Introductory Course on Non-smooth Optimisation

Lecture 08 - Alternating direction methods of multipliers

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Primal problem

Primal problem

$$\min_{x\in\mathbb{R}^n} \; R(x) + J(Ax).$$

Assumptions

- $R \in \Gamma_0(\mathbb{R}^n)$.
- $A : \mathbb{R}^n \to \mathbb{R}^m$.
- $J \in \Gamma_0(\mathbb{R}^m)$.

Dual problem

Conjugate

$$J^*(v) \stackrel{\text{def}}{=} \sup_{u\in\mathbb{R}^m} \langle u,\, v\rangle - J(u).$$

Bi-conjugate

$$J = J^{**}.$$

Saddle-point problem

$$min_{x\in\mathbb{R}^n} \max_{v\in\mathbb{R}^m} \; R(x) + \langle Ax,\, v\rangle - J^*(v).$$

Dual problem

$$\max_{v\in\mathbb{R}^m} \; -R^*(-A^T v) - J^*(v).$$

NB: Forward–Backward splitting can be applied to dual problem...

Fenchel–Rockafellar duality

Let $R : \mathbb{R}^n \to]-\infty, +\infty]$ and $J : \mathbb{R}^m \to]-\infty, +\infty]$ be proper and A be bounded linear mapping, then

$$R(x) + J(Ax) \geq -R^*(-A^T v) - J^*(v)$$

holds for any $x \in \mathbb{R}^n$ and $v \in \mathbb{R}^m$.

Weak duality

$$R(x^\star) + J(Ax^\star) \geq -R^*(-A^T v^\star) - J^*(v^\star).$$

Strong duality

$$R(x^\star) + J(Ax^\star) = -R^*(-A^T v^\star) - J^*(v^\star).$$

Primal problem

$$\min_{x \in \mathbb{R}^n} \; R(x) \quad \text{s.t. } Ax = b.$$

Assumptions

- $R \in \Gamma_0(\mathbb{R}^n)$.
- $A \in \mathbb{R}^{m \times n}$.

Lagrangian

$$L(x, v) \stackrel{\text{def}}{=} R(x) + \langle v,\ Ax - b \rangle.$$

Dual function

$$H(v) = \inf_{x} L(x, v) = -R^*(-A^T v) - \langle b,\ v \rangle.$$

Dual problem

$$\max_{v \in \mathbb{R}^m} -R^*(-A^T v) - \langle b,\ v \rangle.$$

Outline

Problem

Primal problem

$$\min_{x \in \mathbb{R}^n} \; R(x) \quad \text{s.t.} \;\; Ax = b.$$

Dual problem

$$\max_{v \in \mathbb{R}^m} \; -R^*(-A^T v) - \langle b, \, v \rangle.$$

Lagrangian

$$L(x, v) \stackrel{\text{def}}{=} R(x) + \langle v,\ Ax - b\rangle.$$

Dual ascent

$$\begin{aligned} x_{k+1} &= \operatorname{argmin}_x L(x, v_k) \\ &= \operatorname{argmin}_x R(x) + \langle v,\ Ax\rangle \\ v_{k+1} &= v_k + \gamma_k(Ax_{k+1} - b) \end{aligned}$$

- Gradient ascent for dual problem $v_{k+1} = v_k + \gamma_k \nabla H(x_{k+1})$.
- $\nabla H(x_{k+1}) = Ax_{k+1} - b$ when $x_{k+1} = \operatorname{argmin}_x L(x, v_k)$.
- Works, but needs many strong conditions.

Dual decomposition

- Suppose R is separable

$$R(x) = R_1(x_1) + \cdots + R_\ell(x_\ell), \;\; x = (x_1, \cdots, x_\ell).$$

- L is then separable in x: $L(x, v) = L_1(x_1, v) + \cdots + L_\ell(x_\ell, v)$,

$$L_i(x_i, v) = R_i(x) + \langle v, \; A_i x_i \rangle.$$

- x-minimization in dual ascent splits into ℓ separate minimizations

$$x_{i,k+1} = \mathrm{argmin}_{x_i} L_i(x_i, v_k).$$

  which can be done in parallel fashion

- Dual decomposition

$$x_{i,k+1} = \mathrm{argmin}_{x_i} \; L_i(x_i, v_k), \; i = 1, ..., \ell,$$
$$v_{k+1} = v_k + \gamma_k \big(\textstyle\sum_{i=1}^{\ell} A_i x_{i,k+1} - b \big).$$

- Scatter v_k, update x_i in parallel, and gather $A_i x_{i,k+1}$.

- Waiting for the slowest x_i update.

