COL 726 Homework 2

Due: Thursday, 31 January 2019

- 1. Suppose **A** is an $m \times n$ matrix with singular values $\sigma_1 \ge \cdots \ge \sigma_n$ and singular vectors $\mathbf{u}_1, \ldots, \mathbf{u}_n$ and $\mathbf{v}_1, \ldots, \mathbf{v}_n$.
 - (a) Let $S_k = \langle \mathbf{v}_1, \dots, \mathbf{v}_k \rangle$ be the span of the first k right singular vectors. Prove that

$$\inf_{\mathbf{x}\in S_k}\frac{\|\mathbf{A}\mathbf{x}\|_2}{\|\mathbf{x}\|_2}=\sigma_k.$$

- (b) Prove that for <u>any</u> k-dimensional subspace $S \subseteq \mathbb{R}^n$, there exists a nonzero vector $\mathbf{x} \in S$ with $\|\mathbf{x}\|_2 = 1$ such that $\|\mathbf{A}\mathbf{x}\|_2 \le \sigma_k$.
- 2. Let *S* and *T* be two complementary subspaces in \mathbb{R}^m , and let $\{\mathbf{a}_1, \mathbf{a}_2, \dots\}$ and $\{\mathbf{b}_1, \mathbf{b}_2, \dots\}$ be bases for *S* and *T* respectively (but not necessarily orthonormal bases).
 - (a) Prove that $\{a_1, a_2, \dots\} \cup \{b_1, b_2, \dots\}$ is a linearly independent set that spans \mathbb{R}^m , so it is a basis for the entire space.
 - (b) Find a formula for the matrix P that projects onto S along T.
- 3. Suppose we define a modified inner product $f(\mathbf{u}, \mathbf{v}) = \mathbf{u}^T \mathbf{C} \mathbf{v}$, where C is a diagonal matrix with positive diagonal entries. Then we can say that \mathbf{u} and \mathbf{v} are "C-orthogonal" if $f(\mathbf{u}, \mathbf{v}) = 0$.
 - (a) Recall that the orthogonal projector in the direction of a nonzero vector \mathbf{x} is the matrix $\frac{1}{\mathbf{x}^T \mathbf{x}} \mathbf{x} \mathbf{x}^T$. Find a formula for the <u>C-orthogonal</u> projector in the direction of \mathbf{x} , i.e. a matrix \mathbf{P} such that, for any vector \mathbf{v} , $\mathbf{P}\mathbf{v}$ is a multiple of \mathbf{x} , and $\mathbf{v} \mathbf{P}\mathbf{v}$ is C-orthogonal to \mathbf{x} .
 - (b) Any $m \times n$ matrix **A** has a factorization of the form $\mathbf{A} = \hat{\mathbf{X}}\hat{\mathbf{R}}$, where $\hat{\mathbf{R}}$ is an $n \times n$ upper triangular matrix, and **X** is an $m \times n$ matrix whose columns are C-orthonormal, i.e. $f(\mathbf{x}_i, \mathbf{x}_i) = 1$ and $f(\mathbf{x}_i, \mathbf{x}_j) = 0$ for all $i \neq j$. Give a method in the style of classical or modified Gram-Schmidt for computing such a factorization. (Even if you did not solve part (a), here you may assume you have solution for it.)
- 4. Show that Householder reflectors work as advertised. That is, if \mathbf{x} and \mathbf{x}' are two vectors with $\|\mathbf{x}\|_2 = \|\mathbf{x}'\|_2$ and we define $\mathbf{F} = \mathbf{I} 2\frac{\mathbf{v}\mathbf{v}^T}{\mathbf{v}^T\mathbf{v}}$ where $\mathbf{v} = \mathbf{x} \mathbf{x}'$, show algebraically that $\mathbf{F}^T\mathbf{F} = \mathbf{I}$ and $\mathbf{F}\mathbf{x} = \mathbf{x}'$.
- 5. I have a set of n vectors $\mathbf{a}_1, \dots, \mathbf{a}_n$ in \mathbb{R}^m with m > n. I want to obtain n vectors $\mathbf{b}_1, \dots, \mathbf{b}_n$ in \mathbb{R}^n such that the geometrical relationships between the vectors are exactly preserved, i.e. $\|\mathbf{b}_i\|_2 = \|\mathbf{a}_i\|_2$ and $\mathbf{b}_i^T \mathbf{b}_i = \mathbf{a}_i^T \mathbf{a}_i$ for all i, j. Describe a method to do so, and prove that it has the desired property.

- 6. Low-rank approximations can be used for lossy data compression. Use this idea to compress an image by dividing it into blocks, and treating each one as a single row or column in a data matrix.
 - (a) A colour image of width w and height h is essentially an h×w×3 array of numbers. Construct a set of data points by dividing the image into n×n×3 blocks and treating each block as an 3n²-dimensional vector (assume that w and h are multiples of n). Write a Python function split(img, n) that does this and returns a matrix C. Also write a function join(C, n, w, h) which undoes split, reconstructing the original image.
 - (b) Write a function compress(C, r) that returns an optimal rank-r approximation of a $p \times q$ matrix C, in the form of a $p \times r$ matrix A and an $r \times q$ matrix B such that $AB \approx C$. Then join(A @ B, ...) should reconstruct an approximation of the image from the compressed data. In your report, describe how compress works.
 - (c) Write a function relError(img, img2) which computes the relative error $\|img-img2\|/\|img\|$, where $\|\cdot\|$ denotes the sum of squares of all values. Separately, have compress return as a third output the relative error caused by compression, without actually computing it (or performing any subtractions at all!). In your report, explain how you do so.

We will test your code as follows, so make sure this works:

```
# img is an array with shape (h,w,3), n and r are integers
import hw2
C = hw2.split(img, n)
A, B, e_rel = hw2.compress(C, r)
img2 = hw2.join(A @ B, n, w, h)
# e_rel should be nearly equal to hw2.relError(img, img2)
```

You are encouraged to use the functions

- imread and imsave from the matplotlib.image library to read and write images,
- imshow and show from matplotlib.pyplot to display them,
- svd from scipy.linalg to compute the singular value decomposition,

and any other NumPy or SciPy functions you find useful. Try your code on any of the test images from the Kodak image suite (http://r0k.us/graphics/kodak/) with n = 16, r = 1, ..., 20.