MATH255 - Analysis 2

Basic point-set topology; metric spaces; Hölder-Minkowski Inequalities; compactness.

Based on lectures from Winter, 2024 by Prof. Dimitry Jakobson Notes by Louis Meunier

CONTENTS

I	Introduction			
	1.1	Metric Spaces	3	
2	Point-Set Topology			
	2.1	Definitions	7	
	2.2	Basis	9	
	2.3	Subspaces	10	
	2.4	Continuous Functions	11	
	2.5	Product Spaces	12	
	2.6	Metrizability	15	
	2.7	Compactness, Connectedness	16	
	2.8	Path Components, Connected Components	21	
		2.8.1 Cantor Staircase Function	22	
3	L^p Spaces			
	3.1	Review of ℓ^p Norms	23	
	3.2	ℓ^p Norms, Hölder-Minkowski Inequalities	23	
	3.3	An Aside on Complete Metric Spaces	27	
	3.4	Contraction Mapping Theorem	29	
	3.5	Compactness in Metric Spaces	32	
4	Derivatives			
	4.1	Introduction	35	
	4.2	Chain Rule	35	
	4.3	Critical Points	36	
	4.4	Aside: Continued Fractions	37	
	4.5	Back To Derivatives	38	

	4.7	L'Hopital's Rules	39
5	RIEN	mann Integral	40
	5.1	Introduction	40
	5.2	Cauchy Criterion	41
	5.3	Squeeze Theorem	42
6	App	ENDIX	44
	6.1	Notes from Tutorials	44
	6.2	Miscellaneous	47
	6.3	Class Midterm Solutions	48

52

7 List of Theorems

1 Introduction

1.1 Metric Spaces

→ Definition 1.1: Metric Space

A set *X* is a *metric space* with distance *d* if

- 1. (symmetric) $d(x, y) = d(y, x) \ge 0$
- $2. \ d(x,y) = 0 \iff x = y$
- 3. (triangle inequality) $d(x, y) + d(y, z) \ge d(x, z)$

Remark 1.1. If 1., 3. are satisfied but not 2., d can be called a "pseudo-distance".

○ Definition 1.2: Open Metric Space

Let (X, d) be a metric space. A subset $A \subseteq X$ is open $\iff \forall x \in A, \exists r = r(x) > 0$ s.t. $B(x, r(x)) \subseteq A$.

□ <u>Definition</u> 1.3: Normed Space

Let *X* be a vector space over \mathbb{R} . The norm on *X*, denoted $||x|| \in \mathbb{R}$, is a function that satisfies

- 1. $||x|| \ge 0$
- 2. $||x|| = 0 \iff x = 0$
- 3. $||c \cdot x|| = |c| \cdot ||x||$
- 4. $||x + y|| \le ||x|| + ||y||$

If *X* is a normed vector space over \mathbb{R} , we can define a distance *d* on *X* by d(x, y) = ||x - y||.

\hookrightarrow Proposition 1.1

If *X* is a normed vector space over \mathbb{R} , a distance *d* on *X* by d(x, y) = ||x - y|| makes (X, d) a metric space.

Proof. 1. $d(x, y) = ||x - y|| \ge 0$

- 2. $d(x,y) = 0 \iff ||x-y|| = 0 \iff x-y=0 \iff x=y$
- 3. $d(x,y) + d(y,z) = ||x y|| + ||y z|| \ge ||(x y) + (y z)|| = ||x z|| := d(x,z)$

Solution Example 1.1: L^p distance in \mathbb{R}^n

Let $\overline{x} \in \mathbb{R}^n$, $x = (x_1, x_2, \dots, x_n)$. The L^p norm is defined

$$||x||_p := (|x_1|^p + |x_2|^p + \dots + |x_n|^p)^{\frac{1}{p}}.$$

In the case p = 2, n = 2, we simply have the standard Euclidean distance over \mathbb{R}^2 .

<u>Unit Balls:</u> consider when $||x||_p$ ≤ 1, over \mathbb{R}^2 .

- $p = 1 : |x_1| + |x_2| \le 1$; this forms a "diamond ball" in the plane.
- $p = 2 : \sqrt{|x_1|^2 + |x_2|^2} \le 1$; this forms a circle of radius 1. Clearly, this surrounds a larger area than in p = 2.

A natural question that follows is what happens as $p \to \infty$? Assuming $|x_1| \ge |x_2|$:

$$||x||_{p} = (|x_{1}|^{p} + |x_{2}|^{p})^{\frac{1}{p}}$$

$$= \left[|x_{1}|^{p} \left(1 + \left|\frac{x_{2}}{x_{1}}\right|^{p}\right)\right]^{\frac{1}{p}}$$

$$= |x_{1}| \left(1 + \left|\frac{x_{2}}{x_{1}}\right|^{p}\right)^{\frac{1}{p}}$$

If $|x_1| > |x_2|$, this goes to $|x_1|$. If they are instead equal, then $||x||_p = |x_1| \cdot 2^{\frac{1}{p}} \to |x_1| \cdot 1$ as well. Hence, $\lim_{p\to\infty} ||x||_p = \max\{|x_1|, |x_2|\}$. Thus, the unit ball will approach $\max\{|x_1|, |x_2|\} \le 1$, that is, the unit square.

\hookrightarrow Proposition 1.2

Let $x \in \mathbb{R}^n$. Then, $||x||_p \to \max\{|x_1|, \dots, |x_n|\}$ as $p \to \infty$.

Remark 1.2. This is an extension of the previous example to arbitrary real space; the proof follows nearly identically.

○ Definition 1.4: Convex Set

Let X be a normed space, and take $x, y \in X$. The line segment from x to y is the set

$$\{t\cdot x+(1-t)\cdot y:0\leq t\leq 1\}.$$

Let $A \subseteq X$. A is *convex* $\iff \forall x, y \in A$, we have that

$$(t \cdot x + (1 - t) \cdot y) \in A \,\forall \, 0 \leq t \leq 1.$$

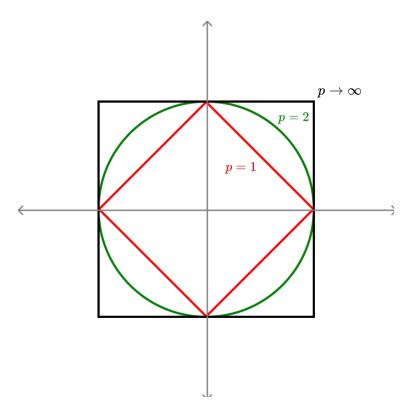


Figure 1: Regions of \mathbb{R}^2 where $||x||_p \le 1$ for various values of p.

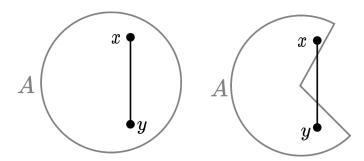


Figure 2: Convex (left) versus not convex (right) sets.

Remark 1.3. Think of this as saying "a set is convex iff every point on a line segment connected any two points is in the set".

\hookrightarrow **Definition 1.5:** ℓ_p

The space ℓ_p of sequences is defined as

$$\{x = (x_1, x_2, \dots, x_n, \dots) : \sum_{n=1}^{\infty} |x_n|^p < +\infty\} *.$$

Then, * defines the ℓ^p norm on the space of sequences; that is, $||x||_p := \left(\sum_{n=1}^{\infty} |x_n|^p\right)^{\frac{1}{p}}$.

Solution Example 1.2: ℓ_p , $x_n = \frac{1}{n}$

. Let $x_n = \frac{1}{n}$. For which p is $x \in \ell_p$? We have, raising the norm to the power of p for ease:

$$||x||_p^p = |x_1|^p + |x_2|^p + \dots + |x_n|^p + \dots$$

= $1^p + \left(\frac{1}{2}\right)^p + \dots < \infty \iff p > 1.$

In the case that p = 1, this becomes a harmonic sum, which diverges.

\circledast Example 1.3: L^p space of functions

Let f(x) be a continuous function. We define the norm of f over an interval [a, b]

$$||f||_p = \left[\int_a^b |f(x)|^p dx\right]^{\frac{1}{p}}.$$

Remark 1.4. Triangle inequality for $||x||_p$ or $||f||_p$ is called Minkowski inequality; $||x||_p + ||y||_p \ge ||x + y||_p$. This will be discussed further.

® Example 1.4: Distances between sets in \mathbb{R}^2

Let A, B be bounded, closed, "nice" sets in \mathbb{R}^2 . We define

$$d(A, B) := Area(A \triangle B),$$

where

$$A \triangle B : (A \setminus B) \cup (B \setminus A) = (A \cup B) \setminus (A \cap B).$$

It can be shown that this is a "valid" distance.

Remark 1.5. \triangle denotes the "symmetric difference" of two sets.

SEXAMPLE 1.5: *p*-adic distance

Let p be a prime number. Let $x = \frac{a}{b} \in \mathbb{Q}$, and write $x = p^k \cdot \left(\frac{c}{d}\right)$, where c, d are not divisible by p. Then, the p-adic norm is defined $||x||_p := p^{-k}$. It can be shown that this is a norm.

Suppose
$$p = 2$$
, $x = 28 = 4 \cdot 7 = 2^2 \cdot 7$. Then, $||28||_2 = 2^{-2} = \frac{1}{4}$; similarly, $||1024||_2 = ||2^{10}||_2 = 2^{-10}$.

More generally, we have that $||2^k||_2 = 2^{-k}$; coversely, $||2^{-k}|| = 2^k$. That is, the closer to 0, the larger the distance, and vice versa, contrary to our notion of Euclidean distance.

→ Proposition 1.3

 $||x||_p$ as defined above is a well-defined norm over \mathbb{Q} .

2 Point-Set Topology

2.1 Definitions

○ Definition 2.1: Topological space

A set X is a topological space if we have a collection of subsets τ of X called *open sets* s.t.

- 1. $\emptyset \in \tau, X \in \tau$
- 2. Consider $\{A_{\alpha}\}_{{\alpha}\in I}$ where A_{α} an open set for any α ; then, $\bigcup_{{\alpha}\in I}A_{\alpha}\in \tau$, that is, it is also an open set.
- 3. If *J* is a finite set, and A_{β} open for all $\beta \in J$, then $\bigcap_{\beta \in J} A_{\beta} \in \tau$ is also open.

In other words, 2.: arbitrary unions of open sets are open, and 3.: finite intersections of open sets are open.

→ Definition 2.2: Closed sets

Closed sets are complements of open sets; hence, axioms for closed sets follow appropriately;

- 1.* X, \emptyset closed;
- 2.* B_{α} closed $\forall \alpha \in I \implies \bigcap_{\alpha \in I} B_{\alpha}$ closed.
- 3.* B_{β} closed $\forall \beta \in J$, J finite, then $\bigcup_{\beta \in J} B_{\beta}$ also closed.

← Lecture 01; Last Updated: Tue Feb 13 09:24:32 EST 2024

→ Definition 2.3: Equivalence of Metrics

Suppose we have a metric space X with two distances d_1 , d_2 ; will these necessarily admit the same topology?

A sufficient condition is that, if $\forall x \neq y \in X$, $\exists 1 < C < +\infty$ s.t.

$$\frac{1}{C} < \frac{d_1(x,y)}{d_2(x,y)} < C.$$

That is, the distances are equivalent, up to multiplication by a constant.

Indeed, this condition gives that $d_2 < Cd_1$ and $d_2 > \frac{d_1}{C}$; this gives

$$B_{d_1}(x,\frac{r}{c}) \subseteq B_{d_2}(x,r) \subseteq B_{d_1}(x,C\cdot r).$$

Hence, d_1 , d_2 define the same open/closed sets on X thus admitting the same topologies. We write $d_1 \times d_2$.

Remark 2.1. If $d_1 \times d_2$ and $d_2 \times d_3$, then also $d_1 \times d_3$. Moreover, clearly, $d_1 \times d_1$ and $d_1 \times d_2 \implies d_2 \times d_1$, hence this is a well-defined equivalence relation.

Hence, its enough to show that $\forall 1 , we have <math>||x||_p \approx ||x||_\infty$ to show that any $||x||_q$ norm are equivalent for all q on \mathbb{R}^n .

→ **Definition** 2.4: Interior, Boundary of a Topological Set

Let *X* be a topological space, $A \subseteq X$ and let $x \in X$. We have the following possibilities

1. $\exists U$ -open : $x \in U \subseteq A$. In this case, we say $x \in \text{the } interior \text{ of } A$, denoted

$$x \in Int(A)$$
.

2. $\exists V$ -open : $x \in V \subseteq X \setminus A = A^C$. In this case, we write

$$x \in Int(X^C)$$
.

3. \forall *U*-open : $x \in U$, $U \cap A \neq \emptyset$ AND $U \cap A^C \neq \emptyset$. In this case, we say x is in the *boundary* of A, and denote

$$x \in \partial A$$
.

○ Definition 2.5: Closure

 $x \in \text{Int}(A) \text{ or } x \in \partial A \text{ (that is, } x \in \text{Int}(A) \cup \partial A) \iff \text{ every open set } U \text{ that contains } x \text{ intersects } A.^1\text{Such points are called } limit points \text{ of } A. \text{ The set of all limits points of } A \text{ is called the } closure \text{ of } A, \text{ denoted } \overline{A}.$

$$\operatorname{Int}(A) \subseteq A \subseteq \overline{A} = \operatorname{Int}(A) \cup \partial A$$
.

\hookrightarrow **Proposition 2.1: Properties of** Int(*A*)

Int(A) is *open*, and it is the largest open set contained in A. It is the union of all U-open s.t. $U \subseteq A$. Moreover, we have that

$$Int(Int(A)) = Int(A).$$

\hookrightarrow Proposition 2.2: Properties of \overline{A}

 \overline{A} is *closed*; \overline{A} is the smallest closed set that contains A, that is, $\overline{A} = \bigcap B$ where B closed and $A \subseteq B$. We have too that

$$\overline{(\overline{A})} = \overline{A}.$$

← Proposition 2.3

- 1. A is open \iff A = Int(A)
- 2. A is closed \iff $A = \overline{A}$

2.2 Basis

Let τ be a topology on X. Let $\mathcal{B} \subseteq \tau$ be a collection of open sets in X such that every open set is a union of open sets in \mathcal{B} .

® Example 2.1: Example Basis

 $X = \mathbb{R}$, and $\mathcal{B} = \{\text{all open intervals } (a, b) : -\infty < a < b < +\infty\}.$

← Proposition 2.4

Let \mathcal{B} be a collection of open sets in X. Then, \mathcal{B} is a basis \iff

- 1. $\forall x \in X, \exists U$ -open $\in \mathcal{B}$ s.t. $x \in U$.
- 2. If $U_1 \in \mathcal{B}$ and $U_2 \in \mathcal{B}$, and $x \in U_1 \cap U_2$, then $\exists U_3 \in \mathcal{B}$ s.t. $x \in U_3 \subseteq U_1 \cap U_2$.

