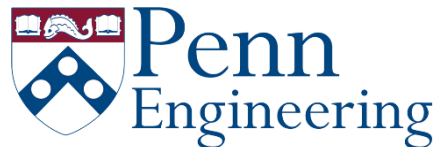


Robotics

Estimation and Learning
with Dan Lee

Basic Intro to Probability



Why Learn About Probability?

- The real world has huge aspects of randomness and uncertainty.
- Still, we hope to make useful predictions and inferences.
- Randomness often follows reliable laws.
- The language of these laws is the language of probability (and statistics).

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1. Definition of Probability
2. Independence
3. Conditional Probability
4. Bayes Rule
5. Random Variables
6. Density and Distribution Functions

1. Definition of Probability

- Consider an (potentially abstract) experiment
 - A **sample space** Ω is the set of *all possible* outcomes of that experiment
 - An **elementary event** ω is a single outcome of the set.
- Example (Rolling two dice):
 - Sample space $\Omega = \{(1,1), (1,2), (1,3), \dots, (6,5), (6,6)\}$
 - Each member $\omega \in \Omega$ is an elementary event
 - Example of non-elementary event : Rolling doubles
$$B = \{(1,1), (2,2), (3,3), \dots, (6,6)\}$$

1. Definition of Probability

- Consider a finite* set Ω
- A **probability space** (Ω, P) is a sample space Ω , together with a function P , satisfying the following:
 - i. $0 \leq P(\omega) \leq 1$ for all $\omega \in \Omega$
 - ii. $\sum_{\omega \in \Omega} P(\omega) = 1$
 - iii. For any event $A \subseteq \Omega$, $P(A) = \sum_{\omega \in A} P(\omega)$
- The function P is called **probability measure**.

*To deal with countably infinite or uncountable space, we need third element called sigma algebra, but here we are simplifying.

1. Definition of Probability

- Basic Consequences

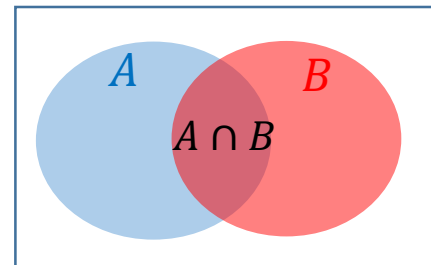
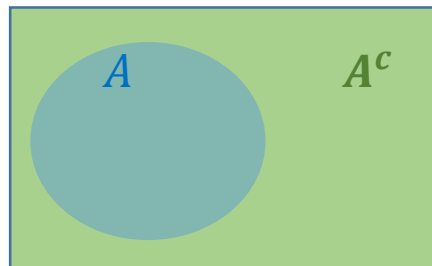
$$P(\emptyset) = 0$$

$$P(\Omega) = 1$$

$$P(A^c) = 1 - P(A)$$

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P(A) = P(A \cap B) + P(A \cap B^c)$$



2. Independence

- Given a probability space, two events A and B are **independent** if and only if:

$$P(A \cap B) = P(A)P(B)$$

- Two events are dependent if they are not independent.

2. Independence

- Example (two coin flip): $\Omega = \{HH, HT, TH, TT\}$
 - Assume $\forall \omega \in \Omega, P(\omega) = \frac{1}{|\Omega|} = \frac{1}{4}$.
 - Define event A: “First flip is H.” $A = \{HH, HT\}$
 - Define event B: “Second flip is H.” $B = \{HH, TH\}$
 - Are A and B Independent?
 - i) $P(A \cap B) = P(\{HH\}) = 1/4$
 - ii) $P(A)P(B) = 1/2 * 1/2 = 1/4 \rightarrow \text{Yes}$

