## MATH456 - Algebra 3

Based on lectures from Fall 2024 by Prof. Henri Darmon. Notes by Louis Meunier

## **Contents**

1	Groups	. 2
	1.1 Review	
	1.2 Actions of Groups	
	1.3 Homomorphisms, Isomorphisms, Kernels	
	1.4 Conjugation and Conjugacy	
	1.1 Conjugation and Conjugacy	. 0

#### 1 Groups

#### 1.1 Review

 $\hookrightarrow$  **Definition 1.1** (Group): A **group** is a set G endowed with a binary composition rule  $G \times G \rightarrow$  $G, (a, b) \mapsto a \star b$ , satisfying

- 1.  $\exists e \in G \text{ s.t. } a \star e = e \star a = a \forall a \in G$
- 2.  $\forall a \in G, \exists a' \in G \text{ s.t. } a \star a' = a' \star a = e$
- 3.  $\forall a, b, c \in G, (a \star b) \star c = a \star (b \star c).$

If the operation on G also commutative for all elements in G, we say that G is abelian or *commutative*, in which case we typically adopt additive notation (i.e. a + b,  $a^{-1} = -a$ , etc).

- $\circledast$  **Example 1.1**: An easy way to "generate" groups is consider some "object" X (be it a set, a vector space, a geometric object, etc.) and consider the set of symmetries of X, denoted Aut(X), i.e. the set of bijections of X that preserve some desired quality of X.
- 1. If X just a set with no additional structure, Aut(X) is just the group of permutations of X. In particular, if X finite, then  $\operatorname{Aut}(X) \cong S_{\#X}$ .
- 2. If X a vector space over some field  $\mathbb{F}$ ,  $\operatorname{Aut}(X) = \{T : X \to X \mid \operatorname{linear}, \operatorname{invertible}\}$ . If  $\dim(X) = \{T : X \to X \mid \operatorname{linear}, \operatorname{invertible}\}$ .  $n < \infty, X \cong \mathbb{F}^n$  as a vector space, hence  $\operatorname{Aut}(X) = \operatorname{GL}_n(\mathbb{F})$ , the "general linear group" consisting of invertible  $n \times n$  matrices with entires in  $\mathbb{F}$ .
- 3. If X a ring, we can always derive two groups from it; (R, +, 0), which is always commutative, using the addition in the ring, and  $(R^{\times}, \times, 1)$ , the units under multiplication (need to consider the units such that inverses exist in the group).
- 4. If X a regular n-gon, Aut(X) can be considered the group of symmetries of the polygon that leave it globally invariant. We typically denote this group by  $D_{2n}$ .
- 5. If X a vector space over  $\mathbb{R}$  endowed with an inner product  $(\cdot,\cdot):V\times V\to\mathbb{R}$ , with dim  $V<\infty$ , we have  $\operatorname{Aut}(V) = O(V) = \{T : V \to V \mid T(v \cdot w) = v \cdot w \forall v, w \in V \}$ , the "orthogonal group".

 $\hookrightarrow$  Definition 1.2 (Group Homomorphism): Given two groups  $G_1,G_2$ , a group homomorphism  $\varphi$ :  $G_1 o G_2$  is a function satisfying  $\varphi(ab) = \varphi(a)\varphi(b)$  for all  $a,b \in G_1$ .

If  $\varphi$  is bijective, we call it an *isomorphism* and say  $G_1, G_2$  are *isomorphic*.

## $\rightarrow$ Proposition 1.1:

- $\bullet \ \varphi \Big( 1_{G_1} \Big) = 1_{G_2}$   $\bullet \ \varphi \big( a^{-1} \big) = \varphi (a)^{-1}$

1.1 Review

**Example 1.2**: Let  $G = \mathbb{Z}/n\mathbb{Z} = \{0, ..., n-1\}$  be the cyclic group of order n. Let  $\varphi \in \operatorname{Aut}(G)$ ; it is completely determined by  $\varphi(1)$ , as  $\varphi(k) = k \cdot \varphi(1)$  for any k. Moreover, it must be then that  $\varphi(1)$  is a generate of G, hence  $\varphi(1) \in (\mathbb{Z}/n\mathbb{Z})^{\times}$  (ie the units of the group considered as a ring), and thus

$$\operatorname{Aut}(G) \cong ((\mathbb{Z}/n\mathbb{Z})^{\times}, *).$$

#### 1.2 Actions of Groups

**Definition 1.3** (Group Action): An *action* of G on an object X is a function  $G \times X \to X, (g, x) \mapsto g \cdot \text{such that}$ 

- $1 \cdot x = x$
- $\bullet \ (g_1g_2)\cdot x=g_1\cdot (g_2\cdot x)$
- $m_q: x \mapsto g \cdot x$  an automorphism of X.