¹"Requires" proof.

⊗ Example 2.2

Consider $X = \mathbb{R}$. Requirement 1. follows from taking $U = (x - \varepsilon, x + \varepsilon)$ for any $\varepsilon > 0$. For 2., suppose $x \in (a,b) \cap (c,d) =: U_1 \cap U_2$. Let $U_3 = (\max\{a,c\}, \min\{b,d\})$; then, we have that $U_3 \subseteq U_1 \cap U_2$, while clearly $x \in U_3$.

→ Proposition 2.5

In a metric space, a basis for a topology is a collection of open balls,

$$\{B(x,r): x \in X, r > 0\} = \{\{y \in X: d(x,y) < r\}: x \in X, r > 0\}.$$

Proof. We prove via proposition 2.4. Property 1. holds clearly; $x \in B(x, \varepsilon)$ -open $\subseteq \mathcal{B}$.

For property 2., let $x \in B(y_1, r_1) \cap B(y_2, r_2)$, that is, $d(x, y_1) < r_1$ and $d(x, y_2) < r_2$. Let

$$\delta := \min\{r_1 - d(x, y_1), r_2 - d(x, y_2)\}.$$

We claim that $B(x, \delta) \subseteq U_1 \cap U_2$.

Let $z \in B(x, \delta)$. Then,

$$d(z, y_1) \stackrel{\triangle \neq}{\leq} d(z, x) + d(x, y_1) < \delta + d(x, y_1) \leq r_1 - d(x, y_1) + d(x, y_1) = r_1,$$

hence, as $d(z, y_1) < r_1 \implies z \in B(y_1, r_1) = U_1$. Replacing each occurrence of y_1, r_1 with y_2, r_2 respectively gives identically that $z \in B(y_2, r_2) = U_2$. Hence, we have that $B(x, \delta) \subseteq U_1 \cap U_2$ and 2. holds.

2.3 Subspaces

○ Definition 2.7

Let *X* be a topological space and let $Y \subseteq X$. We define the subspace topology on *Y*:

1. Open sets in $Y = \{Y \cap \text{ open sets in } X\}$

→ Proposition 2.6: Consequences of Subspace Topologies

Suppose \mathcal{B} is a basis for a topology in X. Then, $\{U \cap Y : U \in \mathcal{B}\}$ forms a basis for the subspace $Y \subseteq X$.

Suppose *X* a metric space. Then, *Y* is also a metric space, with the same distance.

\hookrightarrow Proposition 2.7

Let $Y \subseteq X$ - a metric space. Then, the metric space topology for (Y, d) is the same as the subspace topology.

Proof. (Sketch) A basis for the open sets in X can be written $\bigcup_{\alpha \in I} B(x_\alpha, r_\alpha)$; hence

$$Y \cap (\bigcup_{\alpha \in I} B(x_{\alpha}, r_{\alpha})) = \bigcup_{\alpha \in I} (Y \cap B(x_{\alpha}, r_{\alpha}))$$

is an open set topology for *Y*.

→ Lemma 2.1

Let $A \subseteq X$ -open, $B \subseteq A$; B-open in subspace topology for $A \iff B$ -open in X.

← Lemma 2.2

Let $Y \subseteq X$, $A \subseteq Y$. Then, \overline{A} in $Y = Y \cap \overline{A}$ in X. We can denote this

$$\overline{A}_Y = \overline{A}_X \cap Y$$
.

2.4 Continuous Functions

→ Definition 2.8: Continuous Function

Let X, Y be topological spaces. Let $f: X \to Y$. f is continuous $\iff \forall$ open $V \in Y$, $f^{-1}(V)$ -open in X.

\hookrightarrow Proposition 2.8

This definition is consistent with the normal ε - δ definition on the real line.

Proof. Let $f : \mathbb{R} \to \mathbb{R}$, continuous; that is, $\forall \varepsilon > 0$, $\forall x \in \mathbb{R} \exists \delta > 0$ s.t. $|x_1 - x| < \delta$, then $|f(x_1) - f(x)| < \varepsilon$.

Let $V \subseteq \mathbb{R}$ open. Let $y \in V$. Then, $\exists \varepsilon : (y - \varepsilon, y + \varepsilon) \subseteq V$. Let y = f(x), hence $y \in f^{-1}(V)$. Now, if $d(x, x_1) < \delta$, we have that $d(f(x_1), f(x)) < \varepsilon$ (by continuity of f), hence $f(x_1) \in (y - \varepsilon, y + \varepsilon) \subseteq V$; moreover, $(x - \delta, x + \delta) \subseteq f^{-1}(V)$, thus $f^{-1}(V)$ is open as required.

The inverse of this proof follows identically.

← Lecture 02; Last Updated: Thu Jan 11 08:52:09 EST 2024

← Proposition 2.9

Suppose \mathcal{B} forms a basis of topology for Y. Then, $f: X \to Y$ is continuous if $f^{-1}(U)$ open $\forall U \in \mathcal{B}$.

Proof. If *U*-open set in *Y*, then $\exists I$ -index set and a collection of open sets $\{A_{\alpha}\}_{{\alpha}\in I}, A_{\alpha}\in \mathcal{B}$, s.t. $U=\cup_{{\alpha}\in I}A_{\alpha}$. Then, we have

$$f^{-1}(U)=f^{-1}(\cup_{\alpha\in I}(A_\alpha))=\cup_{\alpha\in I}\underbrace{f^{-1}(A_\alpha)}$$

Hence, if each $f^{-1}(A_{\alpha})$ open, then $\bigcup_{\alpha \in I} f^{-1}(A_{\alpha})$ open; hence it suffices to check if $f^{-1}(U) \forall U$ -open in V is open to see if f continuous.

→ Theorem 2.1: Continuity of Composition

If $f: X \to Y$ continuous and $g: Y \to Z$ continuous, then $g \circ f$ continuous as well.

Proof. Let *U*-open in *Z*. Then

$$(g \circ f)^{-1}(U) = f^{-1}(\underbrace{g^{-1}(U)}_{\text{open in } Y})$$

→ Proposition 2.10

If $f: X \to Y$ continuous and $A \subseteq X$, A has subspace topology, then $f|_A: A \to Y$ is also continuous.²

Proof. Let *U*-open in *Y*. Then

$$(f|_A)^{-1}(U) = \underbrace{f^{-1}(U)}_{\text{open}} \cap \underbrace{A}_{\text{open}}$$

By the definition of subspace topology, this is an open set and hence $f|_A$ is continuous.

2.5 Product Spaces

□ <u>Definition</u> 2.9: Finite Product Spaces

Let X_1, \ldots, X_n be topological spaces. We define

$$(X_1 \times X_2 \times \cdots \times X_n),$$

and aim to define a product topology; a basis of which consists of cylinder sets.

 $^{{}^{2}\}overline{\text{We denote } f|_{A}}$ as the restriction of the domain of f to A.

→ Definition 2.10: Cylinder Set

A cylinder set has the form

$$A_1 \times A_2 \times \cdots \times A_n$$

where each A_i -open in X_i .

⊗ Example 2.3

Given an open interval (a_1, b_1) , $(a_2, b_2) \subset \mathbb{R}$, the set $(a_1, b_1) \times (a_2, b_2) \subset \mathbb{R}^2$ is a basis for the topology on \mathbb{R}^2 .

○ Definition 2.11: Projection

Let $X_1 \times X_2 \times \cdots \times X_n =: X$. The projection $\pi_j : X \to X_j$ maps $(x_1, \dots, x_n) \to x_j \in X_j$.

Remark 2.3. *One can show* π_i *continuous.*

○ <u>Definition</u> 2.12: Coordinate Function

Given a function $f: Y \to X_1 \times \cdots \times X_n = (x_1(y), x_2(y), \dots, x_n(y))$. The *coordinate function* is

$$f_j = \pi_j \circ f; \quad f_j = x_j(y).$$

→ Proposition 2.11

 $f: Y \to X = X_1 \times \cdots \times X_n$ continuous $\iff f_j: Y \to X_j$ continuous.

Proof. Its enough to show that $\forall U \in \mathcal{B}$ -basis for X-product space, $f^{-1}(U)$ -open in Y. Take $U = A_1 \times \cdots A_n$ open. Then, we claim that

$$f^{-1}(U) = f^{-1}(A_1 \times \dots \times A_n) = f_1^{-1}(A_1) \cap f_2^{-1}(A_2) \cap \dots \cap f_n^{-1}(A_n).$$

If this holds, then as each f_i continuous (being a composition of continuous functions) and each A_i open in X_i , then each $f_i^{-1}(A_i)$ open in Y and hence \star , being the finite intersection of open sets in Y, is itself open in Y.

® Example 2.4: Fourier Transform: Motivation for Infinite Product Toplogies

Let $f \in C([0, 2\pi])$ is real-valued. We write the *n*th Fourier coefficients

$$\hat{f}(n) = \frac{1}{2\pi} \int_0^{2\pi} f(x)e^{-inx} dx$$

$$= \frac{1}{2\pi} \int_0^{2\pi} f(x)\cos(nx) dx - i\frac{1}{2\pi} \int_0^{2\pi} f(x)\sin(nx) dx.$$

And the Fourier transform of f as the infinite product

$$f(x) \mapsto (\dots, \hat{f}(-n), \hat{f}(-n+1), \dots, \hat{f}(-1), \hat{f}(0), \hat{f}(1), \dots, \hat{f}(n), \dots) \in \prod_{n \in \mathbb{Z}} (\mathbb{C})_n.$$

Hence, this is an (countably, as indexed by integers) infinite product space.

Now, let $f : \mathbb{R} \to \mathbb{R}$. Suppose $f(x) \to 0$ "fast enough" as $|x| \to \infty$ and f continuous. Then, we can define the Fourier coefficients

$$\hat{f}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x)e^{-itx} \, \mathrm{d}x,$$

where $t \in \mathbb{R}$. We then have the transform

$$f \mapsto \{\hat{f}(t)\}_{t \in \mathbb{R}}.$$

In this case, our index set is \mathbb{R} is (uncountably) infinite.

\hookrightarrow <u>Definition</u> 2.13: Product Topology/Cylinder Sets for ∞ Products

Let $X = \prod_{\alpha \in I} X_{\alpha}$. Then, a basis for X is given by cylinder sets of the form $A = \prod_{\alpha \in I} A_{\alpha}$ where A_{α} -open in X_{α} , AND $A_{\alpha} = X_{\alpha}$ except for finitely many indices α .

That is, there exists a finite set $J = (\alpha_1, \dots, \alpha_k) \subseteq I$, such that we can write $A = \prod_{\alpha \in J} A_\alpha \times \prod_{\alpha \notin J} X_\alpha$ (where A_α open in X_α).

\hookrightarrow Proposition 2.12

Given $f: Y \to \prod_{\alpha \in I} X_{\alpha} = X$, then (taking $f_{\alpha} = \pi_{\alpha} \circ f$ as before) we have that f is continuous in $X \iff f_{\alpha}: Y \to X_{\alpha}$ continuous in $X_{\alpha} \forall \alpha \in I$.

Remark 2.4. Extension of proposition 2.11 to infinite product space.

Proof. Write $U = \prod_{\alpha \in J} A_{\alpha} \times \prod_{\alpha \notin J} X_{\alpha}$. Then,

$$f^{-1}(U) = \bigcap_{\alpha \in I} f_{\alpha}^{-1}(A_{\alpha})$$

which is open in Y, hence f continuous.

Remark 2.5. The intersection of the entire spaces give no restriction.

← Lecture 03; Last Updated: Fri Jan 19 11:49:27 EST 2024

2.6 Metrizability

← Proposition 2.13

Different metrics can define the same topology.

⊗ Example 2.5

- 1. Different ℓ_p metrics in \mathbb{R}^n (PSET 1)
- 2. Let (X, d) be a metric space. Then,

$$\tilde{d}(x,y) := \frac{d(x,y)}{d(x,y)+1}$$

is also a metric (the first two axioms are trivial), and defines the same topology. Note, moreover, that $\tilde{d}(x,y) \leq 1 \,\forall \, x,y$; this distance is bounded, and can often be more convenient to work with in particular contexts.

\hookrightarrow Question 2.1

Suppose (X_k, d_k) are metric spaces $\forall k \ge 1$. Then, we can define the product topology τ on

$$X:=\prod_{k=1}^{\infty}X_k.$$

Does the product topology τ come from a metric? That is, is τ *metrizable*?

Remark 2.6. There do indeed exist examples of non-metrizable topological spaces; this question is indeed well-founded.

Answer. Let $\underline{x} = (x_1, x_2, \dots, x_n, \dots), \underline{y} = (y_1, y_2, \dots, y_n, \dots) \in \prod_{k=1}^{\infty}$ (where $x_i, y_i \in X_i$) be infinite sequences of elements. Then, for each metric space X_k take the metric

$$\tilde{d}_k(x_k,y_k) = \frac{d_k(x_k,y_k)}{1 + d_k(x_k,y_k)}$$

\$2.6 Point-Set Topology: Metrizability

(as in the example above). Then, we define

$$D(\underline{x},\underline{y}) = \sum_{k=1}^{\infty} \frac{\tilde{d}_k(x_k,y_k)}{2^k},$$

noting that $D(\underline{x}, \underline{y}) \leq \sum_{k=1}^{\infty} \frac{1}{2^k} = 1$ (by our construction, "normalizing" each metric), hence this is a valid, *converging* metric (which wouldn't otherwise be guaranteed if we didn't normalize the metrics). It remains to show whether this metric omits the same topology as τ .

2.7 Compactness, Connectedness

○ Definition 2.14: Compact

A set *A* in a topological space is said to be *compact* if every cover has a finite subcover. That is, if

$$A \subseteq \bigcup_{\alpha \in I} U_{\alpha}$$
 – open,

then $\exists \{\alpha_1, \ldots, \alpha_n \in I\}$ such that $A \subseteq \bigcup_{i=1}^n U_{\alpha_i}$.

→ Proposition 2.14

A closed interval [a, b] is compact.

<u>Proof.</u> If a = b, this is clear. Suppose a < b, and let $[a, b] \subseteq \bigcup_{i \in I} U_i =: \mathcal{U}$ be an arbitrary cover. Then, we proceed in the following steps:

1. **Claim:** Given $x \in [a, b], x \neq b, \exists y \in [a, b]$ s.t. [x, y] has a finite subcover.

Let $x \in [a,b]$, $x \neq b$. Then, $\exists U_{\alpha} \in \mathcal{U} : x \in U_{\alpha}$. Since U_{α} open, and $x \neq b$, we further have that $\exists c \in [a,b]$ s.t. $[x,c) \subseteq U_{\alpha}$.

Now, let $y \in (x, c)$; then, the interval $[x, y] \subseteq [x, c) \subseteq U_{\alpha}$, that is, [x, y] has a finite subcover.

