

Introductory Course on Non-smooth Optimisation

Lecture 08 - Alternating direction methods of multipliers

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1 Duality

2 Dual ascent

3 ADMM

Primal problem

$$\min_{x \in \mathbb{R}^n} R(x) + J(Ax).$$

Assumptions

- $R \in \Gamma_0(\mathbb{R}^n)$.
- $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$.
- $J \in \Gamma_0(\mathbb{R}^m)$.

Conjugate

$$J^*(v) \stackrel{\text{def}}{=} \sup_{u \in \mathbb{R}^m} \langle u, v \rangle - J(u).$$

Bi-conjugate

$$J = J^{**}.$$

Saddle-point problem

$$\min_{x \in \mathbb{R}^n} \max_{v \in \mathbb{R}^m} R(x) + \langle Ax, v \rangle - J^*(v).$$

Dual problem

$$\max_{v \in \mathbb{R}^m} -R^*(-A^T v) - J^*(v).$$

NB: Forward-Backward splitting can be applied to dual problem...

Fenchel–Rockafellar duality

Let $R : \mathbb{R}^n \rightarrow]-\infty, +\infty]$ and $J : \mathbb{R}^m \rightarrow]-\infty, +\infty]$ be proper and A be bounded linear mapping, then

$$R(x) + J(Ax) \geq -R^*(-A^T v) - J^*(v)$$

holds for any $x \in \mathbb{R}^n$ and $v \in \mathbb{R}^m$.

Weak duality

$$R(x^*) + J(Ax^*) \geq -R^*(-A^T v^*) - J^*(v^*).$$

Strong duality

$$R(x^*) + J(Ax^*) = -R^*(-A^T v^*) - J^*(v^*).$$

Primal problem

$$\min_{x \in \mathbb{R}^n} R(x) \quad \text{s.t. } Ax = b.$$

Assumptions

- $R \in \Gamma_0(\mathbb{R}^n)$.
- $A \in \mathbb{R}^{m \times n}$.

Lagrangian

$$L(x, v) \stackrel{\text{def}}{=} R(x) + \langle v, Ax - b \rangle.$$

Dual function

$$H(v) = \inf_x L(x, v) = -R^*(-A^T v) - \langle b, v \rangle.$$

Dual problem

$$\max_{v \in \mathbb{R}^m} -R^*(-A^T v) - \langle b, v \rangle.$$

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Primal problem

$$\min_{x \in \mathbb{R}^n} R(x) \quad \text{s.t. } Ax = b.$$

Dual problem

$$\max_{v \in \mathbb{R}^m} -R^*(-A^T v) - \langle b, v \rangle.$$

Lagrangian

$$L(x, v) \stackrel{\text{def}}{=} R(x) + \langle v, Ax - b \rangle.$$

Dual ascent

$$\begin{aligned}x_{k+1} &= \operatorname{argmin}_x L(x, v_k) \\&= \operatorname{argmin}_x R(x) + \langle v, Ax \rangle \\v_{k+1} &= v_k + \gamma_k (Ax_{k+1} - b)\end{aligned}$$

- Gradient ascent for dual problem $v_{k+1} = v_k + \gamma_k \nabla H(x_{k+1})$.
- $\nabla H(x_{k+1}) = Ax_{k+1} - b$ when $x_{k+1} = \operatorname{argmin}_x L(x, v_k)$.
- Works, but needs many strong conditions.

- Suppose R is separable

$$R(x) = R_1(x_1) + \cdots + R_\ell(x_\ell), \quad x = (x_1, \dots, x_\ell).$$

- L is then separable in x : $L(x, v) = L_1(x_1, v) + \cdots + L_\ell(x_\ell, v)$,

$$L_i(x_i, v) = R_i(x_i) + \langle v, A_i x_i \rangle.$$

- x -minimization in dual ascent splits into ℓ separate minimizations

$$x_{i,k+1} = \operatorname{argmin}_{x_i} L_i(x_i, v_k).$$

which can be done in parallel fashion

- Dual decomposition

$$x_{i,k+1} = \operatorname{argmin}_{x_i} L_i(x_i, v_k), \quad i = 1, \dots, \ell,$$

$$v_{k+1} = v_k + \gamma_k \left(\sum_{i=1}^{\ell} A_i x_{i,k+1} - b \right).$$

- Scatter v_k , update x_i in parallel, and gather $A_i x_{i,k+1}$.
- Waiting for the slowest x_i update.

