

MATH255 - Honours Analysis 2

Summary of Results

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1 POINT-SET TOPOLOGY

Topology is about abstracting openness. It can typically suffice to consider open, closed sets in \mathbb{R} for intuition, but is obviously not all-general.

Definition 1 (Metric Space). A space X equipped with a function $d : X \times X \rightarrow [0, \infty)$ is called a metric space and d a metric or distance if

- $d(x, y) = d(y, x) \geq 0$
- $d(x, y) = 0 \iff x = y$
- $d(x, y) + d(y, z) \geq d(x, z)$

for any $x, y, z \in X$.

Definition 2 (Normed Vector Space). A function $\|\cdot\| : X \rightarrow \mathbb{R}$ defined on a vector space X over \mathbb{R} is a norm if

- $\|x\| \geq 0$
- $\|x\| = 0 \iff x = 0$
- $\|c \cdot x\| = |c| \|x\|$
- $\|x + y\| \leq \|x\| + \|y\|$,

for any $x, y \in X, c \in \mathbb{R}$.

Remark 1. We can naturally extend this to arbitrary fields, but seeing as this is a course in Real Analysis, we won't.

Proposition 1. For a normed vector space $(X, \|\cdot\|)$, $d(x, y) := \|x - y\|$ is a metric on X . We call such a metric the one "induced" by the norm.

Definition 3 (Topological Set). A set X is a topological set if we have a collection τ of subsets of X , called open sets, such that

- $\emptyset \in \tau, X \in \tau$
- For $A_\alpha \in \tau$ for α in any I (potentially infinite), $\bigcup_{\alpha \in I} A_\alpha \in \tau$
- For $A_\alpha \in \tau$ for $\alpha \in J$ where J finite, then $\bigcap_{\alpha \in J} A_\alpha \in \tau$

ie, arbitrary unions of open sets are open, and finite intersections of open sets are open.

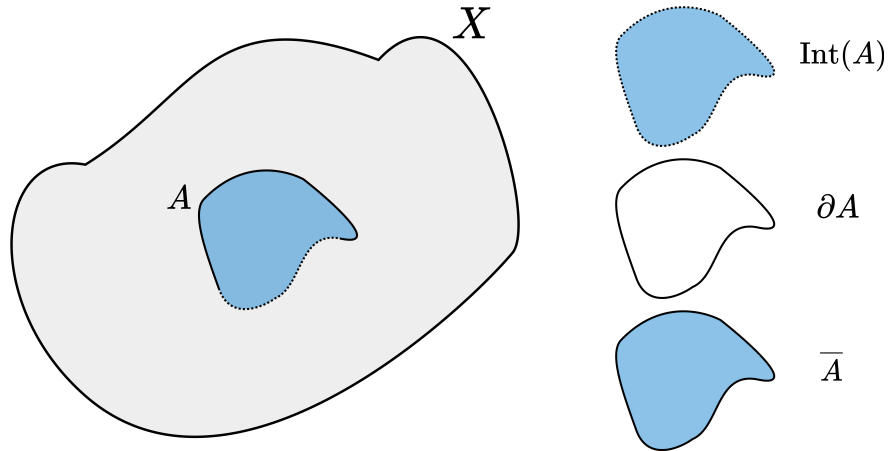
Remark 2. Keep \mathbb{R} in mind when initially working with these definitions; for instance, the set $A_n := (0, \frac{1}{n})$ open in \mathbb{R} for any $n \in \mathbb{N}$, but $\bigcap_{n \in \mathbb{N}} A_n = \{0\}$ which is closed.

Remark 3. Complemented each of these requirements gives similar definitions for closed sets of X .

Definition 4 (Topology on a Metric Space). A subset $A \subseteq X$ open iff $\forall x \in A, \exists r = r(x) \in \mathbb{R}$, where $r(x) > 0$, such that $B(x, r(x)) := \{y \in X : d(x, y) < r(x)\} \subseteq A$. We call such a B an open ball, and \bar{B} a closed ball with the same definition replacing the strict inequality with \leq .

Remark 4. While many of the spaces we look at are metric spaces that induce a topology as such, **not all topological spaces are metric spaces**. Indeed, "metrizable" (ie, equipping a topological space X with a metric that respects the open sets) is not a trivial activity.