- 2. Define $C := \{y \in [a, b] : y > a, [a, y] \text{ has a finite subcover}\}$. We note that
 - $C \neq \emptyset$; taking x = a in Step 1. above, we have that $\exists y \in [a, b]$ such that [a, y] has a finite step cover, so this $y \in C$.
 - *C* bounded; by construction, $\forall y \in C$, $a < y \le c$.

Thus, we can validly define $c := \sup C$, noting that $a < c \le b$. Ultimately, we wish to prove that c = b, completing the proof that [a, b] has a finite subcover.

3. Claim: $c \in C$.

Let $U_{\beta} \in \mathcal{U} : c \in U_{\beta}$. Then, by the openness of U_{β} , $\exists d \in [a, b]$ s.t. $(d, c] \subseteq U_{\beta}$.

³This proof is adapted from that of Theorem 27.1 in Munkre's Topology, an identical theorem but applied to more general ordered topologies.

Supposing $c \notin C$, then $\exists z \in C$ such that $z \in (d, c)$; if one did not exist, then this would imply that d was a smaller upper bound that c, a contradiction. Thus, $[z, c] \subseteq (d, c] \subseteq U_{\beta}$.

Moreover, we have that, given $z \in C$, [a, z] has a finite subcover; call it $U_z \subseteq \mathcal{U}$. This gives, then:

$$[a,c] = [a,z] \cup [z,c] \subseteq U_z \cup U_\beta.$$

But this is a finite subcover of [a, c], contradicting the fact that $c \notin C$. We conclude, then, that $c \in C$ after all.

4. Claim: c = b.

Suppose not; then, since we have $c \le b$, then assume c < b. Then, applying Step 1. with x = c (which we can do, by our assumption of $c \ne b$!), then we have that $\exists y > c$ s.t. [c, y] has a finite subcover, call this $U_y \subseteq \mathcal{U}$.

Moreover, we had $c \in C$, hence [a, c] has a finite subcover, call this $U_c \subseteq \mathcal{U}$.

Then, this gives us that

$$[a,y] = [a,c] \cup [c,y] \subseteq U_c \cup U_y,$$

that is, [a, y] has a finite subcover, and so $y \in C$. But recall that y > c; hence, this a contradiction to c being the least upper bound of C. We conclude that c = b, and thus [a, b] has a finite subcover, and is thus compact.

Remark 2.7. A similar proof shows that [a, b] is connected; we cannot cover it by two disjoint open sets.

Let $A \subseteq \mathbb{R}^n$. Then, A compact \iff A closed and bounded.

→ Proposition 2.15

If X, Y are compact topological spaces, then $X \times Y$ is compact.

Remark 2.8. By induction, if X_1, \ldots, X_n compact, so is $\prod_{i=1}^n X_i$.

→ Proposition 2.16

A closed subset of a compact topological space is compact in the subspace topology.

Proof. (Of theorem 2.2)

(\Leftarrow) If $A \subseteq \mathbb{R}^n$ closed and bounded, then $A \subseteq [-R, +R]^n$ for some R > 0 (it is contained in some "n-cube"). Then, we have that [-R, R] is compact, by proposition 2.14, proposition 2.15, and proposition 2.16, A itself compact.

(\Longrightarrow) Suppose $A \subseteq \mathbb{R}^n$ is compact. Then, $\bigcup_{x \in A} B(x, \varepsilon)$ for some $\varepsilon > 0$ is an open cover of A. As A compact, there must exist a finite subcover of this cover, $A \subseteq \bigcup_{i=1}^N B(x_i, r_i)$. Let $R := \max_{i=1}^N (||x_i|| + r_i)$. Then, $A \subseteq \overline{B(0, R)}$, that is, A is bounded.

Now, suppose x is a limit point of A. Then, any neighborhood of x contains a point in A, so $\forall r > 0$, $B(x,r) \cap A \neq \emptyset$, and so $\overline{B}(x,r)$ also contains a point of A for any r > 0.

Now, suppose $x \notin A$ (looking for a contradiction). Then,

$$U := \bigcup_{r>0} U_r := \bigcup_{r>0} (\mathbb{R}^n \setminus \overline{B(x,r)}) = \mathbb{R}^n \setminus \{x\}$$

is an open cover for the set A. A being compact implies that U has an finite subcover such that $A \subset U_{r_1} \cup U_{r_2} \cup \cdots \cup U_{r_N}$. Let $r_0 = \min_{i=1}^N r_i$. Then, $A \subseteq U_{r_0}$, and $A \cap B(x, r_0) = \emptyset$; but this is a contradiction to the definition of a limit point, hence any limit point x is contained in A and A is thus closed by definition.

→ Proposition 2.17

Compact \implies sequentially compact; that is, every sequence in a compact set has a convergent subsequence.

← Lecture 04; Last Updated: Wed Jan 24 21:27:59 EST 2024

→ Definition 2.15: Connected

A topological space X is not connected if $X = U \cup V$ for two open, nonempty, disjoint sets U, V.

If this does not hold, *X* is said to be *connected*.

A set $A \subseteq X$ is not connected if A is not connected in the subspace topology $\iff A = \subseteq U \cup V$, for U, V-open in $X, (U \cap A) \neq \emptyset, (V \cap A) \neq \emptyset$ and $U \cap V = \emptyset$.

\hookrightarrow Theorem 2.3

Let X be a connected topological space. Let $f: X \to Y$ be a continuous function. Then, f(X) is also connected.

Proof. Suppose, seeking a contradiction, that X is connected, but f(X) is not. Then, we can write $f(X) \subseteq Y$ as $\overline{f(X)} \subseteq U \cup V$, such that U, V open in Y and $U \cap V = \emptyset$. Then,

$$(U\cap f(X))\cap (V\cap f(X))=\varnothing.$$

We also have that

$$X \subseteq \underbrace{f^{-1}(U)}_{\text{open in } X, \neq \varnothing} \cup \underbrace{f^{-1}(V)}_{\text{open in } X, \neq \varnothing}.$$

 $f^{-1}(U) \cap f^{-1}(V) = \emptyset$ (that is, they are disjoint) by our assumption; this is a contradiction to the connectedness of X, as we are able to write it as a subset of two disjoint open sets. Hence, f(X) is indeed connected.

← Lemma 2.3

Any interval (a, b), [a, b], [a, b), ..., $\subseteq \mathbb{R}$ is connected.

Proof.

→ Theorem 2.4: "Intermediate Value Theorem"

Suppose *X* is connected and $f: X \to \mathbb{R}$ is a continuous function. Then, *f* takes intermediate values.

More precisely, let a = f(x), b = f(y) for $x, y \in X$. Assume a < b. Then, $\forall a < c < b$, $\exists z \in X$ s.t. f(z) = c.

Proof. Suppose, seeking a contradiction, that $\exists c : a < c < b \text{ s.t. } c \notin f(X)$ (that is, there exists an intermediate value that is "not reached" by the function).

Let $U = (-\infty, c)$ and $V = (c, +\infty)$; note that these are disjoint open sets. Then, we have that

$$X = f^{-1}(U) \cup f^{-1}(V),$$

by our assumption of $c \notin f(X)$. But this gives that X is not connected, as the union of two open (by continuity), disjoint, nonempty $(f(x) = a \in U \implies x \in f^{-1}(U), \text{ and } f(y) = b \in V \implies y \in f^{-1}(V))$ sets, a contradiction.

\hookrightarrow Theorem 2.5

Suppose X is compact, Y-topological space, $f: X \to Y$ is a continuous function. Then, f(X) is also compact.

Proof. Let $\{U_{\alpha}\}_{{\alpha}\in I}$ be an open cover of $f(X)\subseteq Y$, that is,

$$f(X) \subseteq \bigcup_{\alpha \in I} U_{\alpha} \implies X \subseteq f^{-1}(\bigcup_{\alpha \in I} U_{\alpha}) = \bigcup_{\alpha \in I} f^{-1}(U_{\alpha}) =: \bigcup_{\alpha \in I} V_{\alpha} - \text{open}.$$

Then, this is an open cover of X; X is compact, thus there exists a finite subcover, that is, indices $\{\alpha_1, \ldots, \alpha_n\} \subseteq I$ such that $X = \bigcup_{i=1}^n V_{\alpha_i}$. Thus,

$$f(X)\subseteq\bigcup_{i=1}^n U_{\alpha_i},$$

which is a finite subcover of f(X). Thus, f(X) is compact.

Remark 2.9. Recall the "extreme value theorem": let $f : [a,b] \to \mathbb{R}$ a continuous function; then, a minimum and maximum is obtained for f(x) on this interval for values in this interval.

→ Theorem 2.6

Let *X* compact, and $f: X \to \mathbb{R}$ a continuous function. Then,

$$\max_{x \in X} f(x)$$
 and $\min_{x \in X} f(x)$

are both attained.

<u>Proof.</u> $f(X) \subseteq \mathbb{R}$ is compact by theorem 2.5, and so by theorem 2.2, f(X) is closed and bounded. Let, then, $\overline{m} = \inf f(X)$ and $M = \sup f(X)$; these necessarily exist, since f(X) is bounded. Both m and M are limit points of f(X). But f(X) is closed, and hence contains all of its limit points, and thus $m \in f(X)$ and $M \in f(X)$, and thus $\exists y_m : f(y_m) = m$ and $y_M : f(y_M) = M$. ■

→ Definition 2.16: Path Connected

A set $A \subseteq X$ is called *path connected* if $\forall x, y \in A, \exists f : [a, b] \to X$, continuous, s.t. f(a) = x, f(b) = y and $f([a, b]) \subseteq A$.

The set $\{f(t): a \le t \le b\}$ is called a *path* from x to y.

→ Theorem 2.7: Path connected ⇒ connected

If $A \subseteq X$ is path connected, then A is connected.

Proof. Suppose, seeking a contradiction, that A is path connected, but not connected. Then, we can write $\overline{A \subseteq U} \cup V$, for open, disjoint, nonempty subsets $U, V \subseteq X$.

Let $x \in U \cap A$ and $y \in V \cap A$. Then, $\exists f : [a,b] \to A$ s.t. f(a) = x, f(b) = y, and $f([a,b]) \subseteq A$, by the path connectedness of A. Then,

$$[a,b] \subseteq f^{-1}(A) \subseteq \underbrace{f^{-1}(U \cap A)}_{\text{open}} \cup \underbrace{f^{-1}(V \cap A)}_{\text{open}} =: \underbrace{U_1}_{a \in } \cup \underbrace{U_2}_{b \in },$$

that is, [a, b] is contained in a union of open, nonempty, disjoint sets, contradicting [a, b] the connectedness of [a, b] by lemma 2.3. Thus, A is connected.

Remark 2.10. A counterexample to the opposite side of the implication is the Topologist's sine curve, the set

$$\{(x, \sin\left(\frac{1}{x}\right)) : x \in (0,1]\} \cup \{0\} \times [-1,1].$$

This set is connected in \mathbb{R}^2 , but is not path connected.

→ Proposition 2.18

For open sets in \mathbb{R}^n , path connected \iff connected.

2.8 Path Components, Connected Components

Remark 2.11. Remark that if a metric space X is not connected, then we can write $X = U \cup V$ where U, V are open, nonempty and disjoint. It follows, then, that $U = V^{C}$ (and vice versa) and hence U, V are both open and closed.

→ **Definition** 2.17: Connected Component

A connected component of $x \in X$ is the largest connected subset of X that contains x.

⊗ Example 2.6

Let $X = (0, 1) \cup (1, 2)$. Here, we have two connected components, (0, 1) and (1, 2)

® Example 2.7: Middle Thirds Cantor Set

Let $C_0 := [0, 1]$, and given C_n , define $C_{n+1} := \frac{1}{3} (C_n \cup (2 + C_n))$ for $n \ge 0$. C_∞ is totally disconnected.

→ Definition 2.18: Path Component

A path component P(x) of $x \in X$ is the largest path connected subset of X that contains x.

→ Proposition 2.19

 $P(x) = \{x \in X : \exists \text{ conintuous path } \gamma : [0,1] \rightarrow X : \gamma(0) = x, \gamma(1) = y\}.$

Remark 2.12. Where we "start" a path does not matter. We write $x \sim y$ if $\exists \gamma$ from x to y; this is an equivalence relation on the elements of X.

Remark 2.13. The choice of [0,1] here is arbitrary; any closed interval is homeomorphic.

→ Lemma 2.4

If $P(x) \cap P(y) \neq \emptyset$, then P(x) = P(y).

Proof. $P(x) \cap P(y) \neq \emptyset \implies \exists z : x \sim z \land y \sim z \implies x \sim y.$

← Lemma 2.5

If $A \subseteq X$ is connected, then \overline{A} is also connected.

← Lemma 2.6

Suppose $A \subseteq X$ is both open and closed. Then, if $C \subseteq X$ is connected and $C \cap A \neq \emptyset$, then $C \subseteq A$.

<u>Proof.</u> If A is both open and closed, then $C \cap A$ is both open and closed in C. If $C \cap A^C \neq \emptyset$, then this is also open and closed in C. Hence, we can write $C = (C \cap A) \cup (C \cap A^C)$, that is, a disjoint union of two nonempty open sets, contradicting the connectedness of C. Hence, $C \cap A^C = \emptyset$, and so $C \subseteq A$.

→ Proposition 2.20

Let $\{C_{\alpha}\}_{{\alpha}\in I}$ be a collection of nonempty connected subspaces of X s.t. $\forall \alpha, \beta \in I, C_{\alpha} \cap C_{\beta} \neq \emptyset$. Then, $\bigcup_{\alpha \in I} C_{\alpha}$ is connected.

→ Proposition 2.21

Suppose each $x \in X$ has a path-connected neighborhood. Then, the path components in X are the same as the connected components in X.

2.8.1 Cantor Staircase Function

→ <u>Definition</u> 2.19: An Explicit Definition

Let
$$x \in C : x = 0.a_1 a_2 a_3 \dots$$
 (base 3), ie $a_j = \begin{cases} 0 \\ 2 \end{cases}$. Define

$$f(x) = \begin{cases} \sum \frac{a_j/2}{2^j} & x \in C \\ \text{extend by continuity} & x \notin C. \end{cases}$$

That is, if $x \notin C$, set $f(y) = \sup_{x \in C, x < y} f(x) = \inf_{x \in C, x > y} f(x)$.

→ **Definition 2.20:** Complement Definition

To construct the complement of the Cantor set, begin with [0,1] and at a step n, we remove 2^n open intervals from this interval. f(x) will be constant on each of these intervals with values $\frac{k}{2^n}$ where k odd and $0 < k < 2^n$. Extend by continuity to all $x \in C$.

Remark 2.14. Wikipedia's explanation of this is far better than whatever this definition is trying to say.

