i, x_{i+1}]$  for each interval in  $\dot{\mathcal{P}}$ .

We put diam( $\mathcal{P}$ ) := max<sub>i=1</sub><sup>n</sup> |x<sub>i</sub> - x<sub>i-1</sub>|.

We define the Riemann sum  $S(f, \dot{\mathcal{P}}) := \sum_{i=1}^{n} f(t_i)(x_i - x_{i-1})$ , and say that f Riemann integrable on [a, b] if  $S(f, \dot{\mathcal{P}}) \to L$  as  $\operatorname{diam}(\dot{\mathcal{P}}) \to 0$  for any choice of tag  $t_i$ , and write  $f \in \mathcal{R}([a, b])$ 

More precisely, if  $\forall \varepsilon > 0$ ,  $\exists \delta > 0$ : diam( $\mathcal{P}$ )  $< \delta$ , then for any  $t_i \in [x_i, x_{i+1}]$ ,  $|L - S(f, \dot{\mathcal{P}})| < \varepsilon$ . We then say the (Riemann) integral of f over [a, b] is L and write  $\int_a^b f(x) dx = L$ .

**Proposition 12.** Riemann integrals are unique, linear in f(x), and respect inequalities (if  $f \le g$  on [a,b],  $\int_a^b f(x) dx \le \int_a^b g(x) dx$  if both in  $\mathcal{R}([a,b])$ )

**Proposition 13** ( $\star$ ).  $f \in \mathcal{R}[a,b] \implies f$  bounded on [a,b]

**Proposition 14** (\* Cauchy Criterion for Integrability).  $f \in \mathcal{R}[a,b] \iff \forall \varepsilon > 0, \exists \delta > 0 : if$   $\dot{P}$  and  $\dot{Q}$  are tagged partitions of [a,b] s.t. diam  $\dot{P} < \delta$  and diam  $\dot{Q} < \delta$ , then  $|S(f,\dot{P}) - S(f,\dot{Q})| < \varepsilon$ 

Remark 14. Ala Cauchy Sequence.

**Theorem 16** (Squeeze Theorem).  $f \in \mathcal{R}[a,b] \iff \forall \varepsilon > 0, \exists \alpha_{\varepsilon}, \omega_{\varepsilon} \in \mathcal{R}[a,b] : \alpha_{\varepsilon} \leq f \leq \omega_{\varepsilon} \text{ and } \int_{a}^{b} (\omega_{\varepsilon} - \alpha_{\varepsilon}) < \varepsilon.$ 

**Lemma 1.** Let  $J := [c, d] \subseteq [a, b]$  and  $\varphi_J(x) := \begin{cases} 1 & x \in J \\ 0 & x \notin J \end{cases}$  be the indicator function of J. Then  $\varphi_J \in \mathcal{R}[a, b]$  and  $\int_a^b \varphi_J = d - c$ .

*Remark* 15. Helpful for "approximations"; follows by linearity, induction that step functions (ie sums of indicator functions times constants) are integrable.

**Theorem 17** ( $\star$  Continuous). f continuous on  $[a, b] \implies f \in \mathcal{R}[a, b]$ 

Sketch. Continuity on a closed interval gives uniform continuity and so a "universal  $\delta$ "; then, for any partition, take the x such that f attains its minimum and maximum, and define a  $\alpha_{\varepsilon}$ ,  $\omega_{\varepsilon}$  as the sum of indicator functions taking the minimum, maximum of f respectively on each partition. Then apply the previous theorem and the squeeze theorem.

**Theorem 18** (Additivity).  $f \in \mathcal{R}[a,b] \iff f \in \mathcal{R}[a,c] \text{ and } f \in \mathcal{R}[c,b], \text{ and } \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx.$ 

**Theorem 19** (\* Fundamental Theorem of Calculus). Let  $F, f : [a, b] \to \mathbb{R}$  and  $E \subseteq [a, b]$  a finite set, such that F continuous on  $[a, b], F'(x) = f(x) \forall x \in [a, b] \setminus E, f \in \mathcal{R}[a, b]$ . Then  $\int_a^b f(x) = F(b) - F(a)$ . We call F the "primitive" of f.

**Theorem 20.** For  $f \in \mathcal{R}[a,b]$  and any  $z \in [a,b]$ , put  $F(z) := \int_a^z f(x) dx$ . Then, F continuous on [a,b].

