

MATH358 - Advanced Calculus

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§1 DIFFERENTIATION

We say $\Omega \subset \mathbb{R}^n$ a *domain* if it is open and connected.

→**Definition 1.1** (Differentiation): Let $f = (f_1, \dots, f_m)^T : \Omega \rightarrow \mathbb{R}^m$, Ω a domain in \mathbb{R}^n and $f_j : \Omega \rightarrow \mathbb{R}$. We say f *differentiable* at $x_0 \in \Omega$ if there exists a linear map $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

$$\lim_{x \rightarrow x_0} \frac{\|f(x) - f(x_0) - L(x - x_0)\|}{\|x - x_0\|} = 0.$$

Remark 1.1: Note that the first norm on \mathbb{R}^m , the second on \mathbb{R}^n .

Remark 1.2: In terms of ε, δ , the definition says that $\forall \varepsilon > 0, \exists \delta > 0$ such that if $x \in \Omega \cap B(x_0, \delta)$, then $\|f(x) - f(x_0) - L(x - x_0)\| < \varepsilon \|x - x_0\|$.

→**Theorem 1.1:** L as above is unique if it exists.

PROOF. Suppose $L_1 \neq L_2$ both satisfy the definition. Then, for all $\varepsilon > 0$, there exists $\delta > 0$ such that if $0 < \|x - x_0\| < \delta$, then

$$\begin{aligned} \|(L_1 - L_2)(x - x_0)\| &\leq \|f(x) - f(x_0) - L_1(x - x_0)\| + \|f(x) - f(x_0) - L_2(x - x_0)\| \\ &\leq \varepsilon \|x - x_0\|, \end{aligned}$$

by differentiability (and the previous remark). In particular, $\|(L_1 - L_2)u\| < \varepsilon$ for all unit vectors u , which implies $\|(L_1 - L_2)u\| = 0$ and thus $L_1 = L_2$. ■

→**Definition 1.2:** If f differentiable at x_0 , we'll write $Df(x_0) = L$ for the *differential* of f at x_0 .

→**Proposition 1.1:** f differentiable at x_0 implies f continuous at x_0 . In fact, f is Lipschitz at x_0 .

PROOF. Let $\delta > 0$ such that $\|x - x_0\| < \delta$ implies $\|f(x) - f(x_0) - Df(x_0)(x - x_0)\| < \|x - x_0\|$, which implies

$$\|f(x) - f(x_0)\| \leq \|Df(x_0)(x - x_0)\| + \|x - x_0\| \leq (\|L\| + 1)\|x - x_0\|,$$

which readily proves the statement. ■

→**Proposition 1.2:** f differentiable at a point x_0 iff each of its component functions are differentiable at x_0 .

→**Definition 1.3:** For $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$, define the *partial derivative*

$$\frac{\partial f_j}{\partial x_i}(x_1, \dots, x_m) := \lim_{h \rightarrow 0} \frac{[f_j(x_1, \dots, x_i + h, \dots, x_m) - f_j(x_1, \dots, x_i, \dots, x_m)]}{h},$$

if the limit exists.

→ **Proposition 1.3:** Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ be differentiable at x_0 . Then, $\frac{\partial f_j}{\partial x_i}(x_0)$ exists for each $i = 1, \dots, n$ and $j = 1, \dots, m$, and

$$L = Df(x_0) = \left(\begin{array}{c} \frac{\partial f_j}{\partial x_i}(x_0) \\ \vdots \\ \frac{\partial f_j}{\partial x_i}(x_0) \end{array} \right)_{\substack{1 \leq i \leq n \\ 1 \leq j \leq m}}.$$

We call this matrix the Jacobian or derivative of f at x_0 .

PROOF. Write $L = (a_{ji})$ in the standard basis e_1, \dots, e_n for \mathbb{R}^n . Let $\varepsilon > 0$, fix some i with $1 \leq i \leq n$, and set $x := x_0 + he_i$, with $|h| < \delta$ sufficiently small. By differentiability,

$$\frac{\|f(x) - f(x_0) - L(x - x_0)\|}{\|x - x_0\|} = \left(\sum_{j=1}^m \left[\frac{f_j(x) - f_j(x_0)}{h} - a_{ji} \right]^2 \right)^{1/2}.$$

Since the limit as $h \rightarrow 0$ of the above ratio must be zero, the limit of each term in the summation as $h \rightarrow 0$ must be zero as well (being a sum of nonnegative terms), i.e.

$$\lim_{h \rightarrow 0} \frac{f_j(x) - f_j(x_0)}{h} = a_{ji} \quad \forall j = 1, \dots, m.$$

But the limit on the left is just $\frac{\partial f_j}{\partial x_i}(x_0)$, which proves all of the claims in turn. ■

Remark 1.3: This proposition says that f differentiable at x_0 implies $\frac{\partial f_j}{\partial x_i}(x_0)$ exists for all i, j . The converse need not be true. Consider

$$f(x, y) := \begin{cases} \frac{xy}{\sqrt{x^2+y^2}} & (x, y) \neq 0 \\ 0 & \text{else} \end{cases}.$$