2. Independence

- Example (two coin flip): $\Omega = \{HH, HT, TH, TT\}$
 - Assume $\forall \omega \in \Omega, P(\omega) = \frac{1}{|\Omega|} = \frac{1}{4}$.
 - Define event A: “First flip is H.” $A = \{HH, HT\}$
 - Define event B: “Contains a T.” $B = \{HT, TH, TT\}$
 - Are A and B Independent?
 - i) $P(A \cap B) = P(\{HT\}) = 1/4$
 - ii) $P(A)P(B) = 1/2 * 3/4 = 3/8 \rightarrow \text{No}$

3. Conditional Probability

- Given some probability space (Ω, P) , for any two events A and B , if $P(B) \neq 0$, then we define the **conditional probability** $P(A|B)$ that A occurs given that B occurs as,

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

- From this follows **Chain Rule**:

$$P(A \cap B) = P(A|B) P(B)$$

$$\begin{aligned} P(A \cap B \cap C) &= P(A|B \cap C) P(B \cap C) \\ &= P(A|B \cap C) P(B|C)P(C) \end{aligned}$$

and so on..

3. Conditional Probability

- Example (two coin flip): What is the probability that both are head, GIVEN at least one is head?
- Probability Problem:

$$\Omega = \{HH, HT, TH, TT\}$$

$$B = \{HH, HT, TH\} \rightarrow \text{"At least one is head."}$$

$$A = \{HH\} \rightarrow \text{"Both are heads."}$$

$$P(A \cap B) = P(\{HH\}) = 1/4$$

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{1/4}{3/4} = \frac{1}{3}$$

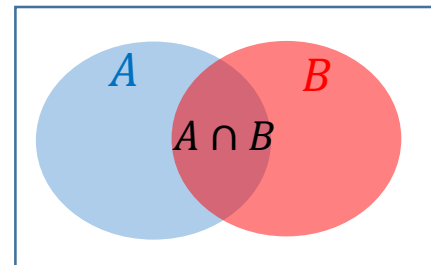
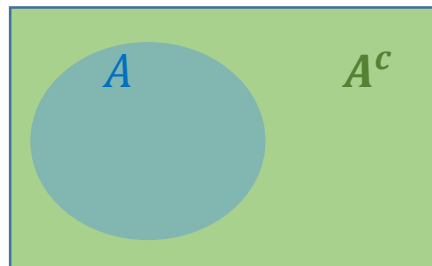
3. Conditional Probability

- Consequences

$$P(\emptyset|B) = 0$$

$$P(B|B) = 1$$

$$P(A|B) = 1 - P(A^c|B)$$



4. Bayes Rule

- Each term is often called:

$$\begin{array}{c} \text{Posterior} \\ P(A|B) \end{array} = \frac{\begin{array}{c} \text{Likelihood} \quad \text{Prior} \\ P(B|A)P(A) \end{array}}{\begin{array}{c} \text{Evidence} \\ P(B) \end{array}}$$

5. Random Variables

- Given some probability space (Ω, P) , a **random variable** $X: \Omega \rightarrow R$ is a *function* that maps the sample space to the reals.
- When we say $P(X = a)$, we actually mean the probability of the inverse image $X^{-1}(a)$. That is,

