

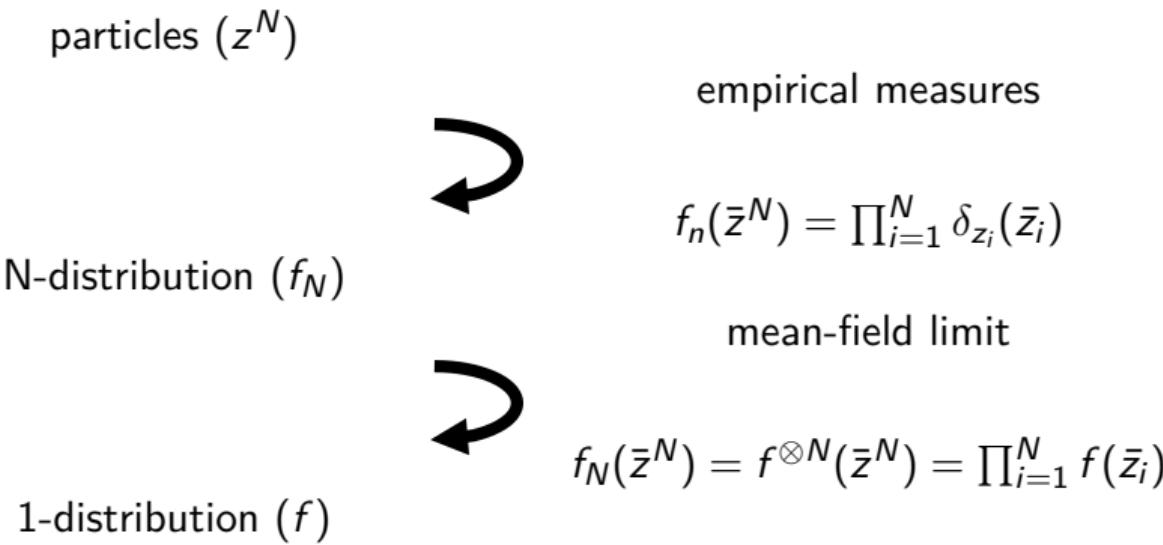
# Interaction Diversity in Mean-Field Settings

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# Objects



# Equations

Investigations of mean-field limits are often broken down into various systems:

Flow Dynamics (NODE)       $\{\dot{z}_i = \frac{1}{N} \sum_{j \neq i}^N K(z_i, z_j)\}$       high dimension

Liouville       $\partial_t f_N + \frac{1}{N} \sum_{i,j=1}^N \nabla_{z_i} \cdot (f_N K(z_i, z_j)) = 0$       high dimension

Vlasov (forward-Kolmogorov)       $\partial_t f + \nabla_z \cdot (f \mathcal{K}[f]) = 0$       low dimension

where  $\mathcal{K}[f](x) = \int K(x, y) f(y) dy$  (sometimes  $\mathcal{K}[f] = K * f$ ).

# Classical Mechanics [1]

Some physical systems, such as

- 1) Vlasov-Poisson   2) Vlasov-Maxwell and   3) incompressible fluids  
are adjacent to the following result:

## Theorem

Assume  $K$

- 1) is skew-symmetric   2) has continuous bounded derivatives and   3) is divergence-free  
then, given an initial distribution  $f_0$ ,

$$\begin{array}{c} \text{Solutions of NODE} \\ (\text{initial conditions sampled from } f_0) \end{array} \xrightarrow{\text{Wasserstein}} \begin{array}{c} \text{Solutions of the Vlasov} \\ (\text{with initial conditions } f_0) \end{array}$$

# Optimization [2]

To search a surface  $F$  for minima, one may apply a "swarm-based" approach by coupling  
 1) gradient descent and 2) simulated annealing  
 in the following system:

$$\begin{cases} \dot{x}_j = -\nabla F(x_j) + \sqrt{2\sigma(m_j)} W_j \\ \dot{m}_j = -(F(x_j) - \mathcal{F}^N)m_j \\ \mathcal{F}^n = \frac{\sum_{j=1}^N m_j F(x_j)}{\sum_{j=1}^N m_j} \end{cases} \rightarrow \begin{cases} \partial_t f = \nabla_x \cdot (f \nabla F) + (F(x) - \mathcal{F}) \partial_m (mf) + \sigma(m) \Delta_x f \\ \mathcal{F} = \frac{\int \int m F(x) f(x, m) dx dm}{\int \int m f(x, m) dx dm} \end{cases}$$

# Optimization [2]

The previous NODE to mean-field system admits the following result:

## Theorem

Under reasonable (physical) constraints of  $\sigma$ ,  $F$ , and initial conditions  $f_0$ ,

$$\begin{array}{ccc} \text{Solutions of NODE} & \xrightarrow{\text{Wasserstein}} & \text{Solutions of the forward-Kolomogorov} \\ (\text{initial conditions sampled from } f_0) & & (\text{with initial conditions } f_0) \end{array}$$