Definition 5 (Equivalence of Metrics). We say two metrics on X are equivalent if they admit the same topology; a sufficient condition is that, $\forall x \neq y \in X, \exists 1 < C < \infty$ such that $\frac{1}{C} < \frac{d_1(x, y)}{d_2(x, y)} < C$, then d_1, d_2 equivalent, where C independent of x, y .



Definition 6 (★ Interior, Boundary, Closure). Let X -topological space, $A \subseteq X, x \in X$.

- If $\exists U$ -open s.t. $x \in U \subseteq A$, then we write $x \in \text{Int}(A)$, the interior of A .
- If $\exists V$ -open s.t. $x \in V \subseteq A^c$, then $x \in \text{Int}(A^c)$.
- If $\forall U$ -open s.t. $x \in U, U \cap A \neq \emptyset$ and $U \cap A^c \neq \emptyset$, then $x \in \partial A$, the boundary of A .

We put $\bar{A} := \text{Int}(A) \cup \partial A$, the closure of A . Equivalently, $x \in \bar{A} \iff$ for every open set $U : x \in U, U \cap A \neq \emptyset$. We call $x \in \bar{A}$ the limit points of A .

Remark 5. The limit point interpretation of the closure can be more intuitive; the points that we can get "arbitrary close to" are the closure. For instance, $\overline{(a, b)} = [a, b] \subseteq \mathbb{R}$ with the standard topology.

Proposition 2. Let $A \subseteq X$ -topological space. Then, $\text{Int}(A)$ is open, the largest open set contained in A , the union of all open sets contained in A , and $\text{Int}(\text{Int}(A)) = \text{Int}(A)$. Also, \overline{A} closed, the smallest closed set that contains A , \overline{A} the intersection of all closed sets that A is contained in, and $\overline{\overline{A}} = \overline{A}$.

Corollary 1. A open $\iff A = \text{Int}(A)$ and A closed $\iff A = \overline{A}$

Remark 6. Remark that these are not exclusive, nor indeed the only possibilities.

Definition 7 (Basis). A basis for a topology X with open sets τ is a collection $B \subseteq \tau$ such that every $U \in \tau$ a union of sets in B .

Remark 7. Don't think about bases for vector spaces in this regard - there is no "minimality" requirement.

Keep in mind $\{(a, b) : -\infty < a < b < \infty\}$, a basis of topology on \mathbb{R} .

Proposition 3. For a metric space (X, d) , $\{B(x, r) : x \in X, r > 0\}$ a basis of topology.

Definition 8 (Subspace Topology). For a subset $Y \subseteq X$ -topological space, we define the subspace topology on Y as $\tau_Y := \{Y \cap U : U \in \tau\}$.

Definition 9 (★ Continuous). For X, Y -topological spaces, a function $f : X \rightarrow Y$ is continuous iff $\forall V$ -open in Y , $f^{-1}(V)$ -open in X .

Remark 8. One can verify that this is consistent with the $\varepsilon - \delta$ definition of continuity for functions on \mathbb{R} .

Theorem 1 (Continuity of Composition). If $f : X \rightarrow Y$, $g : Y \rightarrow Z$ continuous, $g \circ f$ continuous.

Remark 9. Note how much easier this is to prove via topological spaces than the $\varepsilon - \delta$ definition.

Definition 10 (Product Space). For an index set I and $X_\alpha, \alpha \in I$, we define $\prod_{\alpha \in I} X_\alpha$ as a product space; I may be finite or infinite.

Proposition 4. A basis for the product space is given by cylinders of the form $A = \prod_{\alpha \in J} A_\alpha \times \prod_{\alpha \notin J} X_\alpha$ for A_α -open in X_α , where $J \subseteq I$ -finite.

Definition 11 (Compact). A set $A \subseteq X$ is compact if every cover has a finite subcover, that is

$$A \subseteq \bigcup_{\alpha \in I} U_\alpha\text{-open} \implies \exists \{\alpha_1, \dots, \alpha_n\} \subseteq I \text{ s.t. } A \subseteq \bigcup_{i=1}^n U_{\alpha_i}.$$

Proposition 5. Closed intervals $[a, b]$ compact in \mathbb{R} .

