

Math 128A - Programming Assignment #2

Math 128A, Fall 2018

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The programs were written in Python.

Algorithms & Descriptions

Our problem for this assignment was straightforward; we wished to interpolate polynomials through computer programs. The interpolation methods are well-known: the first is Lagrange Interpolation, and the second is Barycentric Interpolation. The inputs for our interpolation algorithms, `xin` and `xout`, were generated through `numpy.linspace`. There are 2 types of `xins`: the first is `xinU`, or uniform vectors, and `xinC`, or Chebyshev vectors. Each type of `linspace` was generated twice, for a total of 8 `linspace`s. `xouts` are simply the function $f(x)$ evaluated at each point of each `xins`.

The first interpolation method, or Lagrange Interpolation, was broken up into 3 parts. The first is `interpolate1(xin, xout)`, which is a `for` loop that iterates through each element of `xout` and generates an interpolated value (which is in turn generated by `lagrange`). `interpolate1` can be thought of as the term $P(x)$ in the Lagrange Interpolation Formula $P(x) = \sum_{j=0}^n f(x_j) * L_j(x)$, $L_j(x) = \prod_{j \neq k} \frac{x-x_k}{x_j-x_k}$.

The second part is `lagrange(x, xin)`. This is the function that actually generates the interpolation values. This function can be thought of as the summation part that follows $P(x)$ in the formula. It computes the summation iteratively.

The third and final part is `L(x, j, xin)` that computes the product $\prod_{j \neq k} \frac{x-x_k}{x_j-x_k}$ iteratively. It can be thought of as the $L_j(x)$ term in the Lagrange Interpolation Formula.

Our second interpolation method is Barycentric Interpolation. Its formula is $P(x) = f(x)$, if $x = x_j$, and

$$P(x) = \frac{\sum_{j=0}^n \frac{\lambda_j f(x_j)}{x-x_j}}{\sum_{j=0}^n \frac{\lambda_j}{x-x_j}} \text{ otherwise. } \lambda_j \text{ is defined as } \lambda_j = \frac{1}{\prod_{j \neq k} (x_j - x_k)}.$$

Similar to Lagrange Interpolation, the code for Barycentric Interpolation is divided into 3 parts. The first part is `interpolate2(xin, xout)`, and it can be thought of as $P(x)$ of the formula where it simply feeds each `x` value of `xout` to P , and the fraction of two sums (the interpolated value) is computed in `barycentric(x, xin)` (for the case where $P(x) = f(x_j)$, we simply evaluate f if the i th term of `xout` is in `xin`).

`barycentric(x, xin)` uses 2 non-nested `for` loops to compute the two summations. It calls the third and final part of the code, `lambda_coeff`, to compute λ_j . `lambda_coeff(j, xin)` iteratively computes the product described as $\lambda_j = \frac{1}{\prod_{j \neq k} (x_j - x_k)}$.

Both `interpolate1` and `interpolate2` were tested against `scipy`'s built-in methods for accuracy, and both functions returned the same values (up to ~6-7 decimal points) as `scipy`'s methods.

The function $f(x) = \frac{1}{1+9x^2}$ is defined separately in both `interpolate1.py` and `interpolate2.py`.

Plots & Descriptions

For plots 1-4, the blue plot represents the function $f(x)$, and the orange plot is the interpolated polynomial. (I tried to use `scipy.interpolate.spline`, but I could not figure out how to properly smooth out the points). I was unable to produce proper semilog plots for 5-8 using `matplotlib`.