**Theorem 21** (\* Fundamental Theorem of Calculus p2). For  $f \in \mathcal{R}[a,b]$  continuous at c, then F(z) differentiable at c and F'(c) = f(c).

**Definition 22** (Lebesgue Measure). We say a set  $A \subseteq \mathbb{R}$  has Lebesgue measure 0 iff  $\forall \varepsilon > 0$ , A can be covered by a union of intervals  $J_k$  such that  $\sum_k |J_k| \le \varepsilon$ . We then call A a "null set".

In particular, any countable set is a null set.

**Theorem 22** (\* Lebesgue Integrability Criterion). Let  $f : [a,b] \to \mathbb{R}$  be bounded. Then  $f \in \mathcal{R}[a,b] \iff$  the set of discontinuities of f has Lebesgue measure  $f \in \mathcal{R}[a,b]$ .

Remark 16. In particular, remark that continuity a stronger requirement than integrability.

**Theorem 23** (Composition). *If*  $f \in \mathcal{R}[a,b]$ ,  $\varphi : [c,d] \to \mathbb{R}$  *continuous and*  $f([a,b]) \subseteq [c,d]$ , *then*  $\varphi \circ f \in \mathcal{R}[a,b]$ .

**Theorem 24** (Integration by Parts). *If* F, G *differentiable* [a,b] *with* f := F', g := G', and f,  $g \in \mathcal{R}[a,b]$ , then

$$\int_a^b f(x)G(x) dx = F(x)G(x) \Big|_a^b - \int_a^b F(x)g(x) dx.$$

Sketch. Uses additivity and the fundamental theorem of calculus.

**Theorem 25** (Taylor's Theorem, Remainder's Version). *Suppose*  $f', f'', \ldots, f^{(n)}$  *exist on* [a, b] *and*  $f^{(n+1)} \in \mathcal{R}[a, b]$ . *Then* 

$$f(b) = f(a) + \frac{f'(a)}{1!}(b-a) + \frac{f''(a)}{2!}(b-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(b-a)^n + R_n,$$

where  $R_n := \frac{1}{n!} \int_a^b f^{(n+1)}(t)(b-t)^n dt$ .

#### 5 Sequences of Functions

A good motivation to keep in mind with the "types" of function-sequence convergence is to answer the question: when can we exchange limits of derivatives of functions and derivatives of limits of functions? What about integrals? What about summations (see next section)? Ie, when does  $\lim_{n\to\infty} f_n'(x) = \frac{\mathrm{d}}{\mathrm{d}x} \lim_{n\to\infty} f_n(x)$ , etc.

**Definition 23** (Pointwise, Uniform Convergence). We say  $f_n \to f$  pointwise on E if  $\forall x \in E$ ,  $f_n(x) \to f(x)$  as  $n \to \infty$ .

We say  $f_n \to f$  uniformly on E if  $\forall \varepsilon > 0, \exists N \in \mathbb{N}$  such that  $\forall n \ge N, x \in E$ ,  $|f_n(x) - f(x)| < \varepsilon$ .

*Remark* 17. Pointwise doesn't care about the "rate of convergence"; as long as each point converges eventually, we're good. Uniform convergence needs all points to converge "at the same rate" (so to speak).

A good example to keep in mind is  $f_n := \begin{cases} 2nx & 0 \le x \le \frac{1}{2n} \\ 0 & x > \frac{1}{2n} \end{cases}$  on [0,1], which converges pointwise to 0 but not uniformly.

A good trick for disproving uniform convergence of  $f_n \to f$  is by showing  $f_n(x_0)$  constant and  $\neq f(x_0)$  for all n. For instance,  $f_n(x) := \sin(\frac{x}{n}) \to 0$  pointwise, but  $f_n(\frac{n\pi}{2}) = 1 \,\forall n$  so the convergence os not uniform.

**Proposition 15.** *Uniform*  $\implies$  *pointwise convergence.* 

**Theorem 26.** The metric space of continuous functions C([a,b]) complete with respect to  $d_{\infty}(f,g) := \sup_{x \in [a,b]} |f(x) - g(x)|$ .