Primal problem

$$\min_{x \in \mathbb{R}^n} R(x) \quad \text{s.t. } Ax = b.$$

Augmented Lagrangian Let $\rho > 0$

$$L_\rho(x, v) \stackrel{\text{def}}{=} R(x) + \langle v, Ax - b \rangle + \frac{\rho}{2} \|Ax - b\|^2.$$

Method of multipliers

$$\begin{aligned}x_{k+1} &= \operatorname{argmin}_x L_\rho(x, v_k) \\&= \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax - b + v_k/\rho\|^2, \\v_{k+1} &= v_k + \rho(Ax_{k+1} - b).\end{aligned}$$

- Specific step-size for dual update.
- Weaker conditions for convergence: non-smooth R and can be take $+\infty$.
- How $\|Ax - b\|^2$ destroy the separable structure of x .

1 Duality

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Primal problem

$$\begin{aligned} \min_{x, y \in \mathbb{R}^n} \quad & R(x) + J(y) \\ \text{s.t.} \quad & Ax + By = c. \end{aligned}$$

Augmented Lagrangian Let $\rho > 0$

$$L_\rho(x, y, v) \stackrel{\text{def}}{=} R(x) + J(y) + \langle v, Ax + By - c \rangle + \frac{\rho}{2} \|Ax + By - c\|^2.$$

Proposed by Gabay, Mercier, Glowinski, Marrocco in 1976.

ADMM

$$\begin{aligned}x_{k+1} &= \operatorname{argmin}_x L_\rho(x, y_k, v_k), \\y_{k+1} &= \operatorname{argmin}_y L_\rho(x_{k+1}, y, v_k), \\v_{k+1} &= v_k + \rho(Ax_{k+1} + By_{k+1} - c).\end{aligned}$$

- Reduce to “method of multipliers” if we minimise x, y jointly.
- One-step Gauss-Seidel method.
- In general **NO** closed form for x_k, y_k .

Augmented Lagrangian

$$\begin{aligned} L_\rho(x, y, v) &= R(x) + J(y) + \langle v, Ax + By - c \rangle + \frac{\rho}{2} \|Ax + By - c\|^2 \\ &= R(x) + J(y) + \frac{\rho}{2} \|Ax + By - c + v/\rho\|^2. \end{aligned}$$

Scale dual $u = v/\rho$

$$v_{k+1} = v_k + \rho(Ax_{k+1} + By_{k+1} - c) \implies u_{k+1} = u_k + (Ax_{k+1} + By_{k+1} - c).$$

Dual scaled ADMM

$$\begin{aligned} x_{k+1} &= \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax + By_k - c + u_k\|^2, \\ y_{k+1} &= \operatorname{argmin}_y J(y) + \frac{\rho}{2} \|Ax_{k+1} + By - c + u_k\|^2, \\ u_{k+1} &= u_k + (Ax_{k+1} + By_{k+1} - c). \end{aligned}$$

- Also known as “split Bregman”...

- Assumption

- R, J are proper convex and lsc.
- $L_{\rho=0}$ has saddle-point.

- Convergence

- Objective function value $R(x_k) + J(y_k) \rightarrow p^*$.
- Feasibility $Ax_k + By_k - c \rightarrow 0$.

- Stronger assumption needed for the convergence of sequence.

- Consider

$$\min_{x \in \mathbb{R}^n} R(x) + J(Ax).$$

- Dual form

$$\max_{y \in \mathbb{R}^m} -R^*(-A^T y) - J^*(y).$$

- Split variable

$$\begin{aligned} \min_{x, y \in \mathbb{R}^n} \quad & R(x) + J(y) \\ \text{s.t.} \quad & Ax - y = 0. \end{aligned}$$

- Augmented Lagrangian

$$\begin{aligned} L_\rho(x, y, v) &= R(x) + J(y) + \langle v, Ax - y \rangle + \frac{\rho}{2} \|Ax - y\|^2 \\ &= R(x) + J(y) + \frac{\rho}{2} \|Ax - y + v/\rho\|^2. \end{aligned}$$

- ADMM

$$x_{k+1} = \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax - y_k + v_k/\rho\|^2,$$

$$y_{k+1} = \operatorname{argmin}_y J(y) + \frac{\rho}{2} \|Ax_{k+1} - y + v_k/\rho\|^2,$$

$$v_{k+1} = v_k + \rho(Ax_{k+1} - y_{k+1}).$$

- Define $u_{k+1} = \rho Ax_{k+1} + v_k - \rho y_k$ and $w_k = v_k + \rho y_k$.