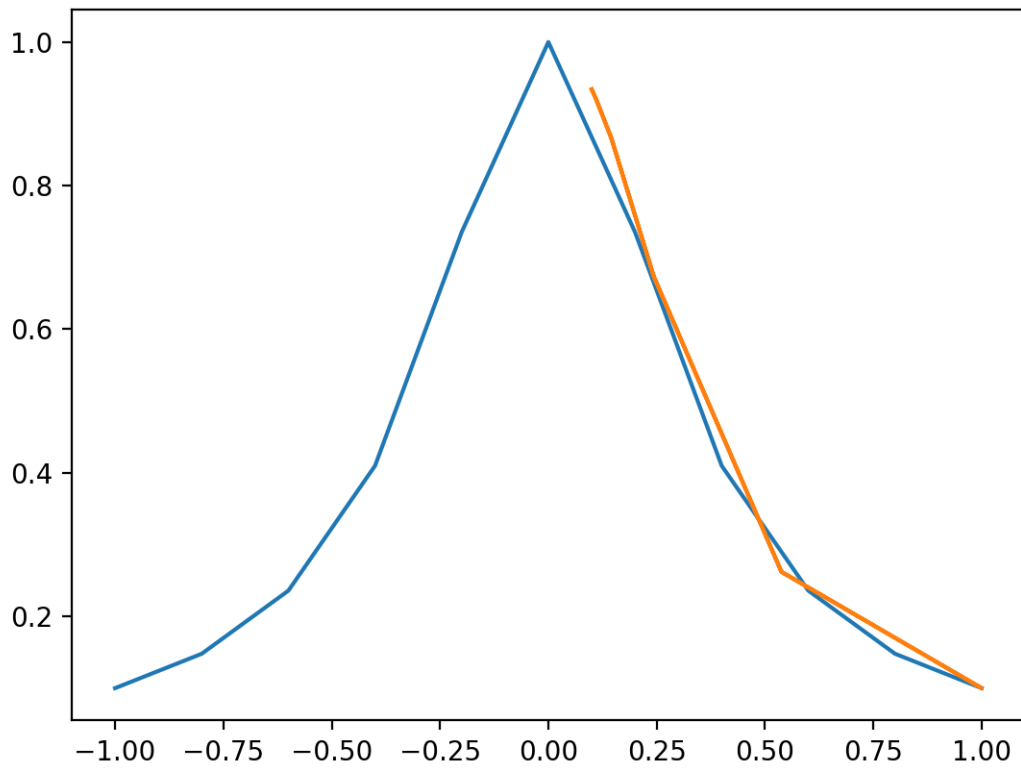


Figure 1: Plot 1

Plot 1 (Chebyshev $n=10$)

The interpolated polynomial follows the general flow of $f(x)$, but narrows out much quickly after $x = 0.5$. This is most likely due to the low n ($n = 10$). It appears to be a good start in interpolating $f(x)$.

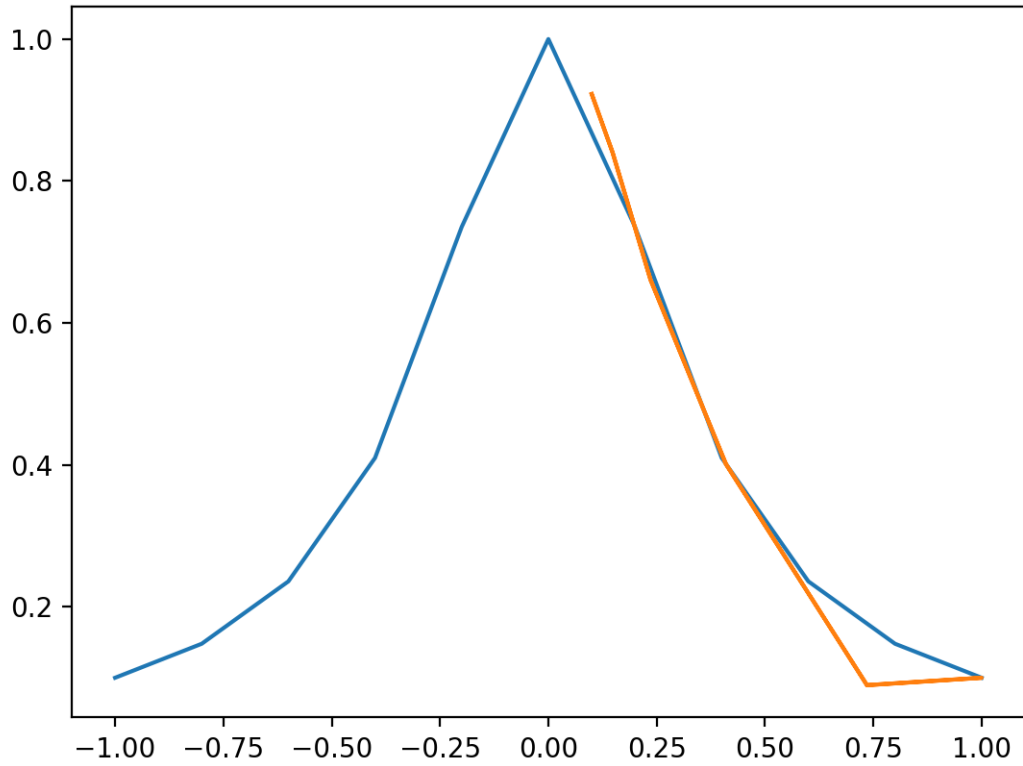


Figure 2: Plot 2

Plot 2 (Uniform $n=10$)

This interpolated polynomial has greater accuracy for values between $x = -0.5$ and $x = 0.5$, but seems to fail after $x = 0.5$. It has a much sharper rate of decrease than the Chebyshev linspace for $n = 10$. We could attribute this to a low n , but it could also be due to the nature of a uniform linspace.