Proposition 6. $A \subseteq \mathbb{R}^n$ compact \iff closed and bounded.

Definition 12 (Connected). X is said to not be connected if $X = U \cup V$ for U, V open, nonempty, disjoint. If X cannot be written as such, X is said to be connected.

Theorem 2. If X connected and $f : X \rightarrow Y$, then $f(X)$ connected in Y .

Proposition 7. Intervals in \mathbb{R} are connected.

Theorem 3 (Intermediate Value Theorem). If X connected, $f : X \rightarrow \mathbb{R}$ continuous, then f takes intermediate value; if $a = f(x), b = f(y)$ for $x, y \in X$ with $a < b$, then for any $a < c < b$ $\exists z \in X$ s.t. $f(z) = c$.

Theorem 4. For X compact, $f : X \rightarrow Y$ continuous, $f(X)$ compact in Y .

Proposition 8. For X compact and $f : X \rightarrow \mathbb{R}$, f attains both max and min on X .

Definition 13 (Path Connected). A set $A \subseteq X$ is path connected if for any $x, y \in A, \exists f : [a, b] \rightarrow X$ continuous such that $f(a) = x, f(b) = y, f([a, b]) \subseteq A$.

Theorem 5. Path connected \implies connected.

For open sets in \mathbb{R}^n , the converse holds too.

Definition 14 (Connected Component, Path Component). For $x \in X$, the connected component of x is the largest connected subset of X containing x and the path component of x is the largest path connected subset of X containing x .

2 METRIC SPACES

We discuss mostly the metric on ℓ_p space and notions of completeness, as well as some topological results specific to metric spaces, namely compactness.

Definition 15 (ℓ_p). For $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ and $1 \leq p \leq +\infty$, we define

$$\|x\|_p := \left(\sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}, \quad \|x\|_\infty := \max_{i=1}^n |x_i|,$$

and similarly, for sequences $x = (x_1, \dots, x_n, \dots)$,

$$\|x\|_p := \left(\sum_{i=1}^{\infty} |x_i|^p \right)^{\frac{1}{p}}, \quad \|x\|_\infty := \sup_{i=1}^{\infty} |x_i|,$$

and define $\ell_p := \{x : \|x\|_p < +\infty\}$. It can be shown that these are well-defined norms on their respective spaces.

Theorem 6 (Holder, Minkowski's Inequalities). For $x = (x_1, \dots, x_n), y = (y_1, \dots, y_n)$ and p, q such that $\frac{1}{p} + \frac{1}{q} = 1$, then

$$\text{Holder's:} \quad \langle x, y \rangle = \left| \sum_{i=1}^n x_i y_i \right| \leq \|x\|_p \|y\|_q$$

and

$$\text{Minkowski's:} \quad \|x + y\|_p \leq \|x\|_p + \|y\|_p.$$

The identical inequalities hold for infinite sequences.

Definition 16 (Completeness). We say a metric space is complete if every Cauchy sequence converges to a limit point in the space.

Proposition 9. For $\{x_n\}_{n \in \mathbb{N}}$, ℓ_p complete for any $1 \leq p \leq +\infty$.

Proposition 10. If $p < q$, $\ell_p \subseteq \ell_q$.

Definition 17 (Contraction Mapping). For a metric space (X, d) , a function $f : X \rightarrow X$ is a contraction mapping if there exists $0 < c < 1$ such that

$$d(f(x), f(y)) \leq c \cdot d(x, y)$$

for any $x, y \in X$.

Theorem 7. Let (X, d) be a complete metric space, $f : X \rightarrow X$ a contraction. Then, there exist a unique fixed point z of f such that $f(z) = z$; ie $\lim_{n \rightarrow \infty} f^n(x) = \lim_{n \rightarrow \infty} f \circ f \circ \dots \circ f(x) = z$ for any $x \in X$.

Theorem 8. ℓ_p complete.

Remark 10. It can be kind of funky to work with sequences in ℓ_p , since the elements of ℓ_p themselves sequences so we have "sequences of sequences".

