

# Models and Control Strategies for Data Center Energy Efficiency

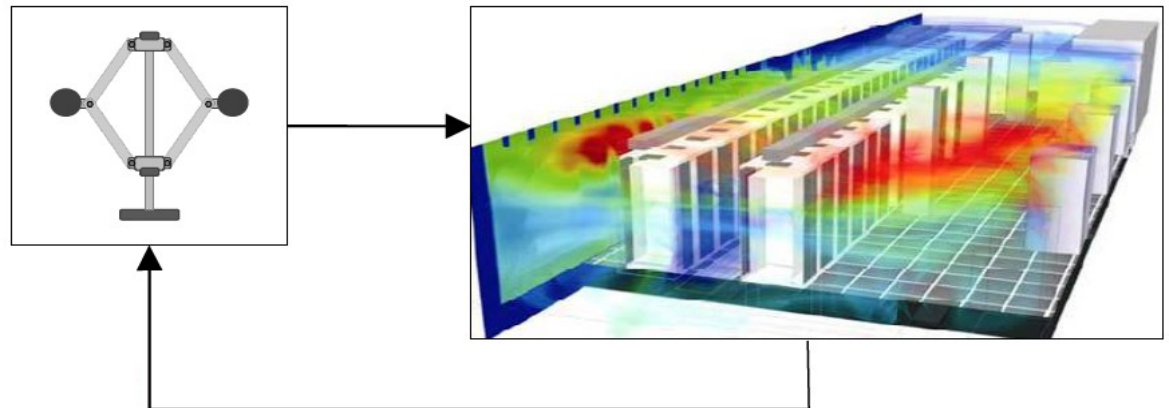
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# Data center examples



## ■ Facebook's data center in North Carolina, US

- 450\$ million project
- ~28.000 m<sup>2</sup> (300.000 ft<sup>2</sup>)
- Operated by 35 - 45 full-time employees



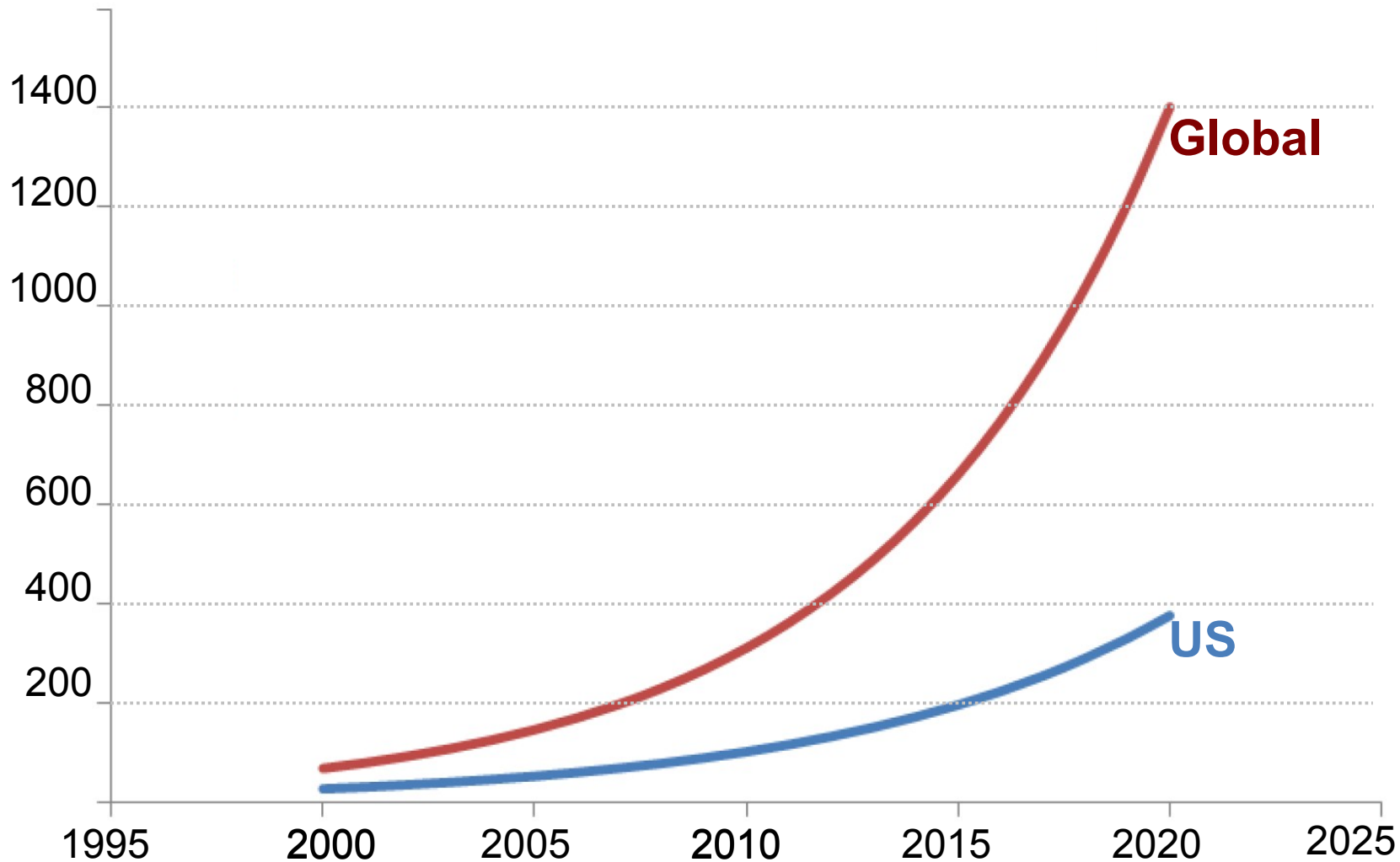
## ■ Racks

- Contain 42 (1U) servers in a rack
- 1 server: 480mm x 800mm x 44mm

	<i>Idle power</i>	<i>Peak power</i>
<i>Server</i>	200 W	350 W
<i>Rack</i>	8.4 kW	~15 kW

# Electricity consumption

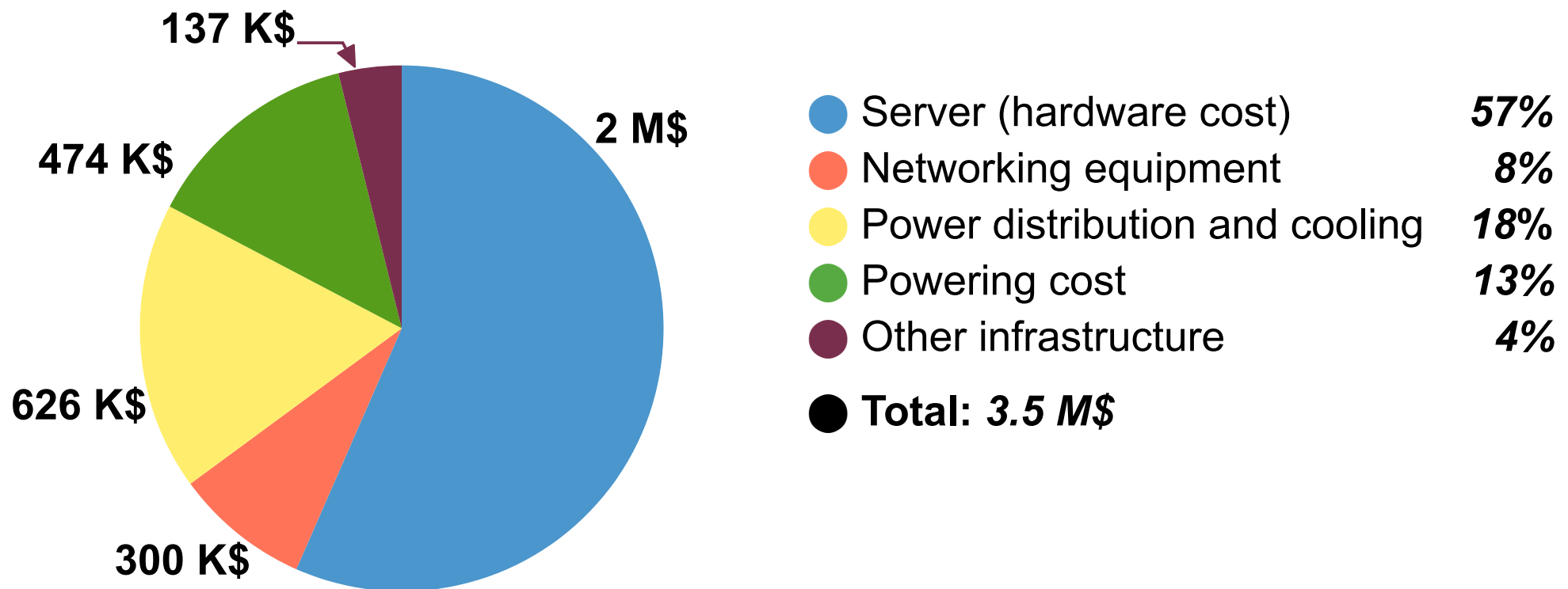
(Billion of Kwh / year)



# Monthly operating cost

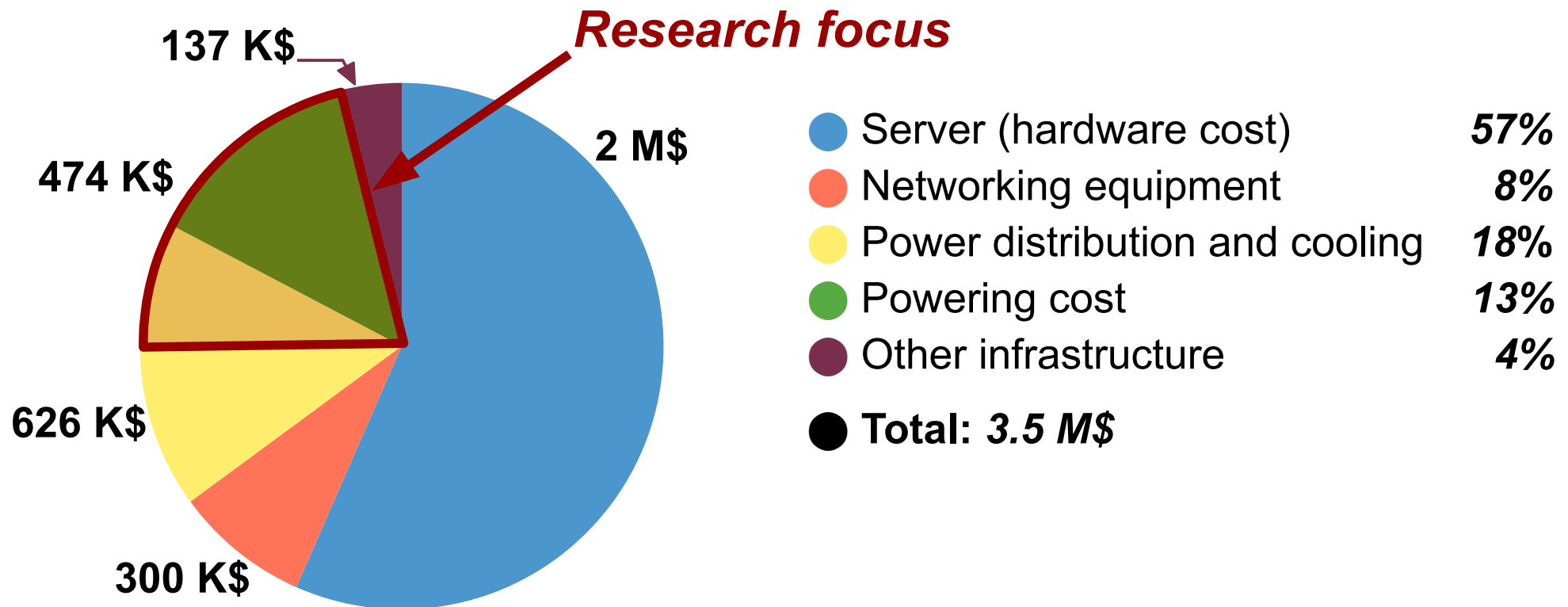
## ■ Large-scale facility, 50K servers

- Facility cost amortized over 10 years
- Server cost amortized over 3 years
- Servers account for 70% of total power consumption

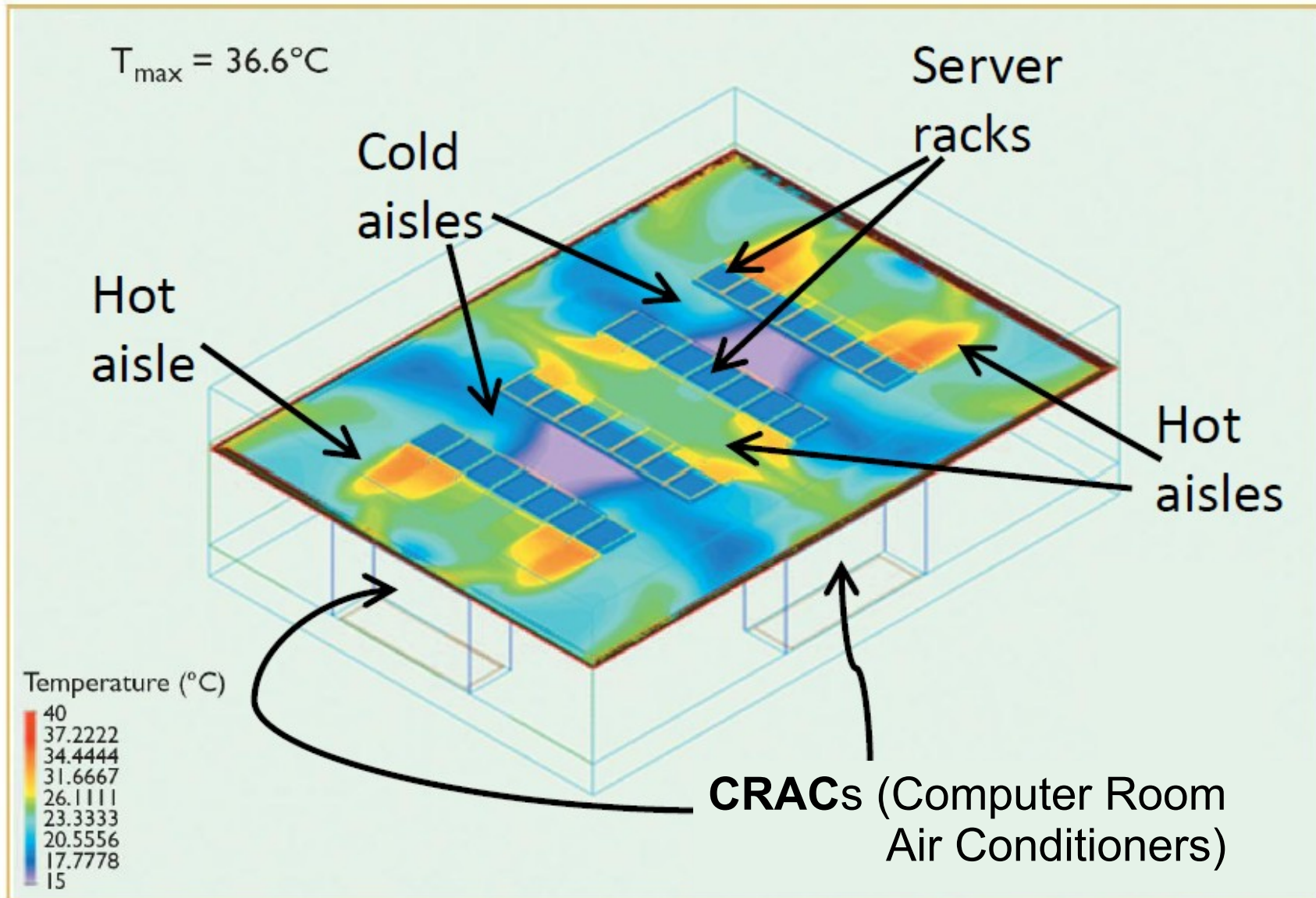


# Monthly operating cost

- **Large-scale facility, 50K servers**
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  - Server cost amortized over 3 years
  - Servers consume 70% of total power consumption