㊂ **Example 1.1:** Another counterexample as in the previous remark is the function

$$f(x, y) := \begin{cases} \frac{x^2 y}{x^2 + y^2} & (x, y) \neq (0, 0), \\ 0 & (x, y) = (0, 0). \end{cases}$$

Claim 1: f continuous at $(0, 0)$. We have, for $(x, y) \neq (0, 0)$,

$$\begin{aligned} |f(x, y) - f(0, 0)| &= \left| \frac{x^2 y}{x^2 + y^2} \right| \\ &= \frac{x^2 |y|}{x^2 + y^2} \\ &\leq |y| \rightarrow 0 \text{ as } (x, y) \rightarrow (0, 0), \end{aligned}$$

so we have continuity indeed.

Claim 2: $\partial_x f, \partial_y f$ exist at the origin, and are equal to zero. Note that $f(x, 0) = 0$ for $x \neq 0$, and $f(0, 0) = 0$, so it follows that $\partial_x f(0, 0) = 0$. Similarly for $\partial_y f(0, 0)$.

Claim 3: f is not differentiable at $(0, 0)$. Suppose otherwise. Then, $L = Df(0, 0) = (0, 0)$, so

$$\begin{aligned} 0 &= \lim_{(x, y) \rightarrow (0, 0)} \frac{|f(x, y) - f(0, 0) - Df(0, 0)(x, y)|}{\|(x, y)\|} \\ &= \lim_{(x, y) \rightarrow (0, 0)} \frac{|f(x, y)|}{\|(x, y)\|} \\ &= \lim_{(x, y) \rightarrow (0, 0)} \frac{x^2 |y|}{(x^2 + y^2) \cdot \sqrt{x^2 + y^2}} \\ &= \lim_{(x, y) \rightarrow (0, 0)} \frac{x^2 |y|}{(x^2 + y^2)^{3/2}}. \end{aligned}$$

Suppose $y = x$ in the final term (i.e., we approach the limit on a diagonal), and $x > 0$, then this ratio simplifies

$$\frac{x^3}{(2x^2)^{3/2}} = \frac{1}{2^{3/2}} \neq 0,$$

so we have a contradiction.

We can get a partial converse, however, if we assume continuity.

↪ **Theorem 1.2:** Let $f = (f_1, \dots, f_m) : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$. Suppose each $\frac{\partial f_j}{\partial x_i}$ is continuous at some $x^0 \in \Omega$. Then, f is differentiable at x^0 .

PROOF. We use MVT, and suppose $n = 2, m = 1$ for simplicity of notation, so that $f : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}$. We write $x = (x_1, x_2) \in \Omega, x^0 = (x_1^0, x_2^0)$. Let $\varepsilon > 0$. By assumption, there exists a $\delta > 0$ such that

$$\|y - x^0\| < \delta \Rightarrow \left| \frac{\partial f}{\partial x_i}(y) - \frac{\partial f}{\partial x_i}(x^0) \right| \leq \frac{\varepsilon}{2}, \quad i = 1, 2.$$

We write

$$\begin{aligned} f(x) - f(x^0) &= f(x_1, x_2) - f(x_1^0, x_2) + f(x_1^0, x_2) - f(x_1^0, x_2^0) \\ (\text{MVT, coordinate-wise}) \quad &= \frac{\partial f}{\partial x_1}(z_1, x_2)(x_1 - x_1^0) + \frac{\partial f}{\partial x_2}(x_1^0, z_2)(x_2 - x_2^0), \end{aligned}$$

for some z_1 between x_1 and x_1^0 and some z_2 between x_2 and x_2^0 . Thus,

$$\begin{aligned} f(x) - f(x^0) - Df(x^0)(x - x^0) &= f(x) - f(x^0) - (\partial_{x_1} f(x^0), \partial_{x_2} f(x^0)) \cdot (x - x^0) \\ &= \frac{\partial f}{\partial x_1}(z_1, x_2)(x_1 - x_1^0) + \frac{\partial f}{\partial x_2}(x_1^0, z_2)(x_2 - x_2^0) \\ &\quad - \frac{\partial f}{\partial x_1}(x^0)(x_1 - x_1^0) - \frac{\partial f}{\partial x_2}(x^0)(x_2 - x_2^0) \\ &= [\partial_{x_1} f(z_1, x_2) - \partial_{x_1} f(x_1^0, x_2^0)](x_1 - x_1^0) \\ &\quad + [\partial_{x_2} f(x_1^0, z_2) - \partial_{x_2} f(x_1^0, x_2^0)](x_2 - x_2^0). \end{aligned}$$