Primal problem

$$\min_{x\in\mathbb{R}^n} \ R(x) \quad \text{s.t.} \ Ax = b.$$

Augmented Lagrangian Let $\rho > 0$

$$L_\rho(x, v) \stackrel{\text{def}}{=} R(x) + \langle v,\ Ax - b\rangle + \frac{\rho}{2}\|Ax - b\|^2.$$

Method of multipliers

$$\begin{aligned} x_{k+1} &= \mathrm{argmin}_x\, L_\rho(x, v_k) \\ &= \mathrm{argmin}_x\, R(x) + \tfrac{\rho}{2}\|Ax - b + v_k/\rho\|^2, \\ v_{k+1} &= v_k + \rho(Ax_{k+1} - b). \end{aligned}$$

- Specific step-size for dual update.
- Weaker conditions for convergence: non-smooth R and can be take $+\infty$.
- How $\|Ax - b\|^2$ destory the separable structure of x.

Outline

Primal problem

$$\min_{x,y\in\mathbb{R}^n} \quad R(x) + J(y)$$
$$\text{s.t.} \quad Ax + By = c.$$

Augmented Lagrangian Let $\rho > 0$

$$L_\rho(x, y, v) \stackrel{\text{def}}{=} R(x) + J(y) + \langle v,\ Ax + By - c\rangle + \frac{\rho}{2}\|Ax + By - c\|^2.$$

Proposed by Gabay, Mercier, Glowinski, Marrocco in 1976.

ADMM

$$
\begin{aligned}
x_{k+1} &= \mathrm{argmin}_x \, L_\rho(x, y_k, v_k), \\
y_{k+1} &= \mathrm{argmin}_y \, L_\rho(x_{k+1}, y, v_k), \\
v_{k+1} &= v_k + \rho(Ax_{k+1} + By_{k+1} - c).
\end{aligned}
$$

- Reduce to “method of multipliers” if we minimise x, y jointly.
- One-step Gauss-Seidel method.
- In general **NO** closed form for x_k, y_k.

Augmented Lagrangian

$$\begin{aligned} L_\rho(x,y,v) &= R(x) + J(y) + \langle v,\, Ax+By-c\rangle + \tfrac{\rho}{2}\|Ax+By-c\|^2 \\ &= R(x) + J(y) + \tfrac{\rho}{2}\|Ax+By-c+v/\rho\|^2. \end{aligned}$$

Scale dual $u = v/\rho$

$$v_{k+1} = v_k + \rho(Ax_{k+1} + By_{k+1} - c) \implies u_{k+1} = u_k + (Ax_{k+1} + By_{k+1} - c).$$

Dual scaled ADMM

$$\begin{aligned} x_{k+1} &= \mathrm{argmin}_x\, R(x) + \tfrac{\rho}{2}\|Ax + By_k - c + u_k\|^2, \\ y_{k+1} &= \mathrm{argmin}_y\, J(y) + \tfrac{\rho}{2}\|Ax_{k+1} + By - c + u_k\|^2, \\ u_{k+1} &= u_k + (Ax_{k+1} + By_{k+1} - c). \end{aligned}$$

- Also known as “split Bregman”...

Convergence

- Assumption
  - R, J are proper convex and lsc.
  - $L_{\rho=0}$ has saddle-point.
- Convergence
  - Objective function value $R(x_k) + J(y_k) \to p^\star$.
  - Feasibility $Ax_k + By_k - c \to 0$.
- Stronger assumption needed for the convergence of sequence.

Connection with Douglas–Rachford

- Consider

$$\min_{x\in\mathbb{R}^n} R(x) + J(Ax).$$

- Dual form

$$\max_{y\in\mathbb{R}^m} -R^*(-A^T y) - J^*(y).$$

- Split variable

$$\begin{aligned} \min_{x,y\in\mathbb{R}^n} \quad & R(x) + J(y) \\ \text{s.t.} \quad & Ax - y = 0. \end{aligned}$$

- Agumented Lagrangian

$$\begin{aligned} L_\rho(x, y, v) &= R(x) + J(y) + \langle v,\ Ax - y\rangle + \tfrac{\rho}{2}\|Ax - y\|^2 \\ &= R(x) + J(y) + \tfrac{\rho}{2}\|Ax - y + v/\rho\|^2. \end{aligned}$$

Connection with Douglas–Rachford

- ADMM

$$
\begin{aligned}
x_{k+1} &= \mathrm{argmin}_x\, R(x) + \tfrac{\rho}{2}\|Ax - y_k + v_k/\rho\|^2, \\
y_{k+1} &= \mathrm{argmin}_y\, J(y) + \tfrac{\rho}{2}\|Ax_{k+1} - y + v_k/\rho\|^2, \\
v_{k+1} &= v_k + \rho(Ax_{k+1} - y_{k+1}).
\end{aligned}
$$

- Define $u_{k+1} = \rho Ax_{k+1} + v_k - \rho y_k$ and $w_k = v_k + \rho y_k$.