**Proposition 1.2**: The map  $m: G \to \operatorname{Aut}(X), g \mapsto m_g$  a group homomorphism.

PROOF. One need show  $m_{g_1g_2}=m_{g_1}\circ m_{g_2}.$ 

 $\hookrightarrow$ **Definition 1.4** (G-set): A *G*-set is a set *X* endowed with an action of *G*.

**Definition 1.5** (Transitive): We say a *G*-set *X* is *transitive* if  $\forall x, y \in X$ , there is a *g* ∈ *G* such that  $g \cdot x = y$ .

A transitive *G*-subset of *X* is called on *orbit* of *G* on *X*.

 $\rightarrow$ **Proposition 1.3**: Every *G*-set is a disjoint union of orbits.

PROOF. Define a relation on X by  $x \sim y$  if there exists a  $g \in G$  such that  $g \cdot x = y$ . One can prove this is an equivalence relation on X. Equivalence relations partition sets into equivalence classes, which we denote in this case by X/G. The proof is done by remarking that an equivalence class is precisely an orbit.

**Remark 1.2.1**: As with most abstract objects, we are more interested in classifying them up to isomorphism. The same follows for G-sets.

1.2 Actions of Groups

 $\hookrightarrow$  Definition 1.6: An *isomorphism of G-sets* is a map between G-sets that respects the group actions. Specifically, if G a group and  $X_1$ ,  $X_2$  are G-sets, with the action G on  $X_1$  denoted  $\star$  and G on  $X_2$  denoted  $\star$ , then an isomorphism is a bijection

$$f: X_1 \to X_2$$

such that

$$f(q \star x) = q * f(x)$$

for all  $g \in G$ ,  $x \in X_1$ .

 $\hookrightarrow$  **Definition 1.7** (Cosets): Let  $H \subseteq G$  be a subgroup of a group G. Then G carries a natural structure as an H set; namely we can define

$$H \times G \rightarrow q$$
,  $(h, q) \mapsto q \cdot h$ ,

which can readily be seen to be a well-defined group action. We call, in this case, the set of orbits of the action of H on G left cosets of H in G, denoted

$$G/H = \{ \text{orbits of } H \text{ acting on } G \}$$
 
$$= \{ aH : a \in G \} = \{ \{ ah : h \in H \} : a \in G \} \subseteq 2^G.$$

Symmetric definitions give rise to the set of *right cosets* of H in G, denoted  $H \setminus G$ , of orbits of H acting by left multiplication on G.

**Remark 1.2.2**: In general,  $G/H \neq H \setminus G$ . Further, note that at face value these are nothing more than sets; in general they will not have any natural group structure. They do, however, have a natural structure as G-sets, as a theorem to follow will elucidate.

**Theorem 1.1**: Let  $H \subseteq G$  be a finite subgroup of a group G. Then every coset of H in G has the same cardinality.

PROOF. Define the map  $H \mapsto aH$  by  $h \mapsto ah$ . This is a bijection.

**Remark 1.2.3**: In general, if one considers the general action of G on some set X, then the orbits X/G need not all have the same size, though they do partition the set. It is in the special case where X a group and G a subgroup of X that we can guarantee equal-sized partitions.

1.2 Actions of Groups 4

 $\rightarrow$  **Theorem 1.2** (Lagrange's): Let G be a finite group and H a subgroup. Then

$$\#G = \#H \cdot \#(G/H).$$

In particular,  $\#H \mid \#G$  for any subgroup H.

PROOF. We know that G/H is a partition of G, so eg  $G=H\sqcup H_1\sqcup \cdots \sqcup H_n$ . By the previous theorem, each of these partitions are the same size, hence

$$\begin{split} \#G &= \#(H \sqcup H_1 \sqcup \cdots \sqcup H_n) \\ &= \#H + \#H_1 + \cdots + \#H_{n-1} \quad \text{since $H_i$'s disjoint} \\ &= n \cdot \#H \quad \text{since each $H$ same cardinality} \\ &= \#(G/H) \cdot \#H. \end{split}$$

 $\rightarrow$ **Proposition 1.4**: G/H has a natural left-action of G given by

$$G \times G/H \to G/H, \quad (g, aH) \mapsto (ga)H.$$

Further, this action is always transitive.