# Temperature distribution

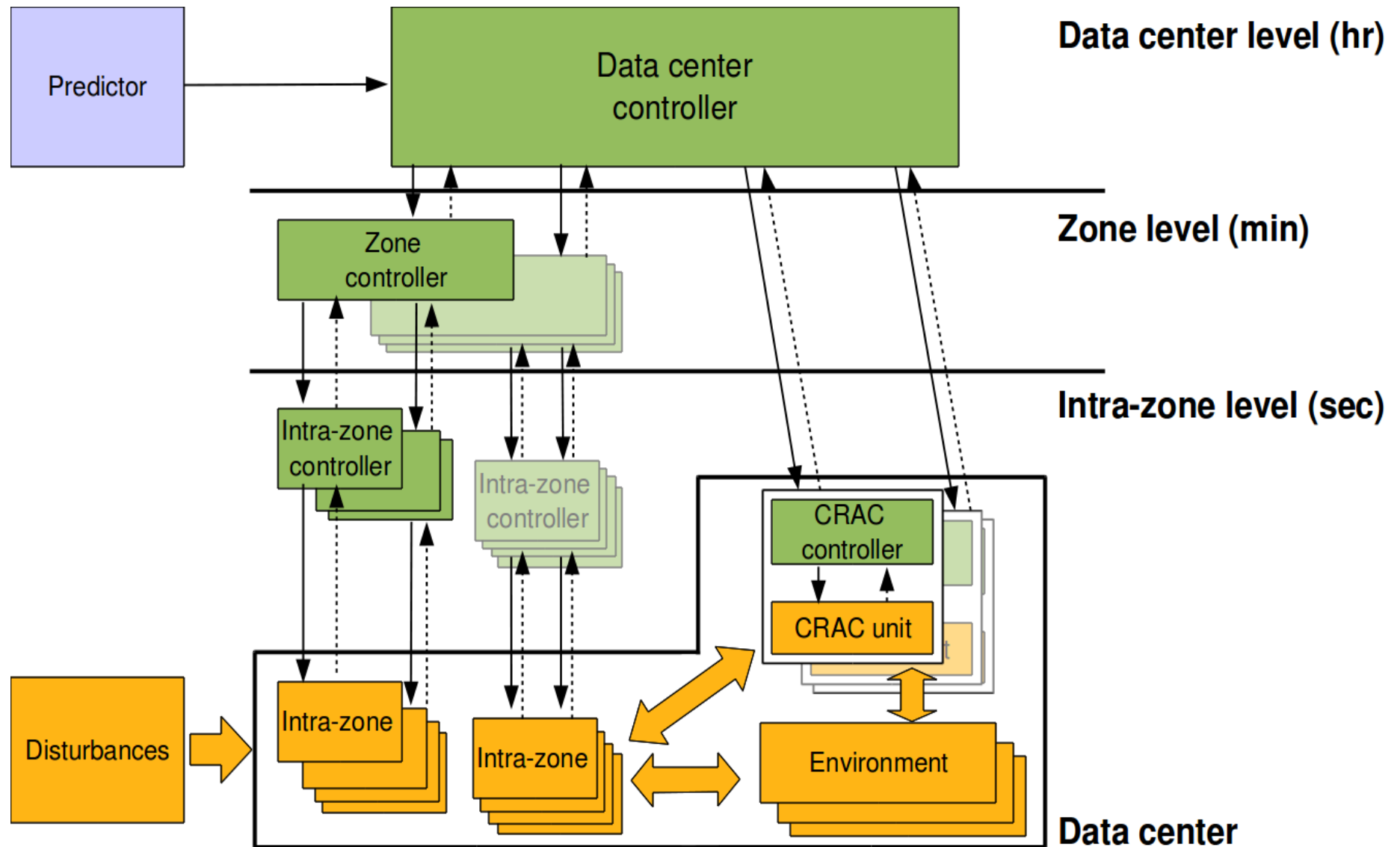




# Outline

- Introduction
- **Control-oriented model**
- Control strategies
- Simulation results
- Conclusion and future work

# Hierarchical control approach



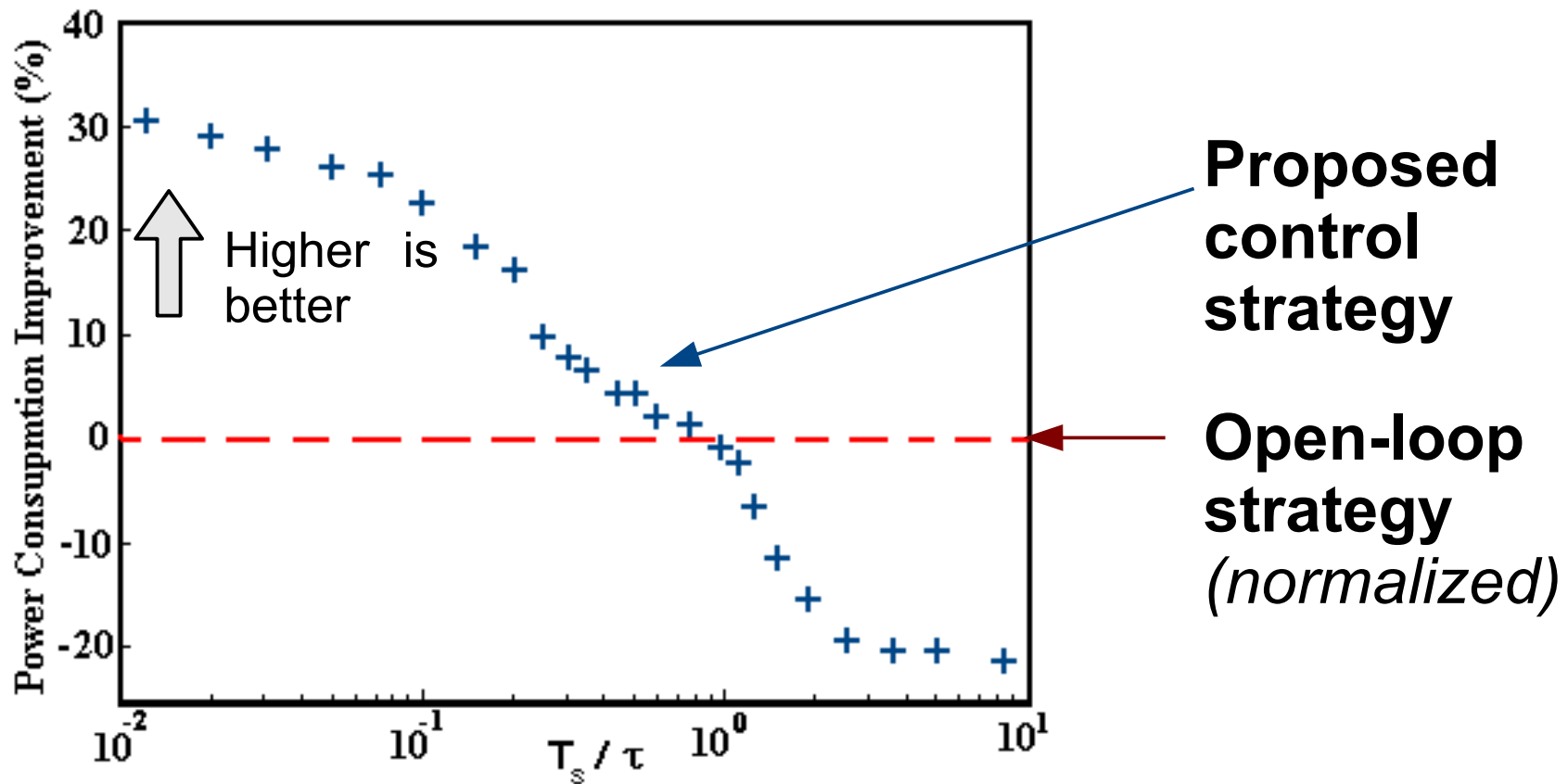


# Zone level control

- **Operates at a faster time-scale**
- **Decides how many servers in the zone should be turned on**
- **Control actions based on**
  - Desired workload execution rate (predictive control)
  - Current resource use in the zone (reactive control)
- **Considers**
  - Time to turn servers on:  $T_s$
  - Variability of workload arrival rate

# Zone level control - simulation results

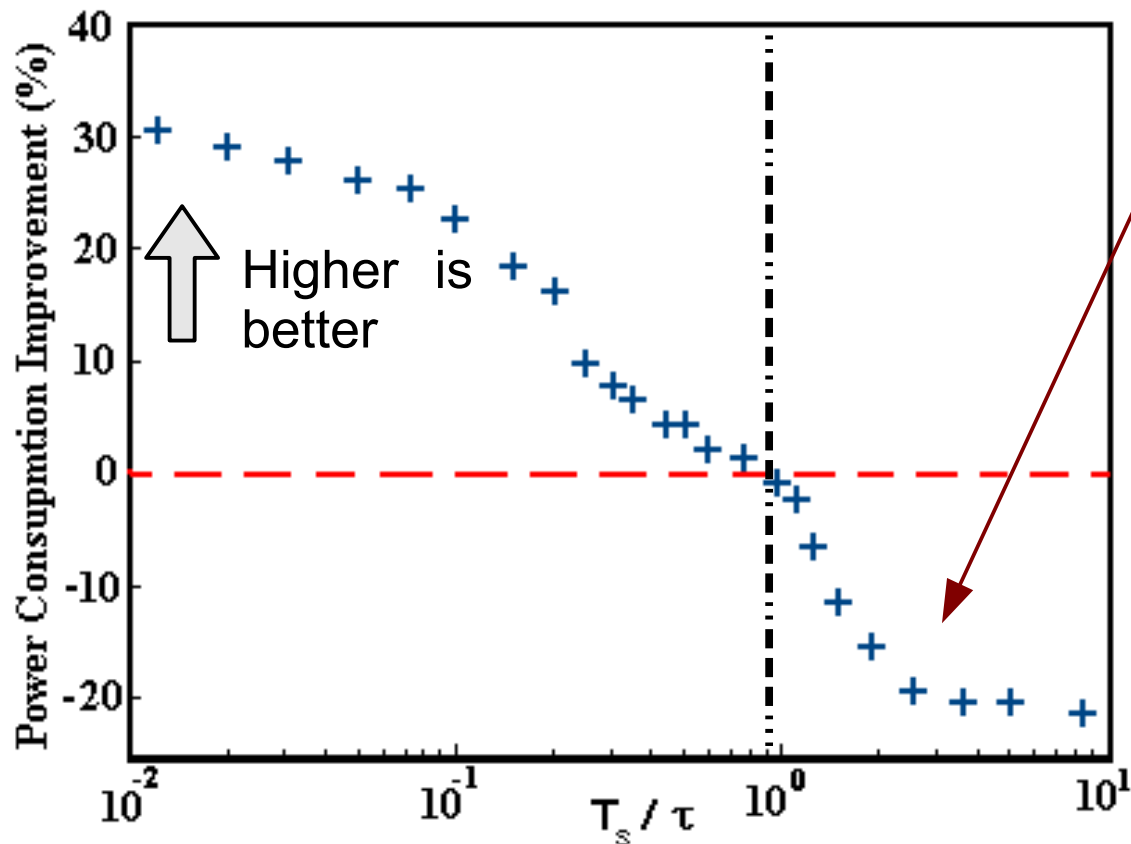
- Compare proposed control approach against optimal open-loop strategy
  - $\tau$ : expected time interval over which the workload arrival rate is constant



# Zone level control - simulation results

- Compare proposed control approach against optimal open-loop strategy

- $\tau$ : expected time interval over which the workload arrival rate is constant



- Workload arrival rate varies too fast with respect to the time to turn servers on

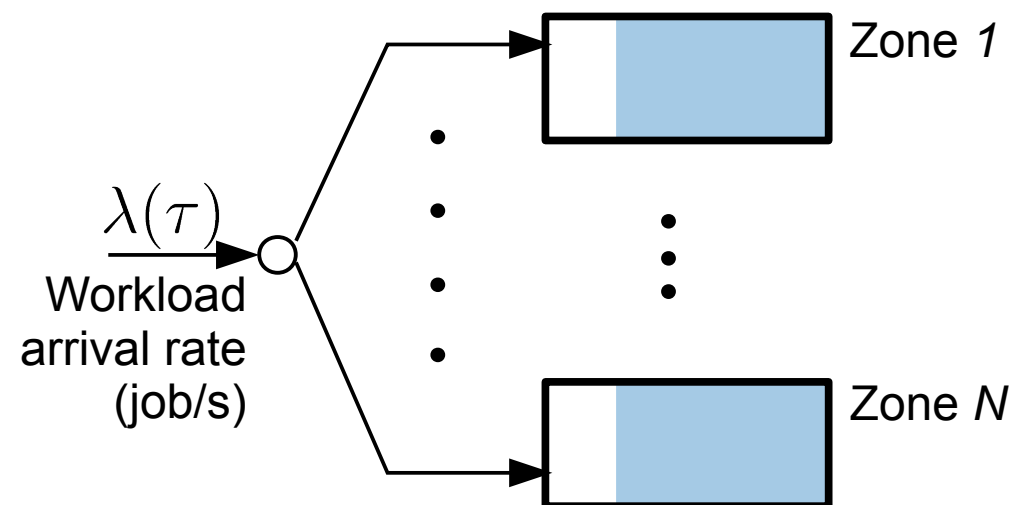
- Best solution is to never turn servers on and off

# Modeling approach: Data Center Level

- **Focuses on processes in the hours time scale**
- **Groups servers into zones**
  - Power consumption of a zone is proportional to the amount of workload executed
  - Data are always available
  - Neglect the time to turn servers On and Off
    - Much shorter than the controller sampling-time
- **Considers**
  - Computational and thermal dynamics
  - Nonlinear efficiency of the CRAC units
    - Service level agreements (SLAs) with users and the power-grid

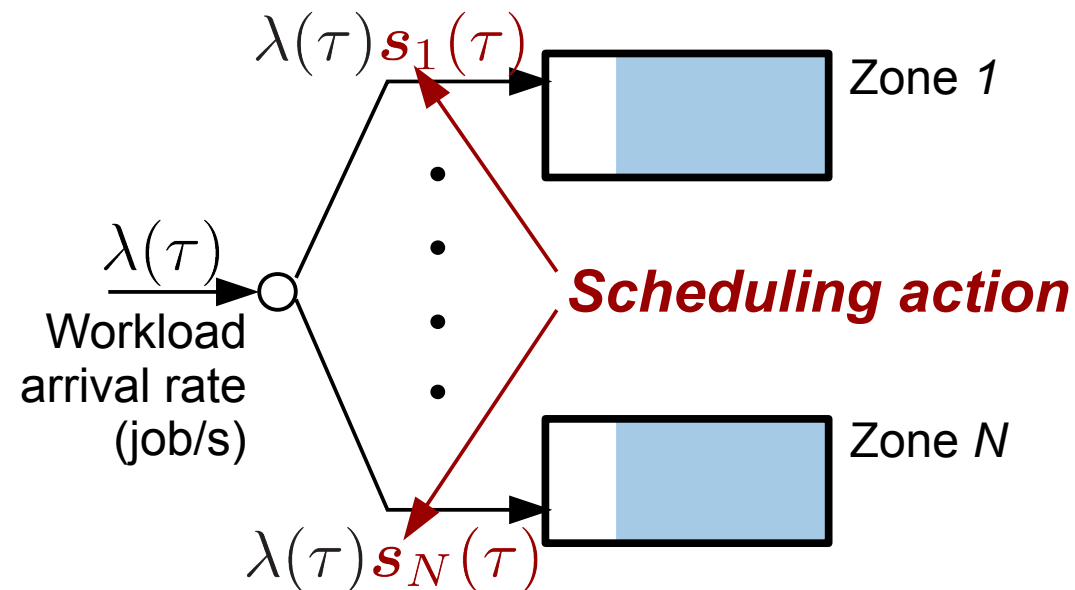
# Computational network

- Describes the evolution of resource usage in the data center
- Based on a fluid approximation of the workload execution and arrival processes
  - First-order approximation of a queuing system