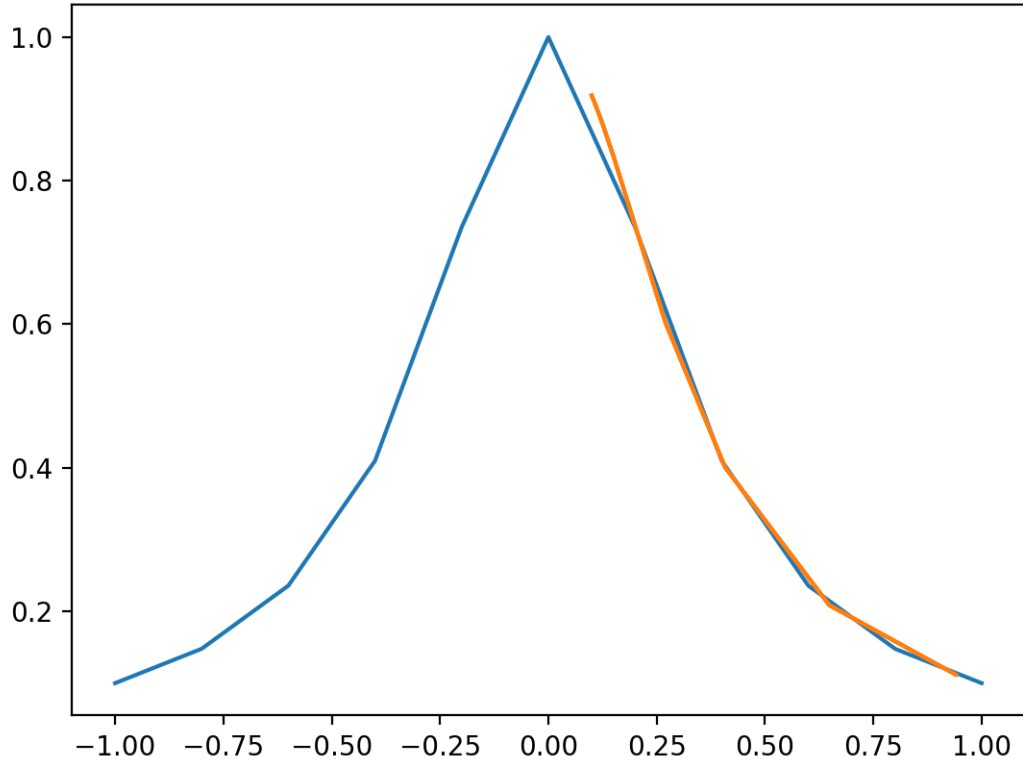


Figure 3: Plot 3

Plot 3 (Chebyshev $n=19$)

The comparison of this interpolation to $n = 10$ (Chebyshev) shows an increasing n for Chebyshev linspaces leads to more accurate interpolations. The shortcomings of the interpolated polynomial after $x = 0.5$ are fixed when compared to $n = 10$, and the interpolated polynomial nearly has the same shape as $f(x)$.

