

# Louis L. W. D. Pahlavi



## PERSONAL DETAILS

**Nationality** French, Canadian  
**@** louis.pahlavi@mail.utoronto.ca  
**📞** +1 (647) 909-5487  
**✉** 106 Wineva Ave, Toronto, ON, M4E 2T2, Canada  
**🔗** lpahlavi.github.io

## LANGUAGES

English	● ● ● ● ●
French	● ● ● ● ●
Italian	● ● ● ● ●
German	● ● ● ● ●
Czech	● ● ● ● ●

## TECHNICAL SKILLS

<b>Build tools</b>	Makefile, CMake
<b>Version control</b>	Git
<b>Platforms</b>	Linux, Raspberry Pi, Arduino
<b>Libraries</b>	Boost, QT, CVX, Tensorflow
<b>Theory</b>	Control theory and robotics, Networking, Optimization, Algorithms and data structures, Machine learning

## PROGRAMMING LANGUAGES

C/C++	● ● ● ● ●
Python	● ● ● ● ●
MATLAB	● ● ● ● ●
Java	● ● ● ● ●

## EDUCATION

### University of Toronto, BSc in Computer Engineering

September 2014–April 2019

- Minor in Robotics and Mechatronics
- Final Project: *Distributed Formation Control of a Swarm of Unicycles*
- 16 month internship between third and fourth years of studies
- Latest term 92.1% average (ranked 4 out of 173), 3.86/4.00 CGPA

## RESEARCH AND INDUSTRY EXPERIENCE

### Systems and Control Engineering Intern

May 2017–August 2018

Verity Studios AG

Zürich, Switzerland

- Worked on improving the onboard estimation and control algorithms of swarms of quadcopters implemented in C++.
- Evaluated and characterized flight performance and effectiveness of calibration routines using Python and successfully improved drone production pipeline.
- Serviced entertainment drone show systems overseas and personally oversaw flight operations for several weeks.
- Maintained and improved offboard control and housekeeping applications including Graphical User Interfaces (GUIs).

### Researcher

May 2016–August 2016

ETH Zürich Laboratory for Biosensors and Bioelectronics

Zürich, Switzerland

- Developed the control and image processing software for a biosensor measuring protein interactions in fluids.

- Created a GUI using QT to control the actuators and interface them with various sensors including a live camera feed and calibration procedures.
- Experimented on the growth of networks of living animal neurons.

#### **Radio Frequencies Engineer**

June 2015–September 2015

University of Toronto Institute for Aerospace Studies - Space Flight Laboratories Toronto, Canada

- Designed and simulated the early prototypes of a deployable antenna mounted on the NORSAT-2 maritime communications satellite (launched in 2017) in collaboration with the European Space Agency.
- Built, tested and tuned antenna prototypes including validation using a Vector Network Analyzer (VNA).

#### **Researcher**

May 2015–June 2015

University of Toronto Reconfigurable Antenna Laboratory

Toronto, Canada

- Created a MATLAB simulation to model a satellite's orbit and predict antenna radiation intensity on the surface of the Earth. Worked on antenna synthesis to find an antenna array for a given desired coverage area.

### **PROJECTS AND TEACHING**

---

#### **Capstone Team Lead**

September 2018–April 2019

University of Toronto Faculty of Engineering

Toronto, Canada

- Implementing a fully distributed algorithm for the formation control of a swarm of wheeled robots in C++.
- Built and tested the communication interfaces between onboard modules and C++ and Python applications.
- Developed a Python simulation framework to test and tune the control algorithms.

#### **Teaching Assistant**

September 2016–December 2016

University of Toronto Faculty of Engineering

Toronto, Canada

- Taught APS100 – 'Orientation to Engineering' to first year Electrical and Computer Engineering students.

#### **Wireless Communications Lead**

September 2014–June 2016

University of Toronto Aerospace Team (Space Systems)

Toronto, Canada

- Designed, built and tested the antenna and communication module PCB, on a student-built nano-satellite.
- Presented our design at several Product Design Reviews and the Critical Design Review in Vancouver.

#### **Ground School Instructor**

September 2014–January 2015

330 Danforth Tech Royal Canadian Air Cadet Squadron

Toronto, Canada

- Coordinated and taught the pilot ground school course at 330 Danforth Tech Royal Canadian Air Cadet Squadron leading several of my students to earn their pilot wings.

### **SCHOLARSHIPS AND AWARDS**

---

- **Faculty of Applied Science and Engineering Dean's Honours List** 2014–Present
- **Gordon R. Slemon Scholarship** – Awarded for engineering design and academic excellence 2016
- **University of Toronto International Exchange Bursary** 2016
- **University of Toronto Centre for International Exchange Award** 2016
- **Royal Canadian Air Cadet Power Pilot Scholarship** 2014
- **Royal Canadian Air Cadet Glider Pilot Scholarship** 2013