By choice of z_1, z_2 and for (x_1, x_2) in $B(x^0, \delta)$, we know $(z_1, x_2) \in B(x^0, \delta)$ and $(x_1^0, z_2) \in B(x^0, \delta)$ as well, so we can appeal to continuity. In addition, it's clear that $|x_i - x_i^0| \leq \|x - x^0\|$. Thus, using continuity, we find

$$|f(x) - f(x^0) - Df(x^0)(x - x^0)| \leq \left(\frac{\varepsilon}{2} + \frac{\varepsilon}{2} \right) \|x - x^0\| = \varepsilon \|x - x^0\|,$$

so dividing both sides by $\|x - x^0\|$ immediately gives the result. ■

→ **Definition 1.4:** Suppose $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ has continuous $\frac{\partial f}{\partial x_i}$ at all points in Ω . Then, we say f is *continuously differentiable* (in Ω), and we write $f \in C^1(\Omega)$.

Remark 1.4: Continuity of partial derivatives is sufficient, but not necessary, for differentiability. For instance,

$$f(x, y) = \begin{cases} \frac{x^2 y^2}{x^2 + y^4} & (x, y) \neq (0, 0) \\ 0 & (x, y) = (0, 0) \end{cases}.$$

On readily computes $\partial_x f(0, 0) = \partial_y f(0, 0) = 0$, but along the parabola $x = t^2, y = t$ ($t \neq 0$),

$$\partial_x f(t^2, t) = \frac{1}{2},$$

so $\partial_x f$ can't be continuous. However, f is still differentiable at $(0, 0)$: we claim $L = 0$, then

$$\frac{|f(x, y) - f(0, 0) - L(x, y)|}{\|(x, y)\|} = \frac{|f(x, y)|}{(x^2 + y^2)^{\frac{1}{2}}} = \frac{x^2 y^2}{(x^2 + y^4)(x^2 + y^2)^{\frac{1}{2}}} \leq \frac{y^2}{|x^2 + y^2|^{\frac{1}{2}}} \leq |y| \underset{(x, y) \rightarrow 0}{\rightarrow} 0.$$

→**Proposition 1.4** (Basic Properties of Differentiation):

1. If $f, g : \Omega \rightarrow \mathbb{R}^m$ both differentiable at $x^0 \in \Omega$, then so is $F = f + g$, and

$$D(f + g)(x^0) = Df(x^0) + Dg(x^0).$$

2. If $f, g : \Omega \rightarrow \mathbb{R}^m$ both differentiable at $x^0 \in \Omega$, then so is $F = fg : \Omega \rightarrow \mathbb{R}$, and

$$DF(x^0) = f(x^0)Dg(x^0) + g(x^0)Df(x^0).$$

3. $f, g : \Omega \rightarrow \mathbb{R}$ both differentiable at x^0 with $g(x^0) \neq 0$, then so is $F = \frac{f}{g}$, and

$$DF(x^0) = \frac{DF(x^0)}{g(x^0)} - \frac{f(x^0)Dg(x^0)}{g^2(x^0)}.$$

4. (Chain Rule) Given $f : \Omega \subset \mathbb{R}^n \rightarrow \tilde{\Omega} \subset \mathbb{R}^m$ and $g : \tilde{\Omega} \rightarrow \mathbb{R}^k$, with f differentiable at x^0 and g differentiable at $y^0 = f(x^0)$, then $H = g \circ f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^k$ is differentiable at x^0 , and

$$DH(x^0) = Dg(y^0) \cdot Df(x^0),$$

in which one should read the “.” as matrix multiplication.

PROOF. 1., 2., 3. left as an exercise. We prove 4., the Chain Rule, for it is realistically the most interesting. Set $L := Dg(y_0) \cdot Df(x_0)$, and we'll write $y = f(x)$ (so in particular $y_0 = f(x_0)$, as in the statement). We need to show

$$\lim_{x \rightarrow x_0} \frac{\|H(x) - H(x_0) - L(x - x_0)\|}{\|x - x_0\|} = 0.$$

Let us work the numerator:

$$\begin{aligned} H(x) - H(x_0) - L(x - x_0) &= g(y) - g(y_0) - Dg(y_0)Df(x_0)(x - x_0) \\ &= g(y) - g(y_0) - Dg(y_0)(y - y_0) \\ &\quad + Dg(y_0)(y - y_0) - Dg(y_0)Df(x_0)(x - x_0) \\ &= g(y) - g(y_0) - Dg(y_0)(y - y_0) \\ &\quad + Dg(y_0)(f(x) - f(x_0) - Df(x_0)(x - x_0)). \end{aligned}$$

This means

$$\begin{aligned} \|H(x) - H(x_0) - L(x - x_0)\| &\leq \overbrace{\|g(y) - g(y_0) - Dg(y_0)(y - y_0)\|}^{=: (A)} \\ &\quad + \overbrace{\|Dg(y_0)\| \|f(x) - f(x_0) - Df(x_0)(x - x_0)\|}^{=: (B)}. \end{aligned}$$