Definition 18 (Totally bounded). A metric space X is said to be totally bounded if $\forall \varepsilon > 0 \exists x_1, \dots, x_n \in X, n = n(\varepsilon)$ such that $\bigcup_{i=1}^n B(x_i, \varepsilon) = X$.

Definition 19 (Sequentially compact). A metric space X is said to be sequentially compact if every sequence has a convergent subsequence.

Theorem 9 (★ Equivalent Notions of Compactness in Metric Spaces). Let (X, d) a metric space. TFAE:

- X compact
- X complete and totally bounded
- X sequentially compact

Remark 11. This is for a metric space, not a general topological space! Hopefully this is clear because some of the requirements necessitate a distance.

3 DIFFERENTIATION

Definition 20 (Differentiable). $f(x)$ differentiable at c if $\lim_{x \rightarrow c} \frac{f(x)-f(c)}{x-c}$ exists, and if so we denote the limit $f'(c)$.

Alternatively, one can view differentiation as a linear map between spaces of differentiable functions.

Theorem 10. *Differentiable \implies continuous.*

Proof. Short enough to write the full proof; $\lim_{x \rightarrow c} (f(x) - f(c)) = \lim_{x \rightarrow c} (x - c) \frac{f(x)-f(c)}{x-c} = 0 \cdot f'(c) = 0$. \square

Theorem 11 (Caratheodory's). *For $f : I \rightarrow \mathbb{R}, c \in I$, f differentiable at c iff $\exists \varphi : I \rightarrow \mathbb{R} : \varphi$ continuous at c , $f(x) - f(c) = \varphi(x)(x - c)$.*

Sketch. Its worth recalling the definition of φ for the forward implication,

$$\varphi(x) := \begin{cases} \frac{f(x)-f(c)}{x-c} & x \neq c \\ f'(c) & x = c \end{cases}.$$

The converse follows by taking limits. \square

Remark 12. While not a particularly enlightening result, used in proofs of the chain rule, etc.

Theorem 12 (Chain Rule). *Let $f : J \rightarrow \mathbb{R}, g : I \rightarrow \mathbb{R}$ s.t. $f(J) \subseteq I$. If $f(x)$ differentiable at c and $g(y)$ at $f(c)$, $g \circ f$ differentiable at c with $(g \circ f)'(c) = g'(f(c)) \cdot f'(c)$.*

Sketch. Apply Caratheodory's to f at c and g at $f(c)$, and compose. \square

Theorem 13 (Rolle's). *Let $f : [a, b] \rightarrow \mathbb{R}$ continuous. If $f'(x)$ exists on (a, b) and $f(a) = f(b) = 0$, $\exists c \in (a, b) : f'(c) = 0$.*

Sketch. If constant function, done. Else, assuming function positive, it obtains a maximum, and thus its derivative 0 at this point. \square

Theorem 14 (★ Mean Value). Let f continuous on $[a, b]$ and differentiable on (a, b) . Then, $\exists c \in (a, b)$ such that $f(b) - f(a) = f'(c)(b - a)$.

Sketch. Let $\phi(x) := f(x) - f(a) - \frac{f(b)-f(a)}{(b-a)}(x - a)$. Then $\phi(a) = \phi(b) = 0$ so applying Rolle's $\exists c \in (a, b) : \phi'(c) = 0 = f'(c) - \frac{f(b)-f(a)}{b-a}$. The proof is done after rearranging. \square

Proposition 11 (L'Hopital's). If $f, g : [a, b] \rightarrow \mathbb{R}$ with $f(a) = g(a) = 0, g(x) \neq 0$ on $a < x < b$, f, g differentiable at $x = 0$ with $g'(a) \neq 0$, then $\lim_{x \rightarrow a^+} \frac{f(x)}{g(x)}$ exists and is equal to $\frac{f'(a)}{g'(a)}$.

Remark 13. Other versions exist, but this is certainly one of them.