$$P(X = a) = P(X^{-1}(a)) = P(\{\omega \in \Omega | X(\omega) = a\})$$

- Example (single coin flip): $\Omega = \{Head, Tail\}$

$$X(Head) = 1, X(Tail) = 0$$

$$P(X = 1) = P(X^{-1}(1)) = P(Head)$$

5. Random Variables

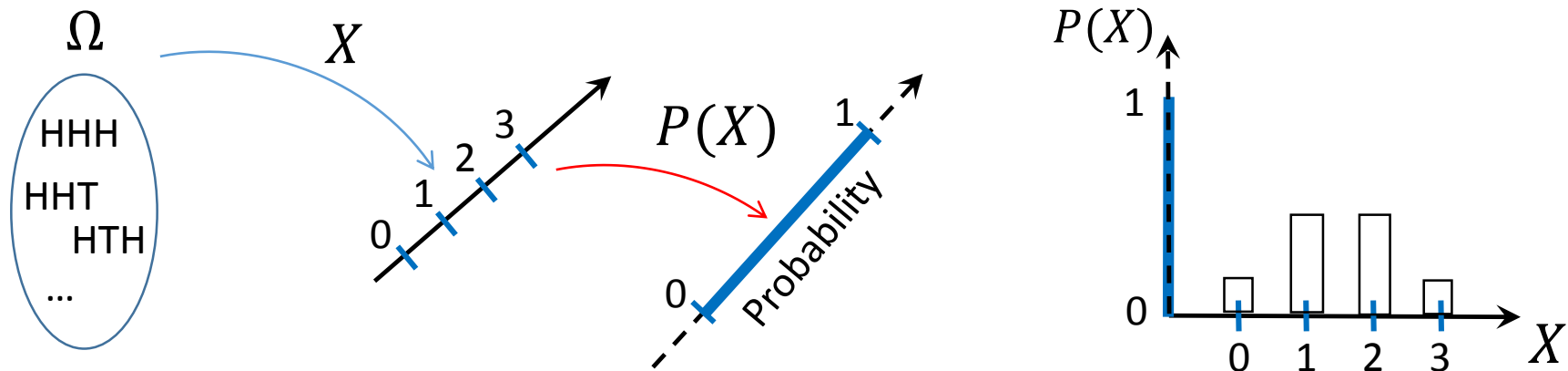
- Example: 3 coin flips

- $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\}$

- Let us define $X(\omega)$ to be the number of Heads in a given flip. Then,

$$X(HHH) = 3, X(HHT) = X(HTH) = 2, \dots, X(TTT) = 0$$

$$P(X = 3) = 1/8, P(X = 2) = P(X = 1) = 3/8, P(X = 0) = 1/8$$

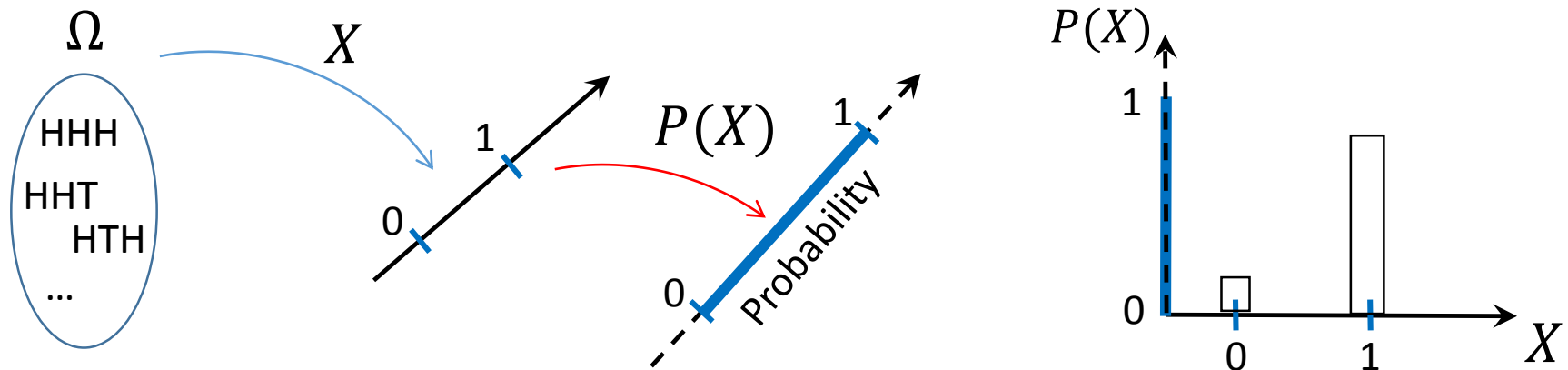


5. Random Variables

- Example: 3 coin flips
 - $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\}$
 - This time, let us define $X(\omega)$ to be 1 if H appears in a given flip, otherwise is 0. Then,