By differentiability of f at x_0 , $(B) \rightarrow 0$ as $\|x - x_0\| \rightarrow 0$. We also have that, since f differentiable it is Lipschitz continuous, there is some $C > 0$ such that for $\|x - x_0\|$ sufficiently small,

$$(A) = \|y - y_0\| \cdot \frac{(A)}{\|y - y_0\|} \leq C\|x - x_0\| \frac{A}{\|y - y_0\|}.$$

By differentiability of g , the ratio $\frac{\|A\|}{\|y-y_0\|} \rightarrow 0$ as $\|y-y_0\| \rightarrow 0$. By continuity of f , $\|y-y_0\| = \|f(x) - f(x_0)\|$ will become small as $\|x-x_0\| \rightarrow 0$, so that we have in all $\frac{A}{\|x-x_0\|} \rightarrow 0$ as $\|x-x_0\| \rightarrow 0$. ■

Exercise 1.1: Let f differentiable in \mathbb{R}^2 and $g(r, \theta) := (r \cos \theta, r \sin \theta)$ with $(r, \theta) \in (0, \infty) \times [0, 2\pi)$. Let $F(r, \theta) = f(g(r, \theta))$. Compute $\frac{\partial F}{\partial \theta}$ and $\frac{\partial F}{\partial r}$.

§1.1 Aside on Tangent Planes

Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ differentiable on Ω . Then $Df(x) = \left(\frac{\partial f}{\partial x_1}(x), \dots, \frac{\partial f}{\partial x_n}(x) \right) =: \nabla f(x)$, called the *gradient* of f . Let $S := \{(x, z) \in \Omega \times \mathbb{R} : z = f(x)\}$ be the *graph* of f . Then, for $x^0 \in \mathbb{R}$,

$$T_{x^0} S = \left\{ (x, z) \in \mathbb{R}^n \times \mathbb{R} : z = f(x^0) + \sum_{j=1}^n \frac{\partial f}{\partial x_j}(x^0)(x_j - x_j^0) \right\}$$

is the *tangent plane* to S at x^0 .

To see this, let $v \in \mathbb{R}^n$ be a unit vector and $x \in \Omega$. Define $g(t) := f(x + tv)$ for $f : \Omega \rightarrow \mathbb{R}$ differentiable (for t sufficiently small, $x + tv$ remains in Ω by openness). We find

$$g'(t) = \langle \nabla f(x + tv), v \rangle$$

for t sufficiently small.

→ **Proposition 1.5:** Suppose $\nabla f(x) \neq 0$. Then, $\nabla f(x)$ points in the direction of steepest increase of f .

PROOF. For v a unit vector, the *directional derivative* in the direction of v is $D_v f(x) = \langle \nabla f(x), v \rangle = \|\nabla f(x)\| \cos(\theta)$ where θ the angle between $\nabla f(x)$ and v . This is maximized when $\theta = 0$, i.e. when $v = \frac{\nabla f(x_0)}{\|\nabla f(x_0)\|}$. ■

We can rewrite the graph S as the level set $\{(x, z) \in \Omega \times \mathbb{R} \mid g(x, z) = 0\}$ where $g(x, z) := z - f(x)$. Heuristically, $\nabla g(x_0, z_0)$ should be *normal* to the surface S at (x_0, z_0) (for steepest increase). As such, we define

$$T_{(x_0, z_0)} S := \{\nabla g(x_0, z_0) \cdot (x - x_0, z - z_0) = 0\}.$$

Note that

$$\nabla g(x_0, z_0) = (-\partial_{x_1} f(x_0), \dots, -\partial_{x_n} f(x_0), 1),$$

so that

$$T_{(x_0, z_0)} = \{z - z_0 = \nabla f(x_0) \cdot (x - x_0)\},$$

which gives the definition from above.

§1.2 Clairault's Theorem

Here, the question is, given $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ twice differentiable, when can we exchange order of second-order partial derivatives, i.e. when is

$$\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_i \partial x_j}, \quad \forall i, j = 1, \dots, n?$$

We need to establish first a generalization of the mean-value theorem. First, note that if

$$\gamma : (a, b) \rightarrow \mathbb{R}^n, \quad g : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$$

are two differentiable functions with $\gamma((a, b)) \subset \Omega$, then by the chain rule, if we put $H(t) := g(\gamma(t))$,

$$\frac{\partial H}{\partial t} = Dg(\gamma(t)) \cdot D\gamma(t), \quad D\gamma(t) = (\gamma'_1(t), \dots, \gamma'_n(t)).$$

→ **Theorem 1.3** (Mean-Value Theorem): Let $B \subset \mathbb{R}^n$ be a ball and $f : B \rightarrow \mathbb{R}$ be differentiable for all $x \in B$. Then, for any $x, y \in B$, there exists $z \in B$ such that

$$f(x) - f(y) = Df(z) \cdot (x - y).$$

In particular, $|f(x) - f(y)| \leq \|Df(z)\| \|x - y\|$.