**Proposition 1.5**: If *X* is a transitive *G*-set, there exists a subgroup  $H \subseteq G$  such that  $X \cong G/H$  as a *G*-set.

In short, then, it suffices to consider coset spaces G/H to characterize G-sets.

PROOF. Fix  $x_0 \in X$ , and define the *stabilizer* of  $x_0$  by

$$H := \operatorname{Stab}_{G}(x_{0}) := \{ g \in G : gx_{0} = x_{0} \}.$$

One can verify H indeed a subgroup of G. Define now a function

$$f: G/H \to X, \quad gH \mapsto g \cdot x_0,$$

which we aim to show is an isomorphism of G-sets.

First, note that this is well-defined, i.e. independent of choice of coset representative. Let gH = g'H, that is  $\exists h \in H$  s.t. g = g'h. Then,

$$f(gH) = gx_0 = (g'h)x_0 = g'(hx_0) = g'x_0 = f(g'H), \\$$

since h is in the stabilizer of  $x_0$ .

For surjectivity, we have that for any  $y \in X$ , there exists some  $g \in G$  such that  $gx_0 = y$ , by transitivity of the group action on X. Hence,

$$f(gH) = gx_0 = y$$

and so *f* surjective.

1.2 Actions of Groups

5

For injectivity, we have that

$$\begin{split} g_1x_0 &= g_2x_0 \Rightarrow g_2^{-1}g_1x_0 = x_0 \\ &\Rightarrow g_2^{-1}g_1 \in H \\ &\Rightarrow g_2h = g_1 \text{ for some } h \in H \\ &\Rightarrow g_2H = g_1H, \end{split}$$

as required.

Finally, we have that for any coset aH and  $g \in G$ , that

$$f(g(aH))=f((ga)H)=(ga)x_0, \\$$

and on the other hand

$$gf(aH) = g(ax_0) = (ga)x_0.$$

Note that we were very casual with the notation in these final two lines; make sure it is clear what each "multiplication" refers to, be it group action on X or actual group multiplication.

 $\hookrightarrow$  Corollary 1.1: If X is a transitive G set with G finite, then  $\#X \mid \#G$ . More precisely,

$$X \cong G/\operatorname{Stab}_G(x_0)$$

for any  $x_0 \in X$ . In particular, the *orbit-stabilizer formula* holds:

$$\#G = \#X \cdot \#\operatorname{Stab}_G(x_0).$$

The assignment  $X \to H$  for subgroups H of G is not well-defined in general; given  $x_1, x_2 \in X$ , we ask how  $\operatorname{Stab}_G(x_1)$ ,  $\operatorname{Stab}_G(x_2)$  are related?

Since X transitive, then there must exist some  $g \in G$  such that  $x_2 = gx_1$ . Let  $h \in \text{Stab}(x_2)$ . Then,

$$hx_1 = x_2 \Rightarrow (hg)x_1 = gx_1 \Rightarrow g^{-1}hgx_1 = x_1,$$

hence  $g^{-1}hg\in \mathrm{Stab}\ (x_1)$  for all  $g\in G, h\in \mathrm{Stab}(x_2).$  So, putting  $H_i=\mathrm{Stab}\ (x_i),$  we have that

$$H_2 = g H_1 g^{-1}$$
.

This induces natural bijections

$$\{ \text{pointed transitive } G - \text{sets} \} \leftrightarrow \{ \text{subgroups of } G \}$$
 
$$(X, x_0) \rightsquigarrow H = \operatorname{Stab}(x_0)$$
 
$$(G/H, H) \rightsquigarrow H,$$

and

$$\{ \text{transitive } G - \text{sets} \} \leftrightarrow \{ \text{subgroups of } G \} / \text{ conjugation}$$
 
$$H_i = g H_j g^{-1}, \text{some } g \in G.$$

Given a G, then, we classify all transitive G-sets of a given size n, up to isomorphism, by classifying conjugacy classes of subgroups of "index n" :=  $[G:H] = \frac{\#G}{n} = \#(G/H)$ .