Theorem 15 (★ Taylor's). Let $f \in C^n([a, b])$ such that $f^{(n+1)}(x)$ exists on (a, b) . Let $x_0 \in [a, b]$, then, for any $x \in [a, b]$, $\exists c$ between x, x_0 such that

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 + \cdots + \frac{f^{(n)}(x_0)}{n!}(x - x_0)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(x - x_0)^{n+1}.$$

Corollary 2. Let $x_0 \in [a, b]$. With the same assumptions as Taylor's (but in a neighborhood of x_0), with $f'(x_0) = f''(x_0) = \cdots = f^{(n-1)}(x_0) = 0$ and $f^{(n)}(x_0) \neq 0$, then

- n even; then f has a local minimum at x_0 if $f^{(n)}(x_0) > 0$ and a local max if $f^{(n)}(x_0) < 0$.
- n odd; neither.

4 INTEGRATION

Its all just rectangles.

Definition 21 (Riemann Integration). Consider an interval (a, b) . We call a subdivision $\mathcal{P} := \{a = x_0, x_1, \dots, x_{n-1}, x_n = b\}$ a partition, and $\dot{\mathcal{P}}$ a marked partition if in addition we are given a point $t_i \in (x_i, x_{i+1}]$ for each interval in $\dot{\mathcal{P}}$.

We put $\text{diam}(\mathcal{P}) := \max_{i=1}^n |x_i - x_{i-1}|$.

We define the Riemann sum $S(f, \dot{\mathcal{P}}) := \sum_{i=1}^n f(t_i)(x_i - x_{i-1})$, and say that f Riemann integrable on $[a, b]$ if $S(f, \dot{\mathcal{P}}) \rightarrow L$ as $\text{diam}(\dot{\mathcal{P}}) \rightarrow 0$ for any choice of tag t_i , and write $f \in \mathcal{R}([a, b])$

More precisely, if $\forall \varepsilon > 0, \exists \delta > 0 : \text{diam}(\mathcal{P}) < \delta$, then for any $t_i \in [x_i, x_{i+1}]$, $|L - S(f, \dot{\mathcal{P}})| < \varepsilon$. We then say the (Riemann) integral of f over $[a, b]$ is L and write $\int_a^b f(x) dx = L$.

Proposition 12. *Riemann integrals are unique, linear in $f(x)$, and respect inequalities (if $f \leq g$ on $[a, b]$, $\int_a^b f(x) dx \leq \int_a^b g(x) dx$ if both in $\mathcal{R}([a, b])$)*

Proposition 13 (★). $f \in \mathcal{R}[a, b] \implies f$ bounded on $[a, b]$

Proposition 14 (★ Cauchy Criterion for Integrability). $f \in \mathcal{R}[a, b] \iff \forall \varepsilon > 0, \exists \delta > 0 : \text{if } \dot{P} \text{ and } \dot{Q} \text{ are tagged partitions of } [a, b] \text{ s.t. } \text{diam } \dot{P} < \delta \text{ and } \text{diam } \dot{Q} < \delta, \text{ then } |S(f, \dot{P}) - S(f, \dot{Q})| < \varepsilon$

Remark 14. Ala Cauchy Sequence.

Theorem 16 (Squeeze Theorem). $f \in \mathcal{R}[a, b] \iff \forall \varepsilon > 0, \exists \alpha_\varepsilon, \omega_\varepsilon \in \mathcal{R}[a, b] : \alpha_\varepsilon \leq f \leq \omega_\varepsilon \text{ and } \int_a^b (\omega_\varepsilon - \alpha_\varepsilon) < \varepsilon$.

Lemma 1. Let $J := [c, d] \subseteq [a, b]$ and $\varphi_J(x) := \begin{cases} 1 & x \in J \\ 0 & x \notin J \end{cases}$ be the indicator function of J . Then

$\varphi_J \in \mathcal{R}[a, b]$ and $\int_a^b \varphi_J = d - c$.

Remark 15. Helpful for "approximations"; follows by linearity, induction that step functions (ie sums of indicator functions times constants) are integrable.

Theorem 17 (★ Continuous). f continuous on $[a, b] \implies f \in \mathcal{R}[a, b]$

Sketch. Continuity on a closed interval gives uniform continuity and so a "universal δ "; then, for any partition, take the x such that f attains its minimum and maximum, and define a $\alpha_\varepsilon, \omega_\varepsilon$ as the sum of indicator functions taking the minimum, maximum of f respectively on each partition. Then apply the previous theorem and the squeeze theorem. \square

Theorem 18 (Additivity). $f \in \mathcal{R}[a, b] \iff f \in \mathcal{R}[a, c] \text{ and } f \in \mathcal{R}[c, b], \text{ and } \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$.