 $\hookrightarrow Lecture~06; Last~Updated:~Tue~Jan~23~11:03:35~EST~2024$

3 L^p Spaces

3.1 Review of ℓ^p Norms

Remark 3.1. Recall that for $1 \le p \le +\infty$, we define for $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ the norm

$$||x||_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}, \quad ||x||_{\infty} = \max_{i=1}^n |x_i|.$$

Similarly, for infinite vector spaces, we had, for $x = (x_1, ..., x_n, ...)$, the norm

$$||x||_p = \left(\sum_{i=1}^{\infty} |x_i|^p\right)^{\frac{1}{p}}, \quad ||x||_{\infty} = \sup_{i \geqslant 1} |x_i|.$$

Here, we define

$$\ell_p := \{x = (x_1, \dots, x_n) : ||x||_p < +\infty\}.$$

3.2 ℓ^p Norms, Hölder-Minkowski Inequalities

→ **Definition** 3.1: Hölder Conjugates

For $1 \le p$, $q \le +\infty$, we say that p, q are said to be *Hölder conjugates* if

$$\frac{1}{p} + \frac{1}{q} = 1.$$

Remark 3.2. We refer to these simply as "conjugates" throughout as no other conception of conjugate numbers will be discussed.

Further, we take by convention $\frac{1}{\infty} = 0$.

→ Proposition 3.1: Hölder's Inequality

Let $x = (x_1, ..., x_n), y = (y_1, ..., y_n) \in \mathbb{R}^n$. Suppose $p, q : 1 \le p, q \le +\infty$ are conjugate. Then,

$$\langle x, y \rangle_{\mathbb{R}^n} := \left| \sum_{i=1}^n x_i y_i \right| \le ||x||_p \cdot ||y||_q$$

⊗ Example 3.1

For the case p = 1 or ∞ (functionally, the same case):

← Lemma 3.1

Let p, q be conjugates, and x, $y \ge 0$. Then,

$$xy \leqslant \frac{x^p}{p} + \frac{y^q}{q}.$$

Remark 3.3. If the inequality holds, then, for some t > 0, let $\tilde{x} = t^{\frac{1}{p}} \cdot x$, $\tilde{y} = t^{\frac{1}{q}}y$. Substituting x for \tilde{x} and y for \tilde{y} , we have

LHS:
$$\tilde{x}\tilde{y} = t^{\frac{1}{p}}x \cdot t^{\frac{1}{q}}y = t^{\frac{1}{p} + \frac{1}{q}} \cdot xy = xy$$

RHS: $\cdots = t(\frac{x^p}{p} + \frac{y^q}{q})$

That is, we have

$$t \cdot xy \le t \left(\frac{x^p}{p} + \frac{y^q}{q} \right),$$

hence, the inequality is preserved under multiplication by a positive scalar; moreover, the original inequality holds iff this "scaled" version holds. Hence, choosing t such that $\tilde{y} = 1$ (let $t = \left(\frac{1}{y}\right)^q$), it suffices to prove the lemma for y = 1.

<u>Proof.</u> If x = 0 or y = 0, then the entire LHS becomes 0 and we are done; assume x, y > 0; by the previous remark, assume wlog y = 1. Then, we have

$$x \cdot y \le \frac{x^p}{p} + \frac{y^q}{q} \iff x \cdot 1 \le \frac{x^p}{p} + \frac{1}{q}$$
 $\iff \frac{x^p}{p} - x + \frac{1}{q} =: f(x) \ge 0.$

Taking the derivative, we have

$$f'(x) = \frac{px^{p-1}}{p} - 1 = x^{p-1} - 1$$

$$p > 1 \implies p - 1 > 0 \implies \begin{cases} f'(x) > 0 & \forall x > 1 \\ f'(x) = 0 & x = 0 \\ f'(x) < 0 & \forall 0 < x < 1 \end{cases}$$

Hence, x = 1 is a local minimum of the function, and thus $f(x) \ge f(1) \, \forall \, 0 < x \le 1$. But $f(1) = \frac{1^p}{p} - 1 + \frac{1}{q} = 1 - 1 = 0$, hence $f(x) \ge 0 \, \forall \, x \ge 0$, as desired, and the inequality holds.

Proof. Assume $||x||_p = ||y||_q = 1$. Then,

$$\left|\sum_{i=1}^{n} x_{i} y_{i}\right| \leq \sum_{i=1}^{n} |x_{i} y_{i}| \qquad (by triangle inequality)$$

$$\leq \sum_{i=1}^{n} \left|\frac{x_{i}^{p}}{p} + \frac{y_{i}^{q}}{q}\right| \qquad (by lemma 3.1)$$

$$= \frac{1}{p} \left(\sum_{i=1}^{n} |x_{i}|^{p}\right) + \frac{1}{q} \left(\sum_{i=1}^{n} |y_{i}|^{q}\right)$$

$$= \frac{1}{p} ||x||_{p}^{p} + \frac{1}{q} ||y||_{q}^{q} \qquad (by staring)$$

$$= \frac{1}{p} \cdot 1^{p} + \frac{1}{q} \cdot 1^{1} = \frac{1}{p} + \frac{1}{q} = 1 \qquad (by assumption)$$

$$= ||x||_{p} \cdot ||y||_{q},$$

and the proposition holds, in the special case $||x||_p = ||y||_q = 1$.

If $||x||_p = 0$ or $||y||_q = 0$, then $x_1 = \cdots = x_n = 0$ or $y_1 = \cdots = y_n = 0$, resp., then we'd have $(||x||_p = 0 \text{ case})$

$$0\cdot y_1+\cdots+0\cdot y_n\leqslant 0,$$

which clearly holds.

Assume, then, $||x||_p > 0$, $||y||_q > 0$. Let $\tilde{x} := \frac{x}{||x||_p}$, $\tilde{y} := \frac{y}{||y||_q}$. Then,

$$||\tilde{x}||_p^p = \frac{\left(\sum_{i=1}^n |x_i|^p\right)}{||x||_p^p} = \frac{||x||_p^p}{||x||_p^p} = 1 \implies ||\tilde{x}||_p = 1.$$

The same case holds for \tilde{y} , hence $||\tilde{y}||_q = 1$; that is, we have "rescaled" both vectors. Hence, we can use the case we proved above for when the norms were identically 1 on \tilde{x} , \tilde{y} . We have:

$$\left| \sum_{i=1}^{n} \tilde{x}_{i} \tilde{y}_{i} \right| \leq 1$$

But by definition of \tilde{x} , \tilde{y} , we have

$$\left|\sum_{i=1}^n \tilde{x}_i \tilde{y}_i\right| = \left|\frac{1}{||x||_p ||y||_q} \sum_{i=1}^n x_i y_i\right| \le 1 \implies \left|\sum_{i=1}^n x_i y_i\right| \le ||x||_p \cdot ||y||_q,$$

and the proof is complete.

→ Proposition 3.2: Minkowski Inequality

Let $1 \le p \le \infty$, $x, y \in \mathbb{R}^n$. Then,

$$||x + y||_p \le ||x||_p + ||y||_p.$$

Remark 3.4. This is just the triangle inequality for ℓ_p norms.

Proof. The cases $p = 1, \infty$ are left as an exercise.

Assume 1 . Then,

$$||x + y||_{p}^{p} = \sum_{j=1}^{n} |x_{j} + y_{j}|^{p} = \sum_{j=1}^{n} |x_{j} + y_{j}| |x_{j} + y_{j}|^{p-1}$$

$$\leq \sum_{j=1}^{\infty} (|x_{j}| + |y_{j}|) \cdot |x_{j} + y_{j}|^{p-1}$$

$$= \sum_{j=1}^{n} |x_{j}| \cdot |x_{j} + y_{j}|^{p-1} + \sum_{j=1}^{n} |y_{j}| \cdot |x_{j} + y_{j}|^{p-1} \quad \circledast$$

Let $\vec{u} = (|x_1|, \dots, |x_n|)$ and $\vec{v} = (|x_1 + y_1|^{p-1}, \dots, |x_n + y_n|^{p-1})$, then, $A = \vec{u} \cdot \vec{v} = \langle \vec{u}, \vec{v} \rangle_{\mathbb{R}^n}$. We have

$$||\vec{u}||_{p} = \left(\sum_{i=1}^{n} (|x_{i}|^{p})\right)^{\frac{1}{p}} = ||x||_{p}$$

$$||\vec{v}||_{q} = \left(\sum_{i=1}^{n} \left(|x_{i} + y_{i}|^{p-1}\right)^{q}\right)^{\frac{1}{q}}$$

$$= \left[\sum_{i=1}^{n} \left(|x_{i} + y_{i}|^{p-1}\right)^{\frac{p-1}{p}}\right]^{\frac{p-1}{p}}$$

$$= \left[\sum_{i=1}^{n} |x_{i} + y_{i}|^{p}\right]^{\frac{p-1}{p}}$$

$$= ||x + y||_{p}^{p-1}$$

where the second-to-last line follows from p, q being conjugate, hence $q = \frac{p}{p-1}$. Thus, by Hölder's Inequality, we have that

$$A = \langle \vec{u}, \vec{v} \rangle \le ||u||_p \cdot ||v||_q = ||x||_p \cdot ||x + y||_p^{p-1}.$$

By a similar construction, we can show that

$$B \le ||y||_p \cdot ||x + y||_p^{p-1}.$$

Thus, returning to our original inequality in ⊕, we have

$$||x + y||_p^p \le A + B$$

$$\le ||x||_p \cdot ||x + y||_p^{p-1} + ||y||_p \cdot ||x + y||_p^{p-1}$$

$$\implies ||x + y||_p \le ||x||_p + ||y||_p,$$

and the proof is complete.

← Lecture 07; Last Updated: Tue Jan 30 12:54:59 EST 2024

3.3 An Aside on Complete Metric Spaces

\hookrightarrow Theorem 3.1

The sequence of centers of balls with monotonically decreasing radii is a Cauchy sequence in *X*.

Proof. Let $\varepsilon > 0$ and let $N : \forall j > N, r_j < \varepsilon$. Then,

$$d(x_j, x_k) < r_{\min(j,k)} = r_j$$

A metric space is complete if every Cauchy sequence converges to a limit in that space.

⊗ Example 3.2: Examples of Complete Metric Spaces

- 1. \mathbb{R} , *p*-adic integers (\mathbb{Z}_p) /rationals (\mathbb{Q}_p) .
- 2. $\ell_p = \{x = (x_i)_{i=1}^{\infty} : \sum_{i=1}^{\infty} |x_i|^p < +\infty\}, 1 \le p \le +\infty$
- 3. $\ell_{\infty} = \{x = (x_i) : \sup_{i=1}^{\infty} |x_i| < +\infty\}.$

\hookrightarrow Proposition 3.3

Hölder's Inequality and Minkowski Inequality inequalities hold for infinite sequences. that is,

1. if
$$x = (x_i) \in \ell_p$$
 and $y = (y_i) \in \ell_q$ with $\frac{1}{p} + \frac{1}{q} = 1$, then

$$\left|\sum_{i=1}^{\infty} x_i y_i\right| \leqslant ||x_i||_{\ell_p} ||y_i||_{\ell_q}.$$

2. if $x, y \in \ell_p$, then

$$||x + y||_p \le ||x||_p + ||y||_p.$$

Remark 3.5. 2. gives the triangle inequality for the $||x||_p$ norm on ℓ_p .

Moreover,

$$||c \cdot x||_{p} = ||(c_{1}x_{1}, \dots, c_{n}x_{n}, \dots)||_{p}$$

$$= \left(\sum_{i=1}^{\infty} |cx_{i}|^{p}\right)^{\frac{1}{p}} = \left(\sum_{i=1}^{\infty} |c|^{p} |x_{i}|^{p}\right)^{\frac{1}{p}}$$

$$= (|c|^{p})^{\frac{1}{p}} ||x||_{p} = c \cdot ||x||_{p}$$

<u>Proof.</u> (of 2.) If $x, y \in \ell_p$, we have that $\sum_{i=1}^{\infty} |x_i|^p < +\infty$, $\sum_{i=1}^{\infty} |y_i|^p < +\infty$, so $\exists N > 0 : \sum_{i=N+1}^{\infty} |x_i|^p < \epsilon$, $\sum_{i=N+1}^{\infty} |y_i|^p < \epsilon$. Let $x_i^{(n)} = (x_1, \dots, x_n, 0, 0, \dots)$ be (x) truncated after n (finite) coordinates. This gives

$$||(x_i + y_i)^{(n)}||_p \le ||x_i^{(n)}||_p + ||y_i^{(n)}||_p \le ||x||_p + ||y||_p$$

by Minkowski on finite spaces. Taking $n \to \infty$ (ie, "detruncating"), we have $(x + y) \in \ell_p$, and thus $||x + y||_p \le ||x||_p + ||y||_p$.

1. left as an exercise.

← Proposition 3.4

Let $1 \le p \le +\infty$, and $||x||_{\infty} = \sup_{i=1}^{\infty} |x_i| = A < +\infty$, $||y||_{\infty} = \sup_{i=1}^{\infty} |y_i| = B < +\infty$. Then, the triangle inequality $||x+y||_{\infty} \le ||x||_{\infty} + ||y||_{\infty}$ holds.

Proof. We have

$$\sup_{i=1}^{\infty} |x_i + y_i| \le \sup_{i=1}^{\infty} (|x_i| + |y_i|) \le \sup_{i=1}^{\infty} |x_i| + \sup_{i=1}^{\infty} |y_i| = ||x||_{\infty} + ||y||_{\infty}.$$

← Proposition 3.5

 $||x||_{\infty} := \sup_{i=1}^{\infty} |x_i|$ is a well-defined norm on ℓ_{∞} .

<u>Proof.</u> The triangle inequality is prove in proposition 3.4. The remainder of the requirements are left as an exercise.

← Proposition 3.6

 $\ell_p \subseteq \ell_q \text{ if } p < q.$

Proof. Let $x \in \ell_p$. If $\sum_{i=1}^{\infty} |x_i|^p < +\infty$, then $\exists N : \forall i \ge N, |x_i| \le 1$. Then,

$$\sum_{i \ge N} |x_i|^q \le \sum_{i \ge N} |x_i|^p < \infty$$

$$\implies \sum_{i=1}^{\infty} |x_i|^q < +\infty \implies x \in \ell_q$$

$$\implies \ell_p \subseteq \ell_q$$

← Lecture 08; Last Updated: Thu Feb 1 09:10:36 EST 2024

3.4 Contraction Mapping Theorem

→ **Definition** 3.3: Contraction Mapping

Let (X, d) be a metric space. A *contraction mapping* on X is a function $f: X \to X$ for which \exists a constant 0 < c < 1 such that

$$d(f(x), f(y)) \le c \cdot d(x, y) \quad \forall x, y \in X.$$

→ Theorem 3.2: Contraction Mapping Theorem

Let (X, d) be a complete metric space, and let $f: X \to X$ be a contraction. Then, there exists a unique fixed point z of f such that f(z) = z.

Moreover, $f^{[n]}(x) := f \circ f \circ \cdots \circ f(x) \to z \text{ as } n \to \infty \text{ for any } x \in X.$

Remark 3.6. The "functional construction" of the Cantor set is an example of a contraction mapping, with $f_1(x) = \frac{x}{3}$, $f_2(x) = \frac{x+2}{3}$. The first has a fixed point of 0, and the second a fixed point of 1.