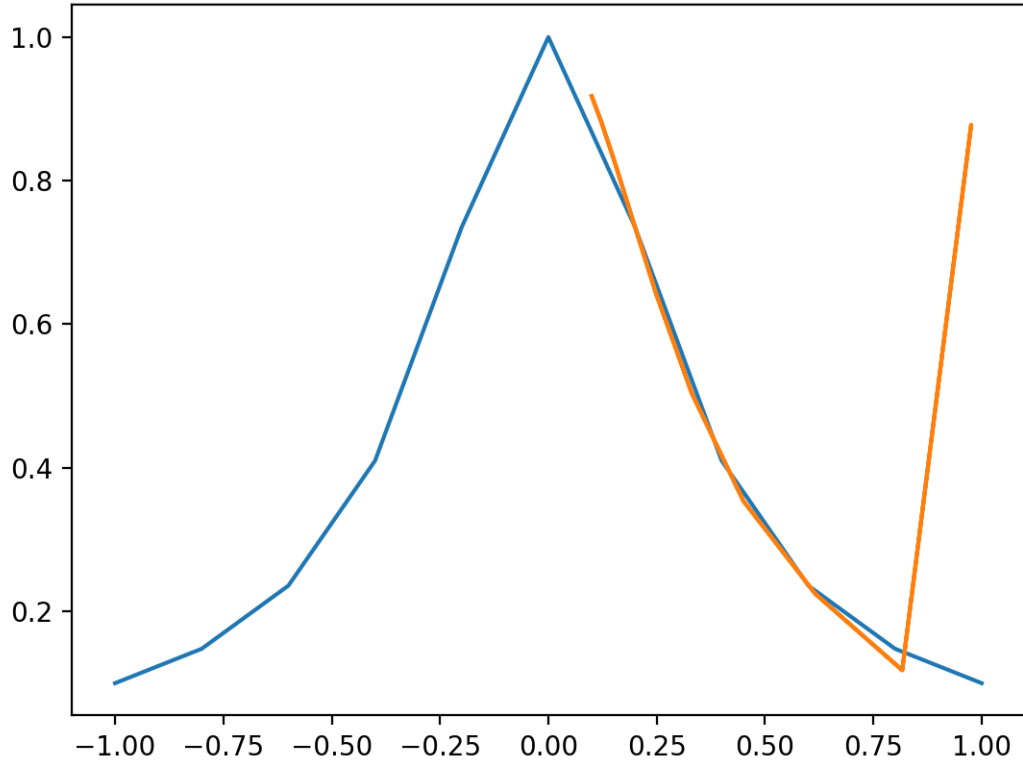


Figure 4: Plot 4

Plot 4 (Uniform $n=19$)

This interpolation shows Chebyshev linspaces are superior to Uniform linspaces. Although this interpolated polynomial follows the general shape of $f(x)$ quite well for $x \in [-0.5, 0.5]$, it completely fails after $x = -0.75, 0.75$. This cannot be attributed to a “low/high” n value, as the Chebyshev interpolation at $n = 19$ showed otherwise. This is clearly due to the nature of Uniform linspaces.

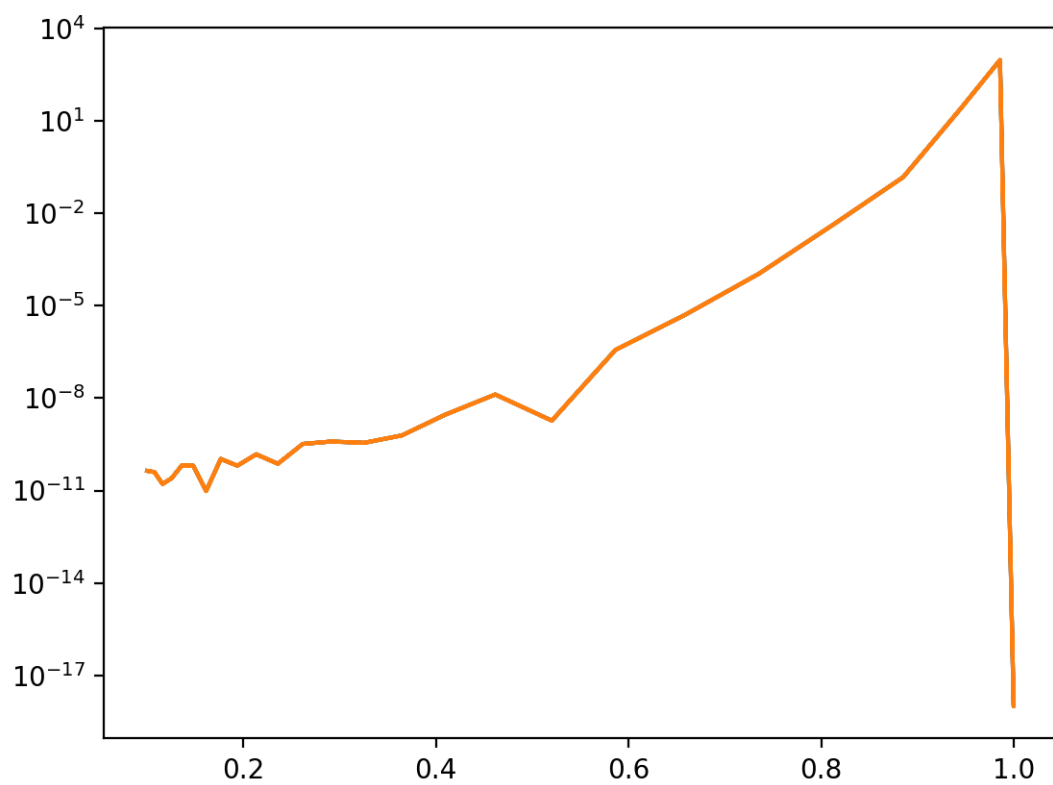


Figure 5: Plot 5

Plot 5 (Uniform $n=50$ Semiloggy)