**Theorem 27** (\* Interchange of Limits). Let  $J \subseteq \mathbb{R}$  be a bounded interval such that  $\exists x_0 \in J$ :  $f_n(x_0) \to f(x_0)$ . Suppose  $f'_n(x) \to g(x)$  uniformly on J. Then,  $\exists f : f_n(x) \to f(x)$  uniformly on J, f(x) differentiable on J, and moreover  $f'_n(x) = g(x) \forall x \in J$ .

**Theorem 28** (\* Interchange of Integrals). Let  $f_n \in \mathcal{R}[a,b]$ ,  $f_n \to f$  uniformly on [a,b]. Then  $f \in \mathcal{R}[a,b]$  and  $\int_a^b f_n(x) dx \to \int_a^b f(x) dx$ 

**Theorem 29** (Bounded Convergence). Let  $f_n \in \mathcal{R}[a,b]$ ,  $f_n \to f \in \mathcal{R}[a,b]$  (not necessarily uniform). Suppose  $\exists B > 0$  s.t.  $|f_n(x)| \leq B \,\forall \, x \in [a,b]$  and  $\forall \, n \in \mathbb{N}$ , then  $\int_a^b f_n \to \int_a^b f$  as  $n \to \infty$ .

*Remark* 18. This provides a weaker condition, but equivalent result as the previous theorem, although remark now that we need the limit function itself to be in  $\mathcal{R}[a,b]$ , which was a result, not a necessity, of the previous theorem. In general, uniform continuity very strong, but leads to helpful results.

**Theorem 30** (Dimi's). *If*  $f_n \in C([a,b])$ ,  $f_n(x)$  *monotone (as a sequence), and*  $f_n \to f \in C([a,b])$ , *then*  $f_n \to f$  *uniformly.* 

#### 6 Infinite Series

**Definition 24** (Covergence of Series). Let  $\{x_j\} \in X$ -normed vector space over  $\mathbb{R}$ . We say  $\sum_{j=1}^{\infty} x_j$  converges absolutely iff  $\sum_{j=1}^{\infty} ||x_j|| < +\infty$ . In particular, if  $X = \mathbb{R}$ , then  $||\cdot|| = |\cdot|$ . We say  $\sum_{j=1}^{\infty} x_j$  converges conditionally if  $\sum_{j=1}^{\infty} x_j < +\infty$ , but  $\sum_{j=1}^{\infty} ||x_j|| = +\infty$ .

**Proposition 16.** Any rearrangement of an absolutely convergent series gives the same sum. Conversely, the order of summation of a conditionally convergent summation can be rearranged such as to equal any real number.

**Proposition 17** (Absolute Convergence Tests). • *Comparison Test:* let  $x_n$ ,  $y_n$  be nonzero real sequences and  $r := \lim_{n \to \infty} \left| \frac{x_n}{y_n} \right|$ . If such a limit exists, then if

(a)  $r \neq 0$ ,  $\sum_{n} x_{n}$  absolutely convergent  $\iff \sum_{n} y_{n}$  absolutely convergent.

- (b) r = 0,  $\sum_n y_n$  absolutely convergent  $\implies \sum_n x_n$  absolutely convergent.
- Root Test: if  $\exists r < 1 \text{ s.t. } |x_n|^{1/n} \leq r \ \forall n \geq K$ -sufficiently large, then  $\sum_{n=K}^{\infty} |x_n|$  converges. Conversely, if  $|x_n|^{1/n} \geq 1$  for  $n \geq K$ -sufficiently large,  $\sum_n x_n$  diverges.
- Ratio Test: if  $x_n \neq 0$  and  $\exists 0 < r < 1$  s.t.  $\left| \frac{x_{n+1}}{x_n} \right| \leq r$  for  $n \geq K$  sufficiently large,  $\sum_n x_n$  absolutely convergent. Conversely, if  $\left| \frac{x_{n+1}}{x_n} \right| \geq 1$  for  $n \geq K$  sufficiently large, then  $\sum_n x_n$  diverges.
- Integral Test: if  $f(x) \ge 0$  non-increasing/non-decreasing function of  $x \ge 1$ ,  $\sum_{k=1}^{\infty} f(k)$  converges iff  $\lim_{k\to\infty} \int_1^k f(x) \, dx$  finite.
- \* Raube's Test: let  $x_n \neq 0$ .
  - (a) If  $\exists a > 1$  s.t.  $\left|\frac{x_{n+1}}{x_n}\right| \le 1 \frac{1}{n} \, \forall \, n \ge K$ -sufficiently large, then  $\sum_n x_n$  converges absolutely.
  - (b) If  $\exists a \leqslant 1 \text{ s.t. } \left| \frac{x_{n+1}}{x_n} \right| \geqslant 1 \frac{1}{n} \forall n \geqslant K$ -sufficiently large,  $\sum_n x_n$  does not converge absolutely.