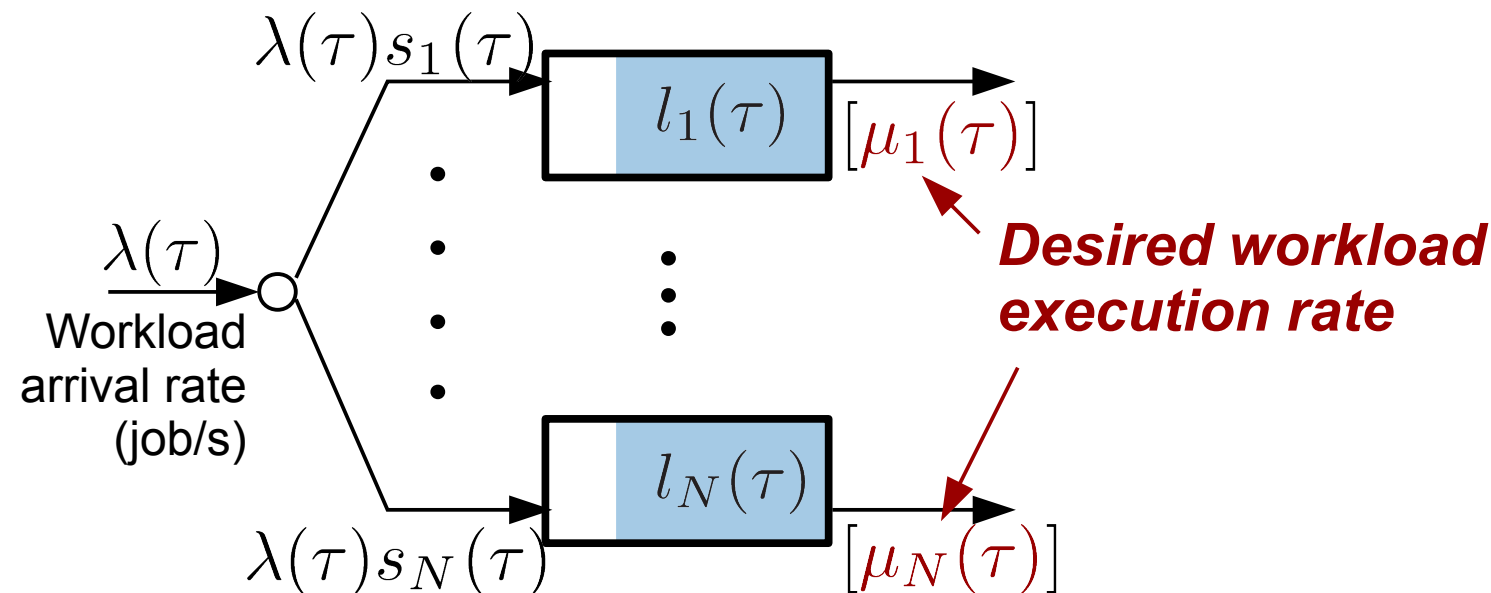
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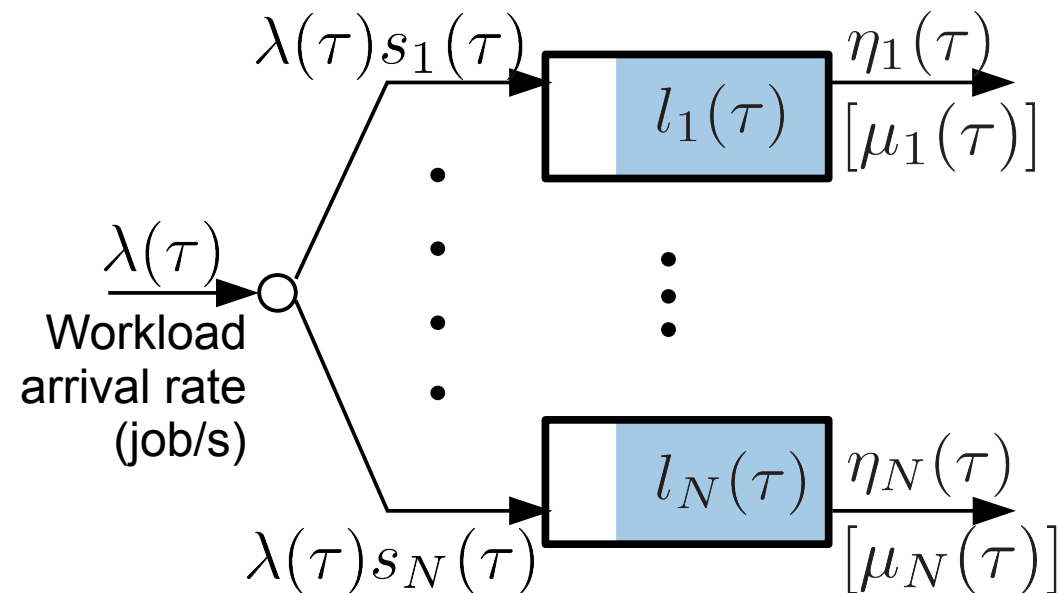
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# Computational network

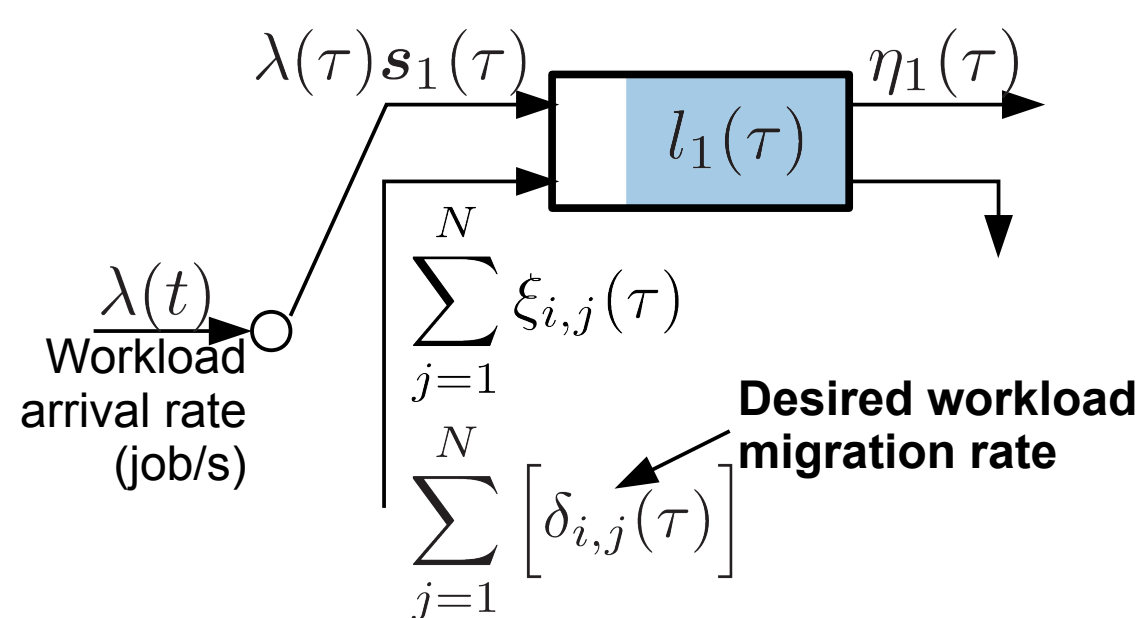
- Describes the evolution of resource usage in the data center
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  - First-order approximation of a queuing system



$$\begin{aligned} a_1(\tau) &= \lambda(\tau)s_1(\tau) \\ d_1(\tau) &= \eta_1(\tau) \\ \dot{l}_1(\tau) &= a_1(\tau) - d_1(\tau) \\ \eta_1(\tau) &= \begin{cases} \mu_1(\tau) & \text{if } l_1(\tau) > 0 \\ & \text{or } a_1(\tau) > \mu_1(\tau) \\ a_1(\tau) & \text{otherwise} \end{cases} \end{aligned}$$

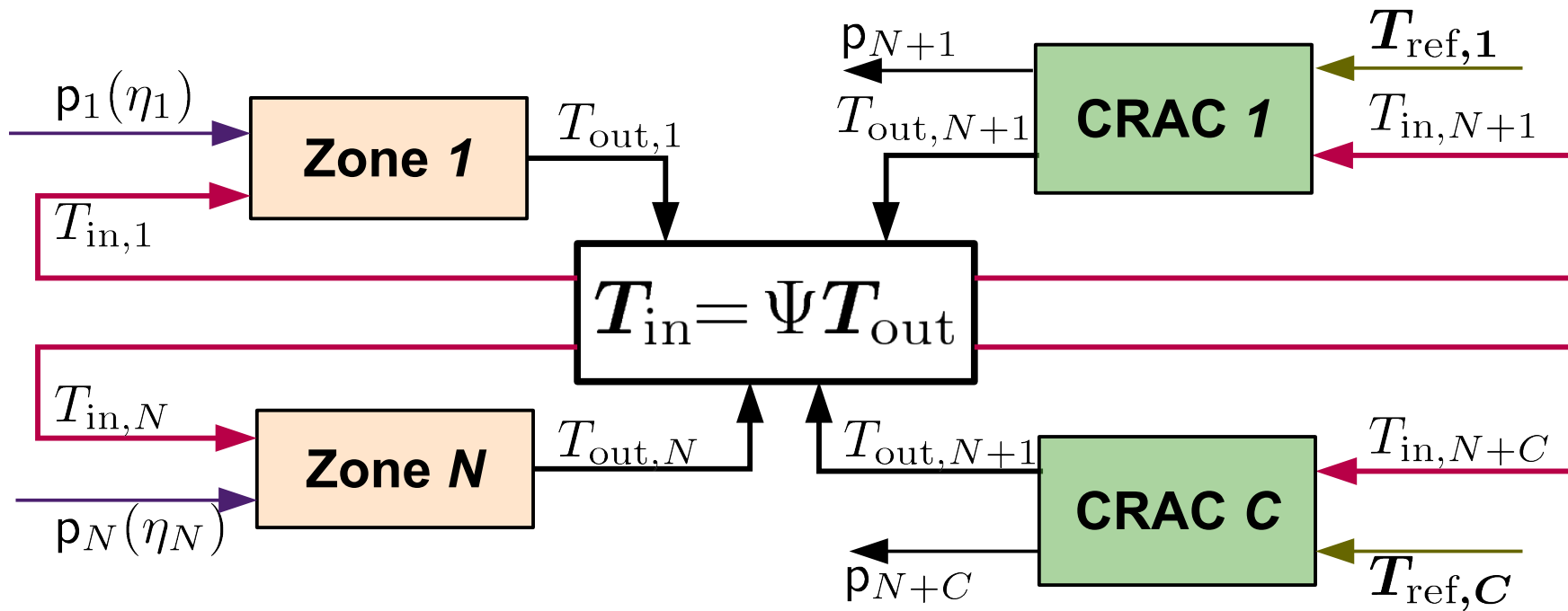
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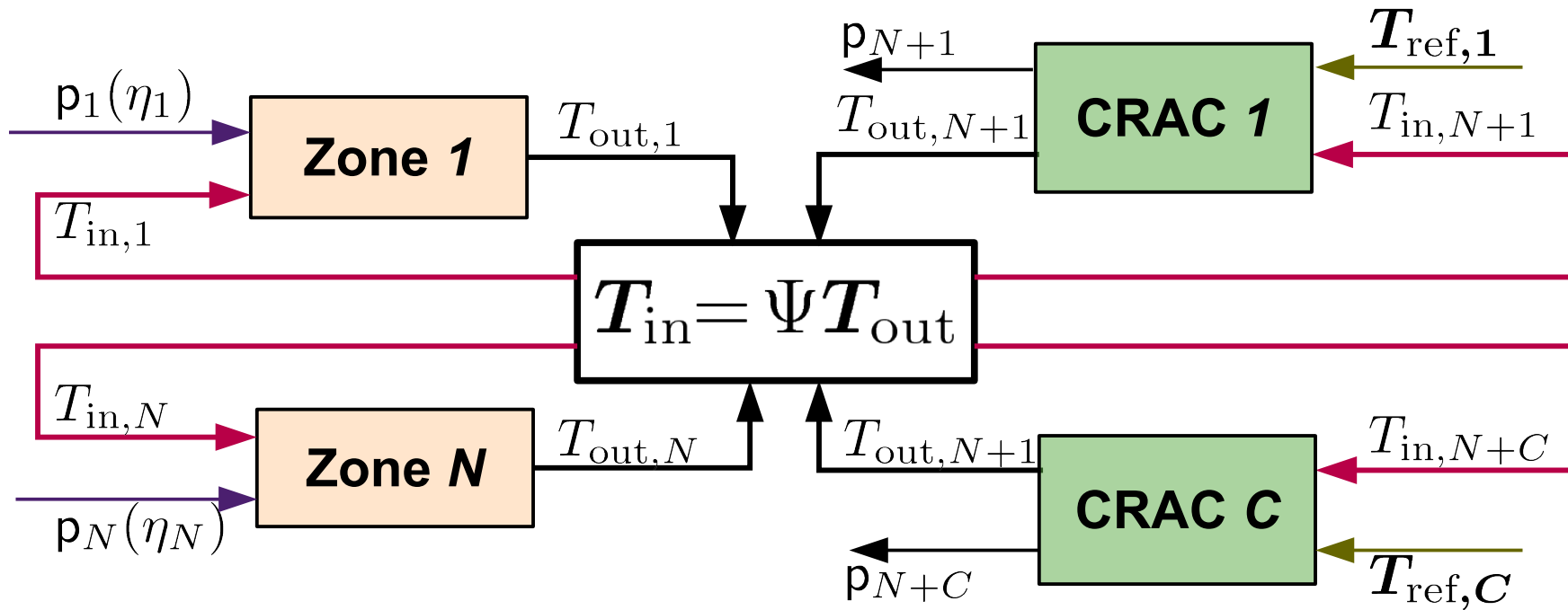


$$\begin{aligned}
 a_1(\tau) &= \lambda(\tau) s_1(\tau) + \sum_{j=1}^N \xi_{1,j}(\tau) \\
 d_1(\tau) &= \eta_1(\tau) + \sum_{j=1}^N \xi_{j,1}(\tau) \\
 \dot{l}_1(\tau) &= a_1(\tau) - d_1(\tau) \\
 \eta_1(\tau) &= \begin{cases} \mu_1(\tau) & \text{if } l_1(\tau) > 0 \\ & \text{or } a_1(\tau) > \mu_1(\tau) \\ a_1(\tau) & \text{otherwise} \end{cases}
 \end{aligned}$$

# Thermal network



# Thermal network



- **Inlet temperature constraint**  $T_{in}(\tau) = \Psi T_{out}(\tau) \leq \overline{T_{in}}$