1.2 Actions of Groups 6

#### **\* Example 1.3:**

- 0.  $G, \{e\}$  are always subgroups of any G, which give rise to the coset spaces  $X = \{\star\}, G$  respectively. The first is "not faithful" (not injective into the group of permutations), and the second gives rise to an injection  $G \hookrightarrow S_G$ .
- 1. Let  $G=S_n$ . We can view  $X=\{1,...,n\}$  as a transitive  $S_n$ -set. We should be able to view X as G/H, where  $\#(G/H)=\#X=n=\frac{\#G}{\#}(H)=\frac{n!}{\#H}$ , i.e. we seek an  $H\subset G$  such that  $\#H=\frac{n!}{n}=(n-1)!$ .

Moreover, we should have H as the stabilizer of some element  $x_0 \in \{1,...,n\}$ ; so, fixing for instance  $1 \in \{1,...,n\}$ , we have  $H = \operatorname{Stab}(1)$ , i.e. the permutations of  $\{1,...,n\}$  that leave 1 fixed. But we can simply see this as the permutation group on n-1 elements, i.e.  $S_{n-1}$ , and thus  $X \cong S_n/S_{n-1}$ . Remark moreover that this works out with the required size of the subgroup, since  $\#S_{n-1} = (n-1)!$ .

2. Let X = regular tetrahedron and consider

$$G = Aut(X) := \{ \text{rotations leaving } X \text{ globally invariant} \}.$$

We can easily compute the size of G without necessarily knowing G by utilizing the orbitstabilizer theorem (and from there, somewhat easily deduce G). We can view the tetrahedron as the set  $\{1, 2, 3, 4\}$ , labeling the vertices, and so we must have

$$\#G = \#X \cdot \# \text{Stab}(1),$$

where  $\operatorname{Stab}(1) \cong \mathbb{Z}/3\mathbb{Z}$ . Hence #G = 12.

From here, there are several candidates for G; for instance,  $\mathbb{Z}/12\mathbb{Z}$ ,  $D_{12}$ ,  $A_4$ , .... Since X can be viewed as the set  $\{1,2,3,4\}$ , we can view  $X \rightsquigarrow G \hookrightarrow S_4$ , where  $\hookrightarrow$  an injective homomorphism, that is, embed G as a subgroup  $S_4$ . We can show both  $D_{12}$  and  $\mathbb{Z}/12\mathbb{Z}$  cannot be realized as such (by considering the order of elements in each; there exists an element in  $D_{12}$  of order 6, which does not exist in  $S_4$ , and there exists an element in  $\mathbb{Z}/12\mathbb{Z}$  of order 12 which also doesn't exist in  $S_4$ ). We can embed  $A_4 \subset S_4$ , and moreover  $G \cong A_4$ . If we were to extend G to include planar reflections as well that preserve X, then our G is actually isomorphic to all of  $S_4$ .

4. Let X be the cube,  $G = \{ \text{rotations of } X \}$ . There are several ways we can view X as a transitive G sets; for instance F = faces, E = edges, V = vertices, where #F = 6, #E = 12, #V = 8. Let's work with F, being the smallest. Letting  $x_0 \in F$ , we have that  $\operatorname{Stab}(x_0) \cong \mathbb{Z}/4\mathbb{Z}$  so the orbit-stabilizer theorem gives #G = 24.

This seems to perhaps imply that  $G = S_4$ , since  $\#S_4 = 24$ . But this further implies that if this is the case, we should be able to consider some group of size 4 "in the cube" on which G acts.

#### 1.3 Homomorphisms, Isomorphisms, Kernels

ightharpoonup Proposition 1.6: If  $\varphi: G \to H$  a homomorphism,  $\varphi$  injective iff  $\varphi$  has a trivial kernel, that is,  $\ker \varphi = \{a \in G : \varphi(a) = e_H\} = \{e\}.$ 

 $\hookrightarrow$  **Definition 1.8** (Normal subgroup): A subgroup  $N \subset G$  is called *normal* if for all  $g \in G, h \in N$ , then  $ghg^{-1} \in N$ .

**Proposition 1.7**: The kernel of a group homomorphism  $\varphi$  : G → H is a normal subgroup of G.

**Proposition 1.8**: Let  $N \subset G$  be a normal subgroup. Then  $G/N = N \setminus G$  (that is, gN = Ng) and G/N a group under the rule  $(g_1N)(g_2N) = (g_1g_2)N$ .