- For x_{k+1} ,

$$0 \in \partial R(x_{k+1}) + \rho A^T (Ax_{k+1} - y_k + v_k/\rho)$$

$$\iff -A^T u_{k+1} \in \partial R(x_{k+1})$$

$$\iff x_{k+1} \in \partial R^*(-A^T u_{k+1})$$

$$\iff -Ax_{k+1} \in \partial(R^* \circ -A^T)(u_{k+1})$$

$$\iff u_{k+1} = (\operatorname{Id} + \rho \partial(R^* \circ -A^T))^{-1}(u_{k+1} - \rho Ax_{k+1})$$

$$\iff u_{k+1} = (\operatorname{Id} + \rho \partial(R^* \circ -A^T))^{-1}(v_k - \rho y_k)$$

$$\iff u_{k+1} = (\operatorname{Id} + \rho \partial(R^* \circ -A^T))^{-1}(2v_k - w_k).$$

- For y_{k+1} , $v_{k+1} = v_k + \rho(Ax_{k+1} - y_{k+1})$

$$0 \in \partial J(y_{k+1}) + \rho(y_{k+1} - Ax_{k+1} - v_k/\rho)$$

$$\iff v_k + \rho(Ax_{k+1} - y_{k+1}) \in \partial J(y_{k+1})$$

$$\iff \rho y_{k+1} \in \rho \partial J^*(v_{k+1})$$

$$\iff v_{k+1} = (\text{Id} + \rho \partial J^*)^{-1}(v_{k+1} + \rho y_{k+1})$$

$$\iff v_{k+1} = (\text{Id} + \rho \partial J^*)^{-1}(w_{k+1}).$$

- Summarise

$$u_{k+1} = (\text{Id} + \rho \partial(R^* \circ -A^T))^{-1}(2v_k - w_k)$$

$$w_{k+1} = w_k + u_{k+1} - v_k$$

$$v_{k+1} = (\text{Id} + \rho \partial J^*)^{-1}(w_{k+1}).$$

- A should be injective, i.e. has full column rank.

- Take x_{k+1} update, $t_k = y_k - v_k/\rho$

$$x_{k+1} = \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax - t_k\|^2.$$

- No closed form solution owing to A .

- Let Q be symmetric and positive definite, and

$$x_{k+1} = \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax - t_k\|^2 + \frac{1}{2} \|x - x_k\|_Q^2.$$

- Choose $Q = \frac{1}{\tau} \operatorname{Id} - \rho A^T A$, τ is smaller enough such that Q is SPD

$$\begin{aligned} x_{k+1} &= \operatorname{argmin}_x R(x) + \frac{\rho}{2} \|Ax - t_k\|^2 + \frac{1}{2} \|x - x_k\|_Q^2 \\ &= \operatorname{argmin}_x R(x) + \frac{\rho}{2} x^T A^T A x - \rho \langle x, A^T t_k \rangle + \frac{1}{2} x^T Q x - \langle x, Q x_k \rangle \\ &= \operatorname{argmin}_x R(x) + \frac{1}{2} x^T \left(\frac{1}{\tau} \operatorname{Id} - \rho A^T A + \rho A^T A \right) x - \langle x, \rho A^T t_k + Q x_k \rangle \\ &= \operatorname{argmin}_x R(x) + \frac{1}{2} \|x - (\rho A^T t_k + Q x_k)\|^2. \end{aligned}$$

LASSO

$$\min_{x \in \mathbb{R}^n} \mu \|x\|_1 + \frac{1}{2} \|Ax - b\|^2.$$

ADMM formulation

$$\begin{aligned} \min_{x, y \in \mathbb{R}^n} \quad & \mu \|y\|_1 + \frac{1}{2} \|Ax - b\|^2 \\ \text{s.t.} \quad & x - y = 0. \end{aligned}$$

ADMM

$$x_{k+1} = (\text{Id} + \rho A^T A)^{-1} (A^T b + \rho y_k - v_k),$$

$$y_{k+1} = \mathcal{T}_{\mu/\rho}(x_{k+1} + v_k/\rho),$$

$$v_{k+1} = v_k + \rho(x_{k+1} - y_{k+1}).$$

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