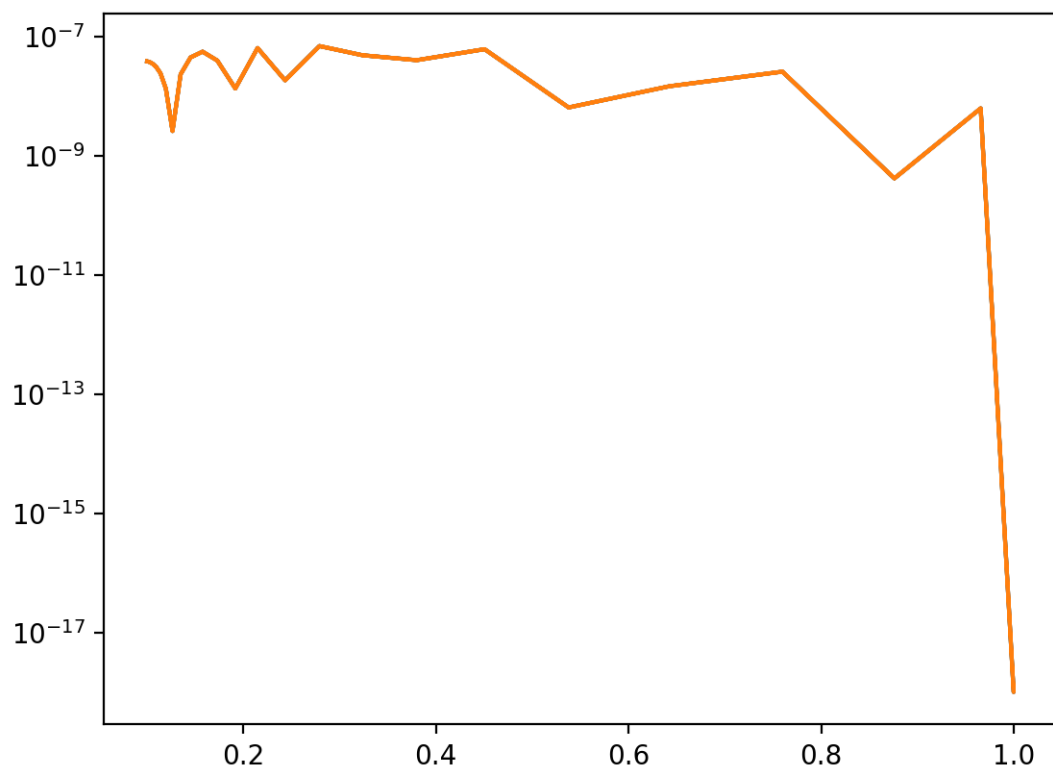


Figure 6: Plot 6

Plot 6 (Chebyshev $n=50$ Semilog)

