Activity 10 Short Report

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#### Tasks

- Integration of image processing skills (image segmentation, morphological operations, labelling, etc.)
- Measure several properties of cells (e.g., areas, centroids, eccentricities) using blob analysis

Given the image in Fig. 1, we were to segment the cells perfectly (i.e., no overlaps, no fused blobs), so that we could subject them to blob analysis and measure several properties.

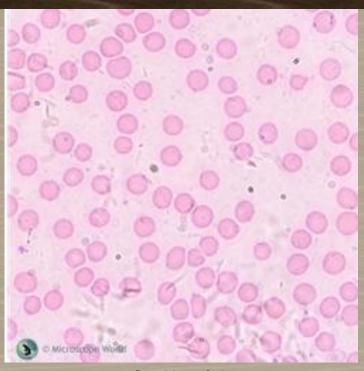


Figure 1. Image of cells

Upon segmentation, we get the resulting image displayed in Fig. 2. At first glance, the initial result might seem good enough. However, some of the blobs are connected, when in reality, they should be completely separated. Blob analysis here would be erroneous.

We then attempt to separate these connected blobs.

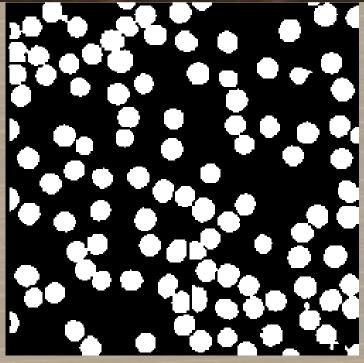


Figure 2. Segmented image of cells

To do this, we take only the connected blobs from the segmented image as in Fig. 3. To separate the blobs, we use a segmentation technique known as watershed segmentation.

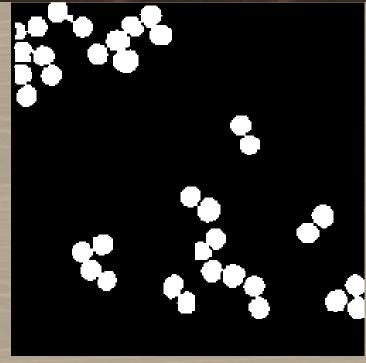


Figure 3. Connected blobs from segmented image.

Watershed segmentation makes use of the idea of <u>watersheds</u> and <u>catchment basins</u>. In its literal definition, watersheds are ridges that divide different catchment basins, and catchment basins are areas that drain into rivers or reservoirs.

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Relating this to image processing, say, we have two dark blobs, its corresponding watershed and catchment basin is shown in Fig. 4.



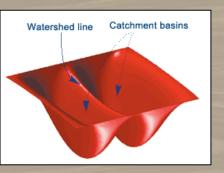
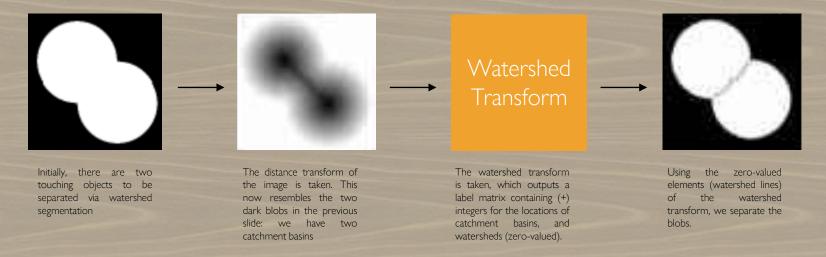


Figure 4. L: Two dark blobs R: Corresponding watershed and catchment basin.

[1] – For more info about watershed segmentation, visit: <a href="https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.htm">https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.htm</a>

The watershed() function is then able to find the watershed lines and catchment basins for grayscale images. The general procedure for watershed segmentation is presented below:



[1] — For more info about watershed segmentation, visit: <a href="https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.html">https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.html</a>

Going back to our image of connected blobs. We now take its distance transform.

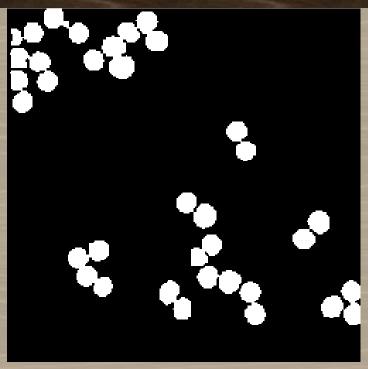


Figure 3. Connected blobs from segmented image.

Going back to our image of connected blobs. We now take its distance transform. From Fig. 5, the catchment basins are very apparent.

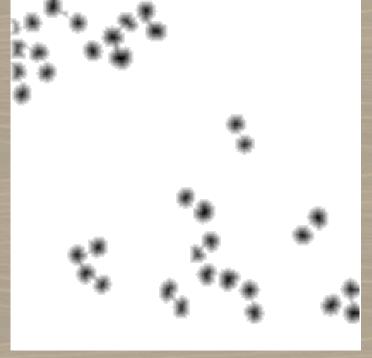


Figure 5. Distance transform of connected blobs

Going back to our image of connected blobs. We now take its distance transform. From Fig. 5, the catchment basins are very apparent. We could now take the watershed transform, and then completely separate the connected blobs.

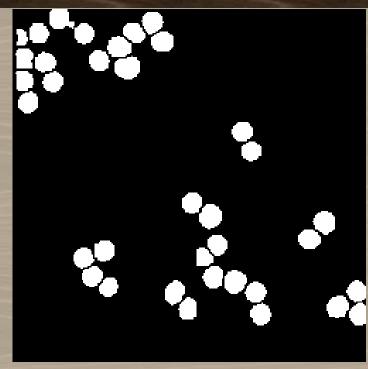


Figure 6. Separation of connected blobs via watershed segmentation.