PROOF. Let $x, y \in B$ fixed and let $\gamma(t) := tx + (1 - t)y$ for $t \in [0, 1]$. We see that $\gamma(t) \in B$ for all $t \in [0, 1]$, and that $D\gamma(t) = x - y$. Set $F(t) := f(\gamma(t))$ (i.e., we restrict f to its values along the straight line along x and y), noting $F : \mathbb{R} \rightarrow \mathbb{R}$. So, by 1-dimensional mean-value theorem, there is some $t^* \in [0, 1]$ such that

$$\begin{aligned} f(x) - f(y) &= F(1) - F(0) = F'(t^*) = Df\left(\underbrace{t^*x + (1 - t^*)y}_{=: z \in B}\right) \cdot D\gamma(t) \\ &= Df(z) \cdot (x - y). \end{aligned}$$

■

Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ differentiable. Remember that $Df : \Omega \rightarrow \mathbb{R}^{m \times n}$.

→ **Definition 1.5:** We say f twice differentiable at x if Df exists locally to x and Df is differentiable at x . We write

$$D^2f = D(Df),$$

and similarly

$$D^k f := D(D^{k-1}f)$$

with an analogous definition.

→ **Definition 1.6:** Given $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$, we see that $f \in C^k(\Omega)$ for $k \in \mathbb{Z}_+$ if all the partial derivatives to order k exist and are continuous in Ω .

→ **Definition 1.7:** If $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ twice differentiable, the *Hessian matrix* is given by

$$H_f(x) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_n} \end{pmatrix}.$$

Exercise 1.2: Let $f(x, y) := \begin{cases} \frac{(xy)(x^2-y^2)}{x^2+y^2} & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$ and compute $H_f(x, y)$.

→ **Theorem 1.4 (Clairault):** Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ be twice differentiable at $x \in \Omega$. Then,

$$\frac{\partial^2 f}{\partial x_i \partial x_j}(x) = \frac{\partial^2 f}{\partial x_j \partial x_i}(x), \quad \forall i, j = 1, \dots, n.$$

→ **Corollary 1.1:** If $\frac{\partial^2 f}{\partial x_i \partial x_j}$ are all continuous at $x \in \Omega$ for $i, j = 1, \dots, n$, then $\frac{\partial^2 f}{\partial x_i \partial x_j}(x) = \frac{\partial^2 f}{\partial x_j \partial x_i}(x)$.

PROOF. (Of Clairault's) It's enough to consider $n = 2$. Fix $(x, y) \in \Omega$, and note that for $s, t \in \mathbb{R}$ sufficiently small, $(x + s, y + t) \in \Omega$ by openness. Set

$$\begin{aligned} \Delta(s, t) &:= f(x + s, y + t) - f(x, y + t) - f(x + s, y) + f(x, y) \\ &= g_t(x + s) - g_t(x), \quad g_t(u) := f(u, y + t) - f(u, y). \end{aligned}$$

By the mean-value theorem, there is some $\xi_{s,t}$ between x and $x + s$ such that

$$\Delta(s, t) = \frac{\partial g_t}{\partial x}(\xi_{s,t}) \cdot s = \left[\frac{\partial f}{\partial x}(\xi_{s,t}, y + t) - \frac{\partial f}{\partial x}(\xi_{s,t}, y) \right] s. \quad (\ddagger)$$

By assumption, $\frac{\partial f}{\partial x}$ is differentiable at (x, y) , so

$$\frac{\partial f}{\partial x}(z_1, z_2) = \frac{\partial f}{\partial x}(x, y)(z_1 - x) + \frac{\partial^2 f}{\partial x^2}(x, y)(z_2 - y) + E_1(z_1, z_2), \quad (\dagger)$$

where

$$\frac{|E_1(z_1, z_2)|}{\sqrt{(z_1 - x)^2 + (z_2 - y)^2}} \rightarrow 0, \quad \text{as } (z_1, z_2) \rightarrow (x, y).$$

Evaluating (\dagger) at $(z_1, z_2) = (\xi_{s,t}, y + t)$ and $(\xi_{s,t}, y)$, and plugging into (\ddagger) yields

$$\Delta(s, t) = \left(\frac{\partial^2 f}{\partial y \partial x}(x, y)t + E_1(\xi_{s,t}, y + t) - E_1(\xi_{s,t}, y) \right) s.$$

Let $s = t$ and let $t \rightarrow 0$. We claim that

$$\frac{\partial^2 f}{\partial y \partial x}(x, y) = \lim_{s=t \rightarrow 0} \frac{\Delta(s, t)}{st} = \frac{\partial^2 f}{\partial x \partial y}(x, y).$$

The first equality is obvious from the assumptions on the error terms. On the other hand, we can switch the order of the middle terms in $\Delta(s, t)$ and write

$$\begin{aligned}\Delta(s, t) &= f(x + s, y + t) - f(x, y + t) - f(x + s, y) + f(x, y) \\ &= h_s(y + t) - h_s(y), \quad h_s(u) := f(x + s, u) - f(x, u).\end{aligned}$$