*Heat removed rate (W)*  $\rightarrow \dot{Q}_i(t)$

- **CRAC power consumption**  $p_i(t) = \frac{\dot{Q}_i(t)}{COP_i(T_{out,i}(t))}$

# Variables at step $k$

			Variables
Input	Controllable	Job scheduling	$\mathbf{s}(k)$
		Resource allocation	$\boldsymbol{\mu}(k)$
		Job migration	$\boldsymbol{\delta}(k)$
		CRAC unit reference temperature	$T_{\text{ref}}(k)$
	Uncontrollable	Job arrival	$\boldsymbol{\lambda}(k)$
Output	Zone power consumption		$\mathbf{p}_N(k)$
	Power consumption of CRAC nodes		$\mathbf{p}_c(k)$
	Input temperatures of zones		$T_{in}(k)$
State	Number of jobs in every zones		$\mathbf{l}(k)$
	Output temperatures of CRACs and zones		$T_{out}(k)$

# Outline

- Introduction
- Control-oriented model
- **Control strategies**
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# Control strategies

## ■ Baseline

- Open-loop strategy
- Sets control variables for the worst-case scenario

## ■ Uncoordinated

- Manages the computational and the thermal resources independently
- Neglects the thermal-computational coupling in the data center

## ■ Coordinated

- Manages the computational and the thermal resources in a single optimization problem



# Baseline & uncoordinated approaches

## ■ Baseline

$$\mu(\tau) = \bar{\mu} \quad \delta(\tau) = 0 \quad s(\tau) = \mathbf{1} \frac{1}{N} \quad T_{\text{ref}}(\tau) = \underline{T_{\text{ref}}}$$

## ■ Uncoordinated controller

$$\min_{\mathcal{M}, \mathcal{S}, \mathcal{D}} \sum_{h=k}^{k+\mathcal{T}-1} \mathbf{1}^T \hat{\mathbf{p}}_{\mathcal{N}}(h|k) \quad \leftarrow \text{Minimize expected zone power consumption}$$

s.t.  $\hat{l}(k|k) = l(k)$   
 for all  $h = k, \dots, k + \mathcal{T} - 1$   
 computational dynamics  
 QoS constraints

$0 \leq \hat{\mu}(h|k) \leq \bar{\mu}, \quad \hat{\delta}(h|k) = 0$   
 $0 \leq \hat{s}(h|k) \leq 1, \quad \mathbf{1}^T \hat{s}(h|k) \leq 1$

■ Computational dynamics  
 ■ Quality of service (QoS) constraints  
 ■ Control constraints

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$$\mathcal{D} = \left\{ \hat{\delta}(k|k), \dots, \hat{\delta}(k+\mathcal{T}-1|k) \right\} \quad \mathcal{T}_{\text{ref}} = \left\{ \hat{T}_{\text{ref}}(k|k), \dots, \hat{T}_{\text{ref}}(k+\mathcal{T}-1|k) \right\}$$

$$\mathcal{M} = \left\{ \hat{\mu}(k|k), \dots, \hat{\mu}(k+\mathcal{T}-1|k) \right\} \quad \mathcal{S} = \left\{ \hat{s}(k|k), \dots, \hat{s}(k+\mathcal{T}-1|k) \right\}$$

# Baseline & uncoordinated approaches

## ■ Baseline

$$\mu(\tau) = \bar{\mu} \quad \delta(\tau) = 0 \quad s(\tau) = \mathbf{1} \frac{1}{N} \quad T_{\text{ref}}(\tau) = \underline{T_{\text{ref}}}$$

## ■ Uncoordinated controller

$$\min_{\mathcal{M}, \mathcal{S}, \mathcal{D}} \sum_{h=k}^{k+\mathcal{T}-1} \mathbf{1}^T \hat{\mathbf{p}}_{\mathcal{N}}(h|k)$$

$$\begin{aligned} \text{s.t. } \quad & \hat{l}(k|k) = l(k) \\ & \text{for all } h = k, \dots, k + \mathcal{T} - 1 \\ & \text{computational dynamics} \\ & \text{QoS constraints} \\ & 0 \leq \hat{\mu}(h|k) \leq \bar{\mu}, \quad \hat{\delta}(h|k) = 0 \\ & 0 \leq \hat{s}(h|k) \leq 1, \quad \mathbf{1}^T \hat{s}(h|k) \leq 1 \end{aligned}$$

$$\{\hat{\mathbf{p}}_{\mathcal{N}}(h|k)\} \xrightarrow{\text{blue arrow}}$$

$$\min_{\mathcal{T}_{\text{ref}}} \sum_{h=k}^{k+\mathcal{T}-1} \mathbf{1}^T \hat{\mathbf{p}}_{\mathcal{C}}(h|k)$$

$$\begin{aligned} \text{s.t. } \quad & \hat{T}_{\text{out}}(k|k) = T_{\text{out}}(k) \\ & \text{for all } h = k, \dots, k + \mathcal{T} - 1 \\ & \text{thermal dynamics} \\ & \underline{T_{\text{ref}}} \leq \hat{T}_{\text{ref}}(h|k) \leq \overline{T_{\text{ref}}} \\ & \hat{T}_{\text{in}}(h+1|k) \leq \overline{T_{\text{in}}} \end{aligned}$$

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$$\begin{aligned} \mathcal{D} &= \left\{ \hat{\delta}(k|k), \dots, \hat{\delta}(k+\mathcal{T}-1|k) \right\} & \mathcal{T}_{\text{ref}} &= \left\{ \hat{T}_{\text{ref}}(k|k), \dots, \hat{T}_{\text{ref}}(k+\mathcal{T}-1|k) \right\} \\ \mathcal{M} &= \left\{ \hat{\mu}(k|k), \dots, \hat{\mu}(k+\mathcal{T}-1|k) \right\} & \mathcal{S} &= \left\{ \hat{s}(k|k), \dots, \hat{s}(k+\mathcal{T}-1|k) \right\} \end{aligned}$$

# Coordinated approach

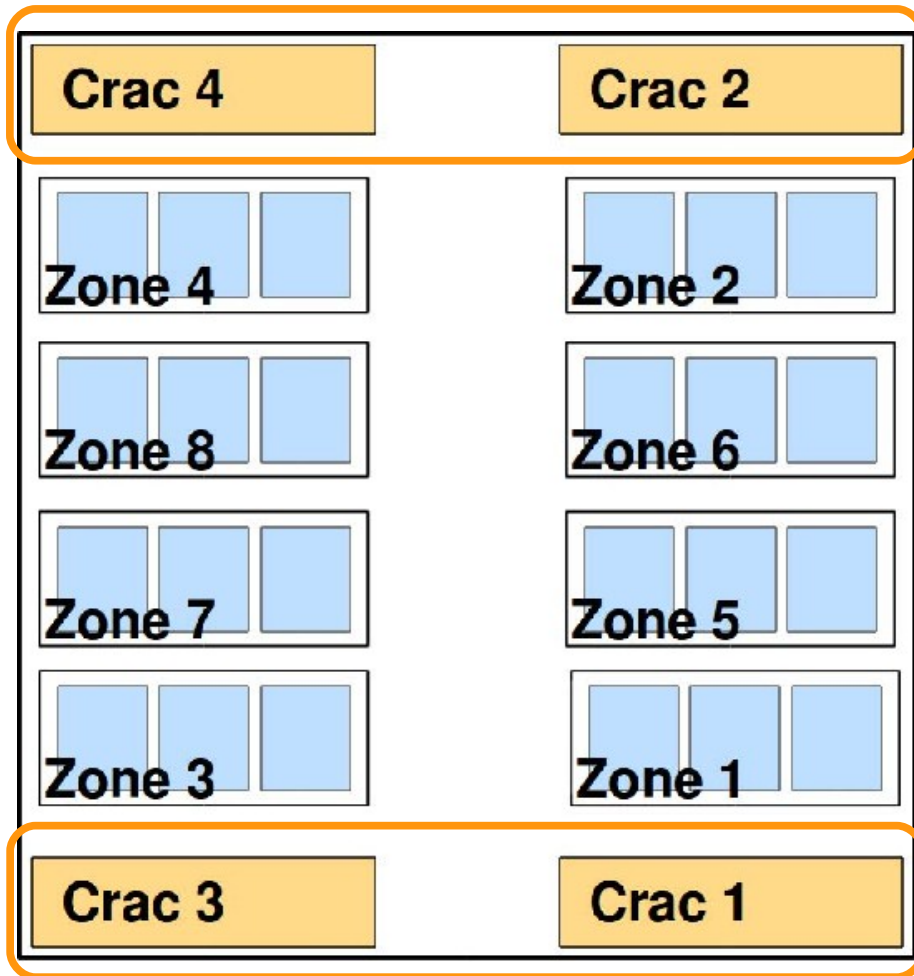
- Considers the computational and the thermal dynamics in the same optimization problem

$$\begin{aligned}
 & \min_{\mathcal{M}, \mathcal{S}, \mathcal{D}, \mathcal{T}_{ref}} \left( \sum_{h=k}^{k+\mathcal{T}-1} \mathbf{1}^T \hat{\mathbf{p}}_{\mathcal{N}}(h|k) + \mathbf{1}^T \hat{\mathbf{p}}_{\mathcal{C}}(h|k) \right) \leftarrow \text{Minimize expected zone and CRAC power consumption} \\
 & \text{s.t. } \hat{l}(k|k) = l(k), \quad \hat{\mathbf{T}}_{\text{out}}(k|k) = \mathbf{T}_{\text{out}}(k) \\
 & \quad \text{for all } h = k, \dots, k + \mathcal{T} - 1 \\
 & \quad \left. \begin{array}{l} \text{computational dynamics,} \\ \text{thermal dynamics,} \\ \text{QoS constraints,} \end{array} \right\} \leftarrow \text{Considers both thermal and computational dynamics} \\
 & \quad \mathbf{0} \leq \hat{\boldsymbol{\mu}}(h|k) \leq \overline{\boldsymbol{\mu}}, \quad \hat{\boldsymbol{\delta}}(h|k) = \mathbf{0} \\
 & \quad \mathbf{0} \leq \hat{\mathbf{s}}(h|k) \leq \mathbf{1}, \quad \mathbf{1}^T \hat{\mathbf{s}}(h|k) \leq 1, \\
 & \quad \underline{\mathbf{T}}_{\text{ref}} \leq \hat{\mathbf{T}}_{\text{ref}}(h|k) \leq \overline{\mathbf{T}}_{\text{ref}}, \quad \hat{\mathbf{T}}_{\text{in}}(h+1|k) \leq \overline{\mathbf{T}}_{\text{in}}, \\
 & \quad \hat{\mathbf{p}}(h|k) = \mathbf{B}_{\eta} \hat{\boldsymbol{\eta}}(h|k) \leftarrow \text{Thermal-computational coupling}
 \end{aligned}$$

# Outline

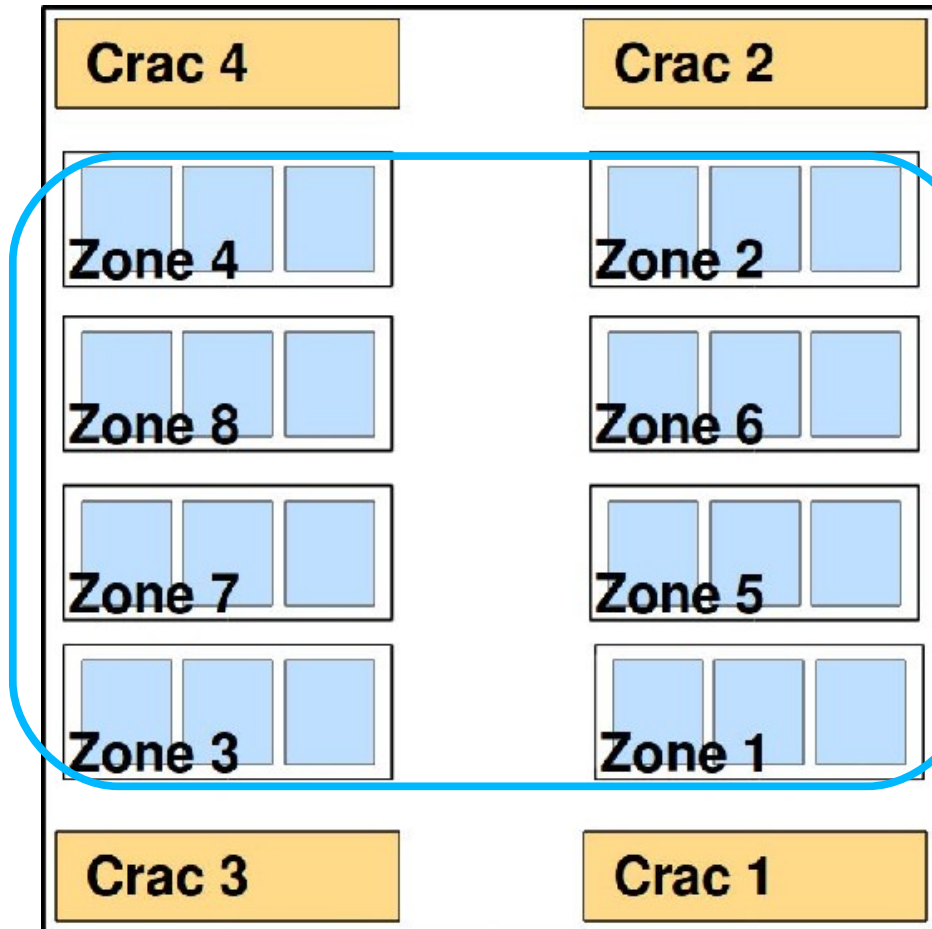
- Introduction
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# Simulation parameters



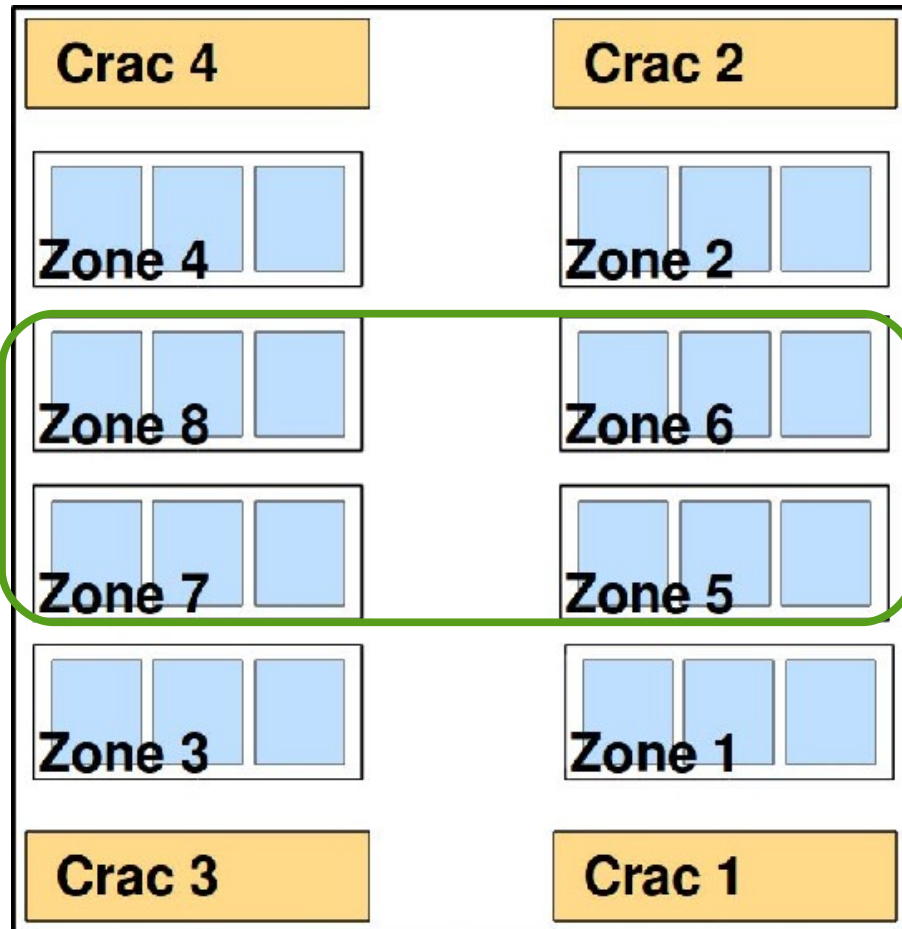
- 4 CRAC units
- Identical to each other