Going back to our image of connected blobs. We now take its distance transform. From Fig. 5, the catchment basins are very apparent. We could now take the watershed transform, and then completely separate the connected blobs.

Finally, we combine the newly-separated blobs with the already-separated blobs from before. Our segmented image is now ready for blob analysis.

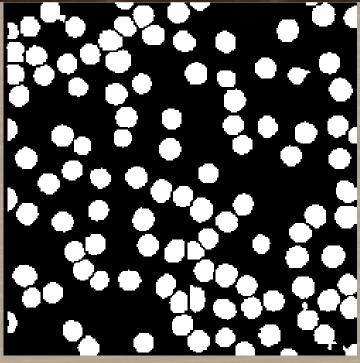


Figure 7. Segmented image with completely separate blobs

First off, we use **regionprops()** to take the centroids and bounding boxes of each blobs in our image. In total, there are 111 cells in our image.

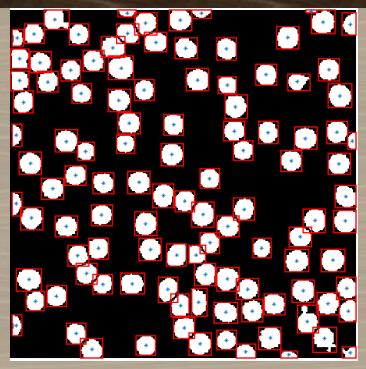


Figure 8. Blobs (cells) marked by the centroids and enclosed in bounding boxes.

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Figure 8. Blobs (cells) marked by the centroids and enclosed in bounding boxes.

Shown to the right is the histogram of the pixel area of the cells. The left region of the histogram (Area < 120) comprises the half-cells at the borders of the image. These half-cells were excluded in computing the average cell size. The best estimate for the average cell size is  $\underline{179.7} \pm \underline{21.4}$  sq. pixels.

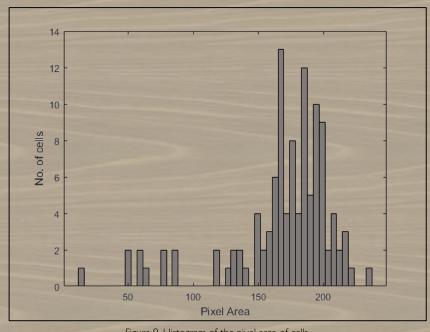


Figure 9. Histogram of the pixel area of cells.

On the other hand, the best estimate for the average perimeter of the cells is  $45.9 \pm 3.4$  pixels.

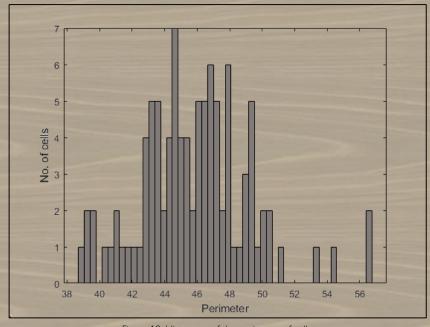


Figure 10. Histogram of the perimeter of cells.

Here we have the histogram of the eccentricity of the cells. We can see that majority of the cells have eccentricities below 0.5, leaning towards being nearly circular. Computing for the average eccentricity we have  $0.39 \pm 0.13$ .

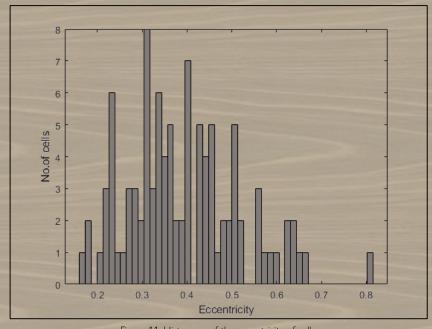


Figure 11. Histogram of the eccentricity of cells.

The average major axis length of the cells is  $16.0 \pm 1.1$  pixels, while the average minor axis length is  $14.5 \pm 1.0$  pixels. The values for both averages are near, indicating that the cells may be nearly circular. This agrees with what we previously observed for the average eccentricity.

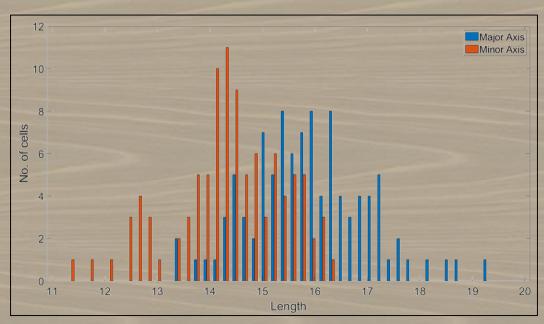


Figure 12. Histogram of major and minor axis lengths of cells.

#### Evaluation

I give myself a score of 11/10 for producing all required output, and applying advanced techniques for image segmentation (watershed segmentation).

#### References:

- [1] The Watershed Transform: Strategies for Image Segmentation. <a href="https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.html">https://www.mathworks.com/company/newsletters/articles/the-watershed-transform-strategies-for-image-segmentation.html</a>
- [2] Watershed transform question from tech support. <a href="https://blogs.mathworks.com/steve/2013/11/19/watershed-transform-question-from-tech-support/">https://blogs.mathworks.com/steve/2013/11/19/watershed-transform-question-from-tech-support/</a>
- [3] Color-Based Segmentation Using K-means Clustering. <a href="https://www.mathworks.com/help/images/color-based-segmentation-using-k-means-clustering.html;">https://www.mathworks.com/help/images/color-based-segmentation-using-k-means-clustering.html;</a>;jsessionid=ffc56fe3a1ed3900594bba3fbde3