Remark 3.7. This is a generalization of this proof done in Analysis I, an equivalent claim over the reals.

Proof. Fix $x \in X$. Consider the sequence $\{x_0, x_1, x_2, \dots, x_n, \dots\} := \{x, f(x), f \circ f(x), \dots, f^{[n]}(x), \dots\}$ (we call $f^{[n]}$ the *orbit* of x under iterations of f). We claim that this is a Cauchy sequence. Let $n \in \mathbb{N}$ arbitrary, then we have, by the property of the contraction mapping,

$$d(f^{[n+1]}(x) - f^{[n]}(x)) \le c \cdot d(f^{[n]}(x) - f^{[n-1]}(x)) \le c^2 d(f^{[n-1]}(x) - f^{[n-2]}(x)).$$

Arguing inductively, it follows that

$$d(f^{[n+1]}(x) - f^{[n]}(x)) \le c^n d(f(x), x).$$
 *

Let now $m, k \in \mathbb{N}, m, k > 0$. It follows that

$$\begin{split} d(f^{[m]},f^{[m+k]}(x) & \leq d(f^{[m]})(x),f^{[m+1]}(x)) + d(f^{[m+1]}(x),f^{[m]}(x)) + \cdots + d(f^{[m+k-1]}(x),f^{m+k}(x)) \\ & \stackrel{\star}{\leq} d(x,f(x))[c^m + c^{m+1} + \cdots + c^{m+k-1}] \\ & \leq c^m d(x,f(x))[1+c+\cdots + c^k + c^{k+1} + \cdots] = \frac{c^m d(x,f(x))}{1-c} \end{split}$$

Now, given $\varepsilon > 0$, choose N such that $\frac{c^N d(x, f(x))}{1-c} < \varepsilon$. It follows, then, that $\{f^{[n]}(x)\}_{n \in \mathbb{N}}$ a Cauchy sequence, and thus converges, $f^{[n]}(x) \to z$ as $n \to \infty$ for some z.

We further have to show that f(z) = z. It is easy to show that f continuous due to the contraction mapping (it is clearly Lipschitz with constant c), and it thus follows that

$$\lim_{n \to \infty} f(f^{[n]}(x)) = \lim_{n \to \infty} f^{[n]}(x) \implies f(z) = z,$$

by sequential characterization of continuous functions.

Finally, we need to show that this limit is unique. Suppose $\exists y_1 \neq y_2$, ie two fixed points with $f(y_1) = y_1$ and $f(y_2) = y_2$. Then, by the property of the contraction mapping,

$$d(f(y_1), f(y_2)) \leqslant c \cdot d(y_1, y_2),$$

but by assumption of being fixed points,

$$d(f(y_1), f(y_2)) = d(y_1, y_2),$$

implying $d(y_1, y_2) \le c \cdot d(y_1, y_2)$. This is only possible if $d(y_1, y_2) = 0$, and thus $y_1 = y_2$ and the fixed point is indeed unique.

\hookrightarrow Theorem 3.3: ℓ_p complete

The space ℓ_p is complete for all $1 \le p \le +\infty$.

Equivalently, if (x^1) , (x^2) , ..., (x^n) is a Cauchy sequence in ℓ^p , $\exists y \in \ell^p$ s.t. $x^n \to y$ as $n \to \infty$.

Proof. (Sketch) We suppose first $p < +\infty$. Consider an arbitrary number of Cauchy sequences in ℓ_p :

$$x^{(1)} = (x_1^{(1)}, \dots, x_n^{(1)}, \dots)$$

$$x^{(2)} = (x_1^{(2)}, \dots, x_n^{(2)}, \dots)$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$x^{(k)} = (x_1^{(k)}, \dots, x_n^{(k)}, \dots) \in \ell_p$$

We claim that, for any $k \in \mathbb{N}$, the $(x_k^{(n)})_{n \in \mathbb{N}}$ is a Cauchy sequence; note that in this definition we are taking a *fixed-index* (namely, the kth) element from different sequences (namely, the nth sequence).

Since $x^{(1)}, x^{(2)}, \ldots, x^{(n)}, \ldots$ are Cauchy sequences in ℓ^p , we have for a fixed $\varepsilon > 0$, $\exists N \in \mathbb{N} : \forall m, n > N$, $d_v(x^{(m)}, x^{(n)}) < \varepsilon$:

$$\begin{split} d_{p}(x^{(m)}, x^{(n)})^{p} &= ||x^{(m)} - x^{(n)}||_{p}^{p} = \sum_{i=1}^{\infty} \left|x_{i}^{(m)} - x_{i}^{(n)}\right|^{p} < \varepsilon^{p} \\ \left|x_{k}^{(m)} - x_{k}^{n}\right|^{p} &\leq \sum_{i=1}^{\infty} \left|x_{i}^{(m)} - x_{i}^{(n)}\right|^{p} \implies \left|x_{k}^{(m)} - x_{k}^{n}\right|^{p} < \varepsilon^{p} \\ &\implies \left|x_{k}^{(m)} - x_{k}^{(n)}\right| < \varepsilon, \end{split}$$

since we are taking "less of the summands in the second line". It follows, then, that for each k, $\exists z_k : x_k^{(n)} \to z_k$ as $n \to \infty$. Let $z = (z_1, \ldots, z_n, \ldots)$. We claim that $x^{(n)} \to z \in \ell_p$ as $n \to \infty$.

First, we show that $d_p(x^{(n)}, z) \to 0$ as $n \to 0$ (that is, $x^{(n)} \to z$ as $n \to \infty$). Fix $\varepsilon > 0$, and choose $N \in \mathbb{N}$ for which $d_p(x^{(m)}, x^{(n)}) < \varepsilon \ \forall m, n \ge N$ (by Cauchy). Fix $K \in \mathbb{N}$, K > 0.

$$d_p^p(x^{(n)}, z) = ||x^{(n)} - z||_p^p = \sum_{i=1}^{\infty} |x_i^{(n)} - z_i|^p$$
$$||x^{(m)} - x^{(n)}||_p^p < \varepsilon^p \implies \sum_{i=1}^K |x_i^{(m)} - x_i^{(n)}|^p \le \varepsilon^p$$

Let $m \to \infty$; then $x_i^{(m)} \to z_i$ (note that *i* fixed!), and we have

$$\sum_{i=1}^K \left| z_i - x_i^{(n)} \right|^p \leqslant \varepsilon^p.$$

Let $K \to \infty$; then,

$$\sum_{i=1}^{\infty} \left| z_i - x_i^{(n)} \right|^p \leqslant \varepsilon^p \implies ||z - x||_p \leqslant \varepsilon \implies d_p(z, x^n) \leqslant \varepsilon,$$

and thus $x^n \to z$ as $n \to \infty$.

It remains to show that $z \in \ell_p$, ie $||z||_p < +\infty$. We have:

$$||z||_p \le \underbrace{||z - x^{(n)}||_p}_{\to 0} + ||x^{(n)}||_p.$$

For sufficiently large n, $||z - x^{(n)}|| \le 1$ (for instance); $x^{(n)} \in \ell_p$, hence $||x^{(n)}||_p < +\infty$ (say, $||x^{(n)}||_p \le M$). Thus:

$$||z||_v \le 1 + M < +\infty \implies z \in \ell_v$$

and the proof is complete.

3.5 Compactness in Metric Spaces

→ Definition 3.4: Totally Bounded

Let (X, d) be a metric space. If for every $\varepsilon > 0$, $\exists x_1, \dots, x_n \in X$, $n = n(\varepsilon)$: $\bigcup_{i=1}^n B(x_1, \varepsilon) = X$, we say X is totally bounded.

← Lecture 09; Last Updated: Tue Feb 27 08:42:17 EST 2024

\hookrightarrow Theorem 3.4

Let (X, d) be a metric space. TFAE:

- 1. *X* is complete and totally bounded;
- 2. *X* is compact;
- 3. *X* is sequentially compact (every sequence has a convergent subsequence).

Proof. (1. \Longrightarrow 2.) Suppose X complete and totally bounded. Assume towards a contradiction that X not compact, ie there exists an open cover $\{U_{\alpha}\}_{{\alpha}\in I}$ of X with no finite subcover.

X being totally bounded gives that it can be covered by finitely many open balls of radius $\frac{1}{2}$. It must be that at least one of these open balls cannot be finitely covered, otherwise we would have a finite subcover. Let F_1 be the closure of this ball. F_1 closed, with diameter diam(F_1) ≤ 1 . X.

We also have that X can be covered by finitely many balls of radius $\frac{1}{4}$; again, there must be at least one ball B_1 such that $B_1 \cap F_1$ cannot be covered by finitely many open sets from the cover. Let $F_2 = \overline{B_1} \cap F_1$ -closed, with diam $(F_2) \leq \frac{1}{4} + \frac{1}{4} = \frac{1}{2}$.

Arguing inductively, at some step n, X can can be covered by finitely many balls of radius $\frac{1}{2^n}$; at least one of these balls B cannot be covered by a finite subcover hence $B \cap F_{n-1}$ cannot be covered by finitely many U_{α} 's. Let $F_n = \overline{B} \cap F_{n-1}$ -closed, with diam $(F_n) \leq \frac{1}{2^{n-1}}$.

As such, we have a nested sequence $F_1 \supseteq F_2 \supseteq \cdots \supseteq F_n \supseteq \cdots$ of closed sets, where $\operatorname{diam}(F_k) \leqslant \frac{1}{2^{k-1}} \to 0$ as $k \to \infty$.

 \hookrightarrow Lemma 3.1 (Cantor Intersection Theorem). $\bigcap_{k=1}^{\infty} F_k \neq \emptyset$.

Proof. (Of Lemma) Let $x_k \in F_k$. Then, $\{x_k\}_{k \in \mathbb{N}}$ is a Cauchy sequence, since

$$d(x_n, x_{n+k}) \leq \operatorname{diam}(F_n) + \dots + \operatorname{diam}(F_{n+k}) \leq \frac{1}{2^{n-1}},$$

by the nested property, which can be made arbitrarily small for sufficiently large n, k. Hence, $x_n \to y \in X$ for some y, as X complete. The tail of x_n lies in F_n for all sufficiently large n, and as each F_n closed, the limit must lie in F_n for all sufficiently large n. We conclude the intersection nonempty.

 $^{{}^4}B_1$ has radius $\frac{1}{4}$ and hence diameter $\frac{1}{2}$. The intersection of B_1 with a set with a larger diameter must have diameter leq $\frac{1}{2}$

This y from the lemma is covered by some U_{α_0} -open for some $\alpha_0 \in I$. Being open, $\exists \varepsilon > 0 : B(y, \varepsilon) \subseteq U_{\alpha_0}$. Let $n: \frac{1}{2^n-1} < \varepsilon$. Then, $y \in F_n$, and as $\operatorname{diam}(F_n) \leq \frac{1}{2^{n-1}}$, we have that $F_n \subseteq B(y, \frac{1}{2^{n-1}}) \subseteq B(y, \varepsilon) \subseteq U_{\alpha_0}$. But then, we have that F_n covered by a single open set U_{α_0} , a contradiction to our inductive construction of F_n . We conclude X compact.

(2. \Longrightarrow 3.) Suppose X compact. Let $\{x_n\}_{n\in\mathbb{N}}\in X$. Let $F_n=\overline{\bigcup_{k\geqslant n}\{x_k\}}$ -closed; we have too that $F_1\supseteq F_2\supseteq\cdots\supseteq F_n\supseteq\cdots$.

○ Definition 3.5: Finite Intersection Property

 \mathcal{F} has finite intersection property provided any finite subcollection of sets in \mathcal{F} has a non-empty intersection.

 \hookrightarrow <u>Lemma</u> 3.2 (Finite Interesection Formulation of Compactness). *X-compact* \iff *every collection* $\mathcal F$ *of closed subsets of* X *with finite intersection property has non-empty intersection.*

Proof.

This lemma directly gives that $\bigcap_{n=1}^{\infty} F_n \neq \emptyset$, $\{F_n\}_{n \in \mathbb{N}}$ being a collection of closed subsets with any subset having nonempty intersection (by the nestedness). Let $y \in \bigcap_{n=1}^{\infty} F_n$. Take $B(y, \frac{1}{k})$, which thus has nonempty intersection with $\{x_k\}_{k \geq n} \forall n$, ie $\exists n_1 : d(y, x_{n_1}) < 1$ and $\exists n_2 > n_1 : d(y, x_{n_2}) < \frac{1}{2}$. Arguing inductively, $\exists n_j > n_{j-1} : d(y, x_{n_j}) < \frac{1}{j}$ for any given n_{j-1} . It follows that $\lim_{j \to \infty} x_{n_j} = y$, and thus $\{x_{n_j}\}$ is a convergent subsequence of $\{x_n\}$ that converges within X, and thus X is sequentially compact.

(3. \Longrightarrow 1.) Suppose X sequentially compact. Let $\{x_n\} \in X$ be a Cauchy sequence in X, which thus have a convergent subsequence $\{x_{n_k}\} \to y$.

 \hookrightarrow Lemma 3.3. Let $\{x_n\}$ be a Cauchy sequence in X where X sequentially compact. Then, if $\{x_{n_k}\} \to y$, so does $\{x_n\} \to y$

<u>Proof.</u>

Then, $\{x_n\}_n \to y$ and so X complete.

Suppose X not totally bounded, ie $\exists \varepsilon > 0 : X$ cannot be covered by a finite union of balls of $B(x_j, \varepsilon)$. Let $x_1 \in X$ s.t. $B(x_1, \varepsilon) \not\supseteq X$; $\exists x_2 \in X \setminus B(x_1, \varepsilon)$, and so $X \not\subseteq B(x_1, \varepsilon) \cup B(x_2, \varepsilon)$ by assumption. Then, choose $x_3 \in X \setminus (B(x_1, \varepsilon) \cup B(x_2, \varepsilon))$. Arguing inductively, we have that $\exists x_n \in X \setminus (\bigcup_{i=1}^n B(x_i, \varepsilon))$, noting that $d(x_n, x_j) \geqslant \varepsilon \, \forall \, 1 \leqslant j \leqslant n$.

Consider the sequence $\{x_j\}_{j\in\mathbb{N}}$:

 \hookrightarrow **Lemma** 3.4. $\{x_i\}$ cannot have a convergent subsequence.

Proof. Follows by $d(x_m, x_n) \ge \varepsilon \forall m, n$.

This contradicts our assumption that *X* sequentially compact, and we conclude *X* must be totally bounded.

Solution Example 3.3: Complete Metric Space Example: L^p **norm**

Let $f \in C([a, b])$. We define the norm

$$||f||_p := \left(\int_a^b |f(x)|^p dx\right)^{\frac{1}{p}}.$$

As desired, $||f||_p \ge 0$; $||f||_p = 0 \iff f \equiv 0$; $||c \cdot f||_p = c \cdot ||f||_p$.

