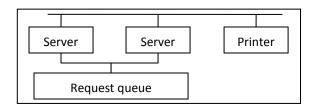
UECS2103 Operating Systems Tutorial 4

- 1. What are the hardware approaches to enforce mutual exclusion?
- 2. What are the disadvantages in using machine instructions to enforce mutual exclusion?
- 3. There are two processes, namely P and Q, and an I/O device. Each process requires the I/O device in their critical section.
 - (a) Write the pseudo code that uses semaphore to control the allocation of I/O device to the process. Assume that the function write data() is called in the critical section.
 - (b) Given that process P has higher priority than process Q, Give a scenario where deadlock may occurs.
- 4. Consider two servers are sharing a request queue and a printer, as shown in the figure below. Each server will get a request from request queue, process it and send to printer. Printer and request queue can be accessed by only 1 server at a time. Write the pseudo code for the server process, use semaphores p and q to control the access to printer and request queue respectively. Assume that function get_request() gets request from the request queue and function print() will process the request and send it to the printer. Initialise the values of semaphores appropriately.



5. Consider the pseudo code segments of two processes below.

```
P(){
P1| semWait(s);
P2| m--;
P3| semWait(t);
P4| k = m * c;
P5| semSignal(t);
P6| semSignal(s);
}
```

```
Q(){
Q1| semWait(t);
Q2| m++;
Q3| semWait(s);
Q4| c++;
Q5| semSignal(s);
Q6| semSignal(t);
}
```

Assume that both processes are assigned with the same priority level and process P executes first, is it possible that the process switching done by operating system can cause the two processes to enter a deadlock. Please explain. (You may use the line numbers as references in your explanation.)

6. How does monitor differ from semaphore?