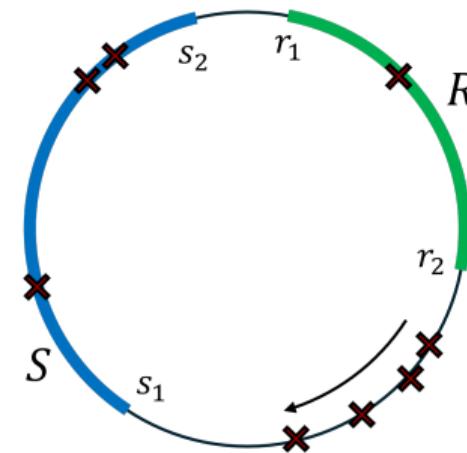
Moreover,  $\liminf_t \lim_N \mathcal{F}^N = \min_x F$ .

## Modeling Yeast Metabolism [3]

Yeast cells have been observed synchronizing their metabolic cycles.

To explain the pattern formation:

Cells in a (S)ignaling region release metabolites that inhibit cells in a (R)esponsive region.



Schematics of Model for Yeast Cell Metabolism with signaling region (blue), responsive region (green), and yeast cells (red)

# Equations

The previous model translates to a NODE of

$$\left\{ \dot{z}_i = 1 + \chi_R(z_i) f \left( \frac{1}{N} \sum_{j=1}^N \chi_S(z_j) \right) \right. \xrightarrow{f(x)=-\alpha x} \left. \dot{z}_i = \frac{1}{N} \sum_{j=1}^N \alpha (1 - \chi_R(z_i) \chi_S(z_j)) \right.$$

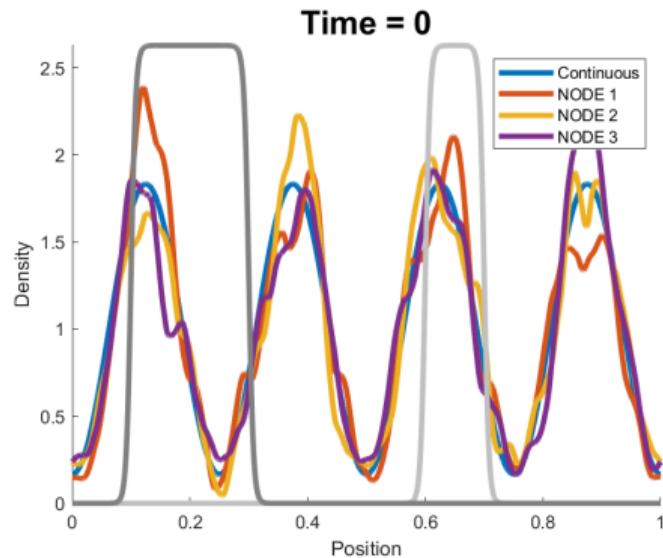
which may be pushed to a Vlasov of

$$\partial_t u + \partial_x \left( u \left( 1 + \chi_R(x) f \left( \int_S u \right) \right) \right) = 0 \xrightarrow{f(x)=-\alpha x} \partial_t u + \partial_x u - \alpha \langle \chi_S, u \rangle \partial_x (u \chi_R(x)) = 0$$

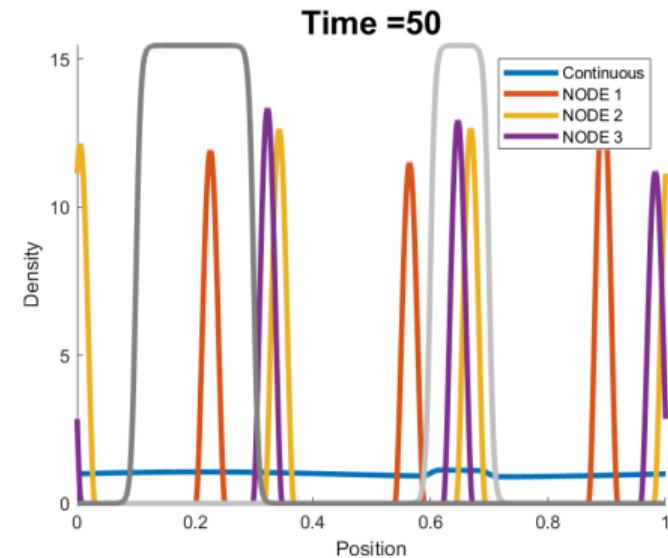
or Vlasov-McKean of

$$\dots \xrightarrow{f(x)=-\alpha x} \partial_t u + \epsilon^2 \Delta u + \partial_x u - \alpha \langle \chi_S, u \rangle \partial_x (u \chi_R(x)) = 0$$

# Simulation



Initial Conditions for Vlasov-McKean (blue) and three 1000-particle samplings of initial conditions (red, yellow, purple).



Numerical simulation of Vlasov-McKean (blue) and three 1000-particle simulations of NODE.

# References

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**Thank You!  
Any Questions?**

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