Repeating the same argument as above with g_t , we get that

$$\Delta(s, t) = \left(\frac{\partial^2}{\partial x \partial y}(x, y)s + E_2(x + s, \eta_{s,t}) - E_2(x, \eta_{s,t}) \right)t,$$

where $\eta_{s,t}$ lies between y and $y + t$, and

$$|E_2(x + s, \eta_{s,t})| \leq |s^2 + t^2|, \quad |E_2(x, \eta_{s,t})| \leq \sqrt{s^2 + t^2}.$$

Setting $s = t$ here, we get

$$\lim_{\substack{s, t \rightarrow 0 \\ s=t}} \frac{\Delta(s, t)}{st} = \frac{\partial^2}{\partial x \partial y}(x, y).$$

This proves the claim. ■

§1.3 Inverse Function Theorem

→ **Theorem 1.5** (In 1D): If $f : (a, b) \rightarrow (c, d)$ is differentiable with $f'(x) > 0$, then there exists $g : (c, d) \rightarrow (a, b)$ differentiable such that $y = f(x) \Leftrightarrow x = g(y)$ (i.e. $x = g(y)$).

In higher dimensions, we recall some preliminaries before proving.

→ **Theorem 1.6:** Let (X, d) a complete metric space and $f : X \rightarrow X$ a contraction mapping, with $d(f(x_2), f(x_1)) \leq \alpha d(x, y)$ for all $x, y \in X$ for some $0 < \alpha < 1$. Then, there exists a unique $x_0 \in X$ such that $f(x_0) = x_0$.

We will write $M_n := \{n \times n \text{ matrices}\} \cong \mathbb{R}^{n^2}$, and $\|A\| := \sqrt{\sum_{i,j=1}^n a_{ij}^2}$ where $A := (a_{ij}) \in M_n$. We use

$$\mathrm{GL}(n) := \{A \in M_n : \det(A) \neq 0\} = \det^{-1}(\mathbb{R} \setminus \{0\}), \quad \det : M_n \rightarrow \mathbb{R}.$$

Remark that since $\mathbb{R} \setminus \{0\}$ is open, and the map \det is continuous (it can be written as a polynomial in the entries a_{ij} 's of the matrix A), we know that $\mathrm{GL}(n)$ an open subset of M_n .

Consider the map

$$f : \mathrm{GL}(n) \rightarrow \mathrm{GL}(n), \quad f(A) := A^{-1}.$$

→ **Lemma 1.1:** $\mathrm{GL}(n) \subset M_n$ open and $f \in C^k$ for all $k = 1, 2, \dots$

PROOF. We already proved the first statement in our remarks above.

Let $A(j|i)$ be $(n - 1) \times (n - 1)$ matrix with its j th row and i th columns deleted, then recall

$$\text{adj}(A) = ((-1)^{i+j} \det A(j|i)).$$

By Cramer's formula from linear algebra,

$$f(A) = A^{-1} \frac{1}{\det(A)} \text{adj}(A),$$

which is in C^k since $\det(A)$ is a polynomial in the coefficients of A and $\det(A) \neq 0$. ■

Theorem 1.7 (Inverse Function Theorem): Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ be C^1 . Let $x_0 \in \Omega$ and assume $Df(x_0) \in \text{GL}(n)$. Then, there exist domains U and V of x_0 and $f(x_0)$ resp. such that $f(U) = V$ and $f|_U$ has a C^1 inverse map $f^{-1} : V \rightarrow U$. Moreover, for any $y \in V$ and $x = f^{-1}(y)$, $Df^{-1}(y) = [Df(x)]^{-1}$.

Remark 1.5: By the first lemma above, if $f \in C^k$, $k \geq 1$, we get the same regularity for f^{-1} .

PROOF. By translation, it's enough to assume $x_0 = f(x_0) = y_0 = 0$ and $Df(x_0) = \text{Id}$ by replacing f with $[Df(0)]^{-1}f$, so we have a mapping

$$f : \Omega \rightarrow \mathbb{R}^n, \quad f(0) = 0, Df(0) = \text{Id}.$$

Fix $y \in V$ and set

$$g_y(x) := y + x - f(x),$$

remark that

$$g_y(x) = x \Leftrightarrow y = f(x),$$

so it suffices to show g_y as a mapping $\mathbb{R}^n \rightarrow \mathbb{R}^n$ is a contraction mapping, and

$$Dg_y(0) = \text{Id} - \text{Id} = 0.$$

If $f \in C^1(U)$, then $g_y \in C^1(U)$ so that $Dg_y \in C^0(U)$ (similar if $f \in C^k \Rightarrow g_y \in C^k$). Since $Dg_0 \in C^0(U)$, there exists some $\delta > 0$ sufficiently small such that $\|Dg_0(x)\| \leq \frac{1}{2}$, for all $x \in B_\delta(0)$. By mean-value theorem, there exists some $z \in B_\delta(0)$ such that