Hölder's and Minkowski's inequalities for functions also hold; for $\frac{1}{p} + \frac{1}{q} = 1$, $1 \le p$, $q \le \infty$,

$$\int |fg| \le ||f||_p \cdot ||g||_q; \quad ||f + g||_p \le ||f||_p + ||g||_q,$$

respectively.

We similarly have the L^{∞} norm, namely, for a function $f:[a,b] \to \mathbb{R}$,

$$||f||_{\infty} = \sup_{x \in [a,b]} |f(x)|,$$

which obeys all the necessary properties as well.

Let $f_n \to f$ in C([a,b]), wrt $||\cdots||_{\infty}$, where $\{f_n\}_{n\in\mathbb{N}}$ a sequence of functions. Namely, we say that

$$\forall \varepsilon > 0, \exists N \in \mathbb{N} : \forall n \ge N, \sup_{x \in [a,b]} |f_n(x) - f(x)| < \varepsilon.$$

If this holds, we say that f_n uniformly converges.

We say that $f_n(x) \to f(x)$ pointwise on [a,b] if $\forall x \in [a,b], f_n(x) \to f(x)$. Note that uniform convergence implies pointwise convergence, but not the converse.

\hookrightarrow Theorem 3.5

Suppose $f_n(x)$ continuous, and $f_n(x) \to f(x)$ uniformly on [a,b]. Then, f(x) also continuous on [a,b].

Proof. Fix $\varepsilon > 0$, $x_0 \in [a,b]$. We have that $\exists N : n \ge N$, $|f_n(x) - f(x)| < \frac{\varepsilon}{3}$, $\forall x \in [a,b]$.

Let $n \ge N$. $f_n(x)$ continuous at x_0 , hence $\exists \delta(x_0) > 0 : |y - x_0| \implies |f_n(y) - f_n(x_0)| < \frac{\varepsilon}{3}$. We have

$$|f(x_0) - f(y)| \le |f(x_0) - f_n(x_0)| + |f_n(x_0) - f_n(y)| + |f_n(y) - f(y)|$$

 $\le \frac{\varepsilon}{3} + \frac{\varepsilon}{3} + \frac{\varepsilon}{3} = \varepsilon,$

completing the proof.

Remark 3.8. This does not hold with pointwise convergence.

Remark 3.9. We will prove later that C([a,b]) is complete for $||f||_{\infty}$, but not for arbitrary $||f||_p$, $1 \le p < +\infty$. To "complete" C([a,b]) for $p \ne \infty$, we will need to consider measurable functions and redefine our notion of integration.

← Lecture 11; Last Updated: Thu Feb 8 09:51:13 EST 2024

4 Derivatives

4.1 Introduction

→ Definition 4.1: Differentiable

We say f(x) differentiable at c if $\exists \lim_{x\to c} \frac{f(x)-f(c)}{x-c}$. If so, we denote the limit f'(c).

Remark 4.1. For x close to c, then $f(x) \approx f(c) + f'(c)(x - c)$; this is a linear approximation of f at c.

SEXAMPLE 4.1: Weierstrass

 $f(x) = \sum_{n=1}^{\infty} \frac{\cos(3^n)x}{2^n}$ is continuous in \mathbb{R} , but nowhere differentiable.

○→ Definition 4.2

The derivative, dx, is a linear map $C^{([a,b])} \rightarrow C^{0}([a,b])$.

4.2 Chain Rule

Remark 4.2. See Analysis I notes as well.

→ **Theorem** 4.1: Caratheodory's Theorem

Let $f: I \to \mathbb{R}$, $c \in I$. f is differentiable at x = c iff $\exists \varphi(x) : I \to \mathbb{R}$ s.t. φ continuous at c and $f(x) - f(c) = \varphi(x)(x - c)$.

Proof. If f'(c) exists, let

$$\varphi(x) = \begin{cases} \frac{f(x) - f(c)}{x - c} & x \neq c \\ f'(c) & x = c. \end{cases}$$

which is well defined. Moreover, for $x \neq c$, $\varphi(x)(x-c) = \frac{f(x)-f(c)}{x-c}(x-c) = f(x)-f(c)$ as desired; the case for x=c is clear. Continuity at c:

$$\lim_{x \to c} \varphi(x) = \lim_{x \to c} \frac{f(x) - f(c)}{x - c} = f'(c) = \varphi(c).$$

⁵If not stated otherwise, sets named *I* or *J* are intervals.

Conversely, suppose such a φ exists. Then, by continuity,

$$\exists \varphi(c) = \lim_{x \to c} \varphi(x) = \lim_{x \to c} \frac{f(x) - f(c)}{x - c}$$

which gives directly that f differentiable at c.

→ Theorem 4.2: Chain Rule

Let $f: J \to \mathbb{R}$, $g: I \to \mathbb{R}$, $f(J) \subseteq I$. If f(x) differentiable at c and g(y) is differentiable at y = f(c), then $g \circ f(x)$ is also differentiable at c, and

$$(g \circ f)'(c) = g'(f(c))f'(c).$$

Proof. Using Caratheodory's Theorem, $\exists \varphi : f(x) - f(c) = \varphi(x)(x - c)$ with $\varphi(c) = f'(c)$. Let d = f(c), then similarly $\exists \psi : g(y) - g(d) = \psi(y)(y - d)$ with $\psi(d) = g'(d)$, with φ, ψ continuous at c, d resp. Then,

$$g(f(x)) - g(f(c)) = \psi(f(x))(f(x) - f(c)) = (\psi \circ f)(x) \cdot (\phi(x)(x - c))$$

 $\psi \circ f$ is continuous at c, as a composition of continuous functions (ψ , ϕ continuous by construction, f differentiable and thus continuous). It follows, then, that

$$\lim_{x \to c} \frac{g(f(x)) - g(f(c))}{x - c} = \lim_{x \to c} (\psi \circ f)(x) \cdot \varphi(x) = \psi(f(c))\varphi(c) = g'(f(c)) \cdot f'(c),$$

by construction.

4.3 Critical Points

→ Definition 4.3

 $f: I \to \mathbb{R}$ has a max/min c if $\exists J \subseteq I: x \in J$ s.t. $\max_{x \in J} f(x) / \min_{x \in J} f(x) = f(c)$.

← Theorem 4.3: Rolle's

Let $f:[a,b]\to\mathbb{R}$ continuous. Suppose f'(x) exists for all $x\in(a,b)$ and f(a)=f(b)=0. Then, $\exists c\in(a,b):f'(c)=0$.

Remark 4.3. A "complex-version" of Rolle's:

→ Theorem 4.4: Gauss-Lucas

Let P(z) be a complex-valued polynomial. Then, the roots of P'(z) lie inside the convex hull of roots of P(z), where a convex hull is the smallest polygon with vertices at the roots of P(z).

○ Definition 4.4

Consider $P(z) = z^n - 1$ for some $n \in \mathbb{N}$. If z a root, we can show that $(|z|)^n = 1$, hence all roots lie on the unit circle in the complex plane at multiples of the same angle. This gives us a regular n-gon in the complex plane. We then have that $P'(z) = nz^{n-1}$, with has root z = 0, which clearly lies within the n-gon hull.

← Theorem 4.5: Mean Value

Let f be continuous on [a, b] and differentiable on (a, b). Then, $\exists c \in (a, b)$ s.t. f(b) - f(a) = f'(c)(b - a).

Proof. Let
$$\varphi(x) = f(x) - f(a) = \frac{f(b) - f(a)}{(b - a)}(x - a)$$
, where $\varphi(a) = 0 = \varphi(b)$. By Rolle's theorem, $\exists c \in (a, b) : \varphi'(c) = 0 = f'(c) - \frac{f(b) - f(a)}{(b - a)}$, as desired.

← Lecture 12; Last Updated: Thu Feb 15 09:47:18 EST 2024

4.4 Aside: Continued Fractions

We have that, for any $x \in \mathbb{R}$, $x = \lfloor x \rfloor + \{x\}$, with $\{x\} \in (0,1)$; $\lfloor x \rfloor$ and $\{x\}$ are the integral and fractional parts of x respectively.

Fix $x \in \mathbb{R}$, assuming $x \neq 0$.

Let $x_1 := \frac{1}{\{x\}}$. We can write

$$x = \lfloor x \rfloor + \frac{1}{x_1}.$$

If $\{x_1\} \neq 0$, let $x_2 := \frac{1}{\{x_1\}}$ and write

$$x = \lfloor x \rfloor + \frac{1}{\lfloor x_1 \rfloor + \frac{1}{x_2}}.$$

Continuing in this manner, this process stops if $\{x_i\} = 0$ for some i; if $x \in \mathbb{Q}$, this process will stop, else, it will continue infinitely. For instance, the Golden Ratio $x = \frac{\sqrt{5}\pm 1}{2}$ has continued fraction expansion

$$x = \frac{1}{1 + \frac{1}{1 + \frac{1}{1 + \dots}}}.$$

More succinctly, we can denote $a_0 := \lfloor x \rfloor$ and $a_i = \lfloor x_i \rfloor$, $i \ge 1$, and write

$$x = a_0 + \frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 + \cdots}}}.$$

We notate, accordingly, $x := (a_1, a_2, a_3, ...)$; in this case, the Golden Ratio can be notated (1, 1, 1, ...).

We denote $\frac{p_n}{q_n}$ as the *n*th continued fraction of a given x. It turns out that this is the best possible rational approximation for $x \notin \mathbb{Q}$.

§4.4

4.5 Back To Derivatives

← Theorem 4.6

 $f: I \to \mathbb{R}$, differentiable. f is increasing (resp decreasing) iff $f'(x) \ge 0 \ \forall \ x \in I$ (resp $f'(x) \le 0 \ \forall \ x \in I$).

← Proposition 4.1

Let f continuous on I = [a, b]. Let a < c < b and suppose f differentiable on (a, c) and (c, b). Suppose $f'(x) \ge 0$ on $(c - \delta, c)$ and $f'(x) \le 0$ on $(c, c + \delta)$ for some $\delta > 0$. Then, f has local max at x = c.

← Lemma 4.1

Let $I \subseteq \mathbb{R}$, and assume $f: I \to \mathbb{R}$ is differentiable at $x = c \in I$.

- 1. If f'(c) > 0, then $\exists \delta > 0 : f(x) > f(c) \forall x \in I, x \in (c, c + \delta)$.
- 2. (Reverse statement for f'(c) < 0)

→ Theorem 4.7: Darboux

Suppose f differentiable on I := [a, b] and f'(a) < k < f'(b). Then, $\exists c \in (a, b)$ such that f'(c) = k.

 $\hookrightarrow Lecture~13; Last~Updated:~Thu~Feb~15~09:49:55~EST~2024$

4.6 L'Hopital's Rules

\hookrightarrow Proposition 4.2

Suppose $f(x), g(x) : [a, b] \to \mathbb{R}$ with f(a) = g(a) = 0, and $g(x) \neq 0 \,\forall \, a < x < b$. Suppose f, g are differentiable at x = a and $g'(a) \neq 0$. Then, $\lim_{x \to a^+} \frac{f(x)}{g(x)}$ exists, and moreover, it is equal to f'(a)g'(x).

Proof.

$$\lim_{x \to a^+} \left(\frac{f(x) - f(a)}{x - a} \right) / \left(\frac{g(x) - g(a)}{x - a} \right) = \lim_{x \to a^+} \frac{f(x)}{x - a} \frac{x - a}{g(x)} = \lim_{x \to a^+} \frac{f(x)}{g(x)},$$

but the original line is simply $\frac{f'(a)}{g'(a)}$.

⊗ Example 4.2

 $\lim_{x\to 0} \frac{\sin x}{x} = \frac{\cos(0)}{1} = 1.$

→ Theorem 4.8: Cauchy Mean Value

Let $f(x), g(x) : [a, b] \to \mathbb{R}$ where f, g continuous on [a, b] and differentiable on (a, b). Assuming $g'(x) \neq 0$, $\forall x \in (a, b)$, then $\exists c \in (a, b)$ such that

$$\frac{f(b) - f(a)}{g(b) - g(a)} = \frac{f'(c)}{g'(c)}.$$

→ Proposition 4.3: More General L'Hopital

let $-\infty \le a < b \le +\infty$ and f, g differentiable on (a,b). Suppose $\lim_{x\to a^+} f(x) = 0 = \lim_{x\to a^+} g(x)$.

- 1. If $\exists L := \lim_{x \to a^+} \frac{f'(x)}{g'(x)}$ where L some real number, then $\lim_{x \to a^+} \frac{f(x)}{g(x)} = L$ as well.
- 2. If $\exists L := \lim_{x \to a^+} \frac{f'(x)}{g'(x)}$ where $L = +\infty$ or $-\infty$, then $\lim_{x \to a^+} \frac{f(x)}{g(x)} = L$ as well.

← Proposition 4.4

Let $-\infty \le a < b \le +\infty$, f, g differentiable on (a,b) and $g'(x) \ne 0 \ \forall \ x \in (a,b)$. Suppose $\lim_{x\to a^+} g(x) = \pm \infty$.

- 1. If $\lim_{x\to a^+} \frac{f'(x)}{g'(x)} =: L$ exists and is some finite real number, then $\lim_{x\to a^+} \frac{f(x)}{g(x)} = L$ as well.
- 2. If $\lim_{x\to a^+} \frac{f'(x)}{g'(x)} =: L$ exists and is $\pm \infty$, then $\lim_{x\to a^+} \frac{f(x)}{g(x)} = L$ as well.

4.7 Taylor's Theorem

Let $I = [a, b] \subseteq \mathbb{R}$, $f : I \to \mathbb{R}$, $f \in C^n(I)$ and suppose $f^{(n+1)}(x)$ exists on (a, b). Let $x_0 \in [a, b]$. Then, for any $x \in [a, b]$, $\exists c$ between x, x_0 such that

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2}(x - x_0)^2 + \dots + \frac{f^{(n)}(x_0)}{n!}(x - x_0)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(x - x_0)^{n+1}$$

← Lecture 14; Last Updated: Wed Mar 20 09:07:18 EDT 2024

← Theorem 4.10: Relative Extrema

⁶Let $I \subseteq \mathbb{R}$ be an open interval, $x_0 \in I$, and $n \ge 2$. Suppose $f', f'', \dots, f^{(n)}$ are continuous in a neighborhood of x_0 , and $f'(x_0) = f''(x_0) = \dots = f^{(n-1)}(x_0) = 0$ and $f^{(n)}(x_0) \ne 0$. Then:

- 1. if *n* is even and $f^{(n)}(x_0) > 0$, then *f* has a local minimum at x_0 ;
- 2. if *n* is even and $f^{(n)}(x_0) < 0$, then *f* has a local maximum at x_0 ;
- 3. if n is odd, then f has neither a local minimum nor maximum at x_0 .