Remark 19. Proofs of these tests aren't really important (Dima-speaking), but knowing the conditions in which they apply is.

**Proposition 18** (Tests for Non-Absolute Convergence). • *Alternating Series:* if x > 0,  $x_{n+1} \le x_n$  such that  $\lim_{n\to\infty} x_n = 0$ , then  $\sum_n (-1)^n x_n$  converges.

- Dirichlet's Test: if  $x_n$  decreasing with limit 0, and the partial sum  $s_n := y_1 + \cdots + y_n$  is bounded, then  $\sum_n x_n y_n$  converges.
- Abel's Test: let  $x_n$  convergent and monotone, and suppose  $\sum_n y_n$  converges. Then  $\sum_n x_n y_n$  also converges.

**Definition 25** (Convergence of Series of Functions). We say a series  $\sum_n f_n(x)$  converges absolutely to some g(x) on E if  $\sum_n |f_n(x)|$  converges for all  $x \in E$ .

We say that the convergence is uniform if it is uniform for any  $x \in E$ , ie  $\forall \varepsilon > 0 \exists N \in \mathbb{N}$  s.t.  $\forall n \ge N, x \in E, |g(x) - \sum_n f_n(x)| < \varepsilon$ .

**Proposition 19** (Interchanging Integrals and Summations). Suppose for  $f_n : [a,b] \to \mathbb{R}$ ,  $\sum_n f_n(x) \to g(x)$  uniformly and  $f_n \in \mathcal{R}[a,b]$ . Then  $\int_a^b g(x) = \sum_{n=1}^\infty \int_a^b f_n(x) dx$ .

**Proposition 20** (Interchanging Derivatives and Summations). Let  $f_n : [a,b] \to \mathbb{R}$ ,  $f'_n \exists f(x)$  converges for some [a,b] and  $\sum_n f'_n(x)$  converges uniformly. Then, there exists some  $g:[a,b] \to \mathbb{R}$  such that  $\sum_n f_n \to g$  uniformly, g differentiable, and  $g'(x) = \sum_n f'_n(x)$ , all on [a,b].

**Theorem 31** (\* Cauchy Criterion of Series).  $f_n(x): D \to \mathbb{R}$  converges uniformly on D iff  $\forall \varepsilon > 0, \exists N \ s.t. \ \forall m, n \geqslant N, \sum_{i=n+1}^m f_i(x) < \varepsilon \ \forall x \in D.$ 

Remark 20. Letting  $s_n := \sum_{i=1}^n x_n$ , remark that this is equivalent to  $|s_n - s_m| < \varepsilon$ , ie the Cauchy criterion for sequences.

**Proposition 21** (Weierstrass M-Test). If  $|f_n(x)| \le M_n \, \forall \, x \in D \subseteq \mathbb{R}$  and  $\sum_n M_n < +\infty$ , then  $\sum_n f_n(x)$  converges uniformly on D.

**Definition 26** (Power Series). A function of the form  $f(x) := \sum_{n=0}^{\infty} a_n (x-c)^n$  is said to be a power series centered at c.

Put  $\rho := \limsup_{n \to \infty} \sqrt[n]{|a_n|}$ , and put

$$R := \begin{cases} \frac{1}{\rho} & 0 < \rho < +\infty \\ 0 & \rho = +\infty \end{cases}.$$

$$\infty \quad \rho = 0$$

We call R the radius of convergence of f.

**Theorem 32** (\* Cauchy-Hadamard). Let R be the radius of converges of f. Then, f(x) converges if |x - c| < R, and diverges if |x - c| > R.

*Sketch.* Apply the root test to the definition of *R*.

Remark 21. If |x - c| = R, the theorem is inconclusive, and we need to manually check.