# Simulation parameters



- **4 CRAC units**
  - Identical to each other
- **8 Zones**
  - 3 Racks each (126 servers per zone)

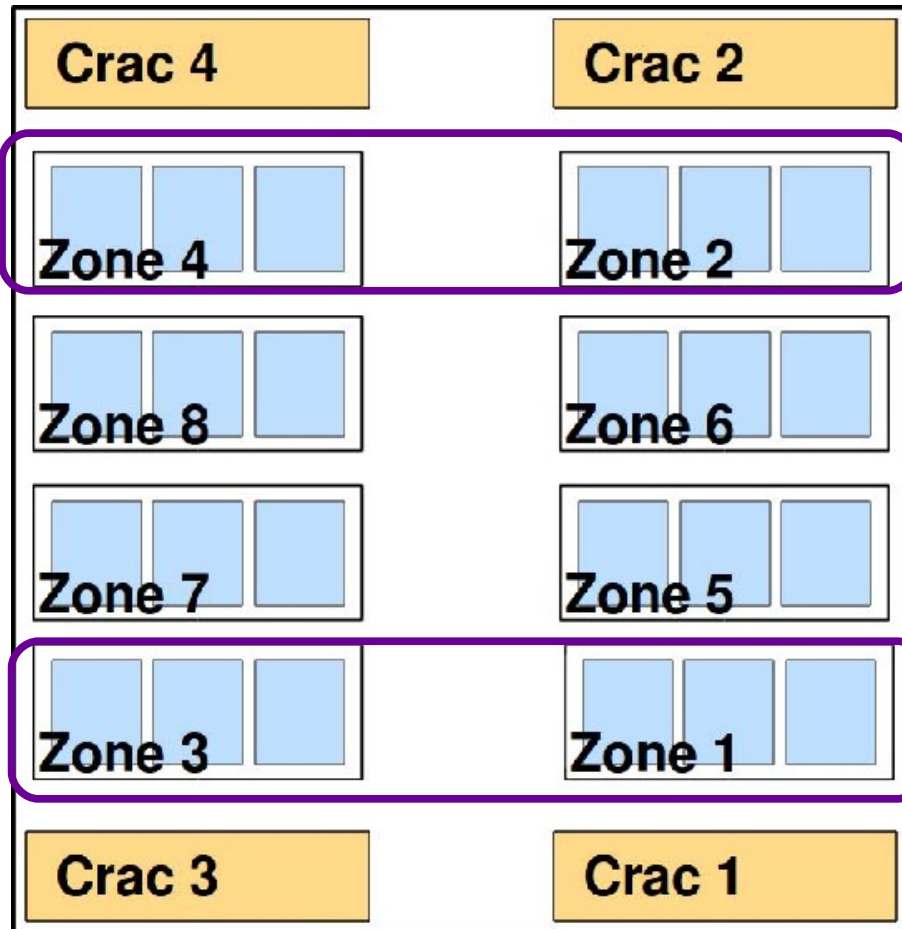
# Simulation parameters



- **4 CRAC units**
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- **8 Zones**
  - 3 Racks each (126 servers per zone)
  - Energy efficient servers

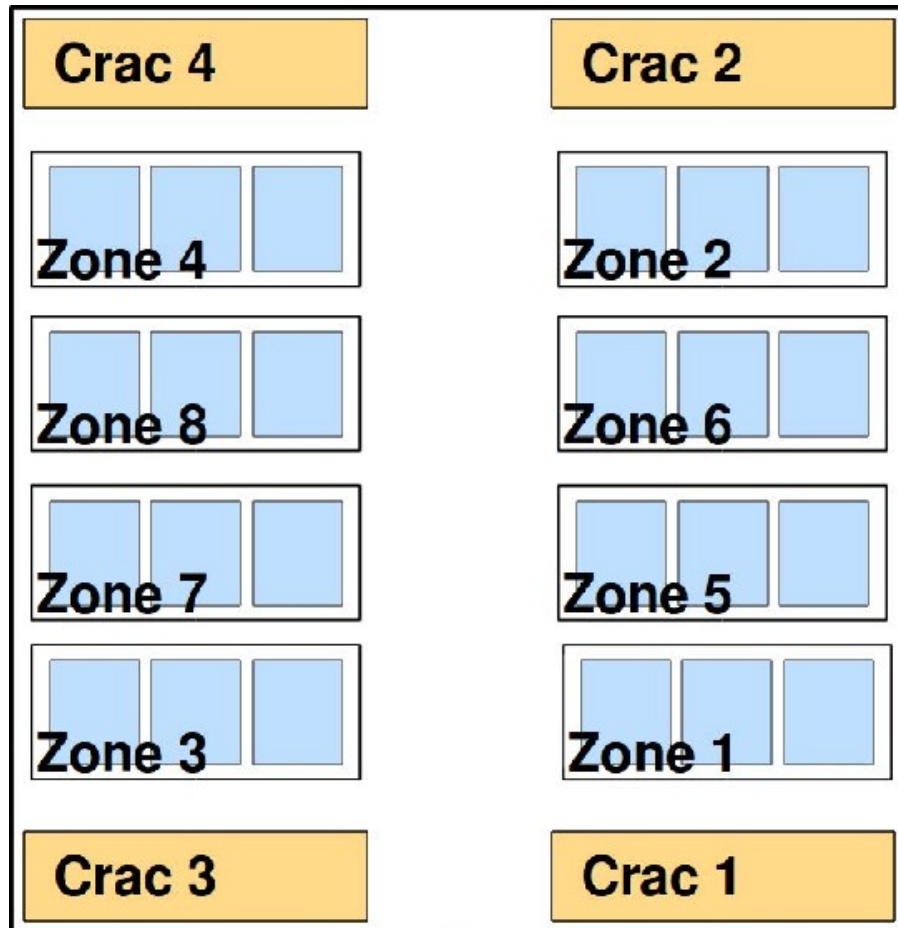


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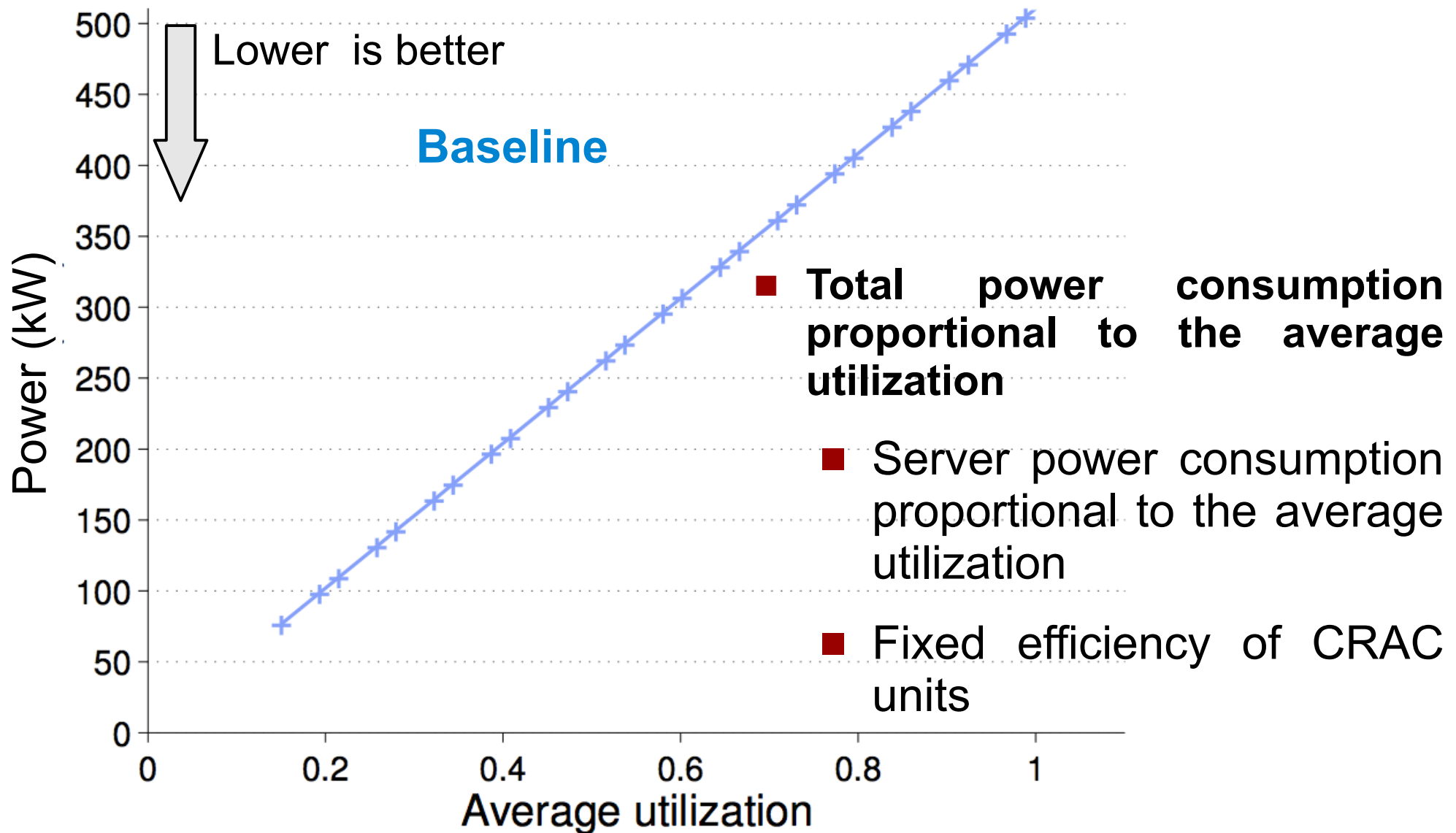
- **4 CRAC units**
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  - 3 Racks each (126 servers per zone)
  - Energy efficient servers
  - Efficiently cooled servers

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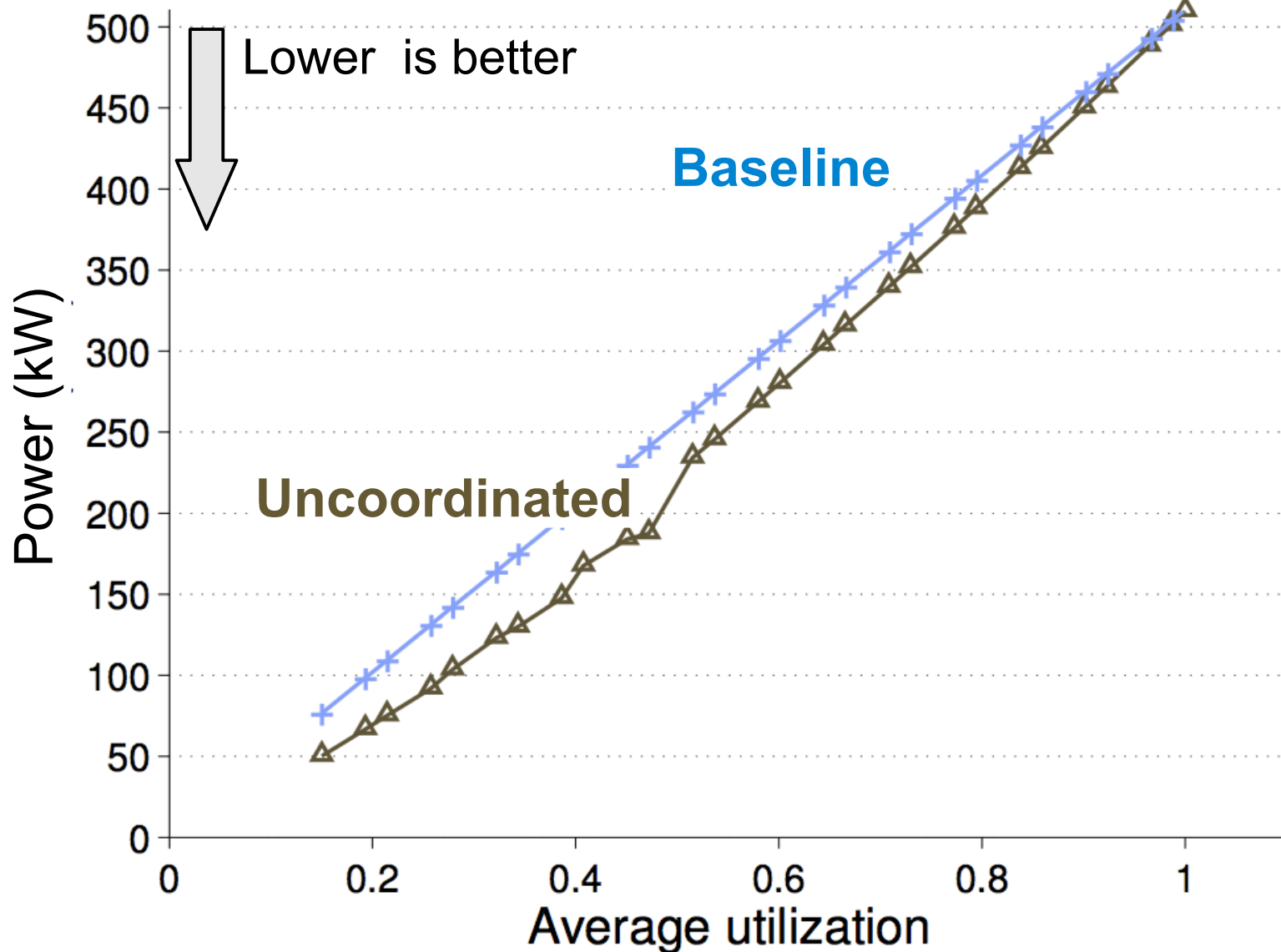


- **4 CRAC units**
  - Identical to each other
- **8 Zones**
  - 3 Racks each (126 servers per zone)
  - Energy efficient servers
  - Efficiently cooled servers
- **Analyze the average power consumption for different workload arrival rates**
- **Modeling language: TomSym**
- **Solver: KNITRO 7.0**