Theorem 19 (★ Fundamental Theorem of Calculus). Let $F, f : [a, b] \rightarrow \mathbb{R}$ and $E \subseteq [a, b]$ a finite set, such that F continuous on $[a, b]$, $F'(x) = f(x) \forall x \in [a, b] \setminus E$, $f \in \mathcal{R}[a, b]$. Then $\int_a^b f(x) = F(b) - F(a)$. We call F the "primitive" of f .

Theorem 20. For $f \in \mathcal{R}[a, b]$ and any $z \in [a, b]$, put $F(z) := \int_a^z f(x) dX$. Then, F continuous on $[a, b]$.

Theorem 21 (★ Fundamental Theorem of Calculus p2). For $f \in \mathcal{R}[a, b]$ continuous at c , then $F(z)$ differentiable at c and $F'(c) = f(c)$.

Definition 22 (Lebesgue Measure). We say a set $A \subseteq \mathbb{R}$ has Lebesgue measure 0 iff $\forall \varepsilon > 0$, A can be covered by a union of intervals J_k such that $\sum_k |J_k| \leq \varepsilon$. We then call A a "null set".

In particular, any countable set is a null set.

Theorem 22 (★ Lebesgue Integrability Criterion). Let $f : [a, b] \rightarrow \mathbb{R}$ be bounded. Then $f \in \mathcal{R}[a, b] \iff$ the set of discontinuities of f has Lebesgue measure 0.

Remark 16. In particular, remark that continuity a stronger requirement than integrability.

Theorem 23 (Composition). If $f \in \mathcal{R}[a, b]$, $\varphi : [c, d] \rightarrow \mathbb{R}$ continuous and $f([a, b]) \subseteq [c, d]$, then $\varphi \circ f \in \mathcal{R}[a, b]$.

Theorem 24 (Integration by Parts). If F, G differentiable $[a, b]$ with $f := F', g := G'$, and $f, g \in \mathcal{R}[a, b]$, then

$$\int_a^b f(x)G(x) dx = F(x)G(x) \Big|_a^b - \int_a^b F(x)g(x) dx.$$

Sketch. Uses additivity and the fundamental theorem of calculus. □

Theorem 25 (Taylor's Theorem, Remainder's Version). Suppose $f', f'', \dots, f^{(n)}$ exist on $[a, b]$ and $f^{(n+1)} \in \mathcal{R}[a, b]$. Then

$$f(b) = f(a) + \frac{f'(a)}{1!}(b-a) + \frac{f''(a)}{2!}(b-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(b-a)^n + R_n,$$

where $R_n := \frac{1}{n!} \int_a^b f^{(n+1)}(t)(b-t)^n dt$.

5 SEQUENCES OF FUNCTIONS

A good motivation to keep in mind with the "types" of function-sequence convergence is to answer the question: when can we exchange limits of derivatives of functions and derivatives of limits of functions? What about integrals? What about summations (see next section)? Ie, when does $\lim_{n \rightarrow \infty} f'_n(x) = \frac{d}{dx} \lim_{n \rightarrow \infty} f_n(x)$, etc.

Definition 23 (Pointwise, Uniform Convergence). We say $f_n \rightarrow f$ pointwise on E if $\forall x \in E$, $f_n(x) \rightarrow f(x)$ as $n \rightarrow \infty$.

We say $f_n \rightarrow f$ uniformly on E if $\forall \varepsilon > 0, \exists N \in \mathbb{N}$ such that $\forall n \geq N, x \in E$, $|f_n(x) - f(x)| < \varepsilon$.

Remark 17. Pointwise doesn't care about the "rate of convergence"; as long as each point converges eventually, we're good. Uniform convergence needs all points to converge "at the same rate" (so to speak).

A good example to keep in mind is $f_n := \begin{cases} 2nx & 0 \leq x \leq \frac{1}{2n} \\ 0 & x > \frac{1}{2n} \end{cases}$ on $[0, 1]$, which converges pointwise to 0 but not uniformly.