$$\begin{aligned} \|g_0(x)\| &= \left\| g_0(x) - \underbrace{g_0(0)}_{=0} \right\| \\ &\leq \|Dg_0(z)\| \|x\| \\ &\leq \frac{\|x\|}{2} < \frac{\delta}{2}, \end{aligned}$$

which implies we can view

$$g_0 : B_\delta(0) \rightarrow B_{\delta/2}(0).$$

It follows that

$$g_y : B_\delta(0) \rightarrow B_\delta(0), \quad \forall y \in B_{\delta/2}(0),$$

using the fact $g_y = y + g_0$ and the triangle inequality. By MVT once again for any $x, x' \in B_\delta(0)$, there exists $y \in B_{\delta/2}(0)$ such that

$$\begin{aligned}\|g_y(x) - g_y(x')\| &= \|g_0(x) - g_0(x')\| \\ &\leq \|Dg_0(y)\| \|x - x'\| \\ &\leq \frac{\|x - x'\|}{2}\end{aligned}$$

hence $g_y : B_\delta \rightarrow B_\delta$ is a contraction mapping. By the fixed-point theorem, there exists a unique point $x \in B_\delta(0)$ such that $g_y(x) = x \Leftrightarrow y = f(x)$. That is, there exists an inverse map $f^{-1} : B_{\delta/2}(0) \rightarrow B_\delta(0)$. Moreover, for any $x, x' \in B_\delta(0)$,

$$\begin{aligned}\|x - x'\| &\leq \|f(x) - f(x')\| + \|g_0(x) - g_0(x')\| \\ &\leq \|f(x) - f(x')\| + \frac{1}{2}\|x - x'\|,\end{aligned}$$

i.e.

$$\|x - x'\| \leq 2\|f(x) - f(x')\|.$$

From here, we know that for $y, y' \in B_{\delta/2}(0)$,

$$\|f^{-1}(y) - f^{-1}(y')\| \leq 2\|y - y'\| \Rightarrow f^{-1} \in C^0(B_{\delta/2}(0)).$$

Next, we need to show that $Df^{-1}(y)$ exists for $y \in B_{\delta/2}(0)$ for small $\delta > 0$. Since $Df(0) \in \text{GL}(n)$, we know $Df(x) \in \text{GL}(n)$ if $x \in B_\delta(0)$ (possible after shrinking $\delta > 0$). Set

$$W := f^{-1}(B_{\delta/2}(0)),$$

and choose $R > 0$ suff. small so that

$$\overline{B_R(0)} \subset W.$$

Since $[Df]^{-1} \in C^0(\overline{B_R})$ and $\overline{B_R}(0)$ is compact,

$$\|[Df(x)]^{-1}\| \leq K, x \in \overline{B_r(0)}.$$

Then, given $y, y' \in B_{\delta/2}(0)$ and with $x = f^{-1}(y), x' = f^{-1}(y')$, we find

$$\begin{aligned}\frac{\|f^{-1}(y) - f^{-1}(y') - [Df(x')]^{-1}(y - y')\|}{\|y - y'\|} &= \frac{\|x - x' - [Df(x')]^{-1}(f(x) - f(x'))\|}{\|f(x) - f(x')\|} \\ &= \frac{\|x - x'\|}{\|f(x) - f(x')\|} \frac{\|[Df(x')]^{-1}(f(x) - f(x') - Df(x')(x - x'))\|}{\|x - x'\|} \\ &\leq 2K \frac{\|f(x) - f(x') - Df(x')(x - x')\|}{\|x - x'\|},\end{aligned}$$

which converges to zero by differentiability of f . This proves the claim $Df^{-1}(y) = [Df(x)]^{-1}$ where $y = f(x)$. ■

Remark 1.6: The inverse function theorem is *local*. In general we can't expect to find a single global inverse. For instance, let

$$f(x, y) := (e^y \cos(x), e^y \sin(x)).$$

One easily verifies

$$\det(Df(x, y)) = e^{-y} \neq 0.$$

However,

$$f(x + 2k\pi, y) = f(x, y), \forall k \in \mathbb{Z},$$

so there is certainly no hope of a global inverse, for f is not even injective.

↪ **Theorem 1.8** (Implicit Function Theorem): Let $F : \Omega \subset \mathbb{R}_x^n \times \mathbb{R}_y^m \rightarrow \mathbb{R}_y^m$ be a C^k map. Denote $X = (x, y) \in \mathbb{R}^n \times \mathbb{R}^m$, and let $X_0 = (x_0, y_0) \in \Omega$ with $F(X_0) = 0$. Writing $F = (F_1, \dots, F_m)$, assume that

$$D_y F(X_0) = \begin{pmatrix} \frac{\partial F_1}{\partial y_1} & \cdots & \frac{\partial F_1}{\partial y_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_m}{\partial y_1} & \cdots & \frac{\partial F_m}{\partial y_m} \end{pmatrix}(X_0)$$

is invertible. Then, there exist neighborhoods U and V of $x_0 \in \mathbb{R}^n$ and $y_0 \in \mathbb{R}^m$ resp. and a unique C^k map $f : U \rightarrow V$ such that

$$F(x, f(x)) = 0, \quad \forall x \in U.$$

In other words, the level set of F is locally to x_0 the graph of some function f of the same regularity as F .