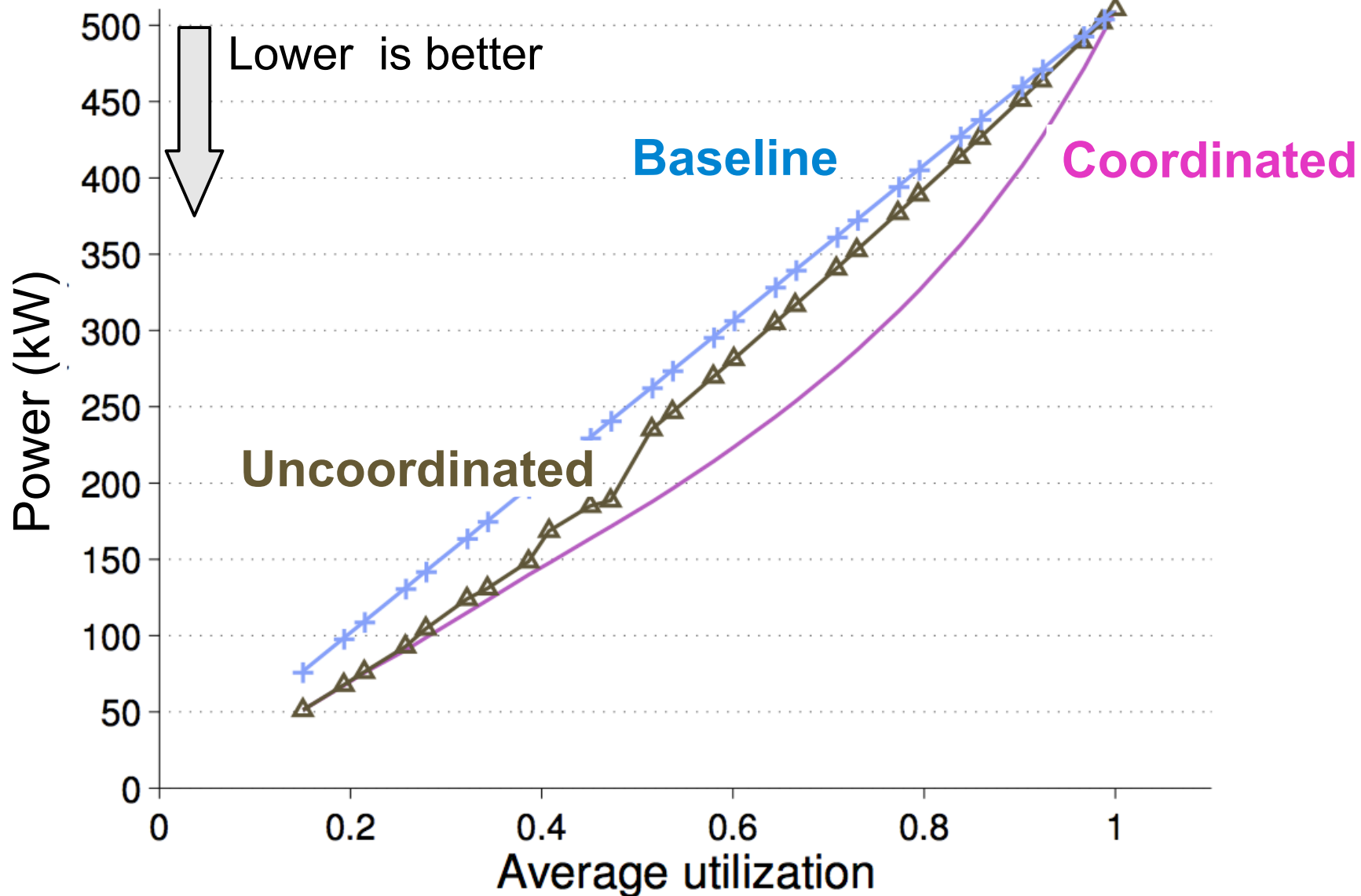
# Total power consumption



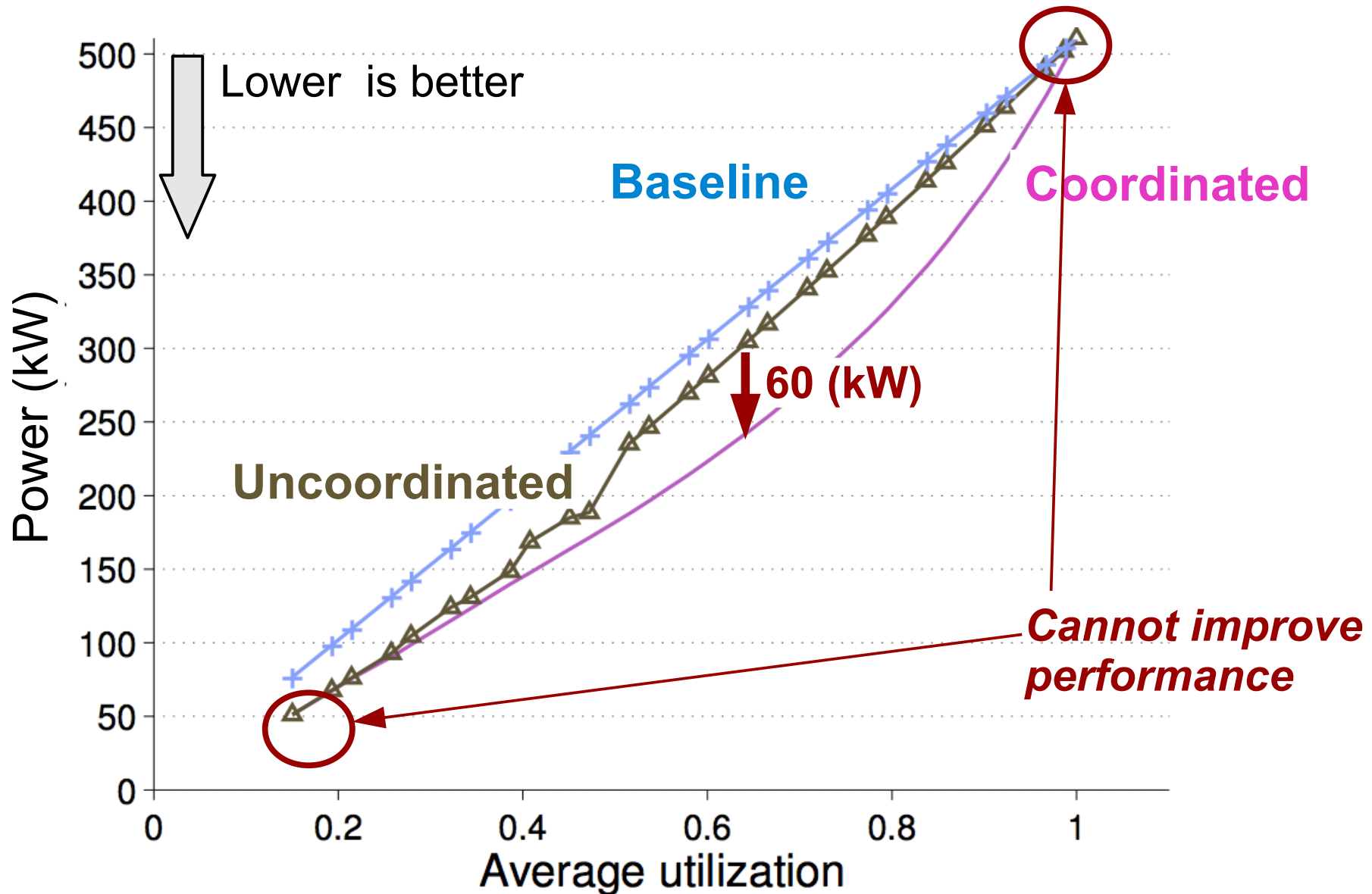
# Total power consumption



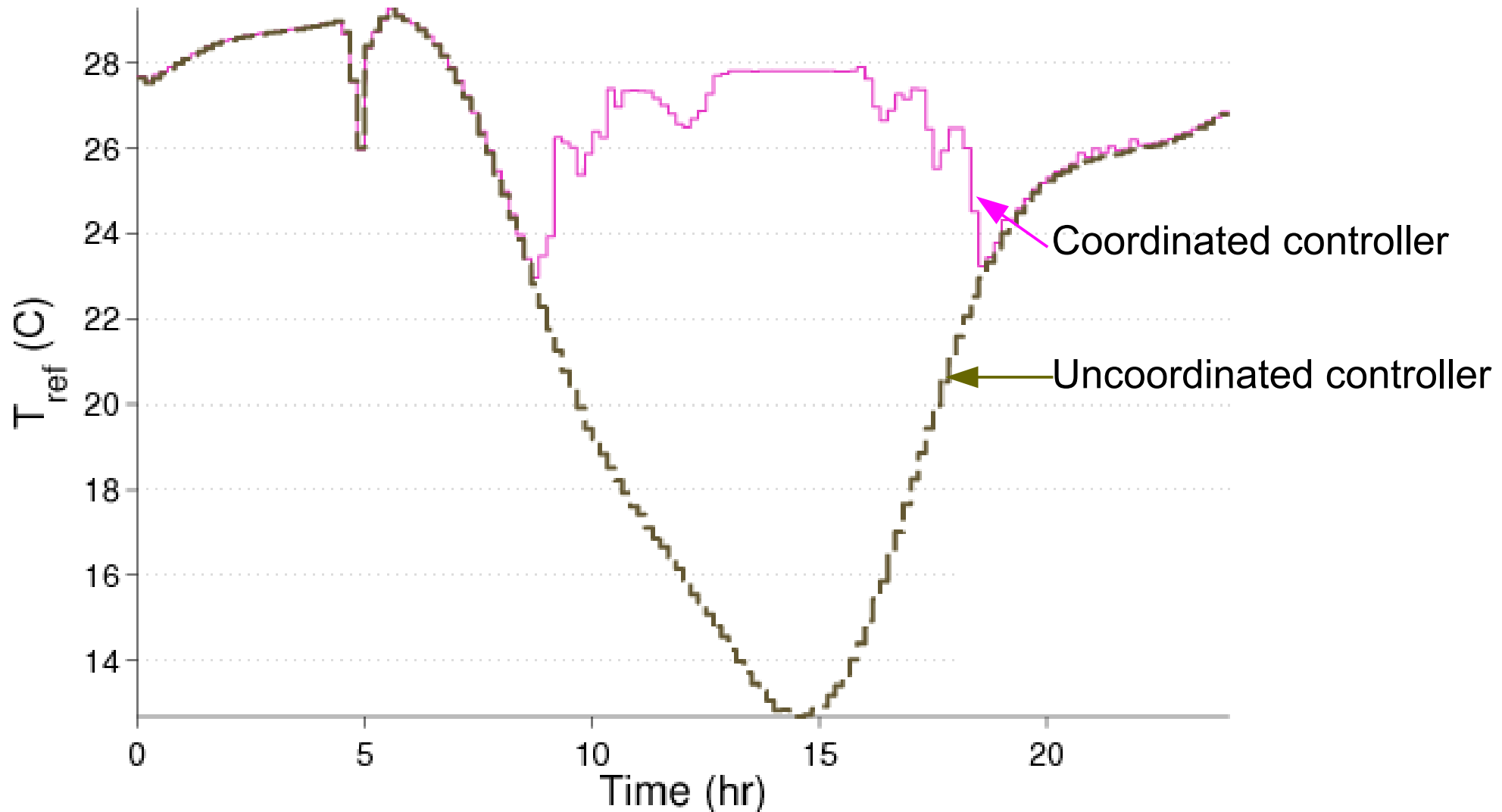
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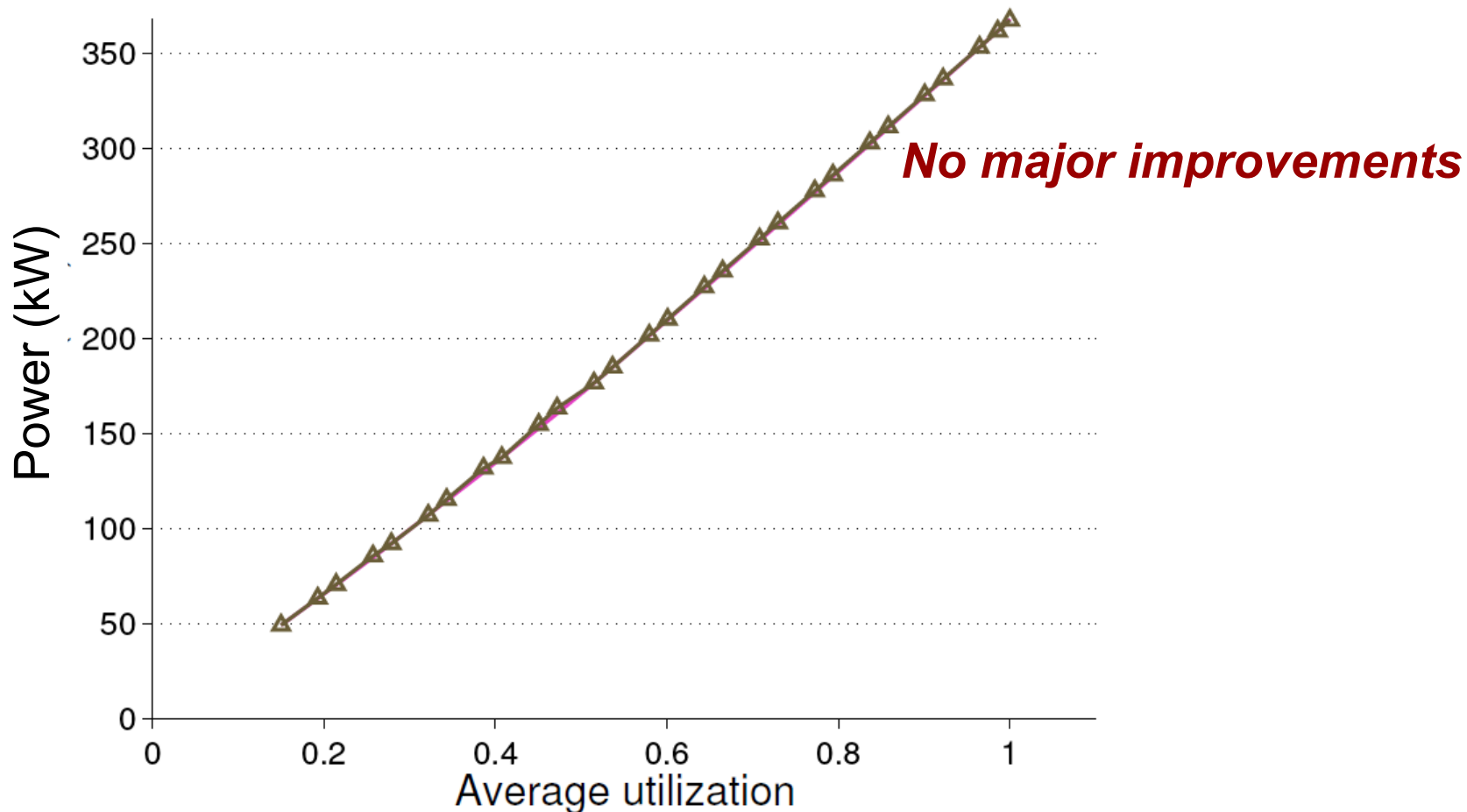
# Average reference temperatures