Proposition 15. *Uniform \implies pointwise convergence.*

Theorem 26. *The metric space of continuous functions $C([a, b])$ complete with respect to $d_\infty(f, g) := \sup_{x \in [a, b]} |f(x) - g(x)|$.*

Theorem 27 (★ Interchange of Limits). *Let $J \subseteq \mathbb{R}$ be a bounded interval such that $\exists x_0 \in J : f_n(x_0) \rightarrow f(x_0)$. Suppose $f'_n(x) \rightarrow g(x)$ uniformly on J . Then, $\exists f : f_n(x) \rightarrow f(x)$ uniformly on J , $f(x)$ differentiable on J , and moreover $f'_n(x) = g(x) \forall x \in J$.*

Theorem 28 (★ Interchange of Integrals). *Let $f_n \in \mathcal{R}[a, b]$, $f_n \rightarrow f$ uniformly on $[a, b]$. Then $f \in \mathcal{R}[a, b]$ and $\int_a^b f_n(x) dx \rightarrow \int_a^b f(x) dx$*

Theorem 29 (Bounded Convergence). Let $f_n \in \mathcal{R}[a, b]$, $f_n \rightarrow f \in \mathcal{R}[a, b]$ (not necessarily uniform). Suppose $\exists B > 0$ s.t. $|f_n(x)| \leq B \forall x \in [a, b]$ and $\forall n \in \mathbb{N}$, then $\int_a^b f_n \rightarrow \int_a^b f$ as $n \rightarrow \infty$.

Remark 18. This provides a weaker condition, but equivalent result as the previous theorem, although remark now that we need the limit function itself to be in $\mathcal{R}[a, b]$, which was a result, not a necessity, of the previous theorem. In general, uniform continuity very strong, but leads to helpful results.

Theorem 30 (Dimi's). If $f_n \in C([a, b])$, $f_n(x)$ monotone (as a sequence), and $f_n \rightarrow f \in C([a, b])$, then $f_n \rightarrow f$ uniformly.

6 INFINITE SERIES

Definition 24 (Covergence of Series). Let $\{x_j\} \in X$ -normed vector space over \mathbb{R} . We say $\sum_{j=1}^{\infty} x_j$ converges absolutely iff $\sum_{j=1}^{\infty} \|x_j\| < +\infty$. In particular, if $X = \mathbb{R}$, then $\|\cdot\| = |\cdot|$.

We say $\sum_{j=1}^{\infty} x_j$ converges conditionally if $\sum_{j=1}^{\infty} x_j < +\infty$, but $\sum_{j=1}^{\infty} \|x_j\| = +\infty$.

Proposition 16. Any rearrangement of an absolutely convergent series gives the same sum. Conversely, the order of summation of a conditionally convergent summation can be rearranged such as to equal any real number.

Proposition 17 (Absolute Convergence Tests). • **Comparison Test:** let x_n, y_n be nonzero real sequences and $r := \lim \left| \frac{x_n}{y_n} \right|$. If such a limit exists, then if

(a) $r \neq 0$, $\sum_n x_n$ absolutely convergent $\iff \sum_n y_n$ absolutely convergent.

(b) $r = 0$, $\sum_n y_n$ absolutely convergent $\implies \sum_n x_n$ absolutely convergent.

• **Root Test:** if $\exists r < 1$ s.t. $|x_n|^{1/n} \leq r \forall n \geq K$ -sufficiently large, then $\sum_{n=K}^{\infty} |x_n|$ converges. Conversely, if $|x_n|^{1/n} \geq 1$ for $n \geq K$ -sufficiently large, $\sum_n x_n$ diverges.

• **Ratio Test:** if $x_n \neq 0$ and $\exists 0 < r < 1$ s.t. $\left| \frac{x_{n+1}}{x_n} \right| \leq r$ for $n \geq K$ sufficiently large, $\sum_n x_n$ absolutely convergent. Conversely, if $\left| \frac{x_{n+1}}{x_n} \right| \geq 1$ for $n \geq K$ sufficiently large, then $\sum_n x_n$ diverges.