Proof. If n := 2m-even and $f^{(2m)}(x_0) > 0$, then $f^{(n)}(c) > 0$ so $f(x) - f(x_0) = f^{(2m)}(c)(x - x_0) > 0$.

4.8 Convex Sets

→ Definition 4.5: Convex Set

 $A \subseteq V$ -vector space over \mathbb{R} is *convex* if for any $x, y \in A$ and any $0 \le t \le 1$, $t \cdot x + (1 - t) \cdot y \in A$.

→ Definition 4.6: Convex Function

Let $f: I \to \mathbb{R}$. f is *convex* if $\forall x_1, x_2 \in I$ and $0 \le t \le 1$,

$$f((1-t)x_1 + tx_2) \le (1-t)f(x_1) + tf(x_2).$$

← Lecture 15; Last Updated: Thu Feb 22 21:53:23 EST 2024

5 RIEMANN INTEGRAL

5.1 Introduction

\hookrightarrow **Definition** 5.1: Partitions

A partition is a division of an interval (a, b), denoted

$$\mathcal{P} = \{a = x_0, x_1, \dots, x_{n-1}, x_n = b\}.$$

We define diam(\mathcal{P}) := max_n |x_i - x_{i-1}|.

A marked partition, denoted \dot{P} , is one in which, for each interval we choose some $t_i \in (x_i, x_{i+1}]$.

⁶Bartle-Sherbert, Theorem 6.4.4

→ Definition 5.2: Riemann Sum

We denote

$$S(f, \dot{\mathcal{P}}) = \sum_{i=1}^{n} f(t_i)(x_i - x_{i-1}).$$

→ Definition 5.3: Riemann Integrable

A function f is *Riemann Integrable* if [a,b] if $S(f,\dot{\mathcal{P}}) \to L$ as diam $(\dot{\mathcal{P}}) \to 0$ for any choice of $t_i \in [x_i,x_{i+1}]$.

That is, $\forall \varepsilon > 0, \exists \delta$: if diam(\mathcal{P}) < δ , then for any choice of $t_i \in [x_i, x_{i+1}]$ we have $|L - S(f, \dot{\mathcal{P}})| < \varepsilon$.

→ Proposition 5.1

- 1. If *L* exists, it is unique.
- 2. The integral is linear in f(x); if $\int_a^b f(x) dx$ and $\int_a^b g(x) dx$ exist, then $\int_a^b (c_1 f + c_2 g) dx = c_1 \int_a^b f dx + c_2 \int_a^b g dx$.
- 3. If $f \le g$ are Riemann integrable on [a, b], then $\int_a^b f(x) dx \le \int_a^b g(x) dx$.

← Proposition 5.2

If f(x) integrable on [a, b], the f(x) is bounded on [a, b].

<u>Proof.</u> Suppose $\int_a^b f$ exists. Let $\varepsilon > 0$, and δ such that if $\operatorname{diam}(\dot{\mathcal{P}}) < \delta$ then $|L - S(f, \dot{\mathcal{P}})|$. Let $\varepsilon = 1$. Then, $S(f, \dot{\mathcal{P}}) \leq |L| + 1$.

Let $Q = \{a = x_0, ..., x_n = b\}$ be a partition of [a, b] such that $\operatorname{diam}(Q) < \delta$. Suppose towards a contradiction that f is not bounded on [a, b]. Then, f is unbounded on at least one interval $[x_i, x_{i+1}]$, say, on $[x_k, x_{k+1}]$. Let $t_i = x_i$ for $i \neq k$ and choose $t_k \in [x_k, x_{k+1}]$ such that $|f(t_k)|(x_{k+1} - x_k) > |L| + 1 + |\sum_{i \neq k} f(t_i)(x_{i+1} - x_i)|$ (which we can do by assumption of f being unbounded).

By assumption, $|S(f, \dot{Q})| \leq |L| + 1$, but we have that

$$S(f, \dot{Q}) = \underbrace{\sum_{i \neq k} f(t_i)(x_{i+1} - x_i) + |f(t_k)| (x_{k+1} - x_k) > 2N + |L| + 1,}_{:=N}$$

contradiction.

5.2 Cauchy Criterion

→ Proposition 5.3: Cauchy Criterion for Integrability

 $f \in \mathcal{R}[a,b] \iff \forall \varepsilon > 0, \exists \delta > 0 : \text{if } \dot{P} \text{ and } \dot{Q} \text{ are tagged partitions of } [a,b] \text{ s.t. diam } \dot{P} < \delta \text{ and diam } \dot{Q} < \delta \text{, then } |S(f,\dot{P}) - S(f,\dot{Q})| < \varepsilon.^7$

5.3 Squeeze Theorem

\hookrightarrow Theorem 5.1

Let $f:[a,b]\to\mathbb{R}$. Then $\int_a^b f$ exists \iff $\forall \, \varepsilon>0, \exists \alpha_\varepsilon(x), \omega_\varepsilon(x)\in\mathcal{R}[a,b], \alpha_\varepsilon\leqslant f\leqslant \omega_\varepsilon$, and

$$\int_a^b (\omega_\varepsilon - \alpha_\varepsilon) < \varepsilon$$

Proof. If $f \in \mathcal{R}[a,b]$ then take $\alpha_{\varepsilon} = f = \omega_{\varepsilon}$.

Conversely, let $\varepsilon > 0$. Since α_{ε} , $\omega_{\varepsilon} \in \mathcal{R}[a,b]$, then, $\exists \delta > 0$ such that for any tagged partition with $\dim \dot{P} < \delta$, then $\left| S(\alpha_{\varepsilon},\dot{P}) - \int_a^b \alpha_{\varepsilon} \right| < \varepsilon$ and $\left| S(\omega_{\varepsilon},\dot{P}) - \int_a^b \omega_{\varepsilon} \right| < \varepsilon$, thus

$$\int_a^b \alpha_{\varepsilon} - \varepsilon < S(\alpha_{\varepsilon}, \dot{P}) \leq S(f, \dot{P}) \leq S(\omega_{\varepsilon}, \dot{P}) < \int_a^b \omega_{\varepsilon} + \varepsilon.$$

Let \dot{Q} be any other tagged partition with diam $\dot{Q} < \delta$; then, the same inequality holds ie $\int_a^b \alpha_\varepsilon - \varepsilon < S(f, \dot{Q}) < \int_a^b \omega_\varepsilon + \varepsilon$. Subtracting one from the other, we see that

$$|S(f,\dot{P}) - S(f,\dot{Q})| < \int_a^b \omega_{\varepsilon} - \int_a^b \alpha_{\varepsilon} + 2\varepsilon < 3\varepsilon,$$

and thus $f \in \mathcal{R}[a, b]$ by Cauchy Criterion.

← Lecture 16; Last Updated: Tue Feb 27 13:18:19 EST 2024

← Lecture 17; Last Updated: Tue Mar 12 08:39:22 EDT 2024

<u>Comma</u> 5.1: BS-7.2.4

Let $J \subseteq [a, b]$ an invterval with endpoints c < d. If

$$\varphi_J(x) := \begin{cases} 1 & x \in J \\ 0 & x \notin J \end{cases}.$$

Then, $\varphi_J \in \mathcal{R}[a,b]$ and $\int_a^b \varphi_J = d - c$.

⁷Note that $\mathcal{R}[a,b]$ is the set of all real-valued functions integrable on the interval [a,b].

$\hookrightarrow \underline{Theorem} 5.2$

Let $\varphi : [a, b] \to \mathbb{R}$, $\varphi \in \mathcal{R}[a, b]$; that is, step functions are integrable.

← Lecture 18; Last Updated: Tue Mar 26 14:57:35 EDT 2024

← Lecture 19; Last Updated: Wed Mar 20 14:58:59 EDT 2024

6 APPENDIX

6.1 Notes from Tutorials

\hookrightarrow Theorem 6.1

Let (X, d) be a compact metric space. 8 Let $C(X) := \{f : X \to \mathbb{R} : f \text{ continuous}\}$ be a vector space. Take the uniform norm $||f|| := \sup_{x \in X} |f(x)|$ on C(x). Then, $(C(x), || \bullet ||)$ is complete. 9

Proof. Denote the "canonical norm" $\rho(f,g) := ||f - g||$.

Let $(f_n) \in C(X)$ be a Cauchy sequence. Then, $\forall \varepsilon > 0, \exists N \in \mathbb{N} : \forall m, n \ge N, \rho(f_n, f_m) < \varepsilon$.

Fix $x \in X$, noting that

$$|f_n(x) - f_m(x)| \le \sup_{y \in X} |f_n(y) - f_m(y)| = \rho(f_n, f_m) < \varepsilon.$$
 *1

Define, for this fixed x, a sequence in \mathbb{R} $\{f_n(x)\}_{n\in\mathbb{N}}$. By $*^1$, we have that this sequence is Cauchy in \mathbb{R} , but as \mathbb{R} complete, $f_n(x)$ hence converges, to some limit we call $f(x) := \lim_{n\to\infty} f_n(x)$. Note that x is still fixed at this point; these are but real numbers we are working with here.

Now, as x was completely arbitrary, we can repeat this process for all of X, and define a function $f: X \to \mathbb{R}$ where $f(x) := \lim_{n \to \infty} f_n(x)$.

For a fixed x, we have that $f_m(x) \to f(x)$ as $m \to \infty$. This implies:

$$0 \leq \lim_{m \to \infty} |f_n(x) - f_m(x)| \leq \lim_{m \to \infty} \varepsilon = \varepsilon$$

$$\implies |f_n(x) - f(x)| \leq \varepsilon \,\forall \, n \geq N$$

$$\implies \rho(f_n, f) = \sup_{x \in X} |f_n(x) - f(x)| \leq \varepsilon \implies f_n \to f$$

It remains to show that $f \in C(X)$. Let $c \in X$ and $\varepsilon > 0$, and the corresponding $N \in \mathbb{N}$: $\rho(f_n, f) < \frac{\varepsilon}{3} \forall n \ge N$. By construction, $f_N \in C(X)$, and is thus continuous at c. This gives that $\exists \delta > 0 : |f_N(x) - f_N(c)| < \frac{\varepsilon}{3}$ whenever $d(x, c) < \delta$.

Hence, if $d(x, c) < \delta$, we have

$$\begin{split} |f(x)-f(c)| &\leq |f(x)-f_N(x)| + |f_N(x)-f_N(c)| + |f_N(c)-f(c)| \\ &\leq \rho(f,f_N) + \frac{\varepsilon}{3} + \frac{\varepsilon}{3} \\ &< \frac{\varepsilon}{3} + \frac{\varepsilon}{3} + \frac{\varepsilon}{3} = \varepsilon, \end{split}$$

⁹In this proof, the compactness is necessary for the norm to be well-defined.

⁹In this way, this becomes a Banach Space: a complete, normed vector space.

¹⁰Be careful here, there are three different metrics going on; ρ from the vector space, d from the underlying metric space, and $|\cdots|$ from \mathbb{R} .

hence f continuous at c, which was completely arbitrary, and thus $f \in C(X)$.

→ Theorem 6.2

Let (X, d)-complete. Let $\{F_n\}$ be a decreasing family of non-empty closed sets with $\lim_{n\to\infty} \operatorname{diam}(F_n) = 0$. Then, $\exists z : \bigcap_{n\in\mathbb{N}} F_n = \{z\}$.

→ Theorem 6.3

Let (X, d)-complete, and $f: X \to X$ an "expanding map", such that $d(x, y) \le d(f(x), f(y)) \forall x, y \in X$. Then, f is a surjective isometry, ie, f(X) = X and $d(f(x), f(y)) = d(x, y) \forall x, y \in X$.

→ Lemma 6.1

Differentiable \Longrightarrow Continuous.

<u>Proof.</u> Let $f: I \to \mathbb{R}$, and $c \in I$ arbitrary. Notice that $\forall x \neq c \in I$, $f(x) - f(c) = (x - c) \frac{f(x) - f(c)}{x - c}$. Hence,

$$\lim_{x \to c} (f(x) - f(c)) = \lim_{x \to c} (x - c) \frac{f(x) - f(c)}{x - c}$$

$$= \lim_{x \to c} (x - c) \cdot \lim_{x \to c} \frac{f(x) - f(c)}{x - c}$$

$$= 0 \cdot f'(x) = 0$$

$$\implies \lim_{x \to c} f(x) = f(c),$$

hence *f* continuous, noting that the splitting of the limits is valid as both are defined.

⊗ Example 6.1

Let
$$f : \mathbb{R} \to \mathbb{R}$$
, $f(x) := \begin{cases} x^2 & x \in \mathbb{Q} \\ 0 & x \notin \mathbb{Q} \end{cases}$

Claim: f discontinuous at all $x \neq 0$.

Proof. Let $x \neq 0 \in \mathbb{R}$. By density of $\mathbb{Q} \subseteq \mathbb{R}$, there exist sequences $(r_n) \in \mathbb{Q}$ s.t. $r_n \to x$ and $(z_n) \in \mathbb{R} \setminus \mathbb{Q}$ s.t. $z_n \to x$. Then:

$$\lim_{n \to \infty} f(r_n) = \lim_{n \to \infty} r_n^2 = x^2$$
$$\lim_{n \to \infty} f(z_n) = \lim_{n \to \infty} 0,$$

hence f discontinuous by the sequential criterion at $x \neq 0$.

Claim: f'(0) = 0.

Proof. Let $\varepsilon > 0$ and $\delta = \varepsilon$. Notice that $f(x) \le x^2 \, \forall x$. Then, we have that $\forall |x| < \delta$,

$$\left| \frac{f(x) - f(0)}{x - 0} - 0 \right| = \left| \frac{f(x)}{x} \right|$$

$$\leq \left| \frac{x^2}{x} \right| = |x| < \delta = \varepsilon$$

→ Definition 6.1

Let $f: I \to \mathbb{R}$. A point $c \in I$ is a local max (resp min) if $\exists \delta > 0$ s.t. $f(x) \leq f(c)$ (resp $f(x) \geq f(c)$) $\forall x \in (c - \delta, c + \delta) \cap I$.

← Lemma 6.2

Let $f: I \to \mathbb{R}$ be differentiable at $c \in I^{\circ}$. If c a local extrema of f, then f'(c) = 0.

Proof. Assume wlog that c a local max; if a local min, take $\tilde{f} := -f$ and continue.

Since I° open, $\exists \delta_1 > 0 : (c - \delta_1, c + \delta_1) \subseteq I^{\circ} \subseteq I$. We also have that $\exists \delta_2 > 0 : f(x) \leq f(c) \forall x \in (c - \delta_2, c + \delta_2) \cap I$, by c an extrema.

Let $\delta := \min\{\delta_1, \delta_2\}$. Then, we have both $(c - \delta, c + \delta) \subseteq I$ and $f(x) \le f(c) \forall x \in (c - \delta, c + \delta)$.