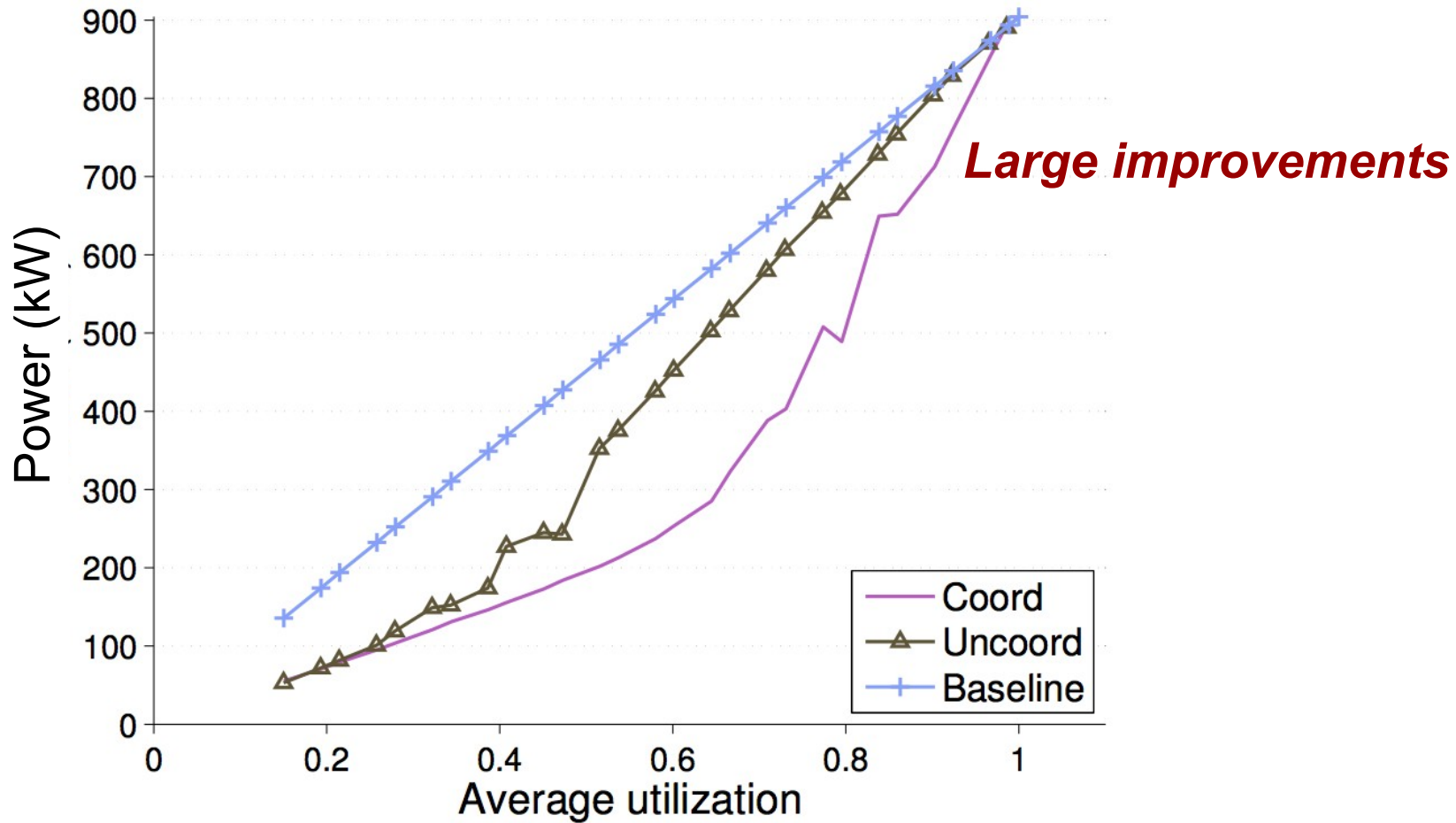
# Total power consumption

- How do the controllers perform when all of the zones are efficiently cooled?



# Total power consumption

- How do the controllers perform when large variability exists among the zone efficiency cooling?



# Cyber-Physical index

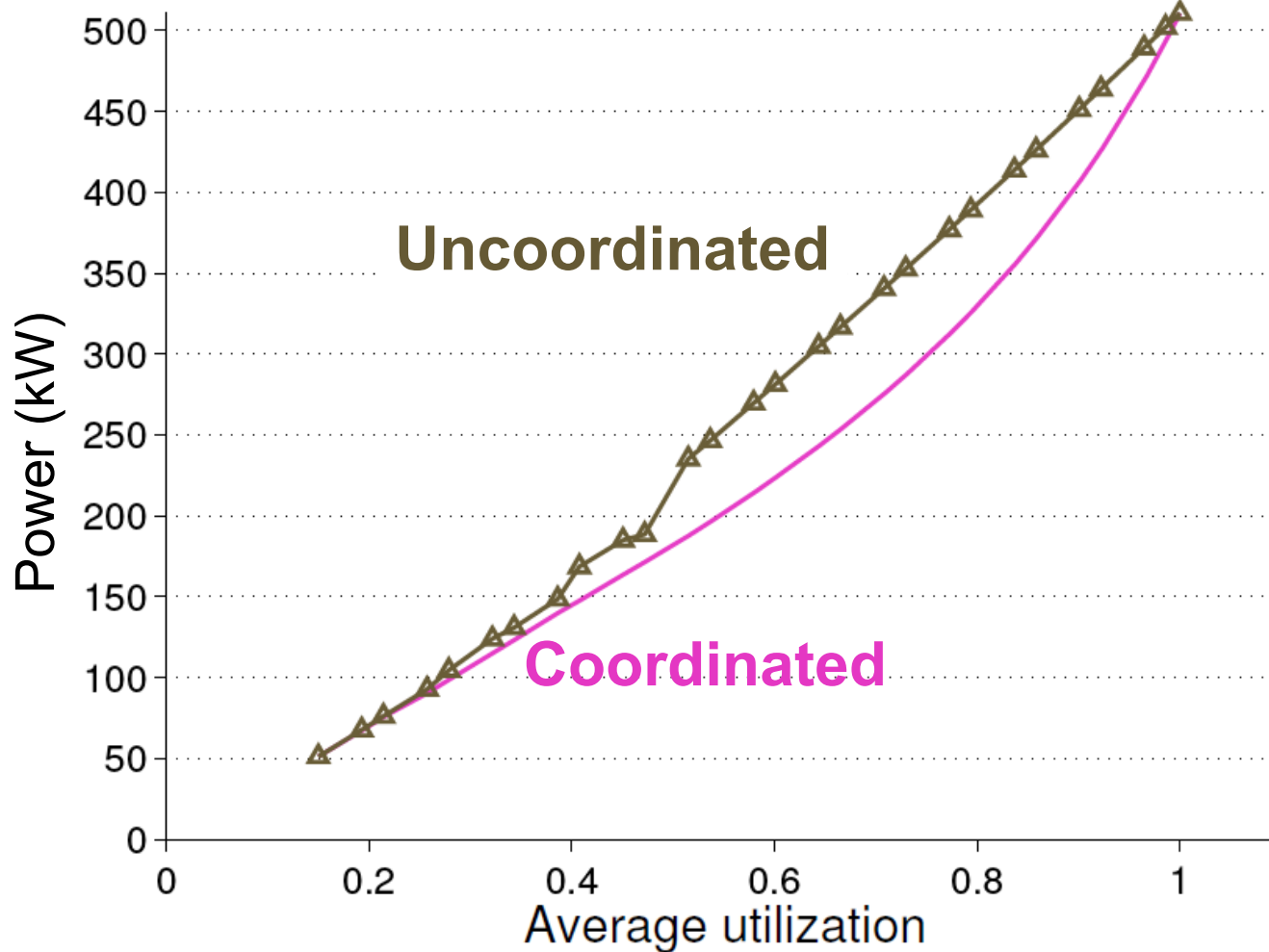
- **Given a data center**

- How much energy can be saved by a coordinated controller, with respect to an uncoordinated controller?

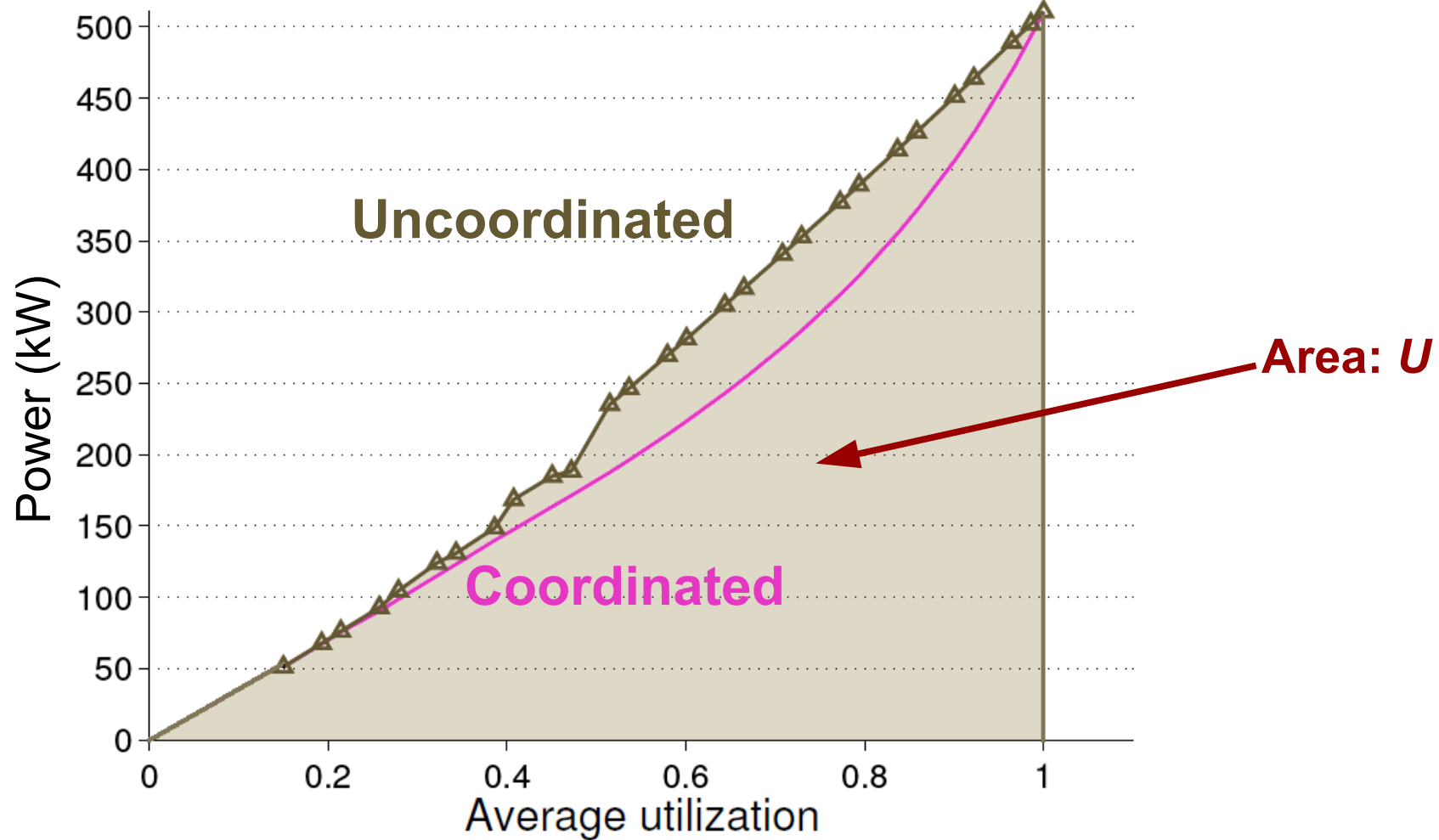
# Cyber-Physical index

- **Given a data center**
  - How much energy can be saved by a coordinated controller, with respect to an uncoordinated controller?
- **Cyber-Physical index (CPI), values in  $[0,1]$** 
  - When CPI is close to 1, then a coordinated approach is advisable
  - When CPI is close to 0, then an uncoordinated approach tends to be as efficient as a coordinated approach
- **CPI is function of the sensitivity of the zones with respect to variations of the workload departure rate and of reference temperatures**