- **Integral Test:** if $f(x) \geq 0$ non-increasing/non-decreasing function of $x \geq 1$, $\sum_{k=1}^{\infty} f(k)$ converges iff $\lim_{k \rightarrow \infty} \int_1^k f(x) dx$ finite.

* **Raabe's Test:** let $x_n \neq 0$.

(a) If $\exists a > 1$ s.t. $\left| \frac{x_{n+1}}{x_n} \right| \leq 1 - \frac{1}{n} \forall n \geq K$ -sufficiently large, then $\sum_n x_n$ converges absolutely.

(b) If $\exists a \leq 1$ s.t. $\left| \frac{x_{n+1}}{x_n} \right| \geq 1 - \frac{1}{n} \forall n \geq K$ -sufficiently large, $\sum_n x_n$ does not converge absolutely.

Remark 19. Proofs of these tests aren't really important (Dima-speaking), but knowing the conditions in which they apply is.

Proposition 18 (Tests for Non-Absolute Convergence). • **Alternating Series:** if $x > 0$, $x_{n+1} \leq x_n$ such that $\lim_{n \rightarrow \infty} x_n = 0$, then $\sum_n (-1)^n x_n$ converges.

- **Dirichlet's Test:** if x_n decreasing with limit 0, and the partial sum $s_n := y_1 + \dots + y_n$ is bounded, then $\sum_n x_n y_n$ converges.

- **Abel's Test:** let x_n convergent and monotone, and suppose $\sum_n y_n$ converges. Then $\sum_n x_n y_n$ also converges.

Definition 25 (Convergence of Series of Functions). We say a series $\sum_n f_n(x)$ converges absolutely to some $g(x)$ on E if $\sum_n |f_n(x)|$ converges for all $x \in E$.

We say that the convergence is uniform if it is uniform for any $x \in E$, ie $\forall \varepsilon > 0 \exists N \in \mathbb{N}$ s.t. $\forall n \geq N, x \in E, |g(x) - \sum_n f_n(x)| < \varepsilon$.

Proposition 19 (Interchanging Integrals and Summations). Suppose for $f_n : [a, b] \rightarrow \mathbb{R}$, $\sum_n f_n(x) \rightarrow g(x)$ uniformly and $f_n \in \mathcal{R}[a, b]$. Then $\int_a^b g(x) = \sum_{n=1}^{\infty} \int_a^b f_n(x) dx$.

Proposition 20 (Interchanging Derivatives and Summations). Let $f_n : [a, b] \rightarrow \mathbb{R}, f'_n \exists$, $\sum_n f(x)$ converges for some $[a, b]$ and $\sum_n f'_n(x)$ converges uniformly. Then, there exists some $g : [a, b] \rightarrow \mathbb{R}$ such that $\sum_n f_n \rightarrow g$ uniformly, g differentiable, and $g'(x) = \sum_n f'_n(x)$, all on $[a, b]$.

Theorem 31 (★ Cauchy Criterion of Series). $f_n(x) : D \rightarrow \mathbb{R}$ converges uniformly on D iff $\forall \varepsilon > 0, \exists N$ s.t. $\forall m, n \geq N, \sum_{i=n+1}^m f_i(x) < \varepsilon \forall x \in D$.

Proposition 21 (Weierstrass M-Test). If $|f_n(x)| \leq M_n \forall x \in D \subseteq \mathbb{R}$ and $\sum_n M_n < +\infty$, then $\sum_n f_n(x)$ converges uniformly on D .

Definition 26 (Power Series). A function of the form $f(x) := \sum_{n=0}^{\infty} a_n(x - c)^n$ is said to be a power series centered at c .

Put $\rho := \limsup_{n \rightarrow \infty} \sqrt[n]{|a_n|}$, and put

$$R := \begin{cases} \frac{1}{\rho} & 0 < \rho < +\infty \\ 0 & \rho = +\infty \\ \infty & \rho = 0 \end{cases}.$$

We call R the radius of convergence of f .

Theorem 32 (★ Cauchy-Hadamard). Let R be the radius of convergence of f . Then, $f(x)$ converges if $|x - c| < R$, and diverges if $|x - c| > R$.

Sketch. Apply the root test to the definition of R . □

Remark 20. If $|x - c| = R$, the theorem is inconclusive, and we need to manually check.