Since f'(c) exists, $\lim_{x\to c^+} \frac{f(x)-f(c)}{x-c} = \lim_{x\to c^-} \frac{f(x)-f(c)}{x-c}$. But we have from the property of being a maximum

that

$$\lim_{x \to c^{+}} \frac{f(x) - f(c)}{x - c} \ge 0, \qquad \lim_{x \to c^{-}} \frac{f(x) - f(c)}{x - c} \le 0,$$

hence, as these two limits must agree, they must equal 0 and thus f'(c) = 0.

6.2 Miscellaneous

⊗ Example 6.2: Rudin, Chapter 7: Differentiability

1. Let f be defined $\forall x \in \mathbb{R}$, and suppose that $|f(x) - f(y)| \le (x - y)^2$, $\forall x, y \in \mathbb{R}$. Prove that f is constant.¹¹

Proof. Let $x > y \in \mathbb{R}$. Then, as |x - y| = x - y, we have

$$|f(x) - f(y)| \le (x - y)^2 \implies \left| \frac{f(x) - f(y)}{x - y} \right| \le x - y = |x - y| \to 0 \text{ as } y \to x$$

$$\implies \left| \frac{f(x) - f(y)}{x - y} \right| \to 0$$

This implies, then, that f'(x) is defined $\forall x \in \mathbb{R}$, and moreover, that $f'(x) = 0 \forall x \in \mathbb{R}$. We conclude, then, that f(x) constant $\forall x \in \mathbb{R}$.

2. Suppose f'(x) > 0 in (a, b). Prove that f is strictly increasing in (a, b), and let g be its inverse function. Prove that g is differentiable, and that

$$g'(f(x)) = \frac{1}{f'(x)}$$
 (a < x < b).

<u>Proof.</u> Fix $x > y \in (a, b)$. Then, by the mean value theorem, $\exists z \in (x, y) : f'(z) = \frac{f(x) - f(y)}{x - y}$. Since f'(z) > 0, it follows that

$$\frac{f(x) - f(y)}{x - y} > 0 \implies f(x) - f(y) > x - y > 0 \implies f(x) > f(y),$$

hence, f increasing, as x > y arbitrary.

Let now $g := f^{-1}$.

¹¹Note that this means that *f Hölder continuous* with constant $\alpha = 2$. Indeed, Hölder continuous functions with $\alpha > 1$ are always constant by a similar proof. For $0 < \alpha \le 1$, we have the inclusion continuously differentiable \implies Lipschitz $\implies \alpha$ −Hölder \implies uniformly continuous \implies continuous.

6.3 Class Midterm Solutions

→ Question 6.1

Let *X* be a topological space, and let $f, g: X \to \mathbb{R}$ be two continuous functions. Show that the set $\{x \in X: f(x) > g(x)\}$ is an open subset of *X*.

<u>Proof.</u> Let $A := \{x \in X : f(x) > g(x)\}$. Letting $\varphi(x) := f(x) - g(x) = (f - g)(x)$, then remark that $\overline{A} \equiv \{x \in X : \varphi(x) > 0\}$, and since differences of continuous functions are continuous, φ continuous. Letting $B := (0, \infty) \subseteq \mathbb{R}$, then, we have that $A = \varphi^{-1}(B)$. But B an open set, and the inverse images of open sets by continuous functions are open, hence A open.

\hookrightarrow Question 6.2

- (a) List three equivalent properties (definitions) of compact sets in metric spaces; you don't need to prove anything.
- (b) Is the unit ball¹²in the space ℓ^2 of infinite sequences compact? Prove or disprove. You may use any of the properties from (a).
- $\underline{\underline{Proof}}$. (a) Every open cover admits a finite subcover \iff sequentially compact \iff complete and totally bounded.
 - (b) Denote the closed unit ball centered at $(0,0,\ldots)$ in ℓ^2 , $B:=\{x\in \ell^2: d_2^2(0,x)=\sum_{i=1}^\infty |x_i|\leqslant 1\}$. Consider the sequence of "unit sequences"

$$\{e^n\}_{n\in\mathbb{N}}\in B, \qquad e^n_i:=\delta_{in}.$$

Then, for any $i \neq j$, $d_2(e^n, e^m) = \sqrt{2} > 1$. It follows that, although $e^n \in B$ for any n, there cannot exist a subsequence of x^n that converges within B (verify why this is!). Thus, B cannot be sequentially compact and thus not compact.

§6.3

¹²Jakobson said in class this is supposed to be a closed ball.

\hookrightarrow Question 6.3

- (a) Define a complete metric space.
- (b) State (without proof) the contraction mapping theorem.
- (c) Let $f:(0,1) \to (0,1)$ be defined by f(x) = x/2. Is f a contraction?
- (d) Does f have a fixed point in the open interval I = (0,1)? Does that contradict the contraction mapping theorem?
- <u>Proof.</u> (a) A complete metric space is a metric space in which every Cauchy sequence converges within that space.
 - (b) Let (X, d) be a complete metric space, and let $f: X \to X$ be a contraction mapping, ie for any $x, y \in X$, $d(f(x), f(y)) \le c \cdot d(x, y)$ for some $c \in (0, 1)$. Then, the contraction mapping states that f has a unique fixed point $z \in X$, ie f(z) = z and $\lim_{n \to \infty} f^{(n)}(x) = z$ for any x.
 - (c) For any $x, y \in (0, 1)$, we have

$$d(f(x), f(y)) = |f(x) - f(y)| = \left| \frac{x - y}{2} \right| = \frac{1}{2} |x - y| = c \cdot d(x, y),$$

so *f* indeed a contraction mapping with $c := \frac{1}{2}$.

(d) We have that for any $x \in I$, $f^{(n)}(x) = \frac{x}{2^n}$ so x a fixed point iff $\frac{x}{2^n} = \frac{x}{2^{n-1}}$ for some n, which is only possible if x = 0, but $0 \notin I$, so indeed f has no fixed point in I. This is not a contradiction to the contraction mapping theorem since I := (0,1) not complete (indeed, $\frac{1}{n} \in I \forall n \text{ but } \frac{1}{n} \to 0 \notin I$).

○ Question 6.4

Let $x = (x_1, x_2,...)$ and $y = (y_1, y_2,...)$ be infinite real sequences satisfying $||x||_2 \le 2$ and $||y||_2 \le 3$, where $||\cdots||_2$ the ℓ^2 norm.

- (a) State Holder's inequality and Minkowski inequality for sequences.
- (b) Give an upper bound for $x \cdot y = \sum_i x_i y_i$, and for ||x + y||.

Proof. (a) Holder's inequality: for p, q Holder conjugates and $x \in \ell^p$, $y \in \ell^q$ we have

$$\left| \sum_{i=1} x_i y_i \right| \leqslant ||x||_p ||y||_q.$$

Minkowski inequality: for $x, y \in \ell^p$,

$$||x + y||_p \le ||x||_p + ||y||_p.$$

(b) For x, y as given; by Holders, $x \cdot y \le ||x||_p ||y||_q = 2 \cdot 3 = 6$, and by Minkowski's, $||x + y|| \le ||x|| + ||y|| = 2 + 3 = 5$, so 6, 5 are upper bounds for $x \cdot y$, ||x + y|| respectively.

_

○ Question 6.5

- (a) State (without proof) Taylor's theorem.
- (b) Let $f \in C^4([0,2])$, and let f'(1) = f''(1) = f'''(1) = 0 while $f^{(4)}(1) = 2$. Use (a) to show that f(x) has a local extremum at x = 1, and determine its type.
- <u>Proof.</u> (a) Let $I := [a, b] \subseteq \mathbb{R}$ and let $f : I \to \mathbb{R}$ such that $f \in C^n(I)$, and $f^{(n+1)}(x)$ exists on (a, b). Then, for $x_0 \in [a, b]$, there exists some $c \in (\min(x, x_0), \max(x, x_0))$ such that

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \dots + \frac{f^{(n)}(x_0)}{n!}(x - x_0)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(x - x_0)^{n+1}.$$

(b) By Taylor's, for any $x \in [0, 2]$, there exists some c between x and 1 such that

$$f(x) = f(1) + \underbrace{f'(1)(\cdots) + f''(1)(\cdots) + f'''(1)(\cdots)}_{=0} + \underbrace{\frac{f^{(4)}(c)}{4!}(x-1)^4}_{=0}$$

$$= f(1) + \underbrace{\frac{f^{(4)}(c)}{4!}(x-1)^4}_{=0}$$

$$\implies f(x) - f(1) \ge \frac{f^{(4)}(c)}{4!}(x-1)^4 \, \forall \, x \in [0,2]$$

By continuity of $f^{(4)}$, there exists some neighborhood V of $x_0 = 1$ such that $f^{(4)}(c)$ has the same sign of $f^{(4)}(1)$. So, for any $x \in V$, $\frac{f^{(4)}(c)}{4!} \ge 0$, since $\frac{f^{(4)(1)}}{4!} = \frac{2}{4!} \ge 0$. Thus, since $(x - 1)^4 \ge 0$, we have that for such x in V,

$$f(x) - f(1) \ge 0 \implies f(x) \ge f(1)$$
.

Hence, we have a neighborhood of 1 such that for all x in the neighborhood $f(x) \ge f(1)$. It follows that 1 a local minimum of f.

§6.3

7 List of Theorems

\hookrightarrow <u>Definition</u> 1.1 (Metric Space)
← <u>Definition</u> 1.2 (Open Metric Space)
← <u>Definition</u> 1.3 (Normed Space)
\hookrightarrow Proposition 1.1
\hookrightarrow Definition 1.4 (Convex Set)
\hookrightarrow <u>Definition</u> 1.5 (ℓ_p)
← <u>Definition</u> 2.1 (Topological space)
← Definition 2.2 (Closed sets)
← <u>Definition</u> 2.3 (Equivalence of Metrics)
← <u>Definition</u> 2.4 (Interior, Boundary of a Topological Set)
□ Definition 2.5 (Closure)
\hookrightarrow <u>Proposition</u> 2.1 (Properties of Int(A))
\hookrightarrow <u>Proposition</u> 2.2 (Properties of \overline{A})
\hookrightarrow Proposition 2.3
← Definition 2.6 (Basis for a Toplogy)
$\hookrightarrow \overline{\underline{\text{Definition}}} \ 2.7 \dots \dots$
← <u>Proposition</u> 2.6 (Consequences of Subspace Topologies)
→ Proposition 2.7
← <u>Definition</u> 2.8 (Continuous Function)
→ Proposition 2.9
\hookrightarrow Theorem 2.1 (Continuity of Composition)
← Definition 2.9 (Finite Product Spaces)
→ Definition 2.10 (Cylinder Set)

\hookrightarrow <u>Definition</u> 2.11 (Projection)	13
\hookrightarrow <u>Definition</u> 2.12 (Coordinate Function)	13
	13
\hookrightarrow <u>Definition</u> 2.13 (Product Topology/Cylinder Sets for ∞ Products)	14
	14
	15
\hookrightarrow Question 2.1	15
\hookrightarrow <u>Definition</u> 2.14 (Compact)	16
	16
\hookrightarrow Theorem 2.2 (On Compactness)	17
	17
	17
	18
\hookrightarrow <u>Definition</u> 2.15 (Connected)	18
<u> Theorem</u> 2.3	18
<u> Lemma</u> 2.3	19
$\hookrightarrow \underline{\text{Theorem}} \ 2.4 \ (\text{``Intermediate Value Theorem''}) \ . \ . \ . \ . \ . \ . \ . \ . \ . \ $	19
<u> Theorem</u> 2.5	19
<u> Theorem</u> 2.6	20
\hookrightarrow <u>Definition</u> 2.16 (Path Connected)	20
\hookrightarrow Theorem 2.7 (Path connected \implies connected)	20
	20
← <u>Definition</u> 2.17 (Connected Component)	21
← <u>Definition</u> 2.18 (Path Component)	21
	21
	21
	21
	21
	22
	22
→ <u>Definition</u> 2.19 (An Explicit Definition)	22
→ <u>Definition</u> 2.20 (Complement Definition)	22
← <u>Definition</u> 3.1 (Hölder Conjugates)	23

→ <u>Proposition</u> 3.1 (Hölder's Inequality)	23
	24
← <u>Proposition</u> 3.2 (Minkowski Inequality)	26
<u> Theorem</u> 3.1	27
\hookrightarrow <u>Definition</u> 3.2 (Complete Metric Space)	27
\hookrightarrow Proposition 3.3	27
$\hookrightarrow \underline{\text{Proposition}} \ 3.4 \dots$	28
$\hookrightarrow \underline{\text{Proposition}} \ 3.5 \dots \dots$	28
\hookrightarrow <u>Proposition</u> 3.6	28
← <u>Definition</u> 3.3 (Contraction Mapping)	29
← <u>Theorem</u> 3.2 (Contraction Mapping Theorem)	29
\hookrightarrow Theorem 3.3 (ℓ_p complete)	30
\hookrightarrow <u>Definition</u> 3.4 (Totally Bounded)	32
<u> Theorem</u> 3.4	32
\hookrightarrow <u>Lemma</u> 3.1 (Cantor Intersection Theorem)	32
\hookrightarrow <u>Definition</u> 3.5 (Finite Intersection Property)	33
\hookrightarrow <u>Lemma</u> 3.2 (Finite Interesection Formulation of Compactness)	33
	33
<u> Lemma</u> 3.4	33
<u> Theorem</u> 3.5	34
\hookrightarrow <u>Definition</u> 4.1 (Differentiable)	35
\hookrightarrow <u>Definition</u> 4.2	35
\hookrightarrow Theorem 4.1 (Caratheodory's Theorem)	35
\hookrightarrow Theorem 4.2 (Chain Rule)	36
\hookrightarrow <u>Definition</u> 4.3	36
\hookrightarrow Theorem 4.3 (Rolle's)	36
$\hookrightarrow \underline{\text{Theorem}} \text{ 4.4 (Gauss-Lucas)} \dots $	36
\hookrightarrow <u>Definition</u> 4.4	37
\hookrightarrow Theorem 4.5 (Mean Value)	37
<u> Theorem</u> 4.6	38
\hookrightarrow <u>Proposition</u> 4.1	38
	38
<u> Theorem</u> 4.7 (Darboux)	38

	8
← Theorem 4.8 (Cauchy Mean Value)	9
← Proposition 4.3 (More General L'Hopital)	9
	9
\hookrightarrow Theorem 4.9 (Taylor's Theorem)	9
	0
□ Definition 4.5 (Convex Set)	0
← Definition 4.6 (Convex Function)	0
\hookrightarrow <u>Definition</u> 5.1 (Partitions)	0
\hookrightarrow <u>Definition</u> 5.2 (Riemann Sum)	1
← <u>Definition</u> 5.3 (Riemann Integrable)	1
	1
	1
→ Proposition 5.3 (Cauchy Criterion for Integrability)	2
	2
	2
	3
	4
	5
	5
	5
□ Definition 6.1	6
	6
	8
—————————————————————————————————————	8
—————————————————————————————————————	9
—————————————————————————————————————	
\hookrightarrow Question 6.5	1