# Relative efficiency

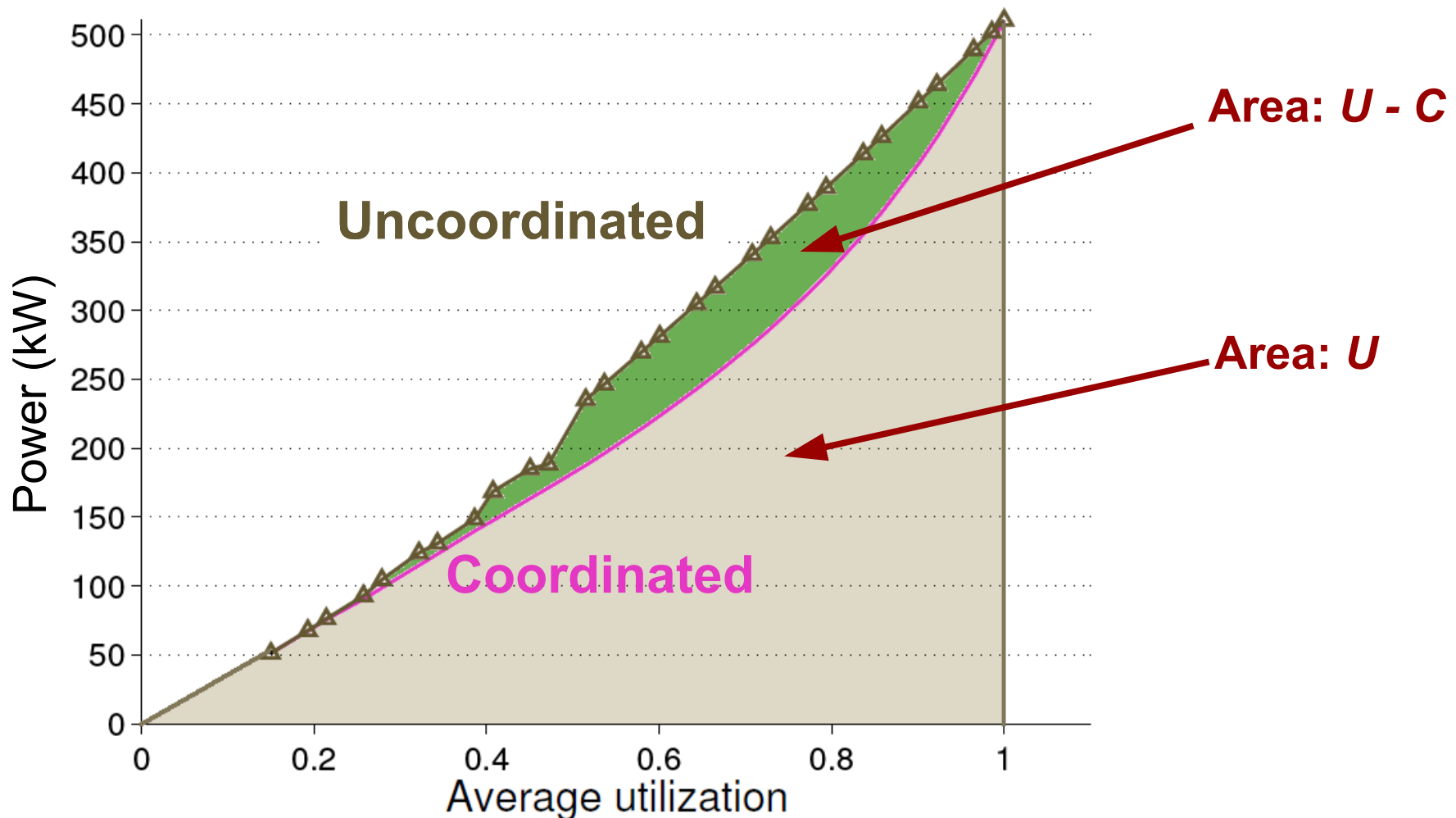


# Relative efficiency



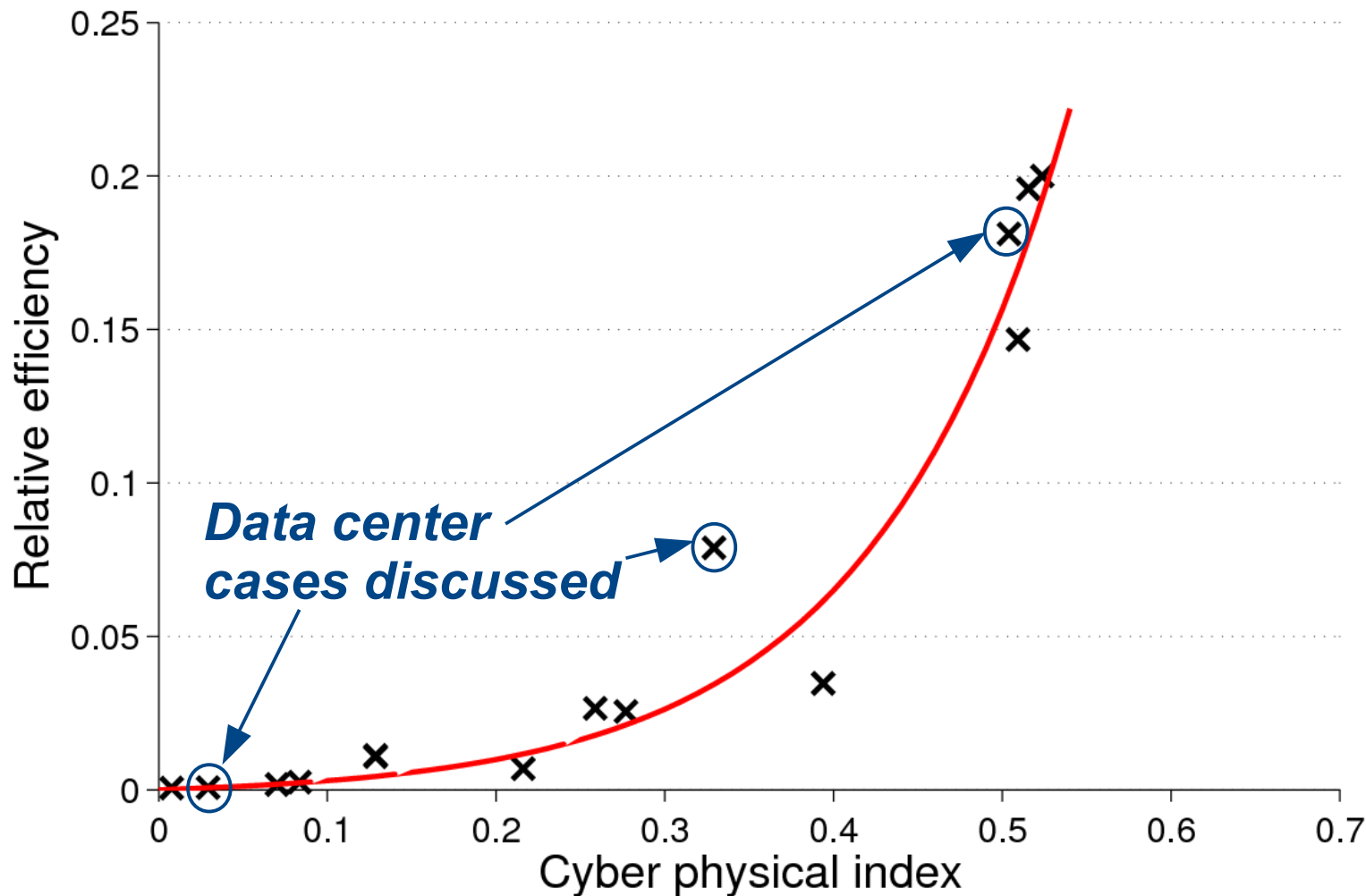
# Relative efficiency

■ Relative efficiency =  $\frac{U - C}{U}$



# Relative savings

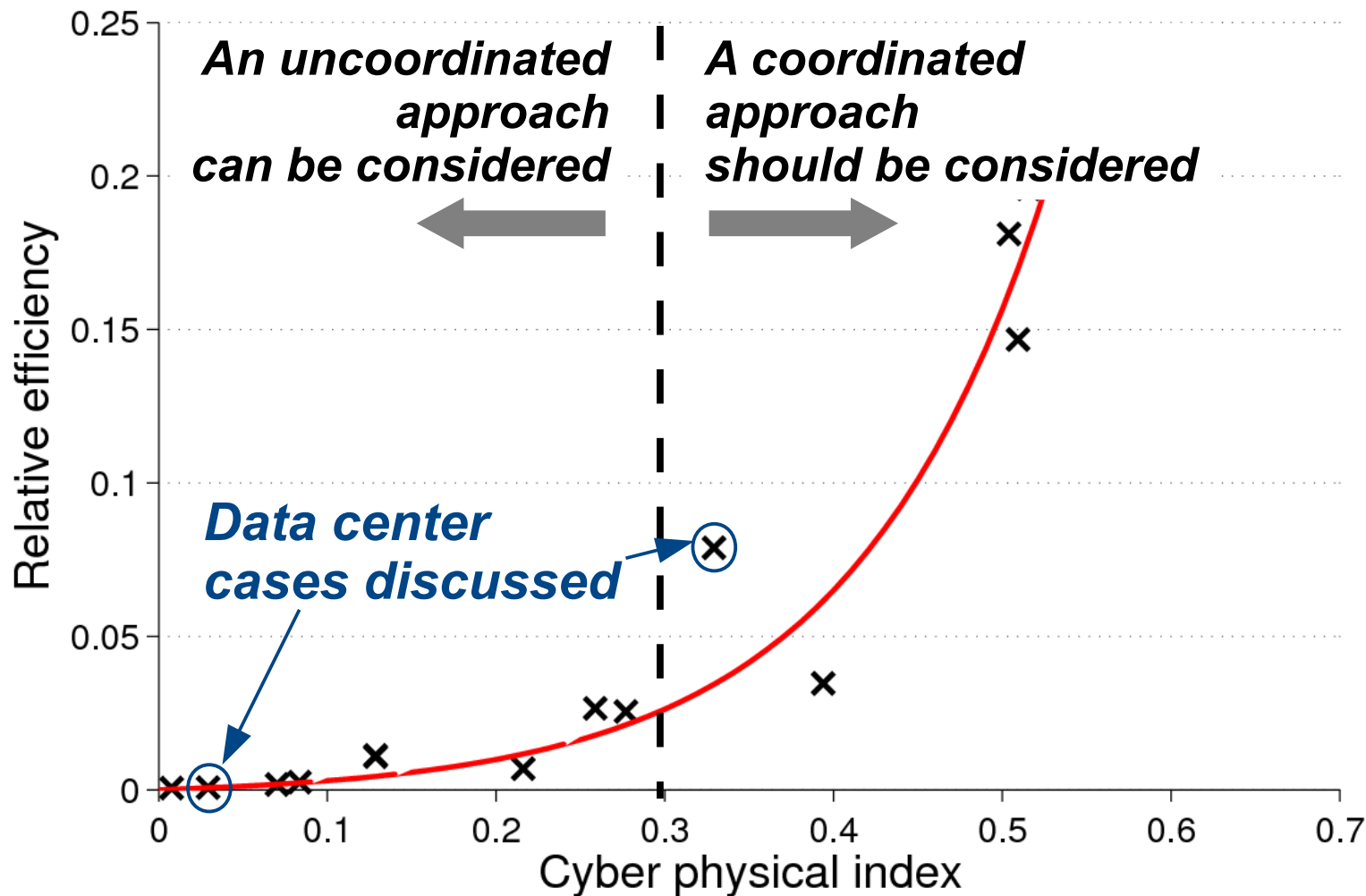
- Every point represents a different data center





# Relative savings

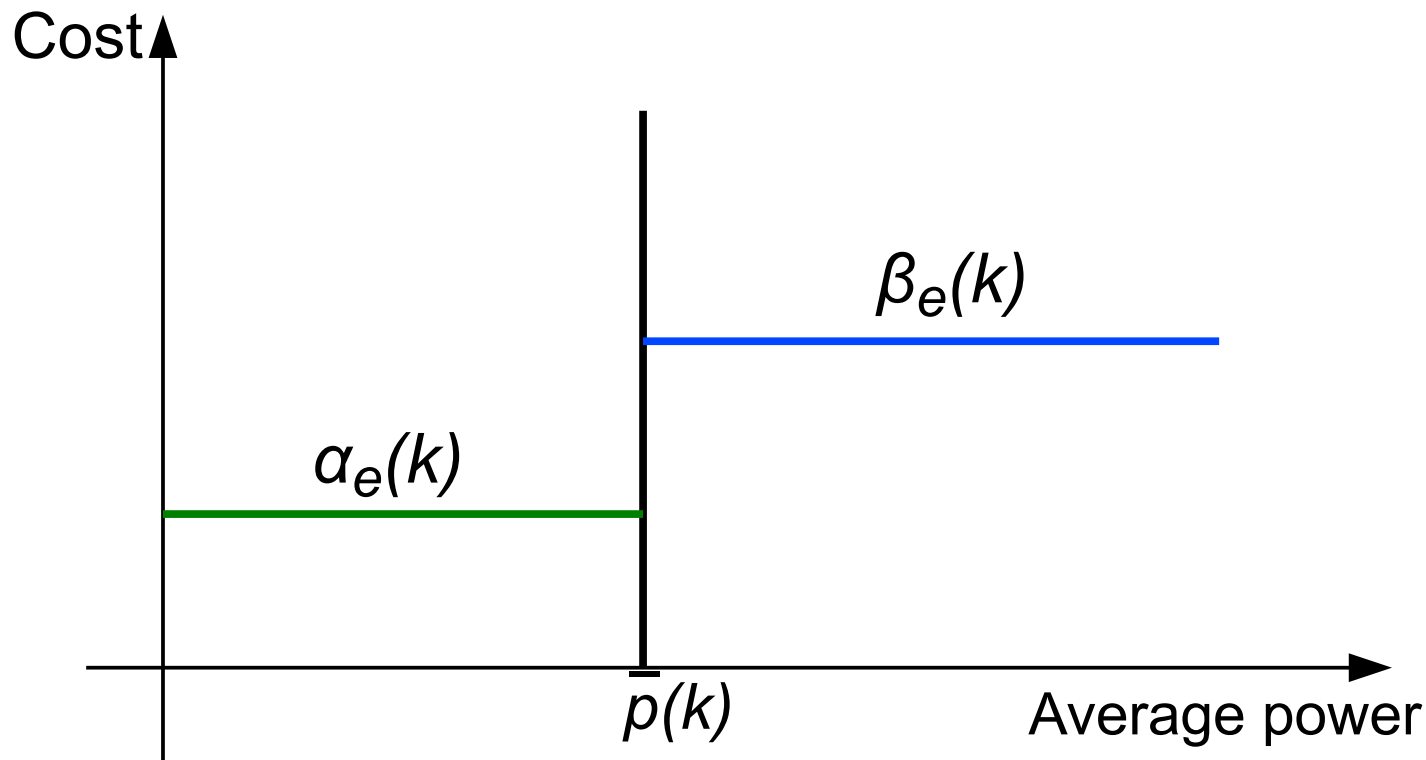
- Every point represents a different data center



# Interaction with the smart grid

## ■ Time-varying electricity price

- Used by the smart-grid to cap the average power consumption of the data center

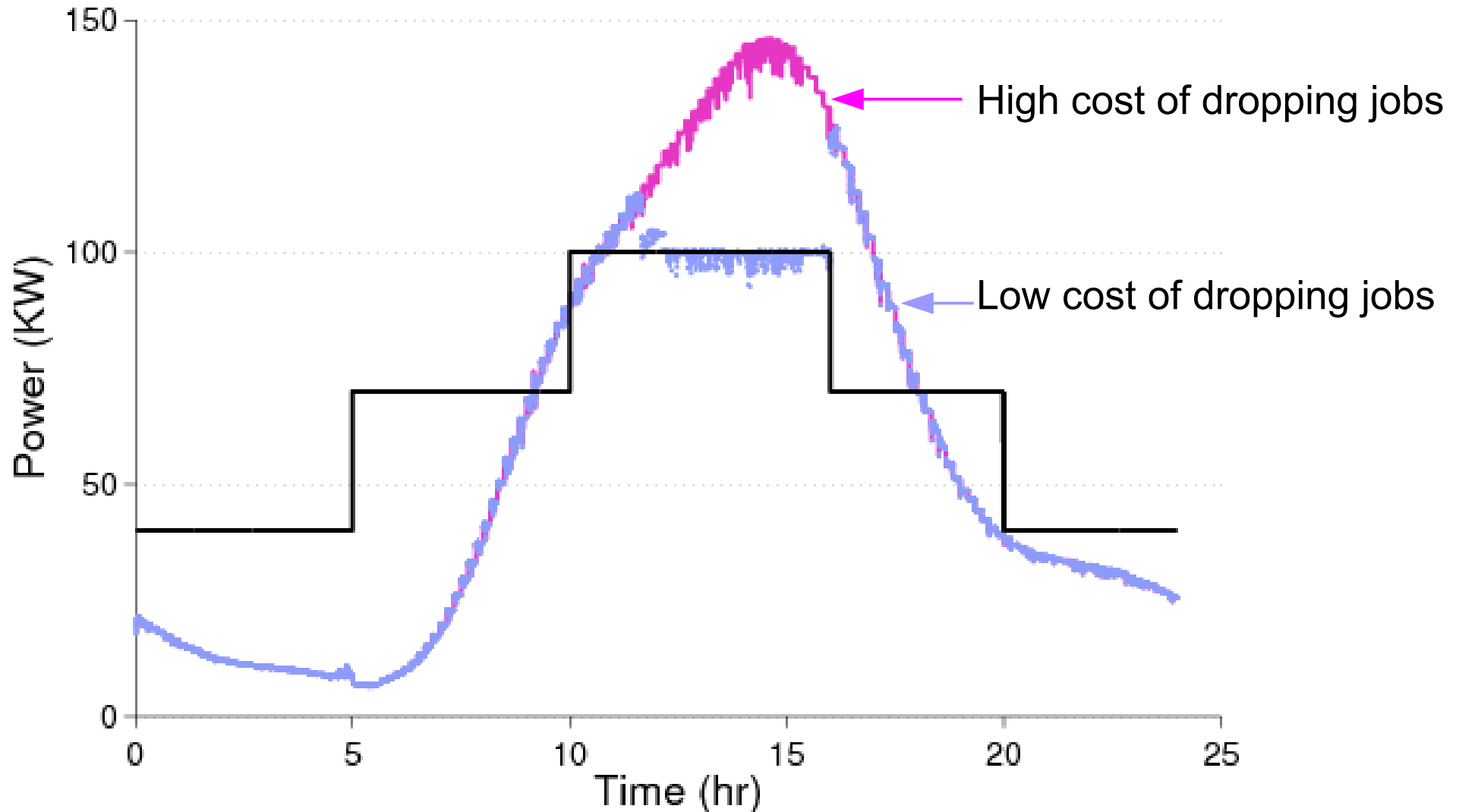


# Run-time cost

- Difference between income due to the workload processing and the cost of powering the data center
- Depends on two service level agreements (SLAs)
  - $SLA_U$ : sets the income based on the quality of service (QoS)
    - Approximated by the ratio between required and assigned hardware resources
  - $SLA_G$ : sets the data center's powering cost
    - The energy cost is time-varying and power consumption dependent



# Total data center power consumption



# Conclusion

- **Discussed a control-oriented data center model**
  - Considers both the computational and the physical characteristics of a data center
  - The model can be extended to consider electricity cost (interaction with the smart-grid) and other data center equipment
- **Introduced two control strategies**
  - Representative of different approaches to data center control
- **Compared the performance of the control strategies under the same scenario**
- **Proposed a cyber-physical index**
  - First attempt to characterize the thermal and computational characteristics of the data center within a single index
- **Analyzed the impact of time-varying electricity prices**

# Future work

- **Controllers can take advantage of service level agreements (SLAs) with both the users and the power grid**
  - Uncoordinated control approach can be as optimal as the coordinated approach
  - Depending on the SLA with the grid, the data center may induce large variations on the real-time electricity price
- **Given a data center, where should we locate its server so as to reduce its CPI?**
- **Feasibility and stability of coordinated and uncoordinated controller**
  - The coordinated controller is always feasible, but does not lead to a stable equilibrium point
  - How should the cost function be formulated so that the closed-loop system has a stable, economically optimal, equilibrium point?