$$X(HHH) = X(HHT) = \dots = 1, X(TTT) = 0$$

$$P(X = 1) = 7/8, P(X = 0) = 1/8$$

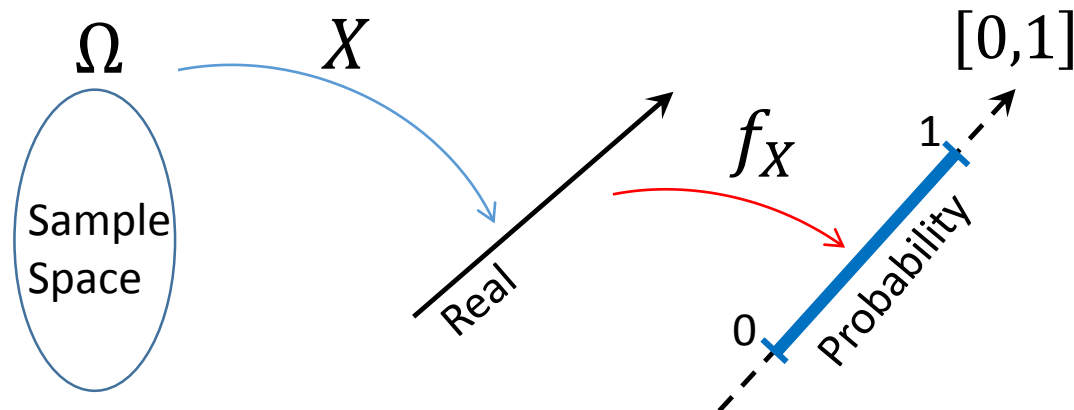


6. Density/Distribution Functions

- **Probability mass function (pmf) of discrete RVs**
- **Probability density function (pdf) of continuous RVs**

$$f: R \rightarrow [0,1]$$

$$\forall a \in R, f_X(a) = P(X = a)$$



6. Density/Distribution Functions

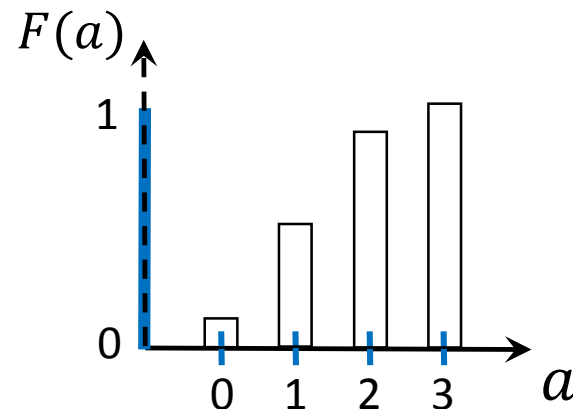
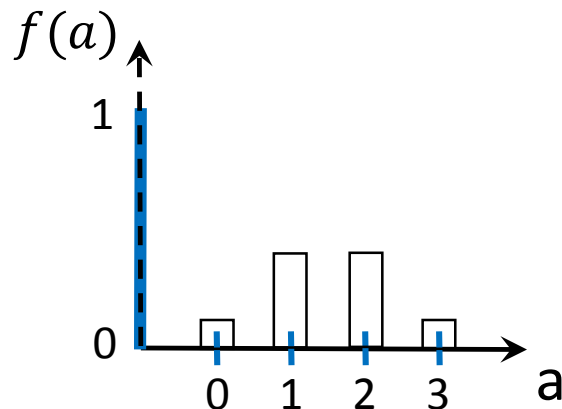
- **Cumulative distribution functions (cdf)**

$$F: R \rightarrow [0,1]$$

$$\forall a \in R, F_X(a) = P(X \leq a)$$

- A cdf is a monotonic nondecreasing function, i.e.,

$$\forall x \leq y, F(x) \leq F(y)$$



Acknowledgement

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