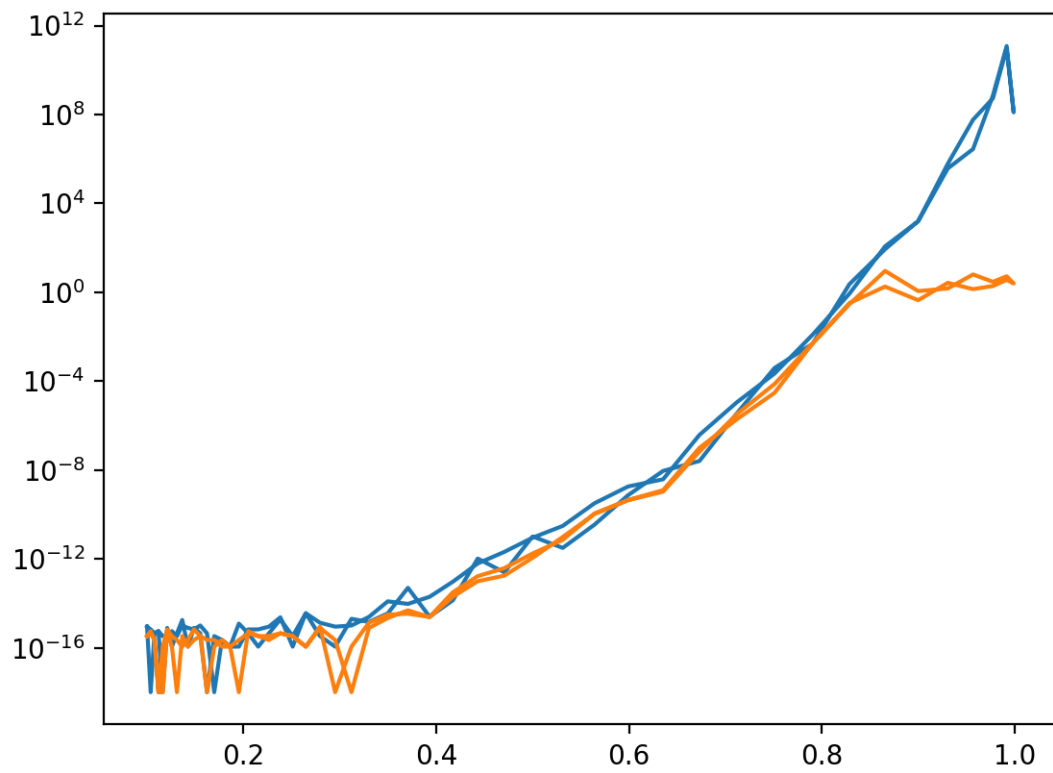


Figure 7: Plot 7

Plot 7 (Uniform $n=99$ Semilog)

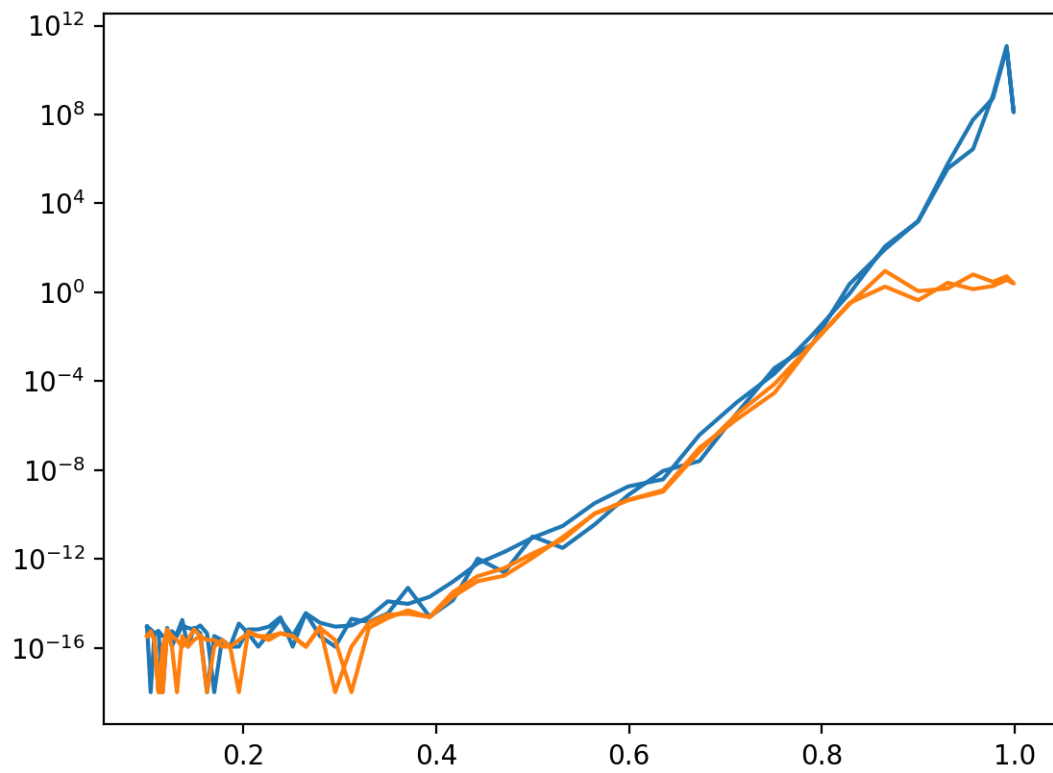


Figure 8: Plot 8

Plot 8 (Chebyshev $n=99$ Semilogy)