PROOF. Define $G : \Omega \rightarrow \mathbb{R}^n \times \mathbb{R}^m$ by

$$G(x, y) := (x, F(x, y)).$$

Obviously G is C^k . We can apply the inverse function theorem to G near X_0 ; indeed,

$$DG(X_0) = \begin{pmatrix} I_{n \times n} & 0 \\ D_x F(X_0) & D_y F(X_0) \end{pmatrix},$$

which means

$$\det DG(X_0) = \det D_y F(X_0) \neq 0,$$

by assumption. Thus there exist neighborhoods W_1, W_2 of $X_0, (x_0, 0)$ respectively (since $(x_0, 0) = G(X_0)$) for which G^{-1} exists (and is C^k) from $W_2 \rightarrow W_1$. Then, there are neighborhoods $U \subset \mathbb{R}^n$ of x_0 and $V \subset \mathbb{R}^m$ of y_0 such that $U \times V \subset W_1$; set $Z = G(U \times V)$ (which is also open, with $Z \subset W_2$). Thus we can view

$$G : U \times V \rightarrow Z, \quad G^{-1} : Z \rightarrow U \times V,$$

which are both C^k maps. Since $G(x, y) = (x, F(x, y))$, we know that $G^{-1}(x, w) = (x, H(x, w))$ for all $(x, w) \in Z$. Here, $H : Z \rightarrow V$ is C^k since G is. Thus,

$$(x, F(x, H(x, w))) = G(x, H(x, w)) = (x, w),$$

using the definition of G in the first equality and the inverse fact in the second line.
Thus, it follows that

$$F(x, H(x, w)) = w, \quad \forall (x, w) \in Z,$$

thus taking $f(x) := H(x, 0)$ gives the proof. ■

↪**Corollary 1.2:** Let $F : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ be a $C^k(\Omega)$ function. Let $X = (x', y) \in \mathbb{R}^{n-1} \times \mathbb{R}$ and suppose $(x'_0, y_0) \in \Omega$ with $\frac{\partial f}{\partial y}(x'_0, y_0) \neq 0$. Then, there exist neighborhoods U and V of $x'_0 \in \mathbb{R}^{n-1}$ and $y_0 \in \mathbb{R}$ and a unique $C^k(U)$ function $f : U \rightarrow V$ such that

$$\{F(x', y) = 0\} = \{y = f(x')\}, \quad (x', y) \in U \times V.$$

↪**Theorem 1.9 (Morse Lemma):** Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$ be a C^k function with $k \geq 3$. Let $0 \in \Omega$ be a critical point, i.e. $\nabla f(0) = 0$. Assume further $f(0) = 0$ and $\nabla^2 f(0)$ is invertible. There exist open sets U, V of $0 \in U \cap V$ and $g \in C^{k-2}(U)$, $g : U \rightarrow V$ with $g^{-1} : V \rightarrow U$, $g^{-1} \in C^2(V)$, such that

$$f(g(y)) = y_{\ell+1}^2 + \cdots + y_n^2 - (y_1^2 + \cdots + y_\ell^2),$$

for some $\ell \in \mathbb{Z} \cap [0, n]$.

§1.4 Taylor's Theorem in \mathbb{R}^n

Let $f : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$, $f \in C^{k+1}(\Omega)$. Let $x_0 \in \Omega$ and $|t|$ small. Consider

$$g(t) := f\left(x_0 + t \frac{x - x_0}{\|x - x_0\|}\right), \quad x \neq x_0, \quad g(0) = f(x_0).$$

Since $x_0 \in \Omega$ and Ω open, $x_0 + t \frac{x - x_0}{\|x - x_0\|} \in \Omega$ for t sufficiently small. By Taylor in 1-dimension,

$$g(t) = g(0) + g'(0)t + \frac{g''(0)t^2}{2!} + \cdots + \frac{g^{(k)}(0)t^k}{k!} + R_k(g)(t), \quad \frac{|R_k(g)(t)|}{|t|^k} \leq M |t| \text{ as } t \rightarrow 0.$$

To get Taylor expansion for $f(x)$ around x_0 , we set $t = |x - x_0|$ and apply chain rule to $g(t)$. First, we compute $g^{(j)}(0)$; we get

$$\begin{aligned} g(0) &= f(x_0), \\ g(t) &= g(\|x - x_0\|) = g(x). \end{aligned}$$

By chain rule,

$$g'(0) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(x_0) \frac{x_j - x_j^0}{\|x - x_0\|}.$$

Similarly,