Powering Up Robot
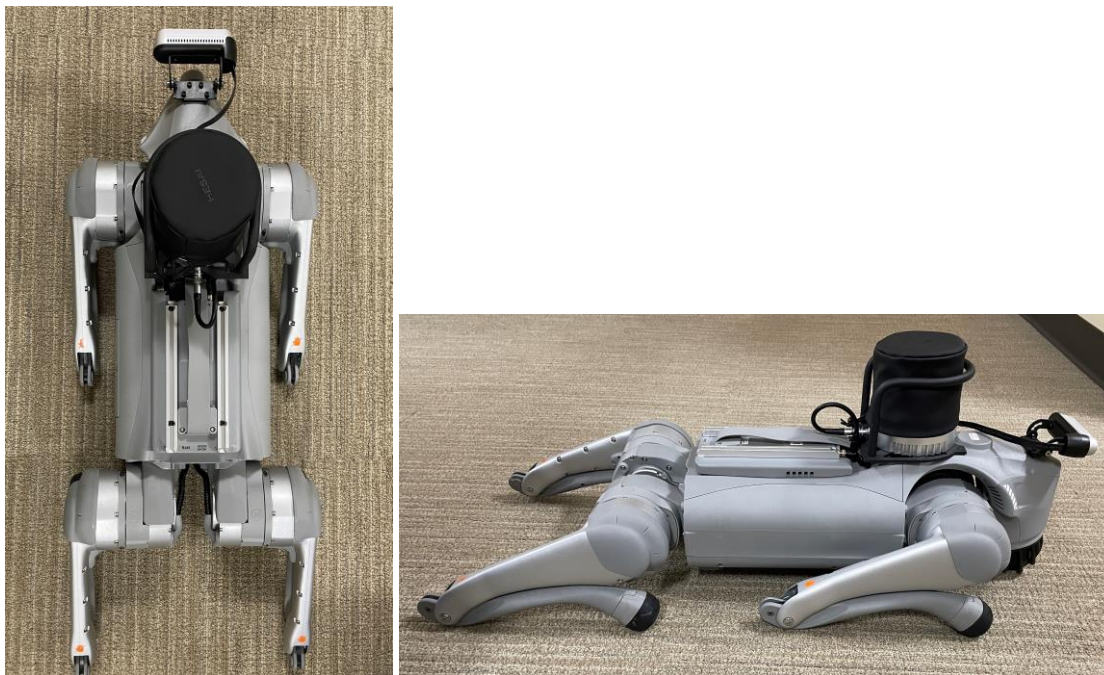
1) Make sure the robot is in the correct position before starting it. The robot should look like a dog lying down with its paws in front.

2) Press and quickly release the power button, then press and hold the power button. Once robot starts release power button.

3) Robot should be in AP mode. In this mode the robot is its own access point.
   a. Robot 01 SSID is Go2Edu, password is Go2Edu2024
   b. Robot 02 SSID is Go2Edu02, password is Go2Edu022024

4) In the iPad go to the Wi-Fi settings and select the SSID for your robot. The password should already be stored but if prompted use the password above.

5) In the Unitree app on the iPad you should see your robot is online. If it is not wait give it another 30 seconds to come online. After it is online you can connect to the robot through the app.

Powering down the robot

1) **Make sure the robot is lying down. If it is not and you power it off, the robot will collapse and may take damage.**

2) Press and quickly release power button, then press and hold power button.

3) The robot should then shut off. Wait for all fans to stop and the LiDAR to stop spinning before putting the robot away.

Large remotes

1) The remotes are tied to a specific robot. On the backs of the remotes are labels 01,02, etc and correspond with the robots. The label on the robots can be found under the handles.
2) The robot works using both the remote and the iPad mini. Before powering on the remote put the iPad mini into the remote, in landscape orientation. Make sure the remote is not pressing on any of the iPad's buttons.
3) To power on the remote press and quickly release power button, then press and hold power button until you hear a beep.
4) If the robot is powered on you should be able to control it.
5) Start the Unitree app on the iPad, connect to the robot, and then press the Go button in the app.

Small remote

1) The remotes are tied to a specific robot. On the backs of the remotes are labels 01,02, etc and correspond with the robots. The label on the robots can be found under the handles.
2) To power on the remote quickly press and release the power button. It is the top of the three buttons on the remote. The remote will beep when it powers on.
3) To power off the remote press and hold the power button until you hear two beeps.
4) To put the robot in follow mode, make sure both the robot and small remote are powered on. Place the remote on your belt and stand with the robot on your right-hand side about 18" from you and slightly in front of the robot. Quickly press and release the M button (the bottom of the three buttons) twice. You should hear the robot now say it is in follow mode. You may begin to walk, and it will follow you at a walking pace. To change to run follow mode stop moving and wait for the robot to stop next to you. Quickly press and release the M button twice. It will now be in run follow mode. You may now move at a slow jog and the robot will be able to keep up with you. To move back to walk follow mode stop moving and wait for the robot to stop next to you and quickly press and release the M button twice.
5) To take the robot out of follow mode move the small joystick at the top of the remote. You will hear the robot say it is leaving follow mode.