- For x_{k+1},

$$
\begin{aligned}
& 0 \in \partial R(x_{k+1}) + \rho A^T\big(Ax_{k+1} - y_k + v_k/\rho\big) \\
\Longleftrightarrow\quad & -A^T u_{k+1} \in \partial R(x_{k+1}) \\
\Longleftrightarrow\quad & x_{k+1} \in \partial R^*\big(-A^T u_{k+1}\big) \\
\Longleftrightarrow\quad & -Ax_{k+1} \in \partial(R^* \circ -A^T)(u_{k+1}) \\
\Longleftrightarrow\quad & u_{k+1} = \big(\mathrm{Id} + \rho\partial(R^* \circ -A^T)\big)^{-1}(u_{k+1} - \rho Ax_{k+1}) \\
\Longleftrightarrow\quad & u_{k+1} = \big(\mathrm{Id} + \rho\partial(R^* \circ -A^T)\big)^{-1}(v_k - \rho y_k) \\
\Longleftrightarrow\quad & u_{k+1} = \big(\mathrm{Id} + \rho\partial(R^* \circ -A^T)\big)^{-1}(2v_k - w_k).
\end{aligned}
$$

Connection with Douglas–Rachford

- For y_{k+1}, $v_{k+1} = v_k + \rho(Ax_{k+1} - y_{k+1})$

$$\begin{aligned} & 0 \in \partial J(y_{k+1}) + \rho\big(y_{k+1} - Ax_{k+1} - v_k/\rho\big) \\ \Longleftrightarrow\quad & v_k + \rho(Ax_{k+1} - y_{k+1}) \in \partial J(y_{k+1}) \\ \Longleftrightarrow\quad & \rho y_{k+1} \in \rho \partial J^*(v_{k+1}) \\ \Longleftrightarrow\quad & v_{k+1} = \big(\mathrm{Id} + \rho \partial J^*\big)^{-1}(v_{k+1} + \rho y_{k+1}) \\ \Longleftrightarrow\quad & v_{k+1} = \big(\mathrm{Id} + \rho \partial J^*\big)^{-1}(w_{k+1}). \end{aligned}$$

- Summarise

$$\begin{aligned} u_{k+1} &= \big(\mathrm{Id} + \rho \partial(R^* \circ -A^T)\big)^{-1}(2v_k - w_k) \\ w_{k+1} &= w_k + u_{k+1} - v_k \\ v_{k+1} &= \big(\mathrm{Id} + \rho \partial J^*\big)^{-1}(w_{k+1}). \end{aligned}$$

- A should be injective, *i.e.* has full column rank.

Preconditioned ADMM

- Take x_{k+1} update, $t_k = y_k - v_k/\rho$

$$x_{k+1} = \mathrm{argmin}_x\, R(x) + \frac{\rho}{2}\|Ax - t_k\|^2.$$

- No closed form solution onwing to A.
- Let Q be symmetric and positive definite, and

$$x_{k+1} = \mathrm{argmin}_x\, R(x) + \frac{\rho}{2}\|Ax - t_k\|^2 + \frac{1}{2}\|x - x_k\|_Q^2.$$

- Choose $Q = \frac{1}{\tau}\mathrm{Id} - \rho A^T A$, τ is smaller enough such that Q is SPD

$$\begin{aligned} x_{k+1} &= \mathrm{argmin}_x\, R(x) + \frac{\rho}{2}\|Ax - t_k\|^2 + \frac{1}{2}\|x - x_k\|_Q^2 \\ &= \mathrm{argmin}_x\, R(x) + \frac{\rho}{2}x^T A^T Ax - \rho\langle x,\, A^T t_k\rangle + \frac{1}{2}x^T Qx - \langle x,\, Qx_k\rangle \\ &= \mathrm{argmin}_x\, R(x) + \frac{1}{2}x^T\big(\frac{1}{\tau}\mathrm{Id} - \rho A^T A + \rho A^T A\big)x - \langle x,\, \rho A^T t_k + Qx_k\rangle \\ &= \mathrm{argmin}_x\, R(x) + \frac{1}{2}\|x - (\rho A^T t_k + Qx_k)\|^2. \end{aligned}$$

LASSO

$$\min_{x\in\mathbb{R}^n} \mu\|x\|_1 + \frac{1}{2}\|Ax-b\|^2.$$

ADMM formulation

$$\begin{aligned} \min_{x,y\in\mathbb{R}^n} \quad & \mu\|y\|_1 + \frac{1}{2}\|Ax-b\|^2 \\ \text{s.t.} \quad & x - y = 0. \end{aligned}$$

ADMM

$$\begin{aligned} x_{k+1} &= \big(\mathrm{Id} + \rho A^T A\big)^{-1}(A^T b + \rho y_k - v_k), \\ y_{k+1} &= \mathcal{T}_{\mu/\rho}(x_{k+1} + v_k/\rho), \\ v_{k+1} &= v_k + \rho(x_{k+1} - y_{k+1}). \end{aligned}$$

Reference

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