**Theorem 1.3** (Fundamental Isomorphism Theorem): If  $\varphi: G \to H$  a homomorphism with  $N := \ker \varphi$ , then  $\varphi$  induces an injective homomorphism  $\overline{\varphi}: G/N \hookrightarrow H$  with  $\overline{\varphi}(aN) := \varphi(a)$ .

 $\hookrightarrow$  Corollary 1.2:  $\operatorname{im}(\varphi) \cong G/N$ , by  $\overline{\varphi}$  into  $\operatorname{im}(\overline{\varphi})$ .

**Example 1.4**: We return to the cube example. Let  $\tilde{G} = \widetilde{\operatorname{Aut}}(X) = \operatorname{rotations}$  and reflections that leave X globally invariant. Clearly,  $G \subset \tilde{G}$ , so it must be that  $\#\tilde{G}$  a multiple of 24. Moreover, remark that reflections reverse orientation, while rotations preserve it; this implies that the index of G in  $\tilde{G}$  is 2. Hence, the action of  $\tilde{G}$  on a set  $O = \{\operatorname{orientations} \operatorname{on}\mathbb{R}^3\}$  with #O = 2 is transitive. We then have the induced map

$$\eta: \tilde{G} \to \operatorname{Aut}(O) \cong \mathbb{Z}/2$$

with kernel given by all of G; G fixes orientations after all.

Remark now the existence of a particular element in  $\tilde{G}$  that "reflects through the origin", swapping each corner that is joined by a diagonal. This is not in G, but notice that it actually commutes with every other element in  $\tilde{G}$  (one can view such an element by the matrix  $\begin{pmatrix} -1 \\ -1 \end{pmatrix}$  acting on  $\mathbb{R}^3$ ). Call this element  $\tau$ . Then, since  $\tau \notin G$ ,  $\tau g \neq g$  for any  $g \in G$ . Hence, we can write  $\tilde{G} = G \sqcup \tau G$ ; that is,  $\tilde{G}$  is a disjoint union of two copies of  $S_4$ , and so

$$\begin{split} \tilde{G} &\cong S_4 \times \mathbb{Z}/2\mathbb{Z} \\ f: S_4 \times \mathbb{Z}/2\mathbb{Z} &\to \tilde{G}, \quad (g,j) \mapsto \tau^j g. \end{split}$$

#### 1.4 Conjugation and Conjugacy

 $\hookrightarrow$  **Definition 1.9**: Two elements  $g_1,g_2\in G$  are *conjugate* if  $\exists h\in G$  such that  $g_2=hg_1h^{-1}$ .

Recall that we can naturally define G as a G-set in three ways; by left multiplication, by right multiplication (with an extra inverse), and by conjugation. The first two are always transitive, while the last is never (outside of trivial cases); note that if  $g^n = 1$ , then  $(hgh^{-1})^n = 1$ , that is, conjugation preserves order, hence G will preserve the order of 1 of the identity element, and conjugation will thus always have an orbit of size 1,  $\{e\}$ .

An orbit, in this case, is called a conjugacy class.

### $\hookrightarrow$ **Proposition 1.9**: Conjugation on $S_n$ preserves cycle shape.

PROOF. Just to show an example, consider  $(13)(245) \in S_5$  and let  $g \in S_5$ , and put  $\sigma := g(13)(245)g^{-1}$ . Then, we can consider what  $\sigma g(k)$  is for each k;

$$\sigma(g(1)) = g(3)$$
 $\sigma(g(3)) = g(1)$ 
 $\sigma(g(2)) = g(4)$ 
 $\sigma(g(4)) = g(5)$ 
 $\sigma(g(5)) = g(2)$ 

hence, we simply have  $\sigma = (g(1)g(3))(g(2)g(4)g(5))$ , which has the same cycle shape as our original permutation. A similar logic holds for general cycles.

 $\hookrightarrow$  **Definition 1.10**: The cycle shape of  $\sigma \in S_n$  is the partition of n by  $\sigma$ . For instance,

$$1 \leftrightarrow 1 + 1 + \dots + 1$$
$$\sigma = (12...n) \leftrightarrow n.$$

# **Example 1.5**: We compute all the "types" of elements in $S_4$ by consider different types of partitions of 4:

Partition	Size of Class
1+1+1+1	1
2 + 1 + 1	$\binom{4}{2} = 6$
3 + 1	$4 \cdot 2 = 8$ (4 points fixed, 2 possible orders)
4	3! = 6 (pick 1 first, then 3 choices, then 2)
2+2	3